

▼ Lab 1\_Program to compute area and volume

Area

$$A = \iint_D dydx$$
$$A = \iint_D dx dy$$

1. Find the area bounded by the curves  $y^2 = x^3$  and  $x^2 = y^3$

```
from sympy import *
x, y = symbols("x y")
f = 1
I = integrate(f, (y, x**(3/2), x**(2/3)), (x, 0, 1))
print("Area=",I)
```

Area= 0.2000000000000000

▼ Polar form

$$A = \iint_D r dr d\theta$$

Find the area lying inside the cardioid  $r = a(1 + \cos\theta)$  and outside the circle  $r = a$

```
from sympy import *
r,t,a = symbols("r t a")
I1=2*integrate(r,(r, a, a*(1+cos(t))), (t, 0, pi/2))
I3=simplify(I1)
pprint(I3)
```

$$\frac{a^2 \cdot (\pi + 8)}{4}$$

Activity-1

- 1. Find the area of a plate in the form of a quadrant of the ellipse  $\frac{x^2}{a^2} + \frac{y^2}{b^2} = 1$ .
- 2. Find the area between the parabolas  $y^2 = 4ax$  and  $x^2 = 4ay$ .
- 3. Find the area lying between the parabola  $y = x^2$  and the line  $x + y - 2 = 0$ .
- 4. Find the area lying between the parabola  $y = 4x - x^2$  and the line  $y = x$ .
- 5. Find the area of the cardiod  $r = a(1 + \cos \theta)$  in second quadrant.
- 6. Find the area of the cardiod  $r = a(1 + \cos \theta)$ .
- 7. Find the area of the Lemniscate  $r^2 = a^2 \cos 2\theta$ .
- 8. Find the area which is inside the circle  $r = 3a \cos \theta$  and outside the cardioid  $r = a(1 + \cos\theta)$ .

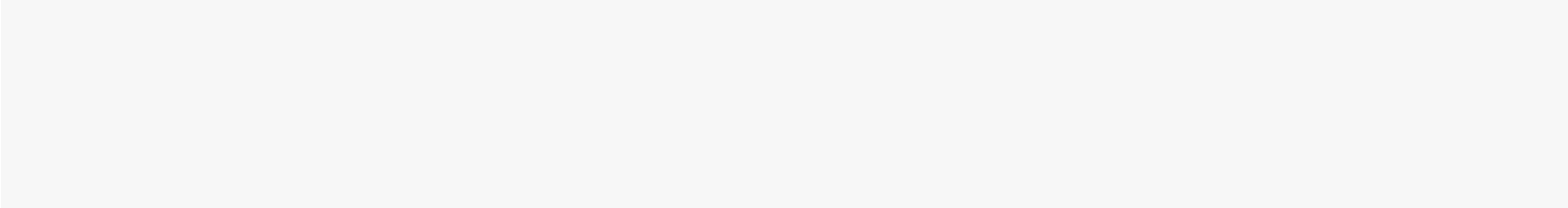
▼ Volume

▼ Find the volume of the tetrahedron bounded by the plane  $\frac{x}{a} + \frac{y}{b} + \frac{z}{c} = 1$  and the co-ordinate planes

```
from sympy import *
x, y,z,a,b,c = symbols("x y z a b c")
f = 1
I = integrate(f, (z,0,c*(1-(x/a)-(y/b))) ,(y, 0, b*(1-(x/a))), (x, 0, a))
pprint(I)
```

$$\frac{a \cdot b \cdot c}{6}$$

▼ Find volume of the sphere  $x^2 + y^2 + z^2 = a^2$  by using triple integration



```
from sympy import *
x,y,z,a,k=symbols('x y z a k',positive=True)
f=1
I1=integrate(f,(z,0,sqrt(k**2-y**2)),(y,0,k))
I2=I1.subs(k,sqrt(a**2-x**2))
V=integrate(I2,(x,0,a))
display(8*V)
```

$$\frac{4\pi a^3}{3}$$

## Activity-2

1. Find the volume of the ellipsoid  $\frac{x^2}{a^2} + \frac{y^2}{b^2} + \frac{z^2}{c^2} = 1$ .

2. Find the volume of the sphere  $x^2 + y^2 + z^2 = a^2$ .

3. Calculate the volume of the solid bounded by the planes  $x = 0, y = 0, z=0$  and  $x + y + z = a$ .

4. Find the volume bounded by the cylinder  $x^2 + y^2 = 4$  and the plane  $y + z = 4$  and  $z = 0$ .

▼ Lab 2\_Evaluation of improper Integrals

1. Evaluate  $\int_0^{\infty} \frac{1}{1+x^2} dx$

```
from sympy import *
x =symbols(' x', positive=True)
integrate(1/(1+x**2),(x,0,oo))
```

$$\frac{\pi}{2}$$

2. Evaluate  $\int_0^{\infty} \frac{t^4}{4^t} dt$

```
from sympy import *
t =symbols(' t', positive=True)
integrate((t**4)/(4**t),(t,0,oo))
```

$$\frac{3}{4\log(2)^5}$$

3. Evaluate  $\int_{-\infty}^{\infty} \frac{1}{a^2+x^2} dx$

```
from sympy import *
x,a =symbols(' x, a', positive=True)
integrate(1/(a**2+x**2),(x,-oo,oo))
```

$$\frac{\pi}{a}$$

4. Evaluate  $\Gamma\left(\frac{5}{2}\right)$

```
from sympy import *
print('Γ(5/2)=',gamma(5/2))
```

$$\Gamma(5/2)= 1.32934038817914$$

5. Evaluate  $\beta\left(\frac{5}{2},\frac{7}{2}\right)$

```
from sympy import *
print('β(5/2,7/2)=',beta(5/2,7/2))
```

$$\beta(5/2,7/2)= 0.0368155389092554$$

## Activity-3

1. Evaluate  $\int_0^{\infty} 3^{-4x^2} dx$ .
2. Evaluate  $\int_0^{\infty} \frac{x^4}{4^x} dx$ .
3. Evaluate  $\int_0^{\infty} e^{-kx} x^{p-1} dx, k > 0$ .

4. Evaluate  $\int_0^{\infty} e^{-t^2} t^{2n-1} dt.$

5. Evaluate  $\int_0^{\infty} \frac{x^{n-1}}{1+x} dx.$

6. Evaluate  $\int_0^{\infty} \frac{1}{1+y^4} dy.$

7. Evaluate  $\int_0^1 x^m (1-x^n)^p dx.$

8. Evaluate  $\int_0^1 \frac{1}{\sqrt{1-x^4}} dx$

Lab 3\_Finding gradient, divergent, curl and their geometrical interpretation.

