

# Chapter 6

- 6.1 The place of model checking in applied Bayesian statistics
- 6.2 Do the inferences from the model make sense?
- 6.3 Posterior predictive checking
- 6.4 Graphical posterior predictive checks (can be skipped)
- 6.5 Model checking for the educational testing example

## Model checking

- demo6\_1: Posterior predictive checking - light speed
- demo6\_2: Posterior predictive checking - sequential dependence
- demo6\_3: Posterior predictive checking - poor test statistic
- demo6\_4: Posterior predictive checking - marginal predictive p-value

# Model checking – overview

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- External validation
  - compare predictions to completely new observations
  - cf. relativity theory predictions
- Internal validation
  - posterior predictive checking
  - cross-validation predictive checking

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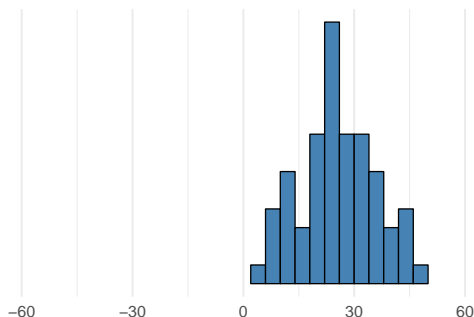
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# Replicates vs. future observation

- Predictive  $\tilde{y}$  is the next not yet observed possible observation.  $y^{\text{rep}}$  refers to replicating the whole experiment (potentially with same values of  $x$ ) and obtaining as many replicated observations as in the original data.

# Posterior predictive checking – example

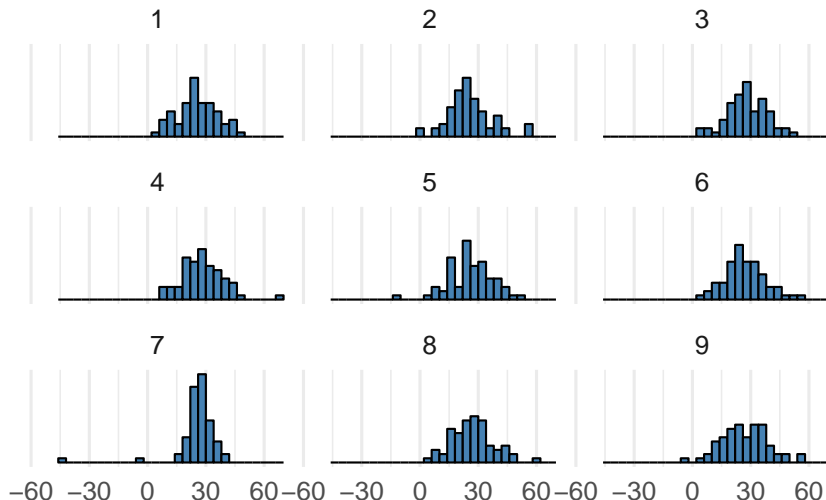
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# Posterior predictive checking with test statistic

- Replicated data sets  $y^{\text{rep}}$
- Test quantity (or discrepancy measure)  $T(y, \theta)$ 
  - summary quantity for the observed data  $T(y, \theta)$
  - summary quantity for a replicated data  $T(y^{\text{rep}}, \theta)$
  - can be easier to compare summary quantities than data sets



## Posterior predictive checking – example

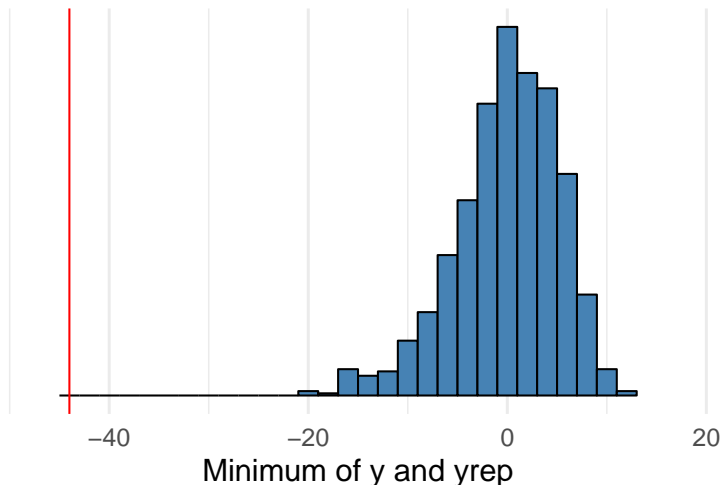
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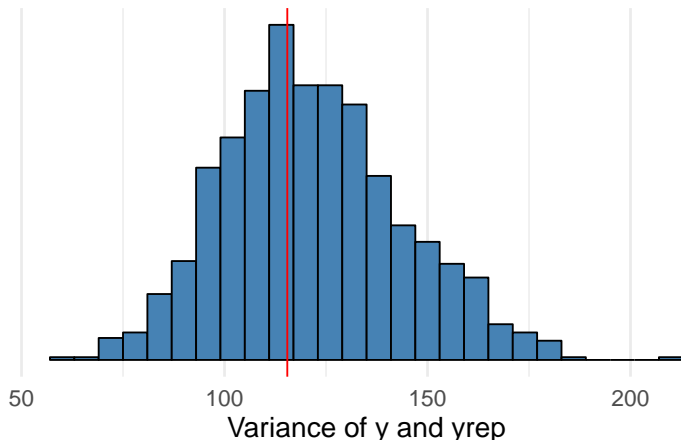
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  - e.g. variance for normal model



