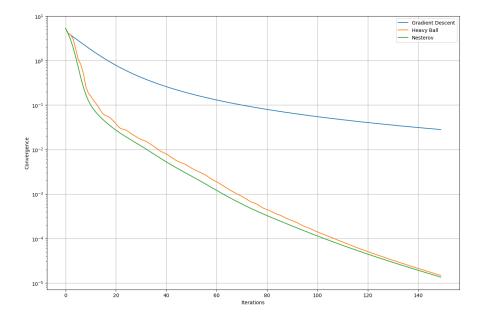
- a) part of the code
- b) mean accuracy (over 10 trials) using GD without stopping criteria: 0.76.
- c) mean iterations using GD: 707 mean accuracy using GD: 0.72
- d) I used beta = 0.91
  - 1) Heavy Ball: mean iterations using heavy ball: 71. mean accuracy using heavy ball: 0.74.
  - 2) Nesterov: mean iterations using Nesterov's method: 64. mean accuracy using Nesterov's method: 0.75.

I would choose Nesterov's method since it can achieve similar accuracies in the least number of iterations as compared to other methods. For the graph below, I used log scale for y-axis as a standard popular plotting method.



## Gradient used:

$$abla_W = X^T \cdot (P - Y) + \lambda \cdot W$$

Where:

- ullet X is the matrix of training examples.
- ullet P is the matrix of predicted probabilities (the softmax probabilities for each class).
- ullet Y is the matrix of one-hot encoded true class labels.
- ullet W is the matrix of weights.
- $\lambda$  is the regularization parameter.