▼ Divergence

Evaluate the divergence of  $2x^2z\hat{i} - xy^2z\hat{j} + 3yz^2\hat{k}$  at the point (1,1,1).

```
from sympy.physics.vector import ReferenceFrame
from sympy.physics.vector import *
from sympy import *
R = ReferenceFrame('R')
x,y,z=symbols("x,y,z")
i,j,k=R.x,R.y,R.z
x,y,z=R[0],R[1],R[2]
F=(2*x**2*z)*i-(x*y**2*z)*j+(3*y*z**2)*k
G = divergence(F, R)
f= G.subs(dict(zip(R.varlist, var('x:z'))))
f1=f.subs({x:1,y:1,z:1}).evalf()
display(f1)
```

8.0

▼ Curl

Evaluate the curl of  $xyz^2\hat{i} + yxz^2\hat{j} + zxy^2\hat{k}$  at (1,2,3)

```
from sympy.physics.vector import ReferenceFrame
from sympy.physics.vector import *
from sympy import *
R = ReferenceFrame('R')
x,y,z=symbols("x,y,z")
i,j,k=R.x,R.y,R.z
x,y,z=R[0],R[1],R[2]
F=(x*y*z**2)*i+(y*z*x**2)*j+(z*x*y**2)*k
G = curl(F, R)
f= G.subs(dict(zip(R.varlist, var('x:z'))))
f1=f.subs({x:1,y:2,z:3}).evalf()
display(f1)
```

10.0*ŕ<sub>x</sub>* + 3.0*ŕ<sub>z</sub>*

Show that the vector field  $\vec{f} = 2x^2z\hat{i} - 10xyz\hat{j} + 3xz^2\hat{k}$  is a solenoidal.

```
from sympy.physics.vector import ReferenceFrame
from sympy.physics.vector import *
from sympy import *
R = ReferenceFrame('R')
x,y,z=symbols("x,y,z")
i,j,k=R.x,R.y,R.z
x,y,z=R[0],R[1],R[2]
F=(2*(x**2)*z)*i-(10*x*y*z)*j+(3*x*(z**2))*k
G = divergence(F, R)
if G==0:
    print("The given vector is solendial")
else:
    print("The given vector is not solendial")
```

The given vector is solendial

Prove that  $\vec{f} = (6xy + z^3)\hat{i} + (3x^2 - z)\hat{j} + (3xz^2 - y)\hat{k}$  is irrotational

```
from sympy.physics.vector import ReferenceFrame
from sympy.physics.vector import *
from sympy import *
```

```
R = ReferenceFrame('R')
x,y,z=symbols("x,y,z")
i,j,k=R.x,R.y,R.z
x,y,z=R[0],R[1],R[2]
F=(6*x*y+z**3)*i+(3*x**2-z)*j+(3*x*z**2-y)*k
G = curl(F, R)
if G==0:
    print("The  given vector is irrotataional")
else:
    print("The  given vector is not irrotataional ")
```

The given vector is irrotataional

Activity-4

1. Find the gradient of  $\phi$  where  $\phi$  is
- (i.)  $x^2 + y^2 + z^2$ .

(ii.)  $3x^2y - y^3z^3$  at  $(1, -2, -1)$

(iii.)  $x^2y^2z^3$  at  $(1, -1, 2)$
2. If  $f(x, y, z) = 3x^2y - y^3z^2$ , find  $\nabla f$ .
3. The force in an electrostatic field given by  $f = 4x^2 + 9y^2 + z^2$  has the direction of the gradient  $\nabla f$ . Find this gradient at  $(5, -1, -11)$ .
4. The temperature of points in space is given  $T(x, y, z) = x^2 + y^2 - z$ . A mosquito located at  $(1, 1, 2)$  desires to fly in such a direction it will get warm as soon as possible. In what direction should it move?
5. If  $\vec{f} = 3x^2y\hat{i} - y^3z^2\hat{j} + xyz^2\hat{k}$ , find  $\nabla \cdot \vec{f}$ .
6. Evaluate divergence and curl at the point  $(1, 2, 3)$  given
- (i.)  $\vec{f} = x^2yz\hat{i} + xy^2z\hat{j} + xyz^2\hat{k}$ .

(ii.)  $\vec{f} = 3x^2\hat{i} + 5xy^2\hat{j} + 5xyz^3\hat{k}$ .

(iii.)  $\vec{f} = xyz\hat{i} + 3x^2y\hat{j} + (xz^2 - y^2z)\hat{k}$ .
7. Show that the vector field  $\vec{f} = 3y^4z^2\hat{i} + 4x^2z^2\hat{j} - 3x^2y^2\hat{k}$  is solenoidal.
8. Verify whether the vector field  $\vec{f} = 3xy\hat{i} + 20yz^2\hat{j} - 15xz\hat{k}$  is solenoidal or not.
9. Verify whether the vector field  $\vec{f} = (x^2 - yz)\hat{i} + (y^2 - zx)\hat{j} + (z^2 - xy)\hat{k}$  is irrotational or not.
10. Prove that  $\vec{f} = (y^2 - z^2 + 3yz - 2x)\hat{i} + (3xz + 2xy)\hat{j} + (3xy - 2xz + 2z)\hat{k}$  is both solenoidal and irrotational.

