

Quiz 01

Version 01

Duration: 30 minutes

Student Name:

Student ID:

Student Tutorial:

Part 1: MSQ Questions (20 marks): *highest 20/25 correct answers will be considered*

- You have to answer by coloring the bubble otherwise the question will **NOT** be marked
- In case of **Otherwise**, you have to fill the dots with the correct answer.

Best of Luck 😊

#	<u>Questions</u>				<u>Answers</u>			
					<u>a</u>	<u>b</u>	<u>c</u>	<u>d</u>
1	The car braking system (ABS) is considered a real-time embedded system.				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) Soft	b) Firm	c) Hard	d) Weakly-hard				
2	An embedded system is general-purpose computers embedded into enclosing products and must interact with the physical environment				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) True	b) False	c)	d)				
3	PMU is an integrated circuit that is responsible for power handling the problem of undervoltage problem only.				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) True	b) False	c)	d)				
4	The real-time embedded systems are subjected to several constraints except for				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) Power capabilities	b) Memory Size	c) No User Interface	d) All of the Above				
5	For both μ Controllers and μ Processor, the memory is considered an essential part of the its internal architecture.				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) True	b) False	c)	d)				

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6	In all types of processors types, the CPU must exist				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) True	b) False	c)	d)				
7	<div style="border: 1px solid black; padding: 10px; margin: 10px;"> <pre>Struct Ta { Char Ta_name [15]; Short int office_number ; } Struct Ta x;</pre> </div> <p>What is the size in bytes of x?</p>				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) 15	b) 19	c) 17	d) Otherwise				
8	<div style="border: 1px solid black; padding: 10px; margin: 10px;"> <pre>void edit (int * a){ a = a+1 ; } int main(void) { int x = 5 ; edit(&x); printf(" the value of 'x' after edit is %d ", x); }</pre> </div> <p>Choose the correct printed value.</p>				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) 5	b) 6	c) 0x00000012	d) 0x00000016				
9	<p>Given that the first arr[0] address is 0x00000000 , what will be the printed statement:</p> <div style="border: 1px solid black; padding: 10px; margin: 10px;"> <pre>void edit_array (int * a){ a = a+2 ; // HINT : a is a local pointer carrying the address of arr (the array name) *(a) = (*a)+5 ; printf(" address is %p ", a); } int main(void) { int arr[] = {1,2,3,4} ; edit_array(arr); }</pre> </div>				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) address is 0	b) address is 0x00000003	c) address is 0x00000004	d) Otherwise				

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10	Based on question 9, choose the correct values if the array arr is printed after calling edit_array				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) {1,2,3,4}	b) {1,2,8,9}	c) {9,8,2,1}	d) <u>Otherwise</u>				
11	Choose the printed output: <pre> void multiply (int m){ m = m*5 ; printf(" 'm' is is %d ", m); } int main(void) { int x = 1 ; multiply(x); printf(" x is %d" , x); } </pre>				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) m is 5, x is 5	b) m is 5, x is 0	c) m is 1, x is 1	d) <u>Otherwise</u>				
12	Choose the printed output: <pre> void add (int t){ *t = *t + 5 ; printf(" 't' is is %d ", t); } int main(void) { int x = 1 ; add(&x); printf(" x is %d" , x); } </pre>				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) t is 6, x is 6	b) t is 1, x is 1	c) t is 6, x is 1	d) <u>Otherwise</u>				

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13	<div>Given that &x is 0x00000004 , &ptr_1 is 0x00000008, &ptr_2 is 0x00000012, and &ptr_3 is 0x00000016</div> <div><pre>int main(void) { int x = 16 ; int *ptr_1 = &x ; int **ptr_2 = &ptr_1 ; int * ptr_3 = ptr_1 ; printf(" value is %d" , **ptr_2) ; printf(" ptr_3 is %p", ptr_3) ; printf(" ptr_1 is %p" , ptr_1) ; }</pre></div>				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) value is 4, ptr_3 is 0x00000016, ptr_1 is 0x00000004	b) value is 16, ptr_3 is 0x00000004, ptr_1 is 0x00000008	c) value is 16, ptr_3 is 0x00000004, ptr_1 is 0x00000004	d) <u>Otherwise</u>				
14	From Figure 1 in page 6, this shows which type of processors				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) FPGA	b) ASIC	c) μ Controller	d) μ Processor				
15	From Figure 1, the architecture of this processor is following Architecture				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) Harvard	b) Von Neumann	c) Not Clear	d)				
16	From Figure 1, the shown processor instruction set type is				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) CISC	b) RISC	c) EPIC	d)				
17	From Figure 1, the processor is capable of optimizing the power.				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) True	b) False	c)	d)				
18	From Figure 1, the core of the processor is component (....)				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) (e)	b) (f)	c) (g)	d) (h)				

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19	From Figure 1, component (...) is considered part of the memory that can be erased by the user at any time				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) (h)	b) (i)	c) (j)	d) (k)				
20	From Figure 1, the interface with the physical environment is done through component (...)				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) (a)	b) (b)	c) (e)	d) (l)				
<p>Given that the temperature being measured is actually (25) ° C. Given that the sensor provides a group of readings as follows: [25.2,24.8,25.3,24.9,25.1]° C.</p>								
21	The average of these readings is $\bar{X} = \frac{1}{N} \sum_{n=1}^N X_n$				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) 24.3	b) 25.2	c) 24.76	d) <u>Otherwise</u>				
22	For sample 5: the measurement error is $\epsilon_n = X_{n, ideal} - X_{n, actual}$				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) 0.2	b) 0.02	c) 0.4	d) <u>Otherwise</u>				
23	For sample 5: the accuracy is $Acc_n = 1 - \left \frac{X_{n, ideal} - X_{n, actual}}{X_{n, ideal}} \right $				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) 99%	b) 97.2%	c) 100%	d) <u>Otherwise</u>				
24	For sample 5: the precision is $Prec_n = 1 - \left \frac{X_{n, actual} - \bar{X}}{\bar{X}} \right $				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) 99%	b) 97.2%	c) 100%	d) <u>Otherwise</u>				
25	These readings indicate that our sensor is characterized by				<input type="radio"/>	<input type="radio"/>	<input type="radio"/>	<input type="radio"/>
	a) High accuracy, High precision	b) High accuracy, Low precision	c) Low accuracy, High precision	d) Low accuracy, Low precision				

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Figure 1: Refer to for questions 14-20:

