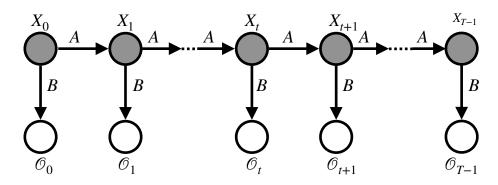
HMM



T: 序列长度 (Length of the observation sequence)

N: 隐藏状态的状态数 (Number of states in the model)

M: 观测状态总数 (Number of observation symbols)

 $X = \{X_0, X_1, \dots, X_{T-1}\}$: 状态序列 (states sequence)

 $Q = \{q_0, q_1, \dots, q_{N-1}\}$: 状态值集合 (distinct states of the Markov process)

 $\mathcal{O} = \{\mathcal{O}_0, \mathcal{O}_1, \cdots, \mathcal{O}_{T-1}\}$: 观测序列 (observation sequence)

 $V = \{v_0, v_1, \cdots, v_{M-1}\}$: 观测值集合 (distinct values of observation)

(i) $\lambda = (\pi, A, B)$

 π : 初始状态的概率分布 (initial state distribution), $\{\pi_0,\pi_1,\cdots,\pi_{N-1}\}$ ($\sum_{i=0}^{N-1}\pi_i=1$)

 $A: [a_{ij}] o$ 转移矩阵 (state transition probabilities), $a_{ij} = P(X_{t+1} = a_j | X_t = q_i)$

 $B: \ [b_j(k)] o$ 发射矩阵 (observation probabilities matrix), $\ b_j(k) = P(\mathcal{O}_t = v_k \, | \, X_t = q_j)$

(ii) 两个假设 (Two propositions)

① 齐次Markov

$$P(X_{t+1} | X_0, X_1, \dots, X_{T-1}, \mathcal{O}_0, \mathcal{O}_1, \dots, \mathcal{O}_{T-1}) = P(X_{t+1} | X_t)$$

② 观测独立

$$P(\mathcal{O}_t|X_0,X_1,\cdots,X_{T-1},\mathcal{O}_0,\mathcal{O}_1,\cdots,\mathcal{O}_{T-1})=P(\mathcal{O}_t|X_t)$$

(iii) 三个问题 (Three problems)

1 Evaluation

给定 λ ,求 $P(\mathcal{O}|\lambda)$ Forward-Backward (evaluate $P(\mathcal{O}|\lambda)$ by given λ)

2 Learning

$$\lambda_{MLE} = \arg\max_{\lambda} P(\mathcal{O} | \lambda)$$
EM

③ Decoding

$$\hat{X} = \arg \max_{X} P(\mathcal{O} | \lambda)$$
 Viterbi

前向算法 (Forward Algorithm)

Define :
$$\alpha_t(i) = P(\mathcal{O}_0, \mathcal{O}_1, \dots, \mathcal{O}_t, X_t = q_i \mid \lambda)$$

$$\begin{split} \alpha_t(i) &= P(\mathcal{O}_0, \mathcal{O}_1, \cdots, \mathcal{O}_t, X_t = q_i) \\ &= \sum_{j=0}^{N-1} P(\mathcal{O}_0, \mathcal{O}_1, \cdots, \mathcal{O}_t, X_{t-1} = q_j, X_t = q_i) \\ &= \sum_{j=0}^{N-1} P(\mathcal{O}_0, \cdots, \mathcal{O}_{t-1}, X_{t-1} = q_j) \cdot P(\mathcal{O}_t, X_t = q_i \mid \mathcal{O}_0, \cdots, \mathcal{O}_{t-1}, X_{t-1} = q_j) \\ &= \sum_{j=0}^{N-1} \alpha_{t-1}(j) \cdot P(\mathcal{O}_t \mid \mathcal{O}_0, \cdots, \mathcal{O}_{t-1}, X_{t-1} = q_i) \cdot P(X_t = q_i \mid \mathcal{O}_0, \cdots, \mathcal{O}_{t-1}, X_{t-1} = q_j) \\ &= \sum_{j=0}^{N-1} \alpha_{t-1}(j) \cdot P(\mathcal{O}_t \mid X_t = q_i) \cdot P(X_t = q_i \mid X_{t-1} = q_j) \\ &= \sum_{j=0}^{N-1} \alpha_{t-1}(j) \cdot b_i(\mathcal{O}_t) \cdot a_{ji} \\ &= \left[\sum_{j=0}^{N-1} \alpha_{t-1}(j) \cdot a_{ji}\right] \cdot b_i(\mathcal{O}_t) \end{aligned}$$