Lab 4\_Finding the dimension, basis of a vector space and Graphical representation of linear transformation (MCS and MES only)

Obtain dimension of the vector space spanned by the vectors  $[1, 2, 3], [2, 3, 1], [3, 1, 2]$

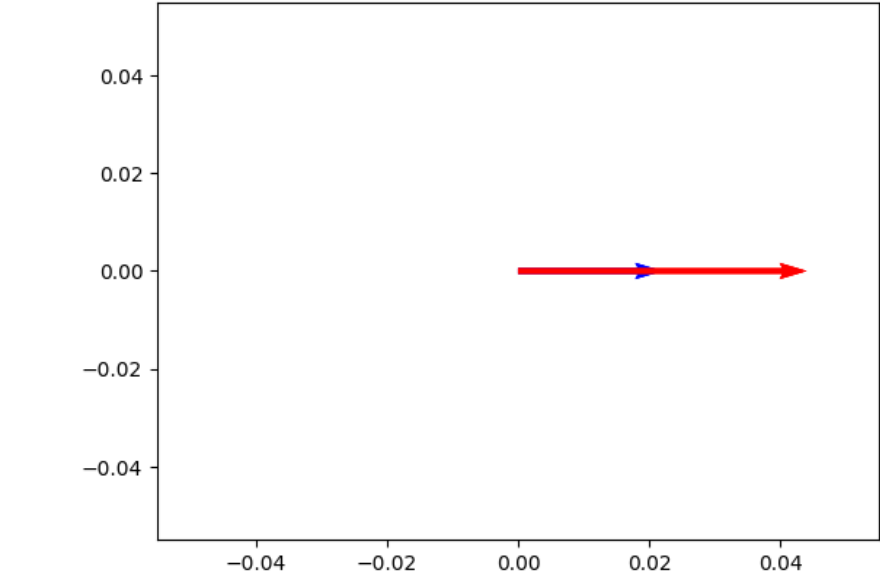
```
import numpy as np
# Define the vector space V
V = np.array([
    [1, 2, 3],
    [2, 3, 1],
    [3, 1, 2]])
# Find the dimension and basis of V
rank= np.linalg.matrix_rank(V)
print("Dimension of the vector space is",rank)
```

Dimension of the vector space is 3

Horizontal Stretch

Represent the horizontal stretch transformation  $T : R^2 \rightarrow R^2$  geometrically. Find the image of vector  $(10, 0)$  when it is stretched horizontally by 2 units.

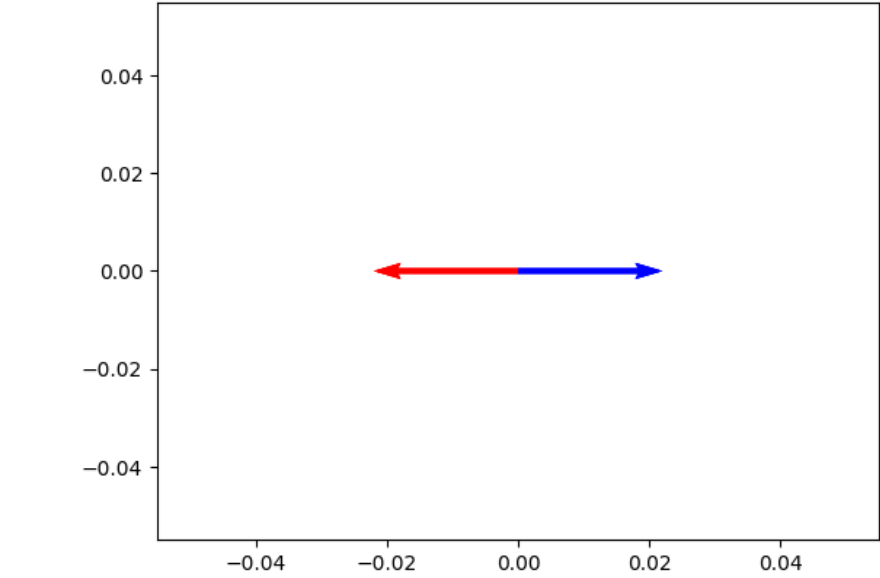
```
import numpy as np
import matplotlib . pyplot as plt
V = np. array ([[10 ,0]])
origin = np. array ([[0, 0, 0],[0, 0, 0]]) # origin point
A=np. matrix ([[2,0],[0,1]])
V1=np. matrix (V)
V2=A*np. transpose (V1)
V2=np. array (V2)
plt . quiver (*origin , V[:,0], V[:,1], color =['b'], scale =50)
plt . quiver (*origin , V2[0,:], V2[1,:], color =['r'], scale =50)
plt . show ()
```



### Reflection

Represent the reflection transformation  $T : R^2 \rightarrow R^2$  geometrically. Find the image of vector  $(10, 0)$  when it is reflected about  $y$ -axis.

```
import numpy as np
import matplotlib . pyplot as plt
V = np. array ([[10 ,0]])
origin = np. array ([[0, 0, 0],[0, 0, 0]]) # origin point
A=np. matrix ([[ -1,0],[0,1]])
V1=np. matrix (V)
V2=A*np. transpose (V1)
V2=np. array (V2)
plt . quiver (*origin , V[:,0], V[:,1], color =['b'], scale =50)
plt . quiver (*origin , V2[0,:], V2[1,:], color =['r'], scale =50)
plt . show ()
```



### Rotation

Represent the rotation transformation  $T : R^2 \rightarrow R^2$  geometrically. Find the image of vector  $(10, 0)$  when it is rotated by  $\pi/2$  radians.

```
import numpy as np
import matplotlib . pyplot as plt
V = np. array ([[10 ,0]])
origin = np. array ([[0, 0, 0],[0, 0, 0]]) # origin point
A=np. matrix ([[0,-1],[1,1]])
V1=np. matrix (V)
V2=A*np. transpose (V1)
V2=np. array (V2)
plt . quiver (*origin , V[:,0], V[:,1], color =['b'], scale =50)
plt . quiver (*origin , V2[0,:], V2[1,:], color =['r'], scale =50)
plt . show ()
```

