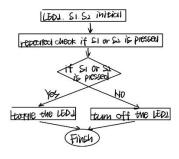
EE 215 Microprocessors LAB #6

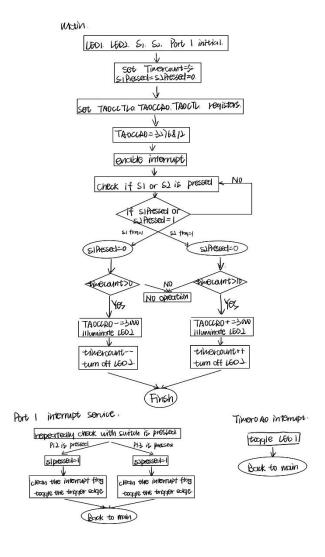
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Flowchart

Lab6a



Lab6b



Code

```
Lab6a
#include <msp430.h>
#define SWITCH_PIN1
#define CPU_F ((double)1000000)
#define delay_ms(x) __delay_cycles((long)(CPU_F*(double)x/1000.0))
int main(void) {
   WDTCTL = WDTPW | WDTHOLD; // Stop watchdog timer
                     // Set P3.7 as output for the LED
   P3DIR |= BIT7;
   P1DIR &= ~(BIT2+BIT3);  // Set P1.3 as input for the switch P1REN |= BIT2+BIT3;  // Enable pull-up resistor for P1.3
   P10UT |= BIT2+BIT3; // Set pull-up resistor as active for
P1.3
   while(1)
   {
       if (((P1IN & BIT2) == 0)||((P1IN & BIT3) == 0)) // Switch is
pressed
       {
           delay ms(20); // Debounce delay
           if (((P1IN & BIT2) == 0)||((P1IN & BIT3) == 0))// Switch
is still pressed after debounce, toggle LED state
               P30UT |= BIT7; // Toggle the LED state
               while (((P1IN & BIT2) == 0)||((P1IN & BIT3) == 0)); //
Wait for the switch to be released
           }
       }
       else
           P30UT &= ~BIT7;
   }
   return 0;
}
Lab6b
#include <msp430.h>
#define CPU F ((double)1000000)
```

```
#define delay_ms(x) __delay_cycles((long)(CPU_F*(double)x/1000.0))
#define LED1_PIN
                  BIT1
#define LED2 PIN
                  BIT7
#define S1 PIN
                  BIT2
#define S2_PIN
                  BIT3
volatile unsigned int timerCount = 5;
volatile unsigned char s1Pressed = 0;
volatile unsigned char s2Pressed = 0;
void main(void)
{
   WDTCTL = WDTPW | WDTHOLD; // Stop the watchdog timer
     P1DIR &= ~(S1_PIN | S2_PIN); // Set buttons as inputs
     P1REN |= S1_PIN | S2_PIN; // Enable pull-up resistors
     P10UT |= S1_PIN | S2_PIN;
     P8DIR |= LED1_PIN;
                          // Set LED1 as output
     P3DIR |= LED2 PIN;
                                  // Set LED2 as output
     // Configure Timer A
     TA0CTL = TASSEL_1 | MC_1; // ACLK, Up mode
     TAOCCRO = 32768/2;
                                   // 1 Hz at 32,768 Hz ACLK
     // Enable Timer A interrupt
     TAOCCTLO |= CCIE;
   // Enable Port 1 interrupt for switches S1 and S2
   P1IE |= S1_PIN | S2_PIN;
   P1IES |= S1 PIN | S2 PIN; // Set interrupt to trigger on
falling edge
   __enable_interrupt(); // Enable global interrupt
   while (1)
   {
       if (s1Pressed) // Check if S1 is pressed
          delay_ms(20);
          if ((P1IN & S1_PIN) == 0)
          {
              s1Pressed = 0;
```

```
if (timerCount > 0)
           {
              TAOCCRO += 3000; // Decrease the frequency by a
reasonable amount
              P3OUT |= LED2_PIN; // Illuminate LED2
              while((P1IN & S1 PIN) == 0);
              {
                  delay_ms(20);
                  while((P1IN & S1 PIN) == 0);
                  {
                      timerCount--;
                      delay ms(120);
                      P3OUT &= ~LED2_PIN;// Turn off LED2
                  }
              }
          }
       }
       if (s2Pressed) // Check if S2 is pressed
          delay_ms(20);
          if ((P1IN & S2_PIN) == 0)
              s2Pressed = 0;
          if (timerCount < 10)</pre>
              TAOCCRO -= 3000; // Increase the frequency by a
reasonable amount
              P3OUT |= LED2_PIN; // Illuminate LED2
              while((P1IN & S2_PIN) == 0);
              {
                  delay_ms(20);
                  while((P1IN & S2 PIN) == 0);
                  {
                      timerCount++;
                      delay ms(120);
                      P30UT &= ~LED2_PIN;// Turn off LED2
                  }
              }
          }
          }
       }
   }
```

```
}
#pragma vector=PORT1_VECTOR
__interrupt void Port1_ISR(void)
{
   if (P1IFG & S1_PIN)
       {
           s1Pressed = 1;
           P1IFG &= ~S1_PIN; // Clear the interrupt flag
           P1IES ^= S1_PIN; //toggle the trigger edge
       }
       if (P1IFG & S2_PIN)
           s2Pressed = 1;
           P1IFG &= ~S2_PIN; // Clear the interrupt flag
           P1IES ^= S2_PIN; //toggle the trigger edge
       }
}
#pragma vector=TIMER0_A0_VECTOR
__interrupt void Timer_A(void)
{
   P8OUT ^= LED1_PIN;
                                 // Toggle LED1
}
```