Then the final probability:

Initialization :
$$\alpha_0(i) = P(\mathcal{O}_0, X_0 = q_i \mid \lambda) = \pi_i \cdot b_i(\mathcal{O}_0)$$

$$\text{Recursions}: \alpha_{\mathit{t}}(i) = \left[\sum_{j=0}^{N-1} \alpha_{\mathit{t}-1}(j) \cdot a_{\mathit{j}i}\right] \cdot b_{\mathit{i}}(\mathcal{O}_{\mathit{t}})$$

The result:

$$\begin{split} P(\mathcal{O} \mid \lambda) &= \sum_{i=0}^{N-1} P(\mathcal{O}_0, \mathcal{O}_1, \cdots, \mathcal{O}_{T-1}, X_{T-1} = q_i \mid \lambda) \\ &= \sum_{i=0}^{N-1} \alpha_{T-1}(i) \end{split}$$

后向算法 (Backward Algorithm)

Define :
$$\beta_t(i) = P(\mathcal{O}_{t+1}, \mathcal{O}_{t+2}, \dots, \mathcal{O}_{T-1} \mid X_t = q_i, \lambda)$$

$$\begin{split} \beta_{t}(i) &= P(\mathcal{O}_{t+1}, \mathcal{O}_{t+2}, \cdots, \mathcal{O}_{T-1} \mid X_{t} = q_{i}) \\ &= \sum_{j=0}^{N-1} P(\mathcal{O}_{t+1}, \mathcal{O}_{t+2}, \cdots, \mathcal{O}_{T-1}, X_{t+1} = q_{j} \mid X_{t} = q_{i}) \\ &= \sum_{j=0}^{N-1} P(\mathcal{O}_{t+2}, \cdots, \mathcal{O}_{T-1} \mid \mathcal{O}_{t+1}, X_{t} = q_{i}, X_{t+1} = q_{j}) \cdot P(\mathcal{O}_{t+1}, X_{t+1} = q_{i} \mid X_{t} = q_{i}) \\ &= \sum_{j=0}^{N-1} P(\mathcal{O}_{t+2}, \cdots, \mathcal{O}_{T-1} \mid \mathcal{O}_{t+1}, X_{t} = q_{i}, X_{t+1} = q_{j}) \cdot P(\mathcal{O}_{t+1}, X_{t+1} = q_{i} \mid X_{t} = q_{i}) \\ &= \sum_{j=0}^{N-1} P(\mathcal{O}_{t+2}, \cdots, \mathcal{O}_{T-1} \mid \mathcal{O}_{t+1}, X_{t} = q_{i}, X_{t+1} = q_{j}) \cdot P(\mathcal{O}_{t+1}, X_{t+1} = q_{i} \mid X_{t} = q_{i}) \\ &= \sum_{j=0}^{N-1} \beta_{t+1}(j) \cdot P(\mathcal{O}_{t+1} \mid X_{t+1} = q_{j}, X_{t} = q_{i}) \cdot P(X_{t+1} = q_{i} \mid X_{t} = q_{i}) \\ &= \sum_{j=0}^{N-1} \beta_{t+1}(j) \cdot P(\mathcal{O}_{t+1} \mid X_{t+1} = q_{j}) \cdot P(X_{t+1} = q_{i} \mid X_{t} = q_{i}) \\ &= \sum_{j=0}^{N-1} \beta_{t+1}(j) \cdot b_{j}(\mathcal{O}_{t+1}) \cdot a_{ij} \end{split}$$