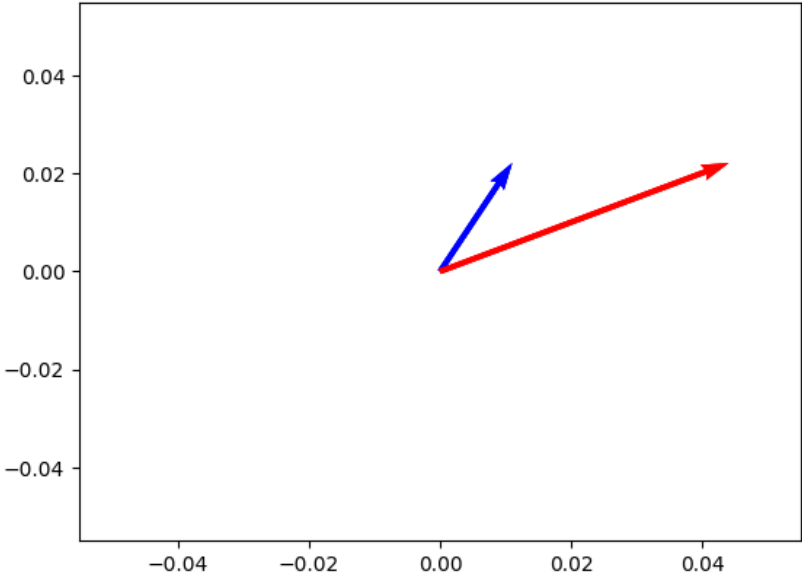


▼ Shear Transformation

Represent the Shear transformation  $T : R^2 \rightarrow R^2$  geometrically. Find the image of  $(2, 3)$  under shear transformation.

```
import numpy as np
import matplotlib . pyplot as plt
V = np. array ([[2,3]])
origin = np. array ([[0, 0, 0],[0, 0, 0]]) # origin point
A=np. matrix ([[1,2],[0,1]])
V1=np. matrix (V)
V2=A*np. transpose (V1)
V2=np. array (V2)
print (" Image of given vectors is:", V2)
plt . quiver (*origin , V[:,0], V[:,1], color =['b'], scale =20)
plt . quiver (*origin , V2[0,:], V2[1,:], color =['r'], scale =20)
plt . show ()
```

Image of given vectors is:  $\begin{bmatrix} 8 \\ 3 \end{bmatrix}$



Activity-5

I. Find dimension of the vector space (or subspace) spanned by the following set of vectors:

- 1.  $S = \{(1, 2), (3, 2)\}$
- 2.  $S = \{(1, 2, 3), (0, 1, 1), (1, 3, 4)\}$
- 3.  $S = \{(1, 0, 0), (0, 1, 0), (0, 3, -1)\}$
- 4.  $S = \{(1, 1, 2), (0, 5, -1), (1, 16, -1)\}$
- 5.  $S = \{(1, -1, 3, 4), (2, 1, 6, 8), (1, 1, 1, 1), (3, 2, 7, 9)\}$
- 6.  $S = \{(2, 2, 0, 4), (1, -2, 3, 7), (1, 2, 1, -3), (4, 2, 4, 8)\}$
- 7.  $S = \{(1, 2, 3, 4), (2, 4, 6, 8), (2, 2, 2, 2)\}$

II. Find the image of  $(1, 4)$  under following  $2D$  transformations:

- 1. Horizontal stretch
- 2. Reflection
- 3. Shear
- 4. Rotation

▼ Lab 5\_Verification of rank - nullity theorem (MCS and MES only)

Verify the rank-nullity theorem for the linear transformation  $T : R^3 \rightarrow R^3$  defined by

▼  $T(x, y, z) = (x + 4y + 7z, 2x + 5y + 8z, 3x + 6y + 9z).$

```
import numpy as np
from scipy.linalg import null_space

# Define a linear transformation
A = np.array([[1, 2, 3], [4, 5, 6], [7, 8, 9]])

# Find the rank of the matrix A
rank = np.linalg.matrix_rank(A)
print("Rank of the matrix",rank)

# Find the null space of the matrix A
ns = null_space(A)
print("Null space of the matrix",ns)
# Find the dimension of the null space
nullity = ns.shape[1]
print("Null space of the matrix",nullity)
# Verify the rank-nullity theorem
if rank + nullity == A.shape[1]:
    print("Rank-nullity theorem holds.")
else:
    print("Rank-nullity theorem does not hold.")
```

Rank of the matrix 2  
Null space of the matrix [[-0.40824829]  
[ 0.81649658]  
[-0.40824829]]  
Null space of the matrix 1  
Rank-nullity theorem holds.

Activity-6

Verify the rank-nullity theorem for the linear transformation  $T : R^n \rightarrow R^m$  defined by:

- 1.  $T(x,y) = (x + 2y, 2x + y)$
- 2.  $T(x,y) = (x - y, -x + y)$
- 3.  $T(x,y) = (y, x)$
- 4.  $T(x,y,z) = (x - y + 2z, 2x + y - z, 3x + z)$
- 5.  $T(x,y,z) = (x + 2y + 3z, 3x + 2y + z, x + y + z)$
- 6.  $T(x,y,z) = (x + y + z, x + y - z, x - y - z)$
- 7.  $T(x,y,z) = (2x - 3y + 4z, 6x - 9y + 12z, 4x - 6y + 8z)$
- 8.  $T(x_1,x_2,x_3,x_4) = (x_1 + 2x_2 - x_3 + x_4, 2x_1 + x_2 + x_3 + 3x_4)$

▼ Lab 4\_Green's Theorem (MME and MCV only)

▼ Statement of Green’s theorem in the plane:

If  $P(x,y)$  and  $Q(x,y)$  be two continuous functions having continuous partial derivatives in a region  $R$  of the  $xy$ –plane, bounded by a simple closed curve  $C$ , then

$$\oint_C (Pdx + Qdy) = \iint_R \left( \frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} \right) dx dy.$$

- Using Green’s theorem, evaluate  $\oint_R ((x + 2y)dx + (x - 2y)dy)$  , where  $R$  is the region bounded by coordinate axes, the line  $x = 1$  and  $y = 1$ .

```
from sympy import *
var ('x,y')
p=x+2*y
q=x-2*y
f= diff (q,x)- diff (p,y)
soln = integrate (f,[x,0,1],[y,0,1])
print ("I=",soln )

I= -1
```

Activit-5

Using Green’s theorem, evaluate the following integrals:

- 1.  $\oint_C ((3x + 4y)dx + (2x - 3y)dy)$  , where  $C$  is closed curve bounded by coordinate axes, the line  $x = 1$  and  $y = 1$ .
- 2.  $\oint_C ((xy + y^2)dx + x^2dy)$  , where  $C$  is closed curve bounded by  $y = x$  and  $y = x^2$ .
- 3.  $\oint_C ((3x - 8y^2)dx + (4y - 6xy)dy)$  , where  $C$  is closed curve bounded by  $x = 0, y = 0$  and  $x + y = 1$ .
- 4.  $\oint_C ((x^2 - 2xy)dx + (x^2y + 3)dy)$  , where  $C$  is closed curve bounded by  $y^2 = 8x$  and  $x = 2$ .

