

CP::pair

Create our own data structure

Intro

- We start writing our own data structure
 - In our own `namespace` (CP)
- We start with a `pair`
 - Good introduction on writing a class
 - Some C++ feature we need to use
 - `const`
 - pass-by-value, pass-by-ref
 - Header file

What should we write in a class

- Class name and namespace
- Member **variables** which define what data we want to store in the class
- Member **functions** which define behavior of the class and how member variable is manipulated
 - Include lots of special function such as **constructor**, **destructor** and **operator overloading**

CP::pair version 0.1 (minimal version)

- Templating
 - Parameter of a code
- No member functions

When we declare a pair,
T1 and T2 must be
declared as a type

In p1, T1 is int, T2 is string

In p2, T1 is bool, T2 is int

```
namespace CP {  
    template <typename T1,typename T2>  
    class pair{  
        public:  
            T1 first;  
            T2 second;  
    };  
}
```

```
int main() {  
    CP::pair<int,string> p1;  
    CP::pair<bool,int> p2;  
}
```

Capabilities

- Can hold 2 pieces of data
- Can use template
- Works with operator=
- Has copy constructor
- Cannot check equal
- Cannot check less than

```
#include <iostream>
#include <string>
using namespace std;
namespace CP {
    template <typename T1,typename T2>
    class pair{
    public:
        T1 first;
        T2 second;
    };
}

int main() {
    CP::pair<int,string> p1, p2; //default ctor
    p1.first = 20; p1.second = "somchai";
    CP::pair<int,string> a(p1); //copy ctor
    p2 = p1;

    cout << p2.first << "," << p2.second << endl;

    /*
    if (p1 == p2) { //won't compile
        cout << "yes" << endl;
    }

    if (p1 < a) { //won't compile
        cout << "yes" << endl;
    }
    */
}
```

CP::pair version 0.2

(comparator overload)

```
namespace CP {
    template <typename T1,typename T2>
    class pair{
    public:
        T1 first;
        T2 second;
        //----- operator -----
        bool operator==(const pair<T1,T2> &other) {
            return (first == other.first && second == other.second);
        }

        bool operator<(const pair<T1,T2>& other) const {
            return ((first < other.first) ||
                    (first == other.first && second < other.second));
        }
    };
}
```

operator< must be **const**

```
int main() {
    CP::pair<int,string> p1, p2; //default ctor
    p1.first = 20; p1.second = "somchai";
    CP::pair<int,string> a(p1); //copy ctor
    p2 = p1;
    cout << p2.first << "," << p2.second << endl;

    if (p1 == p2) { cout << "yes" << endl; }
    if (p1 < a) { cout << "yes" << endl; }
    set<CP::pair<int,int>> s;
    s.insert( {1,2} );
    cout << s.begin()->second << endl;
}
```

20,somchai
yes
2

Now, we can compare and use less<pair<T1,T2>> (and also set, map, priority queue)

const parameter in function

```
void test(int &x, const int& y) {  
    x++;           // Okay; doable  
    cout << y << endl; // Okay, we only read y  
    for (int i = 0; i < y; i++) { // Okay, too  
        cout << i << endl;  
    }  
    y--; // ERROR: we promise NOT to change Y  
}
```

- Declared by putting a keyword const as a prefix
- Const parameter must not be modified inside the function
- Why? So that we know that the function does not modify the data
 - Especially when we pass-by-reference

Recall pass-by-reference && pass-by-value

- Taken from the first slide (c++-intro.pdf)
- **Argument** = things we give to a function
- **Parameter** = variables inside a function

```
void pass_by_value(int x) {  
    cout << "X is" << x << endl;  
    x = 30;  
}  
  
void pass_by_reference(int &x) {  
    cout << "X is" << x << endl;  
    x = 40;  
}
```

```
int main() {  
    cout << "Pass by Value, direct" << endl;  
    pass_by_value(10);  
    cout << endl;  
  
    int x = 20;  
    cout << "Pass by value, variable" << endl;  
    pass_by_value(x);  
    cout << "outside PbR function x = " << x << endl;  
    cout << endl;  
  
    cout << "Pass by reference" << endl;  
    pass_by_reference(x);  
    cout << "outside PbR function x = " << x << endl;  
  
    //the following line cannot be compiled  
    //because we need reference  
    //pass_by_reference(20);  
}
```


Difference

Pass-by-value

- The **arguments** can be either constants or variables
- Modifying **parameters** (variable inside the function) does not change the **argument's** value
- The **argument's** value is copied to the parameter
 - **SLOWER!!!** Because we have to copy

Pass-by-reference

- The **arguments** must be variables
 - Except when we also use **const**
- The **parameters** are the argument's variables
 - Modify the **parameter** also modify the **argument's** variable
- **Faster**

const member function

```
class ccc {
public:
    int a,b;

    void inspect() const { // This function promises NOT to change anything
        if (a < b) cout << "yes" << endl; // Okay

        // b += 20;    // <--- NOT OKAY
    }

    void mutate() { // This function might change something
        if (a < b) a += 10; // Okay
    }
};

void test2(ccc& changeable, const ccc& unchangeable)
{
    changeable.inspect();    // Okay: doesn't change a changeable object
    changeable.mutate();    // Okay: changes a changeable object
    unchangeable.inspect();  // Okay: doesn't change an unchangeable object
    unchangeable.mutate();  // ERROR: attempt to change unchangeable object
}
```

- Declared by putting a keyword `const` after the function declaration
- Const member function cannot modify any member data
 - Also cannot call any other member function that is not const
- Why? So that we know that the function does not modify the data

Custom Constructor

- In STL spec of `std::pair`, it has custom constructor called **initialization constructor**

```
namespace CP {  
    template <typename T1,typename T2>  
    class pair{  
    public:  
        T1 first;  
        T2 second;  
  
        // custom constructor  
        pair(const T1 &a,const T2 &b) {  
            first = a;  
            second = b;  
        }  
  
        //----- operator -----  
        bool operator==(const pair<T1,T2> &other) {...}  
        bool operator<(const pair<T1,T2>& other) const {...}  
    };  
}
```

```
int main() {  
    CP::pair<int, bool> p(10,false);  
    CP::pair<string, int> q("abc",42), r("",0);  
  
    cout << (q < r) << endl;  
    priority_queue<CP::pair<string,int>> pq;  
    pq.push(r);  
    pq.push(q);  
    cout << pq.top().first << endl;  
  
    CP::pair<string, int> x(q);  
    CP::pair<string, int> y = x;  
  
    //-- all below cannot be compiled --  
    //CP::pair<string, int> w;  
    //vector<CP::pair<int,int>> v(10);  
}
```