# Posterior predictive checking

- *Posterior predictive p-value*

$$\begin{aligned} p &= \Pr(T(y^{\text{rep}}, \theta) \geq T(y, \theta) | y) \\ &= \int \int I_{T(y^{\text{rep}}, \theta) \geq T(y, \theta)} p(y^{\text{rep}} | \theta) p(\theta | y) dy^{\text{rep}} d\theta \end{aligned}$$

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- having  $(y^{\text{rep}(s)}, \theta^{(s)})$  from the posterior predictive distribution, easy to compute

$$T(y^{\text{rep}(s)}, \theta^{(s)}) \geq T(y, \theta^{(s)}), \quad s = 1, \dots, S$$



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- Posterior predictive p-value (ppp-value) estimated whether difference between the model and data could arise by chance
- Not commonly used, since the distribution of test statistic has more information

# Marginal and CV predictive checking

- Consider marginal predictive distributions  $p(\tilde{y}_i|y)$  and each observation separately
  - marginal posterior p-values

$$p_i = \Pr(T(y_i^{\text{rep}}) \leq T(y_i)|y)$$

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- if  $Pr(\tilde{y}_i|y)$  well calibrated, distribution of  $p_i$  would be uniform between 0 and 1
  - holds better for cross-validation predictive tests (cross-validation Ch 7)

# Marginal predictive checking - Example

- Marginal tail area or Probability integral transform (PIT)

$$p_i = p(y_i^{\text{rep}} \leq y_i | y)$$

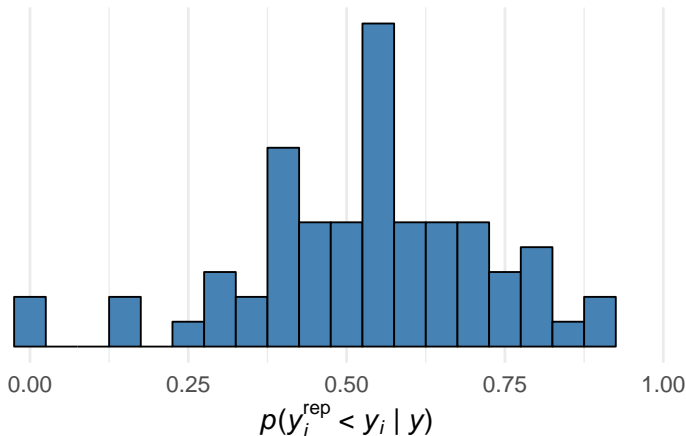
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  - alternatively combine different models to one model
    - e.g. hierarchical model instead of separate and pooled
    - e.g.  $t$  distribution contains Gaussian as a special case
  - robust models are good for testing sensitivity to “outliers”
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# Sensitivity analysis

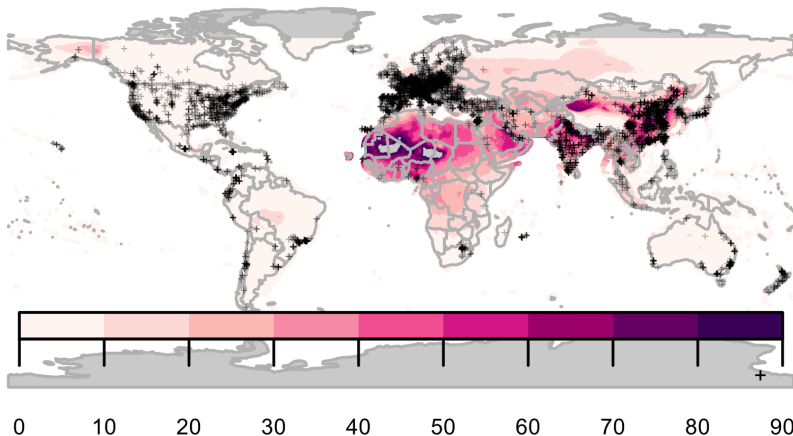
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  - robust models are good for testing sensitivity to “outliers”
    - e.g.  $t$  instead of Gaussian
- Compare sensitivity of essential inference quantities
  - extreme quantiles are more sensitive than means and medians
  - extrapolation is more sensitive than interpolation

## Example: Exposure to air pollution

- Example from Jonah Gabry, Daniel Simpson, Aki Vehtari, Michael Betancourt, and Andrew Gelman (2019). Visualization in Bayesian workflow.  
<https://doi.org/10.1111/rssa.12378>
- Estimation of human exposure to air pollution from particulate matter measuring less than 2.5 microns in diameter ( $PM_{2.5}$ )
  - Exposure to  $PM_{2.5}$  is linked to a number of poor health outcomes and a recent report estimated that  $PM_{2.5}$  is responsible for three million deaths worldwide each year (Shaddick et al., 2017)
  - In order to estimate the public health effect of ambient  $PM_{2.5}$ , we need a good estimate of the  $PM_{2.5}$  concentration at the same spatial resolution as our population estimates.

