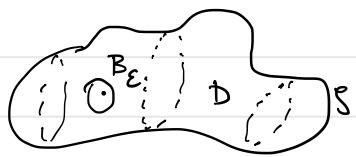


Solution:  $D_\varepsilon = D \setminus B_\varepsilon$



Check that  $\operatorname{div} \vec{F} = 0$  on  $D_\varepsilon$

$$\oint_S \vec{F} \cdot \vec{N} dS = \iint_{D_\varepsilon} \operatorname{div} \vec{F} dV - \oint_{\partial D_\varepsilon} \vec{F} \cdot \vec{N} dS$$



$$\begin{aligned} \oint_{S_\varepsilon} \frac{m \vec{r}}{|\vec{r}|^3} \cdot \left( -\frac{\vec{r}}{|\vec{r}|} \right) dS &= \oint_{S_\varepsilon} \frac{m}{|\vec{r}|^2} dS = -\frac{m}{\varepsilon^2} \oint_{S_\varepsilon} dS = \\ &= -\frac{m}{\varepsilon^2} \cdot 4\pi \varepsilon^2 = -4\pi m \end{aligned}$$

$$\Rightarrow \oint_S \vec{F} \cdot \vec{N} dS = 4\pi m.$$

### Stokes's Theorem

Recall that Green's Theorem is

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_R \left( \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dx dy$$

where  $\vec{F} = (F_1, F_2)$

$\text{Curl } \vec{F}$  is defined only for  $\vec{F} = (F_1, F_2, F_3)$ .  
 We can define  $\text{Curl } \vec{F}$  as a function when  
 $\vec{F} = (F_1(x,y), F_2(x,y))$  in the following way. Given  
 $\vec{F} = (F_1, F_2)$  define  $\vec{G} = (F_1, F_2, 0)$ .  
 Then

$$\begin{aligned}\text{Curl } \vec{G} &= \begin{vmatrix} \vec{e}_1 & \vec{e}_2 & \vec{e}_3 \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_1 & F_2 & 0 \end{vmatrix} = \\ &= \begin{vmatrix} \frac{\partial F_2}{\partial y} & \frac{\partial F_2}{\partial z} \\ F_2 & 0 \end{vmatrix} \vec{e}_1 - \begin{vmatrix} \frac{\partial F_1}{\partial x} & \frac{\partial F_1}{\partial z} \\ F_1 & 0 \end{vmatrix} \vec{e}_2 + \begin{vmatrix} \frac{\partial F_1}{\partial x} & \frac{\partial F_2}{\partial y} \\ F_1 & F_2 \end{vmatrix} \vec{e}_3 \\ &= \left( \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \vec{e}_3 = (\text{Curl } \vec{F}) \vec{e}_3\end{aligned}$$

definition

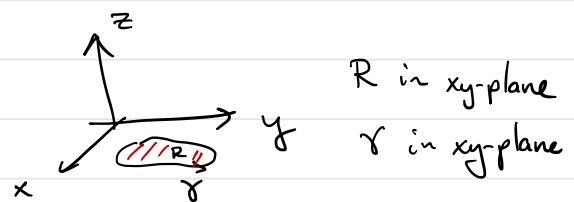
Definition If  $\vec{F} = (F_1, F_2)$  then

$$\text{Curl } \vec{F} = \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y}$$

Green's Theorem can be written

$$\oint_R \vec{F} \cdot d\vec{r} = \iint_R \text{Curl } \vec{F} \, dx \, dy$$

We can also formulate Green's Theorem in the following way:



If  $\vec{F} = (F_1(x,y), F_2(x,y), 0)$  then

$$\oint_R \vec{F} \cdot d\vec{r} = \iint_R \text{Curl } \vec{F} \cdot \vec{e}_3 \, dA$$

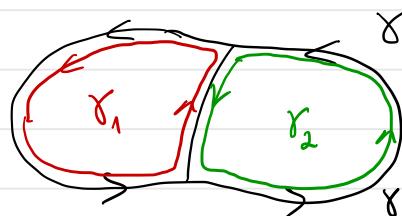
Stokes's Theorem generalizes this to non-planar surfaces.

### Stokes's Theorem

Let  $S$  be a piecewise smooth, oriented surface in  $\mathbb{R}^3$ , having unit normal field  $\vec{N}$  and boundary  $\gamma$  consisting of one or more piecewise smooth, closed curves with orientation inherited from  $S$ . If  $\vec{F}$  is a smooth vector field defined on an open set containing  $S$ , then

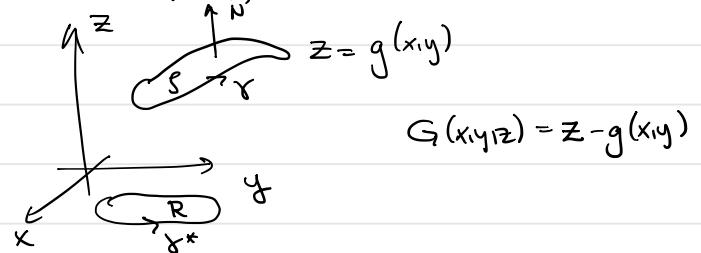
$$\oint_{\gamma} \vec{F} \cdot d\vec{r} = \iint_S \text{Curl } \vec{F} \cdot \vec{N} dS$$

Proof: We cut the surface into pieces that project 1-1 onto a coordinate plane.



$$\begin{aligned} \oint_{\gamma} \vec{F} \cdot d\vec{r} &= \\ &= \oint_{\gamma_1} \vec{F} \cdot d\vec{r} + \oint_{\gamma_2} \vec{F} \cdot d\vec{r} \end{aligned}$$