When we have a constructor, a default constructor is not auto-generated

0
abc

Initialization List

- Instead of writing a code to assign a value to each member, we can use **initialization list**
 - A little bit shorter code
 - Also little bit faster
 - Only way to init **const** member

```
namespace CP {  
    template <typename T1,typename T2>  
    class pair{  
    public:  
        T1 first;  
        T2 second;  
  
        // custom constructor, using initializer list  
        pair(const T1 &a, const T2 &b) : first(a), second (b) { }  
    }  
}
```

Default Constructor

- A constructor is used when we simply declare an object
- Auto-generated as initialization of all members with its default constructor
- Won't be auto-gen if we have any other constructor

```
namespace CP {
    template <typename T1,typename T2>
    class pair{
    public:
        T1 first;
        T2 second;

        // ----- constructor -----
        pair() : first(), second() { }
        pair(const T1 &a, const T2 &b) : first(a), second (b) { }
        //----- operator -----
        //...

    };
}
```

```
int main() {
    CP::pair<int, bool> p(10,false);
    CP::pair<string, int> q("abc",42), r("",0);

    cout << (q < r) << endl;
    priority_queue<CP::pair<string,int>> pq;
    pq.push(r);
    pq.push(q);
    cout << pq.top().first << endl;

    CP::pair<string, int> x(q);
    CP::pair<string, int> y = x;

    //-- all below Okay now --
    CP::pair<string, int> w;
    vector<CP::pair<int,int>> v(10);
    for (auto &x: v) { cout << x.first << endl;}
}
```

Include File

- Usually, our data structure (which is written as a class) will be used by several programs in several files.
 - It is better NOT TO copy our data structure code into each each file
- Rather, put our code in a file and include it where it is needed
 - Better if we want to change it
 - Better compilation
- Introducing “.h” files

C++ header file (.h) and #include

- To put a content of one file into another file, we use `#include "filename"` keyword
- C++ will simply put the content of `filename` into where we `#include` it
- `#includes` has more benefit
 - separation of **declaration** (what it is) and **definition** (how it works)
 - Not really explored in this class
- We usually use `.h` for a file that we will include but this is not a rule, we can use other extension

```
class a {  
    int m1,m2;  
};
```

a.h

```
#include "a.h"  
  
class b {  
    a x;  
};
```

b.h

```
#include "a.h"  
  
class c {  
    a y;  
};
```

c.h

```
class a {  
    int m1,m2;  
};  
  
class b {  
    a x;  
};
```

```
class a {  
    int m1,m2;  
};  
  
class c {  
    a y;  
};
```

Problem with include

```
class a {  
    int m1,m2;  
};
```

```
#include "a.h"  
  
class b {  
    a x;  
};
```

```
#include "a.h"  
  
class c {  
    a y;  
};
```

```
#include "b.h"  
#include "c.h"  
  
int main() {  
    b b1;  
    c c1;  
}
```

```
class a {  
    int m1,m2;  
};
```

```
class b {  
    a x;  
};
```

```
class a {  
    int m1,m2;  
};
```

```
class c {  
    a y;  
};
```

```
int main() {  
    b b1;  
    c c1;  
}
```

There is
multiple copy
of class a

Problem with include

```
#ifndef A_H
#define A_H
class a {
    int m1,m2;
};
#endif
```

```
#include "a.h"

class b {
    a x;
};
```

```
#include "a.h"

class c {
    a y;
};
```

```
#include "b.h"
#include "c.h"

int main() {
    b b1;
    c c1;
}
```

```
#ifndef A_H
#define A_H
class a {
    int m1,m2;
};
#endif
```

```
class b {
    a x;
};
```

```
#ifndef A_H
#define A_H
class a {
    int m1,m2;
};
#endif
```

```
class c {
    a y;
};
```

```
int main() {
    b b1;
    c c1;
}
```

class a here is taken out of compilation, because A_H is defined

```

#ifndef _CP_PAIR_INCLUDED_
#define _CP_PAIR_INCLUDED_

#include <iostream>

namespace CP {
    template <typename T1,typename T2>
    class pair {
    public:
        T1  first;
        T2  second;

        // default constructor, using list initialize
        pair() : first(), second() {}

        // custom constructor, using list initialize
        pair(const T1 &a,const T2 &b) : first(a), second(b) { }

        // equality operator
        bool operator==(const pair<T1,T2> &other) {
            return (first == other.first && second == other.second);
        }
        // comparison operator
        bool operator<(const pair<T1,T2>& other) const {
            return ((first < other.first) ||
                    (first == other.first && second < other.second));
        }
    };
}
#endif

```

Final Version

Summary

Major

- **Templating**: allow use to write a code that works with different data type
- **Constructor**: a function called when we create a variable
 - Default constructor
- **Operator overloading** for less-than and equality
- pass-by-ref vs pass-by-value

Minor

- Header file
- const
- List initialization

Exercise (no grader)

1. Modify `operator<` so that it compare `second` before `first`
2. Modify `operator<` so that when we call `sort(v.begin(), v.end())` where `w` is a vector of our pair, it is sorted from `Max` to `Min`
3. Write `operator!=` and `operator>=`

CP::vector

Our first “real” data structure

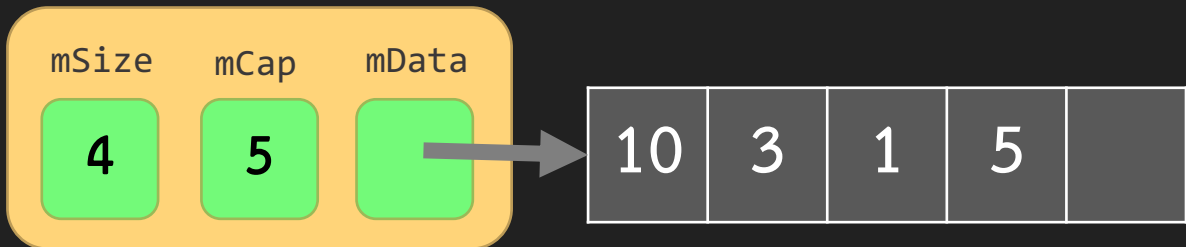
Intro

- Now we will create more complex data structure `CP::vector`
- It can store variable length array
 - Implemented as a dynamic array
- Can be accessed by operator `[]`
 - Additional operator to be overloaded
- We also have to create our own iterator
 - Implemented as a pointer