## hw6 final

## November 28, 2023

```
[]: import numpy as np
     from scipy.io import loadmat
     import matplotlib.pyplot as plt
     # loading dataset
     data = loadmat('imagenet_data.mat')
     X = data['features']
     y = data['labels'].flatten()
     y = y.astype(int)
     # normalizing data
     X_mean = np.mean(X, axis=0)
     X_{norm} = X - X_{mean}
     X_norm /= np.linalg.norm(X_norm, axis=1, keepdims=True)
     X_norm = np.hstack((X_norm, np.ones((X_norm.shape[0], 1))))
     #defining constants
     mu = 0.01
     lambda_ = 0.1
     trials = 10
     no iters = 500
     epsilon = 1e-2
     beta = 0.91
     max_iters = 1000
     iters_plot = 150
     N = X.shape[0] # no of data pts
     C = len(np.unique(y)) # no of classes
     D = X.shape[1] + 1 # no of features + 1 (bias)
     train_size = int(N*0.9)
     test_size = N - train_size
[]: def grad_loss(x_train, y_train, y_enc, w, wx, lambda_):
         ##qradient
         wx_max = np.max(wx, axis=0)
         exp_diff = np.exp(wx - wx_max)
         pred = exp_diff / np.sum(exp_diff, axis=0)
         diff_y = pred - y_enc.T
         grad = np.dot(diff_y, x_train) + lambda_ * w
```

```
##loss
log_sum = np.log(np.sum(exp_diff, axis=0))
g_truth = wx[y_train, np.arange(wx.shape[1])]
loss = (lambda_ / 2) * np.sum(w**2) + np.sum(wx_max - g_truth + log_sum)
return grad, loss

def predict(w, x):
    return np.argmax(np.dot(x, w.T), axis=1)
```

```
[]: ### gd without stoppping criteria ###
     accuracy_ = np.zeros(trials)
     for i in range(trials):
         random_ = np.random.permutation(N)
         x_train = X_norm[random_[:train_size], :]
         y_train = y[random_[:train_size]]
         x_test = X_norm[random_[train_size:], :]
         y_test = y[random_[train_size:]]
         w = np.zeros((C, D))
         w_old = np.zeros((C, D))
         y_train_enc = np.eye(C)[y_train]
         for j in range(no_iters):
             w_x = np.dot(w, x_train.T)
             grad_, loss_ = grad_loss(x_train, y_train, y_train_enc, w, w_x, lambda_)
             w_new = w - mu * grad_
             w = w_new
         y_pred = predict(w, x_test)
         acc_tr = np.mean(y_pred == y_test)
         accuracy_[i] = acc_tr
     mean_acc = np.mean(accuracy_)
     print(f"Mean accuracy using GD without stopping criteria: {mean_acc:.2f}")
```

```
[]: ### gd with stoppping criteria ###

iter_tracker = np.zeros(trials)
accuracy_list = np.zeros(trials)
```

```
for i in range(trials):
         random_ = np.random.permutation(N)
         x_train = X_norm[random_[:train_size], :]
         y_train = y[random_[:train_size]]
         x_test = X_norm[random_[train_size:], :]
         y_test = y[random_[train_size:]]
         w = np.zeros((C, D))
         w_old = np.zeros((C, D))
         y_train_enc = np.eye(C)[y_train]
         for j in range(max_iters):
             w_x = np.dot(w, x_train.T)
             grad_, loss_ = grad_loss(x_train, y_train, y_train_enc, w, w_x, lambda_)
             exp1 = np.linalg.norm(grad_)**2
             exp2 = 1 + np.abs(loss_)
             if exp1 <= epsilon * exp2:</pre>
                 break
             w_new = w - mu * grad_
             w = w_new
         y_pred = predict(w, x_test)
         acc_tr = np.mean(y_pred == y_test)
         accuracy_list[i] = acc_tr
         iter_tracker[i] = j
     mean_iter = np.mean(iter_tracker)
     print(f"Mean iterations using GD: {int(mean_iter)}")
     mean_acc = np.mean(accuracy_list)
     print(f"Mean accuracy using GD: {mean_acc:.2f}")
[]: ### heavy ball ###
     iter_tracker_hb = np.zeros(trials)
     accuracy_list_hb = np.zeros(trials)
     for i in range(trials):
         random_ = np.random.permutation(N)
         x_train = X_norm[random_[:train_size], :]
         y_train = y[random_[:train_size]]
```

```
x_test = X_norm[random_[train_size:], :]
         y_test = y[random_[train_size:]]
         w = np.zeros((C, D))
         w_old = np.zeros((C, D))
         y_train_enc = np.eye(C)[y_train]
         for j in range(max_iters):
             w_x = np.dot(w, x_train.T)
             grad_, loss_ = grad_loss(x_train, y_train, y_train_enc, w, w_x, lambda_)
             exp1 = np.linalg.norm(grad_)**2
             exp2 = 1 + np.abs(loss_)
             if exp1 <= epsilon * exp2:</pre>
                 break
             w_new = w - mu * grad_ + beta * (w - w_old)
             w_old = w
             w = w_new
         y_pred = predict(w, x_test)
         acc_tr = np.mean(y_pred == y_test)
         accuracy_list_hb[i] = acc_tr
         iter_tracker_hb[i] = j
     mean_iter = np.mean(iter_tracker_hb)
     print(f"Mean iterations using heavy ball: {int(mean_iter)}")
     mean_acc = np.mean(accuracy_list_hb)
     print(f"Mean accuracy using heavy ball: {mean_acc:.2f}")
[]: ### Nesterov ###
     iter_tracker_nes = np.zeros(trials)
     accuracy_list_nes = np.zeros(trials)
     for i in range(trials):
         random_ = np.random.permutation(N)
         x_train = X_norm[random_[:train_size], :]
         y_train = y[random_[:train_size]]
         x_test = X_norm[random_[train_size:], :]
         y_test = y[random_[train_size:]]
```

w = np.zeros((C, D))
w\_old = np.zeros((C, D))

