### Chu Yi Herr

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## Skills

- C | C++ | Java | Python | Git | CUDA | Agile | GDB | ARM32/64 Architecture
- Software Engineering | Linux Environment | Agile | Computer Architecture | Operating System | Compilers Design | OOP | CI/CD | Distributed Systems | Graphics Algorithms | Unit Tests | System Testing
- Robotics | Embedded Systems | Firmware | Communication Protocols (I2C, SPI, UART, IoT) | Embedded Design

## Experience \_\_\_\_\_

#### **Software Engineer**

**UC Berkeley** 

Berkeley, CA, USA 10/2022 - 04/2024

- Developing the LLSM GUI applications for multiple platforms such as Mac and Linux using the latest technology C++, and Qt/QTCreator.
- Implement scalable plugins back-end using Java and Javax and managed the UI design for those plugins.
- Created multiple innovative solutions when tackling new problems on multiple projects increasing user-defined behaviors by 10 – 15%.
- Hosted meetings discussing application requirements and software dependencies for workload balancing, software implementation, testing, and configuring metrics systems.
- Continuous Integration/Deployment pipeline integration, pull requests, code reviews, load/stress testing, unit/integration/e2e testing.

#### Education

**Bachelor of Science** San Francisco State University San Francisco, CA 05/2025

Major in Computer Science

**Associates of Science** Clovis Community College Clovis, CA 05/2023

Major in Computer Science

# **Projects**

- A-Compiler: Designing own compiler called A-Compiler (C++, ARM64). Link to the GitHub (02/2024)
- Libhal-Soft: Porting over different drivers such as lpc40, CAN, ADC, DAC for adding support to different arm chips. Contributing to this Open-Source project. (12/2023)
- NovaOS: Developing an Operating System called NovaOS developed using x86 assembly and C/C++ (12/2023)
- Holographic Projection: Lead, designer, and developer of a class group project developing a holographic projector using multiple sensors to give it capabilities to interacting with users (03/2022)

#### Clubs

• SJSU Robotics: Member on the Intelligence Systems team. Role was calibrating firmware of the GPS, Compass, and Lidar sensors to help retrieve data for the autonomous rover navigation system using Python, implementing machine learning algorithms in an embedded environment.