Key Idea

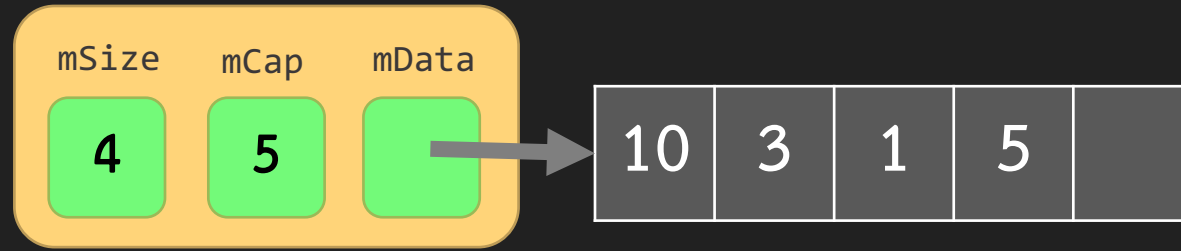
- Vector stored 3 things (3 member data)
 - **mData**: A dynamic array, large enough to store current data and might have reserved space
 - **mSize**: Number of data stored
 - **mCap**: Size of the dynamic array (maybe larger than **mSize**)
- If the dynamic array is full and more data is being added, we create a new dynamic array and relocate data to the new array
 - This is called **expand**
 - Each **expansion** takes very long time
- Dilemma
 - large reserve = less often relocation but use more memory
 - Small reserve = more frequent relocation but less memory

vector

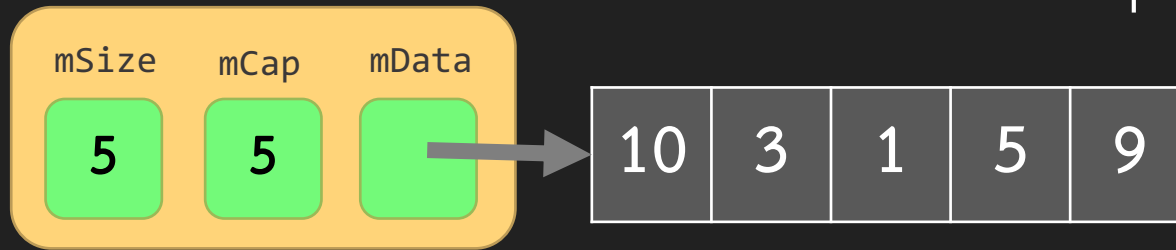


Example

vector



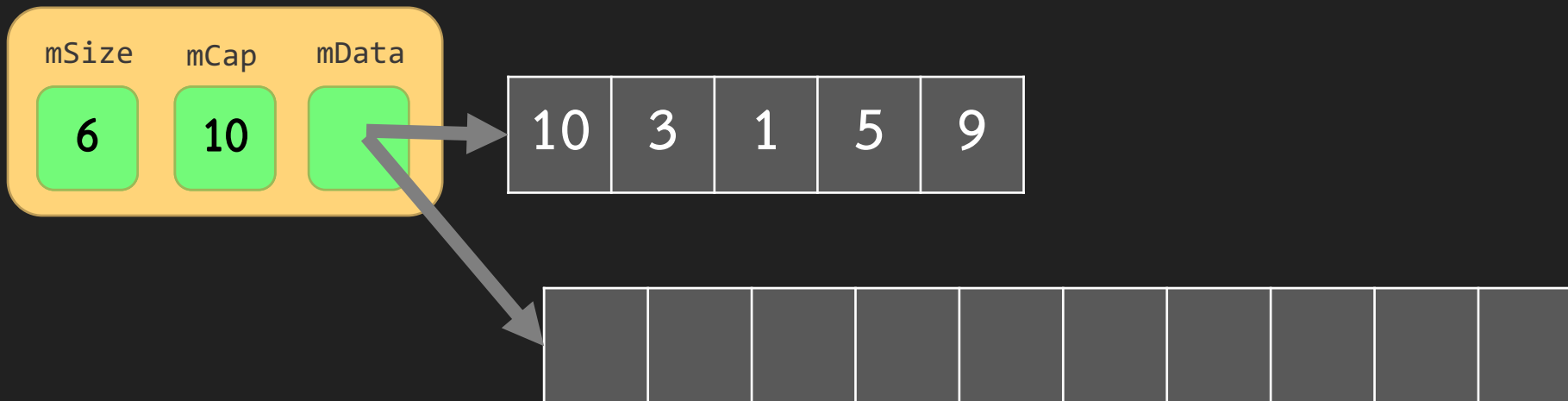
vector



push_back (9)

push_back (4)

vector



How much reserve should we have?

- Whenever we need to relocate, we **double** the capacity that we currently have
- If we start with a vector with zero size and continuously add data one by one, for example by `push_back`
 - Each expansion will take time **equal** to **the number of data** when we relocate (this is very slow)
- By double the size every time we expand, we can show that on average, **each addition of a data** (such as `push_back`, `insert`) **takes constant time!!!**

Pointer

How to implement a dynamic array
(and also iterator)

Pointer & Memory

- Each variable is some block in computer memory
 - Programming language just map our **variable name** to that **block of memory**
 - Programming language works with the address of that block
- Pointer variable is a variable that store **address of memory**
 - Pointer needs type, i.e., address of int is not the same as address of bool
 - We can use operator **&** to ask for the **address** of a **variable**
 - We can use operator ***** to ask for the **data** of an **address**

Example

```
int x,y; //this is normal variable x and y
int *a;  //this is int pointer variable y
int *b;  //another int pointer
```