y\_train\_enc = np.eye(C)[y\_train]

```
for j in range(max_iters):
             z = w + beta * (w - w_old)
             z_x = np.dot(z, x_train.T)
             grad_z, loss_z = grad_loss(x_train, y_train, y_train_enc, z, z_x,_u
      →lambda_)
             exp1 = np.linalg.norm(grad_z)**2
             exp2 = 1 + np.abs(loss_z)
             if exp1 <= epsilon * exp2:</pre>
                 break
             w_new = z - mu * grad_z
             w_old = w
             w = w_new
             y_pred = predict(w, x_test)
             acc_tr = np.mean(y_pred == y_test)
             accuracy_list_nes[i] = acc_tr
             iter_tracker_nes[i] = j
     mean_iter = np.mean(iter_tracker_nes)
     print(f"Mean iterations using Nesterov's method: {int(mean_iter)}")
     mean_acc = np.mean(accuracy_list_nes)
     print(f"Mean accuracy using Nesterov's method: {mean_acc:.2f}")
[]: def calc_conv_gd(w_gd, x_train, y_train):
         conv_ = np.zeros(iters_plot)
         y_train_enc = np.eye(C)[y_train - 1]
         for i in range(iters_plot):
             w_x = np.dot(w_gd, x_train.T)
             grad_, loss_ = grad_loss(x_train, y_train, y_train_enc, w_gd, w_x,_
      →lambda_)
             exp1 = np.linalg.norm(grad_)**2
             exp2 = 1 + np.abs(loss_)
            conv_[i] = exp1 / exp2
             w_new = w_gd - mu * grad_
             w_gd = w_new
         return conv_
```

```
def calc_conv_hb(w_hb, x_train, y_train):
   conv_ = np.zeros(iters_plot)
   w_old = np.zeros((C, D))
   y_train_enc = np.eye(C)[y_train - 1]
   for i in range(iters_plot):
        w_x = np.dot(w_hb, x_train.T)
        grad_, loss_ = grad_loss(x_train, y_train, y_train_enc, w_hb, w_x,_u
 →lambda )
       exp1 = np.linalg.norm(grad_)**2
       exp2 = 1 + np.abs(loss_)
       conv_[i] = exp1 / exp2
       w_new = w_hb - mu * grad_ + beta * (w_hb - w_old)
       w_old = w_hb
       w_hb= w_new
   return conv_
def calc_conv_nes(w_nes, x_train, y_train):
   conv_ = np.zeros(iters_plot)
   w_old = np.zeros_like(w_nes)
   y_train_enc = np.eye(C)[y_train - 1]
   for i in range(iters_plot):
       z = w_nes + beta * (w_nes - w_old)
       z_x = np.dot(z, x_train.T)
       grad_z, loss_z = grad_loss(x_train, y_train, y_train_enc, z, z_x,_u
 →lambda )
        exp1 = np.linalg.norm(grad_z)**2
       exp2 = 1 + np.abs(loss_z)
       conv_[i] = exp1 / exp2
       w_new = z - mu * grad_z
       w_old = w_nes
       w_nes= w_new
   return conv_
```

```
[]: w_gd = np.zeros((C,D))
w_hb = np.zeros((C,D))
w_nes = np.zeros((C,D))

random_ = np.random.permutation(N)
x_train = X_norm[random_[:train_size], :]
y_train = y[random_[:train_size]]
```

```
conv_gd = calc_conv_gd(w_gd, x_train, y_train)
conv_hb = calc_conv_hb(w_hb, x_train, y_train)
conv_nest = calc_conv_nes(w_nes, x_train, y_train)

plt.figure(figsize=(15, 10))

plt.yscale('log')
plt.plot(range(iters_plot), conv_gd, label='Gradient Descent')
plt.plot(range(iters_plot), conv_hb, label='Heavy Ball')
plt.plot(range(iters_plot), conv_nest, label='Nesterov')

plt.xlabel('Iterations')
plt.ylabel('Convergence')
plt.legend()
plt.grid(True)
plt.show()
```