We assume that  $S$  projects 1-1 onto the  $xy$ -plane.  
We have



$$\vec{N} = \frac{\nabla G}{|\nabla G|} \quad dS = |\nabla G| dA$$

$$\iint_S \text{Curl } \vec{F} \cdot \vec{N} \, dS = \iint_R \text{Curl } \vec{F} \cdot \nabla g \, dA =$$

$$= \iint_R \left( \frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \left( -\frac{\partial g}{\partial x} \right) + \left( \frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) \left( -\frac{\partial g}{\partial y} \right) +$$

$$+ \left( \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) \cdot 1 \, dA$$

Also  $\oint_C \vec{F} \cdot d\vec{r} = \oint_{\gamma} F_1 dx + F_2 dy + F_3 dz =$

$$(z = g(x, y) \Rightarrow dz = \frac{\partial g}{\partial x} dx + \frac{\partial g}{\partial y} dy)$$

$$\oint_{\gamma^*} F_1 dx + F_2 dy + F_3 \left( \frac{\partial g}{\partial x} dx + \frac{\partial g}{\partial y} dy \right) =$$

$$\oint_{\gamma^*} \left( F_1 + F_3 \frac{\partial g}{\partial x} \right) dx + \left( F_2 + F_3 \frac{\partial g}{\partial y} \right) dy = \textcircled{*}$$

We apply Green's Theorem

$$\textcircled{*} = \iint_R \frac{\partial}{\partial x} \left( F_2(x, y, g(x, y)) + F_3(x, y, g(x, y)) \frac{\partial g}{\partial y} \right) -$$

$$- \frac{\partial}{\partial y} \left( F_1(x, y, g(x, y)) + F_3(x, y, g(x, y)) \frac{\partial g}{\partial x} \right) dA =$$

$$= \iint_R \frac{\partial F_2}{\partial x} + \frac{\partial F_2}{\partial z} \cdot \frac{\partial g}{\partial x} + \frac{\partial F_3}{\partial x} \cdot \frac{\partial g}{\partial y} + \frac{\partial F_3}{\partial z} \cdot \frac{\partial g}{\partial x} \cdot \frac{\partial g}{\partial y} + F_3 \frac{\partial^2 g}{\partial x \partial y}$$

$$- \left( \frac{\partial F_1}{\partial y} + \frac{\partial F_1}{\partial z} \cdot \frac{\partial g}{\partial y} + \frac{\partial F_3}{\partial y} \cdot \frac{\partial g}{\partial x} + \frac{\partial F_3}{\partial z} \cdot \frac{\partial g}{\partial y} \cdot \frac{\partial g}{\partial x} + F_3 \frac{\partial^2 g}{\partial y \partial x} \right) dA$$

$$= \iint_R \left( \frac{\partial F_3}{\partial y} - \frac{\partial F_2}{\partial z} \right) \left( -\frac{\partial g}{\partial x} \right) + \left( \frac{\partial F_1}{\partial z} - \frac{\partial F_3}{\partial x} \right) \left( -\frac{\partial g}{\partial y} \right) + \left( \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dA$$
⊗

Recap: We have proven

Green's Theorem (in  $\mathbb{R}^2$ )

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_R \left( \frac{\partial F_2}{\partial x} - \frac{\partial F_1}{\partial y} \right) dA$$

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_R \text{Curl } \vec{F} \cdot \vec{e}_3 dA$$

Stokes's Theorem

$$\oint_C \vec{F} \cdot d\vec{r} = \iint_S \text{Curl } \vec{F} \cdot \vec{N} dS$$

$\text{Curl } \vec{F}$  is used to calculate circulation around a curve

Divergence Theorem in the plane

$$\oint_C \vec{F} \cdot \vec{N} dS = \iint_R \text{div } \vec{F} dA$$

Gauss's Theorem

$$\iint_S \vec{F} \cdot \vec{N} dS = \iiint_D \text{div } \vec{F} dV$$

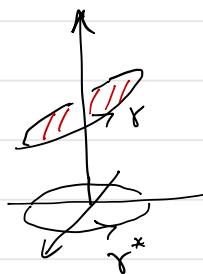
$\text{div } \vec{F}$  is used to calculate flux / flow across a curve or surface

Really the same theorem (called Stokes's Theorem) for differential forms.

Ex Calculate  $\oint_{\gamma} \vec{F} \cdot d\vec{r}$  where

$$\vec{F}(x,y,z) = (-y^3, x^3, -z^3) \text{ and}$$

$\gamma$  is the curve of intersection of the cylinder  $x^2 + y^2 = 1$  and the plane  $2x + 2y + z = 3$  oriented so it has a counter-clockwise projection onto the  $xy$ -plane.



$$\oint_{\gamma} \vec{F} \cdot d\vec{r} = \iint_S (\operatorname{curl} \vec{F}) \cdot \vec{N} dS$$

$$\vec{N} dS = \frac{\nabla G}{|\nabla G|} |\nabla G| dx dy$$

$$= (2, 2, 1) dx dy$$

$$\operatorname{curl} \vec{F} = \begin{vmatrix} \vec{e}_1 & \vec{e}_2 & \vec{e}_3 \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ -y^3 & x^3 & -z^3 \end{vmatrix} = (0, 0, 3x^2 + 3y^2)$$

$$\begin{aligned} \oint_{\gamma} \vec{F} \cdot d\vec{r} &= \iint_S (\operatorname{curl} \vec{F}) \cdot \vec{N} dS = \iint_R 3x^2 + 3y^2 dx dy \\ &= \int_0^{2\pi} \int_0^1 3r^2 \cdot r dr d\theta = \left[ \frac{3r^4}{4} \right]_0^1 2\pi = \frac{3\pi}{2} \end{aligned}$$