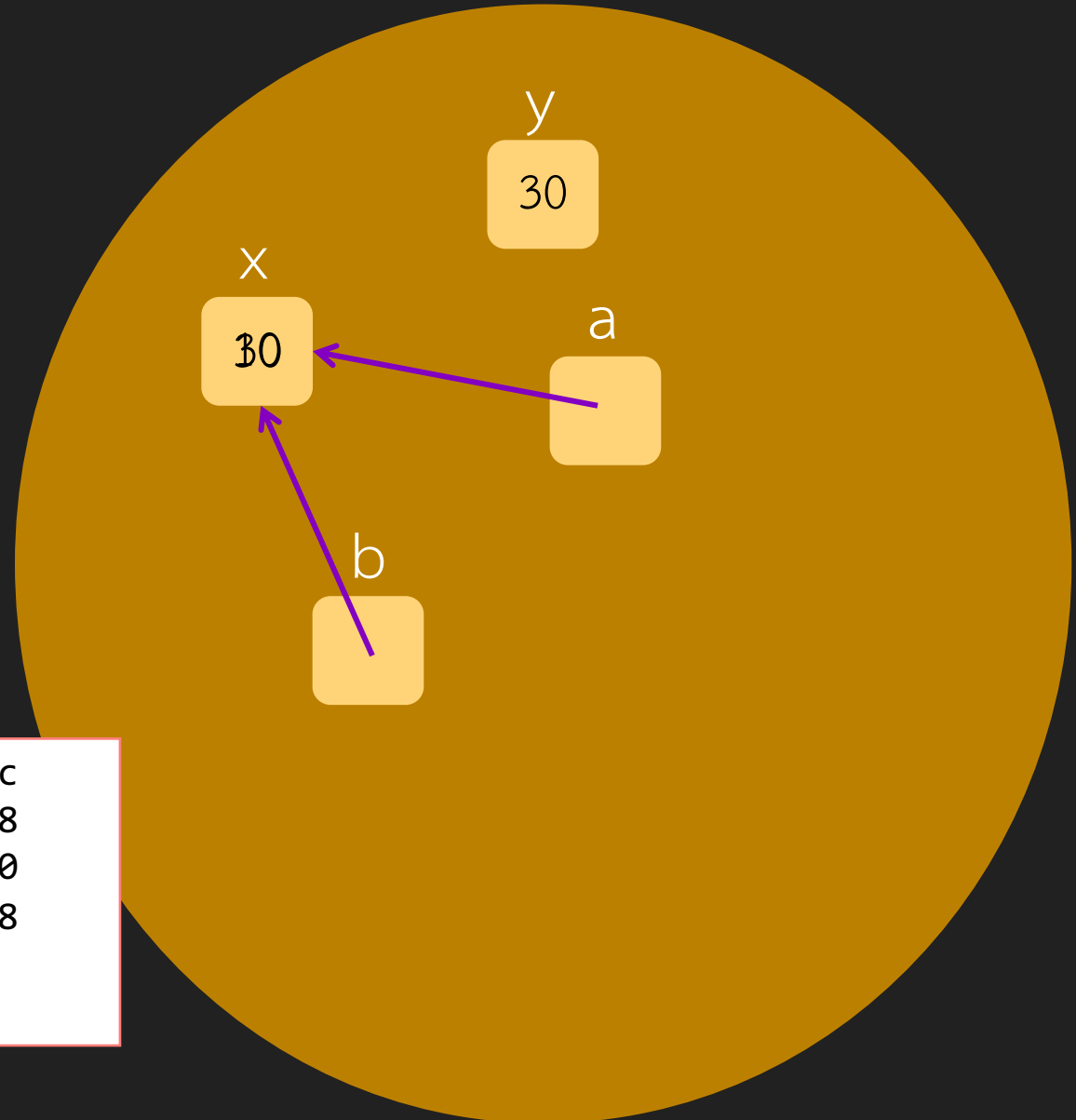
```
x = 10;
a = &x;
b = a;
*b = 30;
y = *b;
```



```
cout << &x << endl;
cout << &y << endl;
cout << &a << endl;
cout << &b << endl;
cout << sizeof(int) << endl;
cout << sizeof(int*) << endl;
```

```
0x7ffee22885ac
0x7ffee22885a8
0x7ffee22885a0
0x7ffee2288598
4
8
```

computer memory



Pointer Arithmetic

- Pointer can be added, subtracted by integer
 - It moves the address by the size of the type of the pointer
 - For example when X is an int (which is 4 bytes) X + 10 result in an address 40 bytes away from X
- Two pointers of the same type can be subtracted
 - The result is the address difference divided by size of the type of the pointer

```
int main()
{
    bool x, y, z;
    x = 1; y = 2; z = 3;
    bool *a,*b;

    a = &x;
    b = a+2;

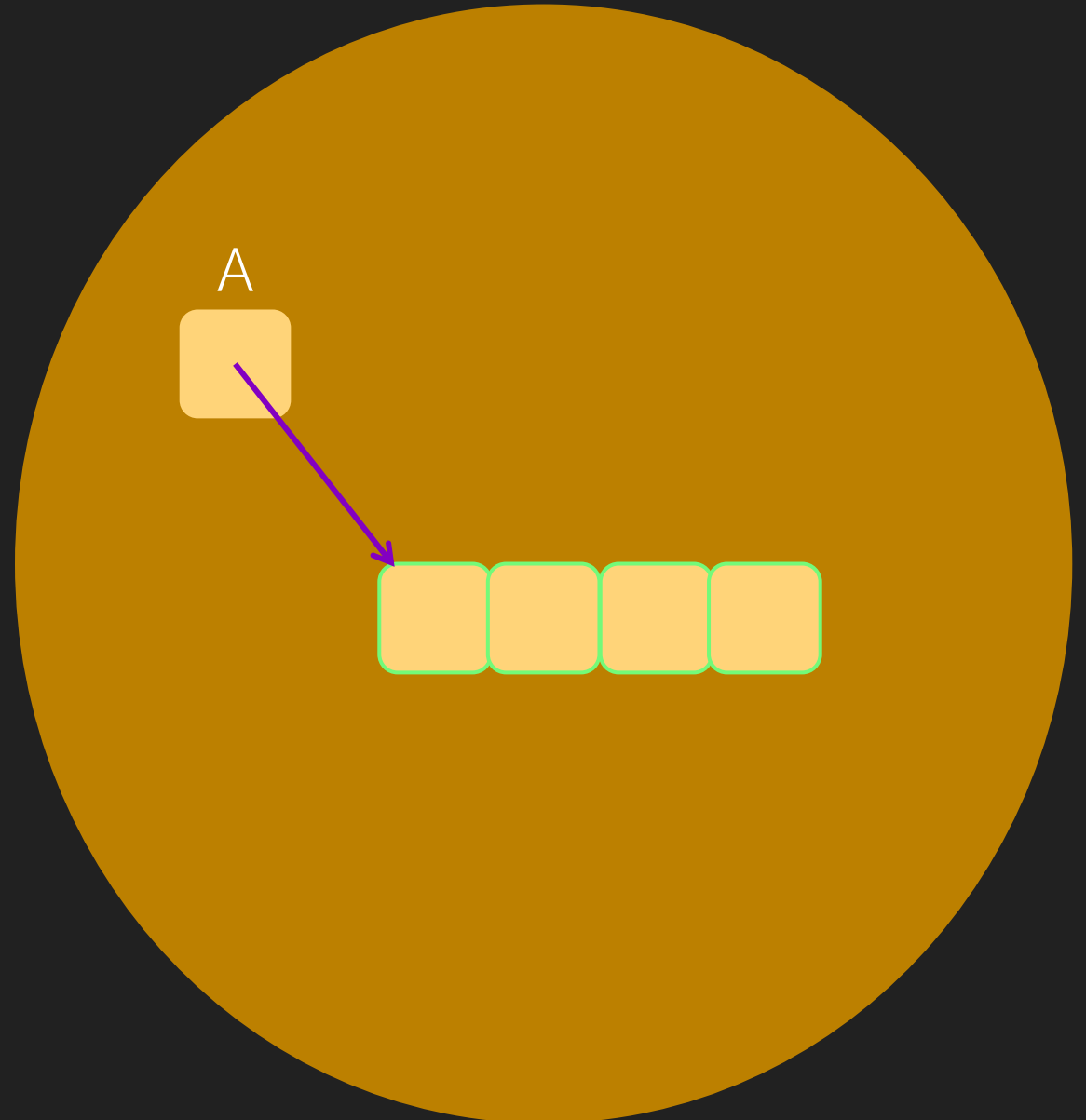
    cout << "&x = " << &x << endl;
    cout << "&y = " << &y << endl;
    cout << "&z = " << &z << endl;
    cout << " a = " << a << endl;
    cout << " b = " << b << endl;
    cout << b-a << endl;
}
```

```
&x = 0x6afedd
&y = 0x6afede
&z = 0x6afedf
a = 0x6afedd
b = 0x6afedf
2
```