▼ Lab 5\_Solution of linear partial differential equations (MME and MCV only)

▼ Solve the PDE:  $2p + 3q = 1$ , where  $p = \frac{\partial z}{\partial x}$  and  $q = \frac{\partial z}{\partial y}$

```
from sympy.solvers.pde import pdsolve
from sympy import *
from sympy.abc import x,y,a
f=Function('f')
z=f(x,y)
zx=z.diff(x)
zy=z.diff(y)
eq=Eq(2*zx+3*zy,1)
display(eq)
soln=pdsolve(eq,z)
display(soln)
```

$$2\frac{\partial}{\partial x}f(x,y)+3\frac{\partial}{\partial y}f(x,y)=1$$
$$f(x,y)=\frac{2x}{13}+\frac{3y}{13}+F(3x-2y)$$

Activity-6

Solve the linear PDE's:


- 1.  $2p + 3q = 1$
- 2.  $xp + 2q = x$
- 3.  $yp + q = y$
- 4.  $xp + yq = z$
- 5.  $x^2p + y^2q = 1$
- 6.  $x^2p + q = z$
- 7.  $\frac{x^2}{y}p + yq = 1$
- 8.  $x^3p + 2xyq = 1$

where  $p = \frac{\partial z}{\partial x}$  and  $q = \frac{\partial z}{\partial y}$

▼ Lab 6\_Solution of algebraic and transcendental equation by Newton-Raphson method

▼ Find a root of the equation  $3x = \cos x + 1$ , near 1, by Newton Raphson method performing 5 iterations.

```
from sympy import *
x= Symbol ('x')
g = input ('Enter the function ') ##3x -cos(x)-1; % function
f= lambdify (x,g)
dg = diff (g);
df= lambdify (x,dg)
x0= float ( input ('Enter the intial approximation ')); # x0=1
n= int( input ('Enter the number of iterations ')); #n=5;
for i in range (1,n+1):
    x1 =(x0 - (f(x0)/df(x0)))
    print ('itration %d \t the root %0.3f \t function value %0.3f \n',(i, x1 ,f(x1))); # print all iteration value
    x0 = x1
```



Enter the function 3\*x-cos(x)-1

Enter the intial approximation 0

Enter the number of iterations 10

itration %d	the root %0.3f	function value %0.3f
(1,	0.6666666666666666,	0.21411273922305196)
itration %d	the root %0.3f	function value %0.3f
(2,	0.6074928533539964,	0.0013968570539599767)
itration %d	the root %0.3f	function value %0.3f
(3,	0.6071016657001078,	6.282984976735406e-08)
itration %d	the root %0.3f	function value %0.3f
(4,	0.6071016481031226,	-1.1102230246251565e-16)
itration %d	the root %0.3f	function value %0.3f
(5,	0.6071016481031226,	-1.1102230246251565e-16)
itration %d	the root %0.3f	function value %0.3f
(6,	0.6071016481031226,	-1.1102230246251565e-16)
itration %d	the root %0.3f	function value %0.3f
(7,	0.6071016481031226,	-1.1102230246251565e-16)
itration %d	the root %0.3f	function value %0.3f
(8,	0.6071016481031226,	-1.1102230246251565e-16)
itration %d	the root %0.3f	function value %0.3f
(9,	0.6071016481031226,	-1.1102230246251565e-16)
itration %d	the root %0.3f	function value %0.3f
(10,	0.6071016481031226,	-1.1102230246251565e-16)



Activity 7

Solve Algebraic and transcendental equations by Newton-Raphson method

- 1.  $x^3 - 3x + 1$  near  $x = 0.5$  Ans: 0.347 and near  $x = 2$  Ans: 1.532
- 2.  $xe^x - 2 = 0$ , near  $x = 0.5$  Ans: 0.853
- 3.  $x\ln(x) - 1.2 = 0$  in(2, 3) correct to 4 decimal places. Ans: 2.7406
- 4.  $3x = \cos(x) + 1$  in the interval (0,1) correct to 4 decimal places Ans: 0.6071
- 5.  $3\sin(x) - 2x + 5$  near  $x = 3$  Ans: 0.684
- 6.  $x\sin(x) + \cos(x) = 0$  near  $x=\pi$  Ans: 2.7985
- 7. Find the fourth root of 32 using Newton-Raphson method. Ans: 2.3784

Lab 7\_Interpolation/Extrapolation using Newton’s forward and backward difference formula.

- 1. Use Newtons forward interpolation to obtain the interpolating polynomial and hence calculate  $y(2)$  for the following:  $x = [1, 3, 5, 7, 9]$  and  $y = [6, 10, 62, 210, 502]$

```
from sympy import *
import numpy as np
n = int( input ('Enter number of data points : '))
x = np. zeros ((n))
y = np. zeros ((n,n))
# Reading data points
print ('Enter data for x and y: ')
for i in range (n):
    x[i] = float ( input ( 'x['+str(i)+'']= '))
    y[i][0] = float ( input ( 'y['+str(i)+'']= '))
#Generating forward difference table
for i in range (1,n):
    for j in range (0,n-i):
        y[j][i] = y[j+1][i-1] - y[j][i-1]
print ('\ nFORWARD DIFFERENCE TABLE \n');
for i in range (0,n):
    print ('%0.2f ' %(x[i]), end='')
    for j in range (0, n-i):
        print ('\t\t%0.2f ' %(y[i][j]), end='')
    print ()
# obtaining the polynomial
t= symbols ('t')
f=[] # f is a list type data

p=(t-x[0])/(x[1]-x[0])
f. append (p)
for i in range (1,n-1):
    f. append (f[i-1]*(p-i)/(i+1))
    poly =y[0][0]
for i in range (n-1):
    poly = poly +y[0][i+1]*f[i]
simp_poly = simplify ( poly )
print ('\ nTHE INTERPOLATING POLYNOMIAL IS\n');
pprint ( simp_poly )
# if you want to interpolate at some point the next session will help
inter = input ('Do you want to interpolate at a point (y/n)? ') # y
if inter =='y':
    a= float ( input ('enter the point ')) #2
    interpol = lambdify (t, simp_poly )
    result = interpol (a)
    print ('\ nThe value of the function at ' ,a,'is\n',result );
```

```
Enter number of data points : 5
Enter data for x and y:
x[0]= 1
y[0]= 6
x[1]= 3
y[1]= 10
x[2]= 5
y[2]= 62
x[3]= 7
y[3]= 210
x[4]= 9
y[4]= 502
\ nFORWARD DIFFERENCE TABLE

1.00          6.00          4.00          48.00          48.00          0.00
3.00          10.00         52.00          96.00          48.00
5.00          62.00        148.00         144.00
7.00          210.00       292.00
9.00           502.00
\ nTHE INTERPOLATING POLYNOMIAL IS
```

```
1.0*t - 3.0*t + 1.0*t + 7.0
Do you want to interpolate at a point (y/n)? y
enter the point 2
\ nThe value of the function at 2.0 is
5.0
```

