```
CSEIRO HOMEWORE #9
   Pr[X = XN] = Pr[X = Xp] = Pr[X = X8] = 3
1.)
   ~ Pr [2 = RIX = XR] = 0.8
  ~ Pr[2 = N [x = XB] = 0.2
          Pr[2RRB | RRO] = 2
     USE P[2r | PRB] + P[28 | PRB] + P[2N | PRB]
    P[2FFB|FFB] = P(2F|X=B) \cdot (\frac{1}{3})
          + 1P(2B|X=R) P(2=B|X=B) · (3)
          @+ np(zN1X=R)2.p(z=n1X=n). (3)
        \eta (0.8)^{2} \cdot (0.2) \cdot (\frac{1}{3}) + factor out the 17/2 
\eta (0.05)^{2} \cdot (0.6) \cdot (\frac{1}{3}) +
        7 (0.15) 2 . (0.2) . (1/3)
        7 ((0.0427) + (0.0008) + (0.0015)
          n (0.0947) = P[2ROB | PPB]
                   = P[ZDER | PFB] = 2
                         0,0997
                     7/
                     0.6447
                  7 = 22.3713646532
         Om (0.8) · (0.2) · (3) = 0.95 45 11 5585
         (3) 1 (0.15) 2· (0.2) (=) = 6:033557047
         P[2R | RRB] = 0.95 45 17 55 85
        P[20 | RRB] = 0.0111856823
        P(2N/PRB] = 0.033557047
```

```
a.) Transition & Sensor model:
                \chi_t = \chi_{t-1} + aut
                   2+=ax_t
  Assume
           \alpha_0 \sim \mathcal{N}(0,1); R~ \mathcal{N}(0,0.2)
           4t = 2 \qquad j \qquad 2t = 5
  Prediction:
              Ft = At Mt-1 + Btllt
              Rt = At Pt-1 + BtUt + Vo
              xt = 1 xt-, + 2 Ut + 0
            2 At = 1 ; Bt = 2 ; Vo = 0
               Zt = Ht Xt + Wt
              2t = 2xt + 0
No Ht = 2 ; We = 0
                                            Standard deviation
              \overline{Z}_t = A_t \overline{Z}_{t-1} A_t + R_t
               Et=(1)(1)(1)+(1)
              10 Zt = 2
              ~> \u03c4 = 1(1/6) +(2/2) = 4
  UPDATE !
               Kt = Et Ht (Ht Et Ht + Qt)-1
               K_{t} = ((a)(a))((a)(a)(a) + (0.2))^{-1}
                  (4) (8.2)-1
            ~ Kt = 0.487804878
               Mt = Ft + Kt (2t - Ht Mt)
              f't = 4 + k_t ((5) - (a)(4))
              1= 4 + K1 ( -3)
            no Mt = 2.536585366
                \Sigma_t = (I - K_t H_t) \bar{\Sigma}_t
               \Sigma_t = (1 - kt \lambda) \lambda
            ~ £1= 0.048780488
    Feturn | Mt = 2.536585366 ; Et = 0.048780488
```