Dynamic Array

- Dynamic Array variable of type T is a pointer to the starting address of consecutive block of type T
- Let A be a dynamic array of int
 - A[x] refer to the xth block starting from A
- Static array works in the same way, that's why accessing A[x] is very fast for an array
 - It just refers to the address
A[x] is $*(A + x * \text{size_of}(T))$

computer memory



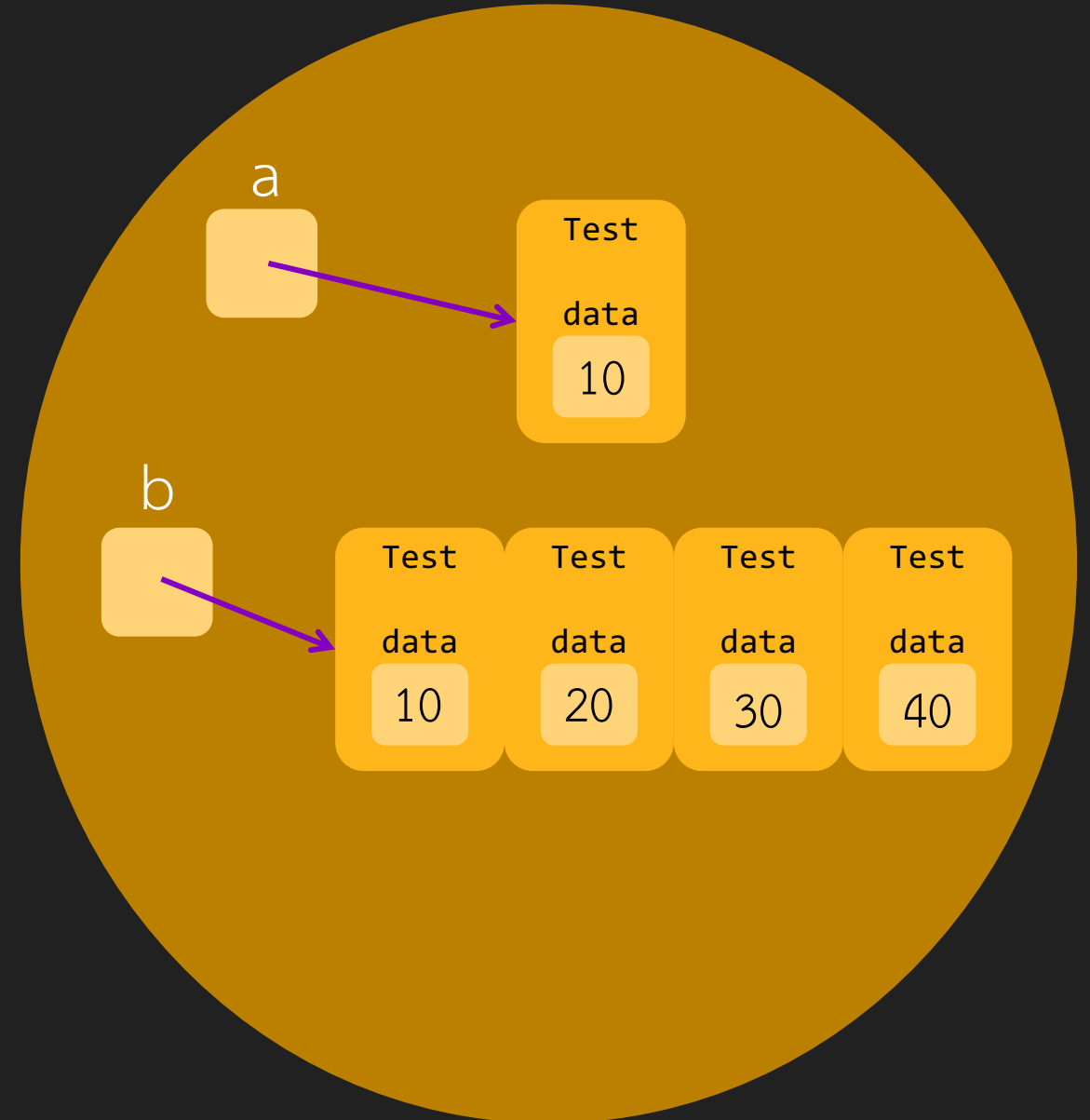
new and delete operator

- For a datatype T, `new T` allocates a block with a size of T and then call a constructor of T, return the address of that memory
- For a datatype T, `new T[n]` allocates n blocks of T and then call a constructor of T in each block, return the address of the first block
 - For example, we use `new int[10]` to create a dynamic int array of 10 elements
- For a pointer X, `delete x` call the destructor and then de-allocates memory pointed by x,
- For a dynamic array X, `delete []` call the destructor of all blocks in the dynamic array and de-allocate the memory allocated by X