Then the final probability:

Initialization :
$$\beta_{T-2}(i) = P(\mathcal{O}_{T-1} \mid X_{T-1} = q_i, \lambda) = b_i(\mathcal{O}_{T-1})$$

Recursions :
$$\beta_t(i) = \sum_{i=0}^{N-1} a_{ij} \cdot b_j(\mathcal{O}_{t+1}) \cdot \beta_{t+1}(j)$$

The result:

$$\begin{split} P(\mathcal{O} \,|\, \lambda) &= \sum_{i=0}^{N-1} P(\mathcal{O}_0, \mathcal{O}_1, \cdots, \mathcal{O}_{T-1}, X_0 = q_i \,|\, \lambda) \\ &= \sum_{i=0}^{N-1} P(\mathcal{O}_0, \mathcal{O}_1, \cdots, \mathcal{O}_{T-1} \,|\, X_0 = q_i, \lambda) \cdot P(X_0 = q_i \,|\, \lambda) \,. \\ &= \sum_{i=0}^{N-1} P(\mathcal{O}_0 \,|\, \mathcal{O}_1, \cdots, \mathcal{O}_{T-1}, X_0 = q_i, \lambda) \cdot P(\mathcal{O}_1, \cdots, \mathcal{O}_{T-1} \,|\, X_0 = q_i, \lambda) \cdot \pi_i \,. \\ &= \sum_{i=0}^{N-1} P(\mathcal{O}_0 \,|\, X_0 = q_i, \lambda) \cdot P(\mathcal{O}_1, \cdots, \mathcal{O}_{T-1} \,|\, X_0 = q_i, \lambda) \cdot \pi_i \,. \\ &= \sum_{i=0}^{N-1} b_i(\mathcal{O}_0) \cdot \beta_0(i) \cdot \pi_i \end{split}$$

Baum-Welch Algorithm

Define :
$$\gamma_t(i) = P(X_t = q_i \mid \mathcal{O}, \lambda)$$

$$\begin{split} \gamma_t(i) &= P(X_t = q_i \mid \mathcal{O}_0, \mathcal{O}_1, \cdots, \mathcal{O}_{T-1}) \\ &= \frac{P(\mathcal{O}_0, \cdots, \mathcal{O}_t, \mathcal{O}_{t+1}, \cdots, \mathcal{O}_{T-1}, X_t = q_i)}{P(\mathcal{O} \mid \lambda)} \\ &= \frac{P(\mathcal{O}_0, \cdots, \mathcal{O}_t, X_t = q_i) \cdot P(\mathcal{O}_{t+1}, \cdots, \mathcal{O}_{T-1} \mid \mathcal{O}_0, \cdots, \mathcal{O}_t, X_t = q_i)}{P(\mathcal{O} \mid \lambda)} \\ &= \frac{P(\mathcal{O}_0, \cdots, \mathcal{O}_t, X_t = q_i) \cdot P(\mathcal{O}_{t+1}, \cdots, \mathcal{O}_{T-1} \mid \mathcal{X}_t = q_i)}{P(\mathcal{O} \mid \lambda)} \\ &= \frac{P(\mathcal{O}_0, \cdots, \mathcal{O}_t, X_t = q_i) \cdot P(\mathcal{O}_{t+1}, \cdots, \mathcal{O}_{T-1} \mid X_t = q_i)}{P(\mathcal{O} \mid \lambda)} \\ &= \frac{P(\mathcal{O}_0, \cdots, \mathcal{O}_t, X_t = q_i \mid \lambda) \cdot P(\mathcal{O}_{t+1}, \cdots, \mathcal{O}_{T-1} \mid X_t = q_i, \lambda)}{P(\mathcal{O} \mid \lambda)} \end{split}$$
 We return back λ
$$&= \frac{\alpha_t(i) \cdot \beta_t(i)}{P(\mathcal{O} \mid \lambda)}$$