2. Use Newtons backward interpolation to obtain the interpolating polynomial and hence calculate  $y(8)$  for the following data:  $x = [1, 3, 5, 7, 9]$  and  $y = [6, 10, 62, 210, 502]$

```
from sympy import *
import numpy as np
import sys
print (" This will use Newton 's backward intepolation formula ")
# Reading number of unknowns
n = int( input ('Enter number of data points : '))
# Making numpy array of n & n x n size and initializing
# to zero for storing x and y value along with differences of y
x = np. zeros ((n))
y = np. zeros ((n,n))
# Reading data points
print ('Enter data for x and y: ')
for i in range (n):
    x[i] = float ( input ( 'x['+str(i)+']= '))
    y[i][0] = float ( input ( 'y['+str(i)+']= '))
# Generating backward difference table
for i in range (1,n):
    for j in range (n-1,i-2,-1):
        y[j][i] = y[j][i-1] - y[j-1][i-1]
print ('\ nBACKWARD DIFFERENCE TABLE \n');
for i in range (0,n):
    print ('%0.2f ' %(x[i]), end='')
    for j in range (0, i+1):
        print ('\t%0.2f ' %(y[i][j]), end='')
    print ()
#obtaining the polynomial
t= symbols ('t')
f=[]
p=(t-x[n-1])/(x[1]-x[0])
f. append (p)
for i in range (1,n-1):
    f. append (f[i-1]*(p+i)/(i+1))
poly =y[n-1][0]
print ( poly )
for i in range (n-1):
    poly = poly +y[n-1][i+1]*f[i]
    simp_poly = simplify ( poly )
print ('\ nTHE INTERPOLATING POLYNOMIAL IS\n');
pprint ( simp_poly )
# if you want to interpolate at some point the next session will help
inter = input ('Do you want to interpolate at a point (y/n)? ')
if inter =='y':
    a= float ( input ('enter the point '))
    interpol = lambdify (t, simp_poly )
    result = interpol (a)
    print ('\ nThe value of the function at ',a,'is\n',result );
```

```

This will use Newton 's backward intepolation formula
Enter number of data points : 5
Enter data for x and y:
x[0]= 1
y[0]= 6
x[1]= 3
y[1]= 10
x[2]= 5
y[2]= 62
x[3]= 7
y[3]= 210
x[4]= 9
y[4]= 502
\ nBACKWARD DIFFERENCE TABLE

1.00      6.00
3.00      10.00    4.00
5.00      62.00    52.00    48.00
7.00      210.00   148.00   96.00    48.00
9.00      502.00   292.00   144.00   48.00    0.00
502.0
\ nTHE INTERPOLATING POLYNOMIAL IS

      3      2
1.0*t - 3.0*t + 1.0*t + 7.0
Do you want to interpolate at a point (y/n)? y
enter the point 8
\ nThe value of the function at 8.0 is
335.0
```

## Activity 7

1. Using Newton's forward formula, compute the pressure of the steam at temperature 1420 from the following steam table. Temperature: [140,150,160,170,180] , Pressure : [3.685,4.854, 6.302, 8.076,10.225]
2. Fit a polynomial of degree three which takes the following values.  $x = [3, 4, 5, 6]$  and  $y = [6, 24, 60, 120]$  Ans: $x^3 - 3x^2 + 2x$

3. The area of a circle (A) corresponding to diameter (D) is given below:  $D = [80, 85, 90, 95, 100]$  and  $A = [5026, 5674, 6362, 7088, 7854]$ . Find the area corresponding to diameter 105 using an appropriate interpolation formula.
4. Given  $f(40) = 184, f(50) = 204, f(60) = 226, f(70) = 250, f(80) = 276, f(90) = 304$ , find  $f(38)$  and  $f(85)$  using suitable interpolation formulae.
5. Given  $\sin 45^\circ = 0.7071, \sin 500^\circ = 0.7660, \sin 550^\circ = 0.8192, \sin 600^\circ = 0.8660$  find  $\sin 570^\circ$  using an appropriate interpolation formula.
6. Find  $f(2.5)$  by using Newton's backward interpolation formula given that  $f(0) = 7.4720, f(1) = 7.5854, f(2) = 7.6922, f(3) = 7.8119, f(4) = 7.9252$
7. From the following data estimate the number of students scoring marks more than 40 but less than 45. Marks: [30-40, 40-50, 50-60, 60-70, 70-80], No. of students: [31, 42, 51, 35, 31]

## Lab 8\_Computation of area under the curve using Trapezoidal Rule, Simpson's (1/3)rd rule, Simpson's (3/8)th rule and Weddle's rule.

### Trapezoidal Rule

```
import numpy as np

a = 0
b = np.pi
n = 11
h = (b - a) / (n - 1)
x = np.linspace(a, b, n)
f = np.sin(x)

I_trap = (h/2)*(f[0] + 2*sum(f[1:n-1]) + f[n-1])

print(I_trap)

1.9835235375094546
```

### Simpsons 1/3<sup>rd</sup> Rule

```
import numpy as np

a = 0
b = np.pi
n = 25
h = (b - a) / (n - 1)
x = np.linspace(a, b, n)
f = np.sin(x)

I_trap =(h/3) * (f[0] + 2*sum(f[:n-2:2])+ 4*sum(f[1:n-1:2]) + f[n-1])

print(I_trap)

2.00000326887716
```

### Simpsons 3/8<sup>th</sup> Rule

```
import numpy as np

a = 0
b = np.pi
n = 20
h = (b - a) / (n - 1)
x = np.linspace(a, b, n)
f = np.sin(x)

I_trap =(3*h/8) * (f[0] + 3*sum(f[1:n-1]) - sum(f[1:n-1:3]) + f[n-1])

print(I_trap)

1.9965856909340378
```