Example

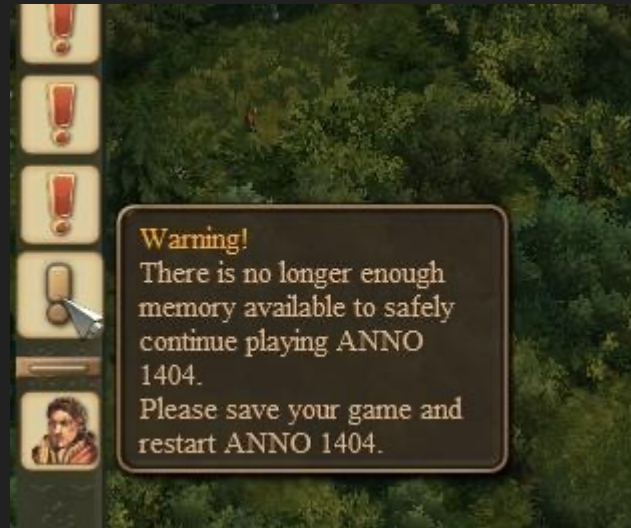
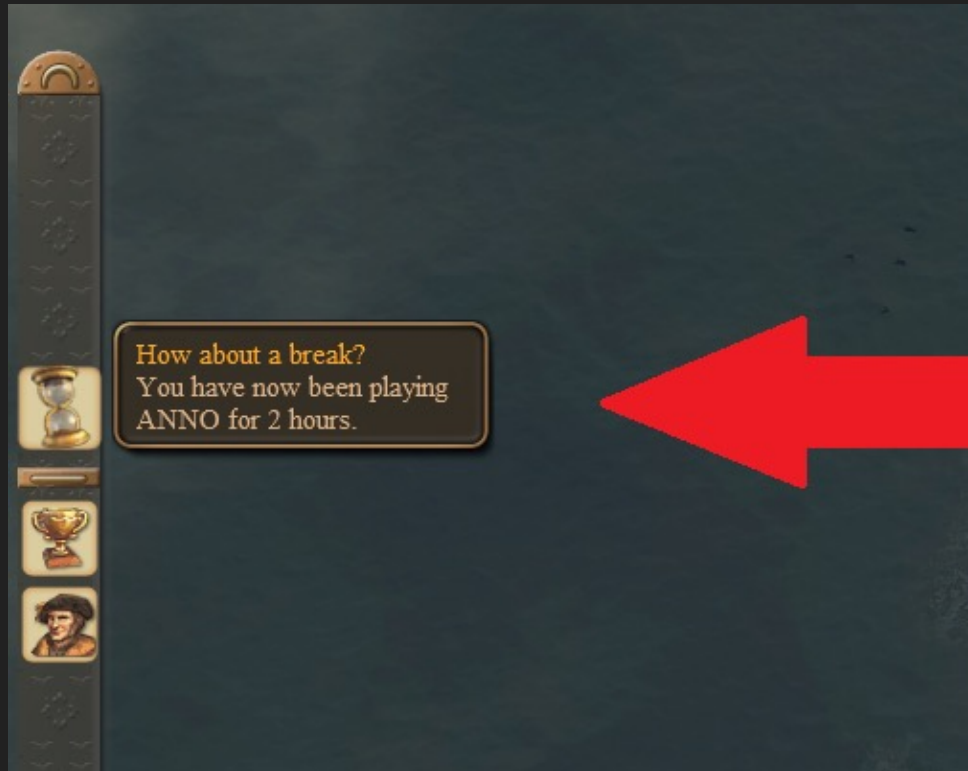
```
class test {  
public:  
    // constructor  
    test() : data() { cout << "created" << endl; }  
    //destructor  
    ~test() { cout << data << " destroyed " << endl; }  
    int data;  
};  
  
int main() {  
    test *a, *b;  
  
    a = new test;  
    a->data = 10;  
    cout << a->data << endl;  
    delete a;  
  
    b = new test[4];  
    b[0].data = 10;  
    b[1].data = 20;  
    b[2].data = 30;  
    b[3].data = 40;  
    delete [] b;  
}
```

computer memory



Memory Leak

- For everything that is created by `new`, we must call `delete` on it
- If you do not, that memory is not deleted until all memory is used up



Smart Pointer (NOT A SUBJECT OF THIS COURSE)

- A better way is to use C++ smart pointer
- Smart pointer is a pointer that can delete itself when it go out of scope
- Similar concept to Java Garbage Collection
- Still possible to have memory leak

vector.h

Finally...

Version 0.1

- Start with vector that can do push_back, pop_back and []
- Also with custom constructor

```
namespace CP {
template <typename T>
class vector
{
protected:
    T *mData;
    size_t mCap;
    size_t mSize;

    void rangeCheck(int n) {...}
    void expand(size_t capacity) {...}
    void ensureCapacity(size_t capacity) {...}
public:
    vector() {...}
    vector(size_t capacity) {...}
    ~vector() {...}
    //----- access -----
    T& at(int index) {...}
    T& operator[](int index) {...}
    //----- modifier -----
    void push_back(const T& element) {...}
    void pop_back() {...}
};
}
```

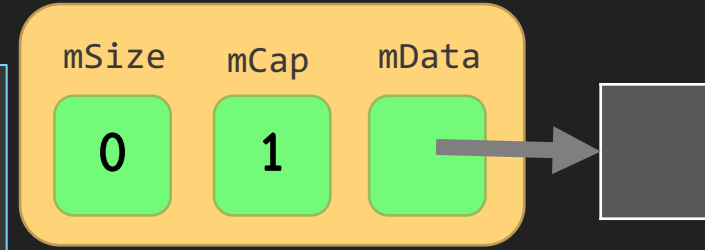
Basic Constructor

```
template <typename T>
class vector {
protected:
    T *mData;
    size_t mCap;
    size_t mSize;
public:
    //----- constructor & copy operator -----
    // default constructor
    vector() {
        int cap = 1;
        mData = new T[cap]();
        mCap = cap;
        mSize = 0;
    }

    // constructor with initial size
    vector(size_t cap) {
        mData = new T[cap]();
        mCap = cap;
        mSize = cap;
    }
}
```

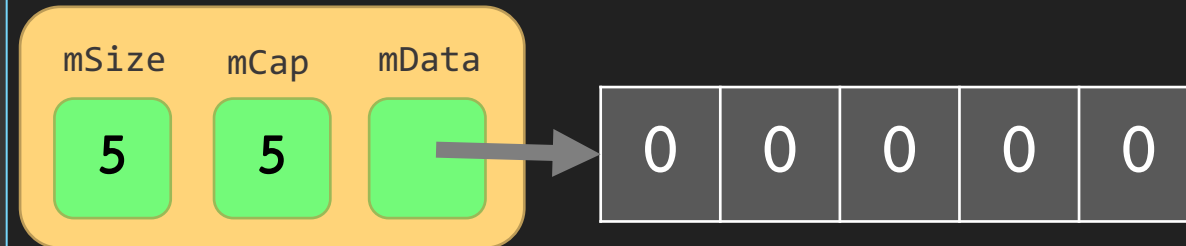
```
vector<int> v;
```

V



```
vector<int> w(5);
```

W



Destructor

- Since we new **mData**, we have to delete it
 - Or face a memory leak problem

```
template <typename T>
class vector {
protected:
    T *mData;
    size_t mCap;
    size_t mSize;
public:
    // destructor
    ~vector() {
        delete [] mData;
    }
}
```

Object Life Cycle

- Normal object
 - Object is created (constructor called) when declared
 - Object is destroyed (destructor called) when go out of scope
- Object created by new (both new T or new T[])
 - Object is created when new
 - Object is destroyed when delete

```
class test {
public:
    // constructor
    test() : data() { cout << "created" << endl; }
    //destructor
    ~test() { cout << data << " destroyed " << endl; }
    int data;
};

int main() {
    cout << "-- Life cycle --" << endl;
    cout << "- normal object -" << endl;
    test u;
    u.data = 99;
    for (int i = 0; i < 5; i++) {
        test t;
        t.data = i*10;
    }
}
```

```
-- Life cycle --
- normal object -
created
0 destroyed
created
10 destroyed
created
20 destroyed
created
30 destroyed
created
40 destroyed
99 destroyed
```

Accessing Data

- The return type is T& which is a reference
- Same deal as pass-by-reference, this is called **return-by-reference**
 - So we can do `v[i] = 30` or `v[i]++`
- What is returned is actually that variable
- Also notice the difference between `at()` and `operator[]`

```
template <typename T>
class vector
{
protected:
    T *mData;
    size_t mCap;
    size_t mSize;

    void rangeCheck(int n) {
        if (n < 0 || (size_t)n >= mSize) {
            throw std::out_of_range("index of out range") ;
        }
    }

public:
    T& at(int index) {
        rangeCheck(index);
        return mData[index];
    }

    T& operator[](int index) {
        return mData[index];
    }
};
```


Add, remove Data

- push_back first check if we have reserved space
 - If not, we expand
- Then, the data is put to mData[mSize]
- Removing Data is done by just reduce the size

```
template <typename T>
class vector {
protected:
    T *mData;
    size_t mCap;
    size_t mSize;
    void expand(size_t capacity) {
        T *arr = new T[capacity]();
        for (size_t i = 0; i < mSize; i++) {
            arr[i] = mData[i];
        }
        delete [] mData;
        mData = arr;
        mCap = capacity;
    }
    void ensureCapacity(size_t capacity) {
        if (capacity > mCap) {
            size_t s = (capacity > 2 * mCap) ? capacity : 2 * mCap;
            expand(s);
        }
    }
public:
    void push_back(const T& element) {
        ensureCapacity(mSize+1);
        mData[mSize++] = element;
    }
    void pop_back() {
        mSize--;
    }
};
```

Create new dynamic array

Move all data

Delete old data and point to new one

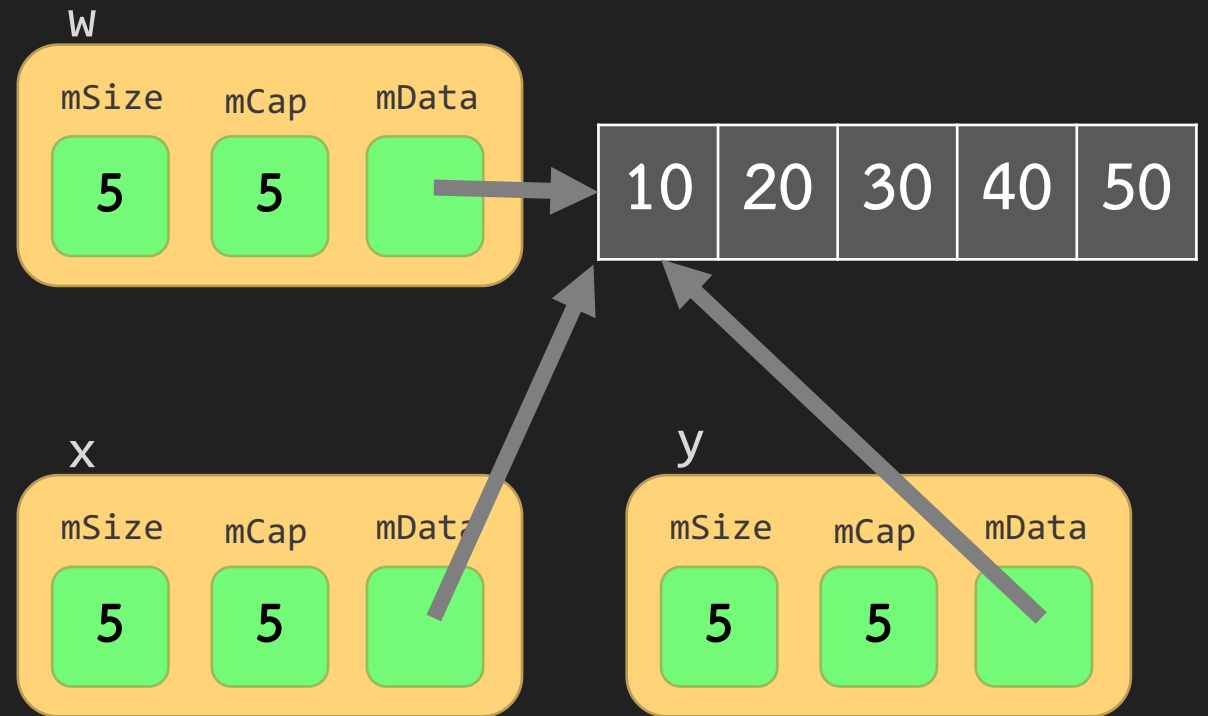
Double the size

Problem of v0.1

- Copy Constructor and assignment operator is incorrect
 - It is auto generate to just copy all variables (but not the data it points to)
- Rule of three in c++
 - Consider destructor, copy constructor, assignment operator
 - If any of them is written in the code, we mostly need all of them
- Since c++11, it's rules of four and a half

Problem of v0.1

```
int main() {  
    CP::vector<int> w(5);  
  
    for (int i = 0; i < 5; i++) w[i] = i*10;  
    CP::vector<int> x(w);  
    CP::vector<int> y = w;  
    x[3] = -1;  
    cout << y[3] << endl;  
    cout << w[3] << endl;  
}
```



v0.2, add small access functions

- empty and size also exists in other data structure
- size_t is non-negative integer type

```
bool empty() const {  
    return mSize == 0;  
}  
  
size_t size() const {  
    return mSize;  
}  
  
size_t capacity() const {  
    return mCap;  
}
```

v0.2 adding copy constructor & assignment operator

```
// copy constructor
vector(const vector<T>& a) {
    mData = new T[a.capacity()]();
    mCap = a.capacity();
    mSize = a.size();
    for (size_t i = 0; i < a.size(); i++) {
        mData[i] = a[i];
    }
}
```

```
// copy assignment operator
vector<T>& operator=(vector<T> &other) {
    //protect against self-destruct
    if (mData != other.mData) {
        //delete current data
        delete [] mData;
        //copy the new data
        mData = new T[other.capacity()]();
        mCap = other.capacity();
        mSize = other.size();
        for (size_t i = 0; i < other.size(); i++) {
            mData[i] = other[i];
        }
    }
}
```

→ Exception can corrupt data

→ self assignment can crash thing

→ If other is small, this is faster then copy-and-swap

Copy-and-swap idiom for assignment operator

- Utilize written copy-constructor and destructor
- Shorter code

```
// copy assignment operator using copy-and-swap idiom
vector<T>& operator=(vector<T> other) {// notice the pass-by-value!!!
    // other is copy-constructed which will be destruct at the end of this scope
    // we swap the content of this class to the other class and let it be destructed
    using std::swap;
    swap(this->mSize, other.mSize);
    swap(this->mCap, other.mCap);
    swap(this->mData, other.mData);
    return *this;
}
```

self-assignment safe because we create another copy.