## Activity 8

1. Use Simpson's 1/3rd rule to find  $\int_0^{0.6} e^{-x^2} dx$ . Ans: 0.5351
2. By using Simpson's 3/8th rule with h= 0.2 find the approximate area under the curve  $y = \frac{x^2-1}{x^2+1}$  between the ordinates  $x = 1$  and  $x = 2.8$ , Ans: 0.9152
3. Evaluate  $I = \int_4^{5.2} \log(x) dx$  a) Simpson's 1/3rd rule, Ans: a) 1.8278472.., b) Simpson's 3/8th rule Ans: b) 1.8278470
4. Evaluate  $\int_0^1 \frac{1}{x^2+1} dx$ . by using Simpson's 1/3rd rule taking four equal strips and hence deduce an approximate value of  $\pi$ . Ans 0.7854

5. Evaluate  $\int_0^1 \frac{1}{x+1} dx$  taking seven ordinates by applying Simpson’s 3/8th rule. Hence deduce the value of  $\ln(2)$  Ans: 0.6932
6. Use Simpson’s 1/3rd & 3/8th rule to evaluate  $\int_1^4 e^{1/x} dx$  Ans 4.9257

## Lab 9\_Solution of ODE of first order and first degree by Taylor’s series and Modified Euler’s method.

### 9.1 Taylor series method to solve ODE

Solve:  $\frac{dy}{dx} - 2y = 3e^x$  with  $y(0) = 0$  using Taylor series method  $x = 0.1, 0.2, 0.3$ .

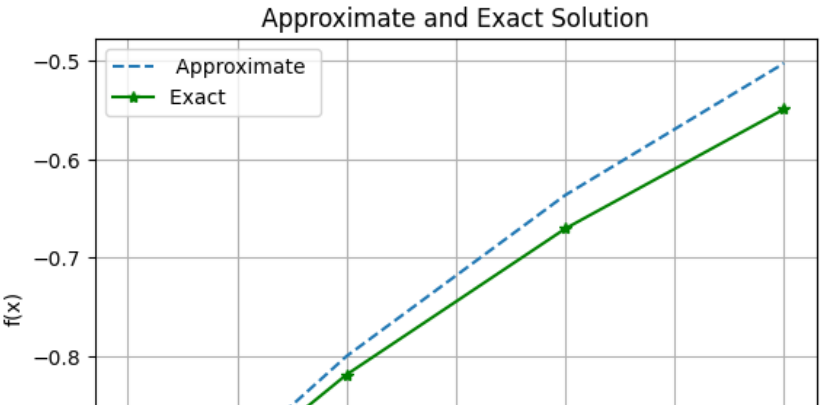
```
from numpy import *
def taylor (deriv ,x,y,xStop ,h):
    X = []
    Y = []
    X.append (x)
    Y.append (y)
    while x < xStop : # Loop over integration steps
        D = deriv (x,y) # Derivatives of y
        H = 1.0
        for j in range (3): # Build Taylor series
            H = H*h/(j + 1)
            y = y + D[j]*H # H = h^j/j!
            x = x + h
        X.append (x) # Append results to
        Y.append (y) # lists X and Y
    return array (X),array (Y) # Convert lists into arrays
# deriv = user - supplied function that returns derivatives in the 4 x n array
def deriv (x,y):
    D = zeros ((4,1))
    D[0] = [2*y[0] + 3*exp(x)]
    D[1] = [4*y[0]+ 9*exp(x)]
    D[2] = [8*y[0]+ 21*exp(x)]
    D[3] = [16*y[0]+ 45*exp(x)]
    return D
x = 0.0 # Initial value of x
xStop = 0.3 # last value
y = array ([0.0]) # Initial values of y
h = 0.1 # Step size
X,Y = taylor (deriv ,x,y,xStop ,h)
print("The required values are :at x= %0.2f , y=%0.5f , x=%0.2f , y=%0.5f , x = %0.2f , y=%0.5f , x = %0.2f , y=%0.5f" %(X[0],Y[0],X[1],Y[1],X[2],Y[2],X[3],Y[3]))
```

### 9.2 Euler’s method to solve ODE:

Solve:  $\frac{dy}{dx} = e^{-x}$  with  $y(0) = -1$  using Taylor series method  $x = 0.2, 0.4, 0.6$ .

```
import numpy as np
import matplotlib . pyplot as plt
# Define parameters
f = lambda x, y: np.exp(-x) # ODE
h = 0.2 # Step size
y0 = -1 # Initial Condition
n=3
# Explicit Euler Method
y=np.zeros(n+1)
x=np.zeros(n+1)
y[0] = y0
x[0]=0
for i in range (0, n):
    x[i+1]=x[i]+h
    y[i + 1] = y[i] + h*f(x[i], y[i])
print ("The required values are at x= %0.2f , y=%0.5f , x=%0.2f , y=%0.5f ,x = %0.2f , y=%0.5f ,x = %0.2f , y=%0.5f"%(x[0],y[0],x[1],y[1],x[2],y[2],x[3],y[3]))
print ("\n\n")
plt . plot (x, y, '--', label = ' Approximate ')
plt . plot (x, -np.exp (-x), 'g*-', label ='Exact ')
plt . title (" Approximate and Exact Solution " )
plt . xlabel ('x')
plt . ylabel ('f(x)')
plt . grid ()
plt . legend ()
plt . show ()
```

The required values are at x= 0.00 , y=-1.00000 , x=0.20 , y=-0.80000 ,x = 0.40 , y=-0.63625 ,x = 0.60 , y=-0.50219



Activity 9

1. Solve the following differential equations using Euler’s modified method:

- a.  $\frac{dy}{dx} = \log x + y$  with  $y(1) = 2$  at  $x = 1.2$  and  $x = 1.4$ . Take  $h = 0.2$
- b.  $y' = x + \sin y$  with  $y(0) = 1$ . Compute  $y(0.2)$  and  $y(0.4)$
- c.  $\frac{dy}{dx} = \frac{y-x}{y+x}$  with the boundary conditions  $y(0) = 1$ . Compute  $y$  at  $x = 0.1$

2. Solve the following differential equations using Taylor's series method:

- a.  $y' = x - y^2$  with  $y(0) = 1$ . Compute  $y(0.1)$
- b.  $y' = x^2 y - 1$  with  $y(0) = 1, h = 0.1$ . Compute  $y(0.2)$
- c.  $y' = x + y$  with  $y(0) = 1, h = 0.1$ . Compute  $y(0.1), y(0.2), y(0.3)$