v0.3 Iterator and typedef keyword

```
template <typename T>
class vector {

protected:
    T *mData;
    size_t mCap;
    size_t mSize;
public:
    typedef T* iterator;

    //----- iterator -----
    iterator begin() {
        return &mData[0];
    }

    iterator end() {
        return begin()+mSize;
    }

};
```

- See that pointer works just like how `std::vector::iterator` works
- In fact, iterator is actually a pointer
- typedef keywords allow us to map a type name
 - `CP::vector<int>::iterator` is `int*`
 - `CP::vector<bool>::iterator` is `bool*`

insert

- push_back actually call insert(end(), element)
- Question: why we need pos?

```
iterator insert(iterator it, const T& element) {  
    size_t pos = it - begin();  
    ensureCapacity(mSize + 1);  
    for(size_t i = mSize; i > pos; i--) {  
        mData[i] = mData[i-1];  
    }  
    mData[pos] = element;  
    mSize++;  
    return begin()+pos;  
}
```

May not be the same as 'it'

```
void push_back(const T& element) {  
    insert(end(), element);  
}
```


erase

- See that both insert and erase also change mSize

```
void erase(iterator it) {  
    while((it+1)!=end()) {  
        *it = *(it+1);  
        it++;  
    }  
    mSize--;  
}
```

Final Version

```
template <typename T>
class vector{
public:
    typedef T* iterator;
protected:
    T *mData;
    size_t mCap;
    size_t mSize;
    void rangeCheck(int n) {...}
    void expand(size_t capacity) {...}
    void ensureCapacity(size_t capacity) {...}
public:
    //----- constructor & copy operator -----
    vector(const vector<T>& a) {...}
    vector() {...}
    vector(size_t cap) {...}
    vector<T>& operator=(vector<T> other) {...}
    ~vector(){...}
    //----- capacity function -----
    bool empty() const {...}
    size_t size() const {...}
    size_t capacity() const {...}
    void resize(size_t n){...}
    //----- iterator -----
    iterator begin(){...}
    iterator end(){...}
    //----- access -----
    T& at(int index){...}
    T& at(int index) const{...}
    T& operator[](int index){...}
    T& operator[](int index) const{...}
    //----- modifier -----
    void push_back(const T& element){...}
    void pop_back(){...}
    iterator insert(iterator it,const T& element) {...}
    void erase(iterator it) {...}
    void clear() {...}
    //----- non-stl below... -----
};
```

Exercise

- Read the following function and see how it works in vector.h
 - resize
 - non-stl function
 - insert_by_pos
 - erase_by_pos
 - erase_by_value
 - contains
 - index_of

Please read the entire vector.h

- in <https://github.com/nattee/data-class/blob/master/stl-cp/vector.h>

Analysis of how many data is copied by push_back

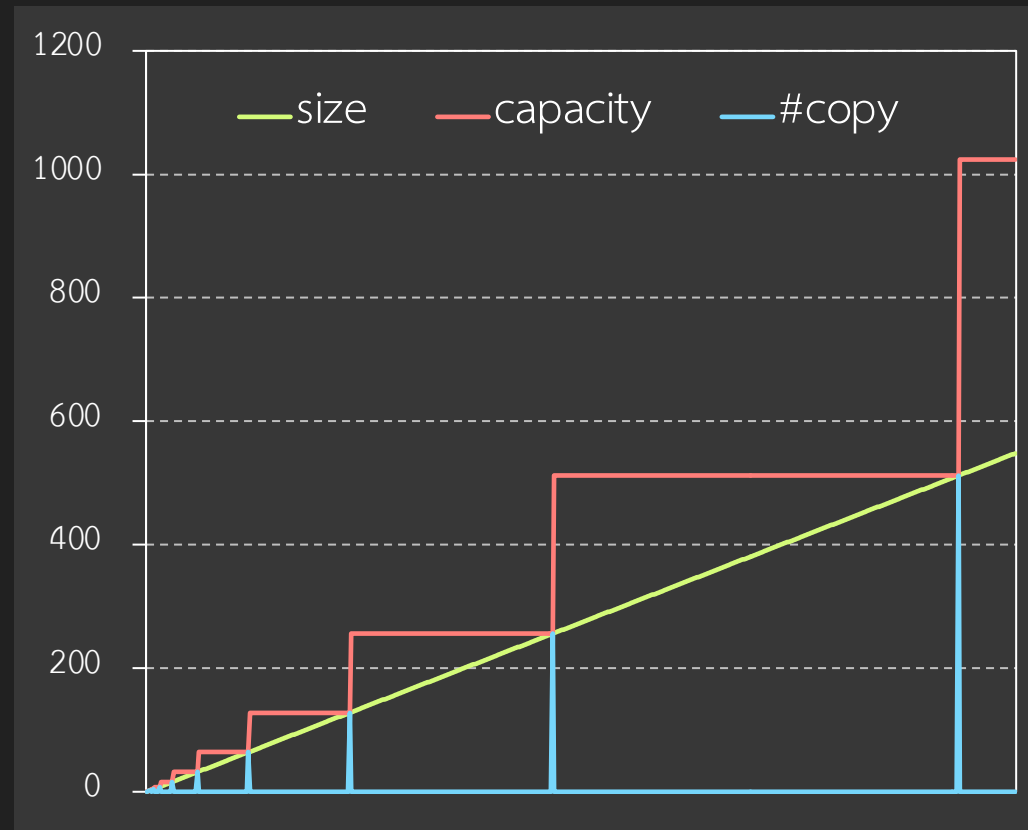
- When full, push_back have to move all data to a new dynamic array
- ensureCapacity double the size

```
void ensureCapacity(size_t capacity) {  
    if (capacity > mCap) {  
        size_t s = (capacity > 2 * mCap) ?  
capacity : 2 * mCap;  
        expand(s);  
    }  
}
```

size	capa	#copy
0	1	
1	1	1
2	2	2
3	4	
4	4	4
5	8	
6	8	
7	8	
8	8	8
9	16	
10	16	
11	16	
12	16	
13	16	
14	16	
15	16	
16	16	16
17	32	
18	32	
19	32	
20	32	
21	32	
22	32	
23	32	
24	32	
25	32	
26	32	
27	32	
28	32	
29	32	
30	32	
31	32	
32	32	32
33	64	
34	64	

Size & Capa & Copy count

- How much copy we need?



What should be in a class T

What?	Auto-generated?	When and Why?
Default constructor	Yes (only when no other constructor)	Need by most operation in C++
Copy constructor (x(y))	Yes (copy of all member)	If we need “deep copy”
Copy assignment operator (operator=)	Yes (copy of all member)	If we need “deep copy”
Destructor	Yes (destruct of all member)	Need it if we explicitly allocate memory (usually because of “deep copy”)
Equality operator (operator==)	No	Need it if we want to easily check if equal
Relational operator (operator<)	No	Need it if we want it to work with sort, set, map or priority_queue