Modified Euler's Method

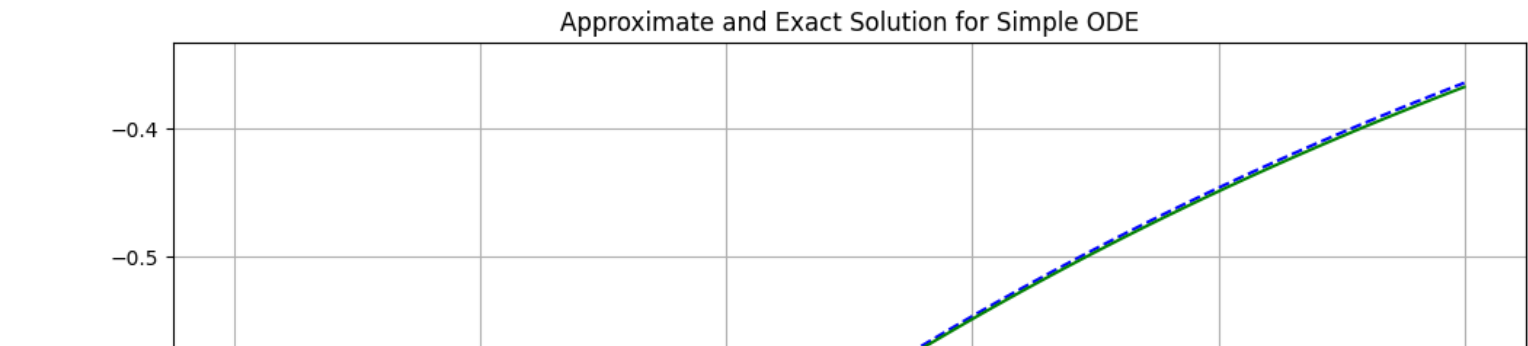
```
import numpy as np
import matplotlib.pyplot as plt

# Define parameters
f = lambda t, s: np.exp(-t) # ODE
h = 0.01 # Step size
t = np.arange(0, 1 + h, h) # Numerical grid
s0 = -1 # Initial Condition

# Explicit Euler Method
s = np.zeros(len(t))
s[0] = s0

for i in range(0, len(t) - 1):
    s[i + 1] = s[i] + h*f(t[i], s[i])

plt.figure(figsize = (12, 8))
plt.plot(t, s, 'b--', label='Approximate')
plt.plot(t, -np.exp(-t), 'g', label='Exact')
plt.title('Approximate and Exact Solution for Simple ODE')
plt.xlabel('t')
plt.ylabel('f(t)')
plt.grid()
plt.legend(loc='lower right')
plt.show()
```



Lab 10\_Solution of ODE of first order and first degree by Runge-Kutta 4th order and Milne’s predictor-corrector method

Runge-Kutta 4<sup>th</sup> order method

Apply the Runge Kutta method to find the solution of  $\frac{dy}{dx} = 1 + \frac{y}{x}$  at  $y(2)$ , taking  $h = 0.2$ . Given that  $y(1) = 2$ .

```
from sympy import *
import numpy as np
def RungeKutta (g,x0 ,h,y0 ,xn):
    x,y= symbols('x,y')
    f= lambdify ([x,y],g)
    xt=x0+h
    Y=[y0]
    while xt<=xn:
        k1=h*f(x0 ,y0)
        k2=h*f(x0+h/2, y0+k1/2)
        k3=h*f(x0+h/2, y0+k2/2)
        k4=h*f(x0+h, y0+k3)
        y1=y0+(1/6)*(k1+2*k2+2*k3+k4)
        Y. append (y1)
        # print ('y(%3.3f %xt ,') is %3.3f %y1)
        x0=xt
        y0=y1
        xt=xt+h
    return np. round (Y,2)
RungeKutta ('1+(y/x)',1,0.2,2,2)

array([2. , 2.62, 3.27, 3.95, 4.66, 5.39])
```

Milne’s predictor and corrector method

Apply Milne’s predictor and corrector method to solve  $\frac{dy}{dx} = x^2 + (y/2)$  at  $y(1.4)$ . Given that  $y(1) = 2$ ,  $y(1.1) = 2.2156$ ,  $y(1.2) = 2.4649$ ,  $y(1.3) = 2.7514$ . Use corrector formula thrice.

```
# Milne 's method to solve first order DE
# Use corrector formula thrice
x0=1
y0=2
y1=2.2156
y2=2.4649
y3=2.7514
h=0.1
x1=x0+h
x2=x1+h
x3=x2+h
x4=x3+h
def f(x,y):
    return x ** 2+(y/2)
y10 =f(x0 , y0)
y11 =f(x1 ,y1)
y12 =f(x2 ,y2)
y13 =f(x3 ,y3)
y4p =y0+(4*h/3)*(2*y11-y12+2*y13)
print ('predicted value of y4 is %3.3f %y4p)
y14 =f(x4 ,y4p );
for i in range (1,4):
    y4=y2+(h/3)*(y14 +4*y13 +y12 );
    print ('corrected value of y4 after',i,'iterations is',y4)
    y14=f(x4 ,y4);

predicted value of y4 is 3.079
corrected value of y4 after 1 iterations is 3.0793962222222224
corrected value of y4 after 2 iterations is 3.079398270370371
corrected value of y4 after 3 iterations is 3.079398304506173
```

# Activity-10

1. Apply Runge-Kutta fourth order method, to find an approximate value of  $y$  when  $x = 0.2$  given that  $\frac{dy}{dx} = x + y$  and  $y = 1$  when  $x = 0$ .
2. Using Runge-Kutta method of fourth order, solve  $\frac{dy}{dx} = \frac{y^2-x^2}{y^2+x^2}$  with  $y(0) = 1$  at  $x = 0.2, 0.4$ .
3. Using Runge-Kutta method of fourth order, find  $y(0.2)$  given that  $\frac{dy}{dx} = 3x + \frac{y}{2}$  with  $y(0) = 1$  taking  $h = 0.1$
4. Apply Runge-Kutta method to find an approximate value of  $y$  for  $x = 0.2$  in steps of 0.1 if  $\frac{dy}{dx} = x + y^2$  given that  $y = 1$ , where  $x = 0$
5. Use Runge-kutta method of order 4, find  $y$  for  $x = 0.1, 0.2, 0.3$  given that  $\frac{dy}{dx} = xy + y^2$
6. Using Milne's method, find  $y(4.5)$  given  $5xy' + y^2 - 2 = 0$  given  $y(4) = 1, y(4.1) = 1.0049, y(4.2) = 1.00097, y(4.3) = 1.0143, y(4.4) = 1.0187$