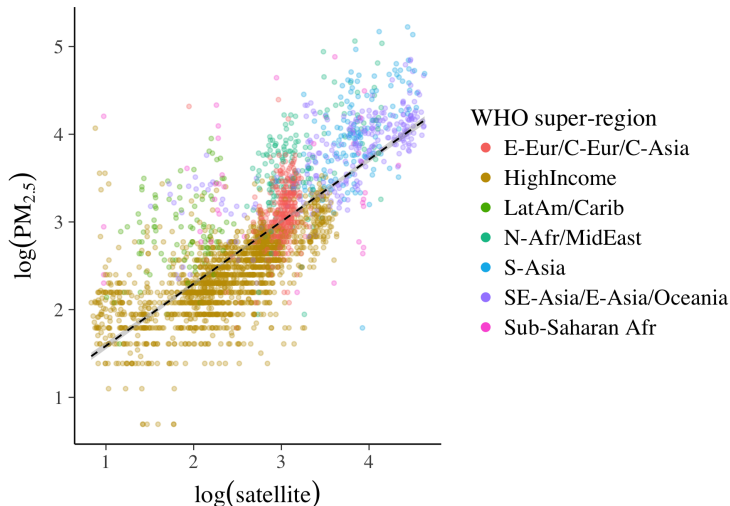
## Example: Exposure to air pollution

- Direct measurements of PM 2.5 from ground monitors at 2980 locations
- High-resolution satellite data of aerosol optical depth



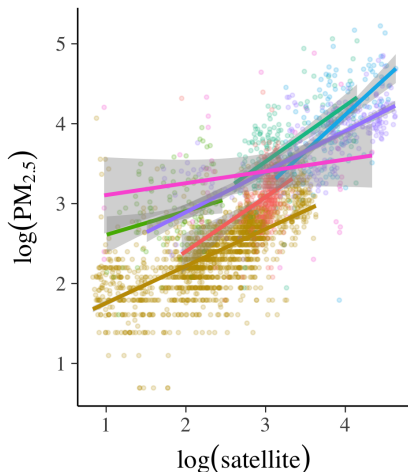
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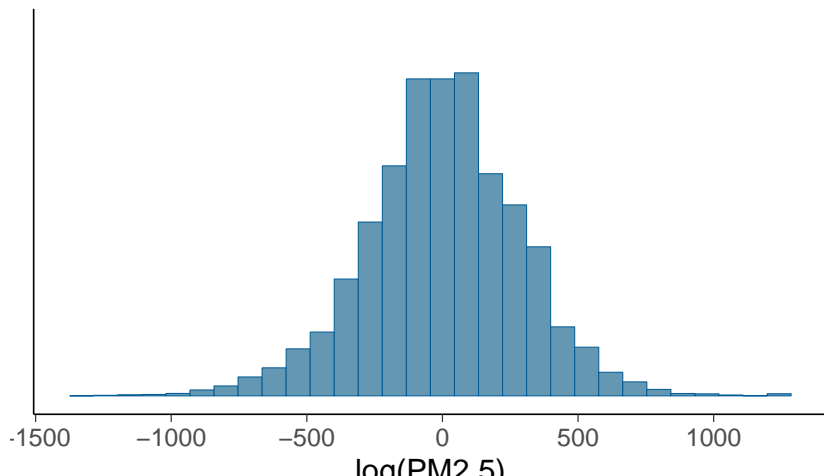
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# Example: Exposure to air pollution

Prior predictive checking

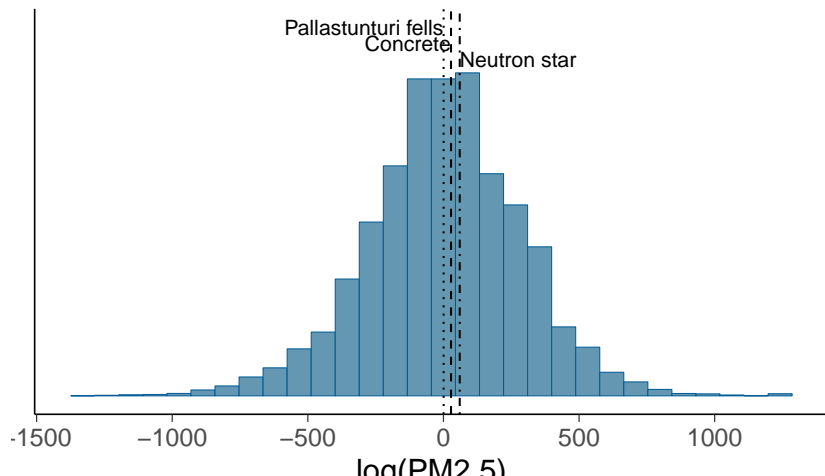
Prior predictive distribution with vague prior



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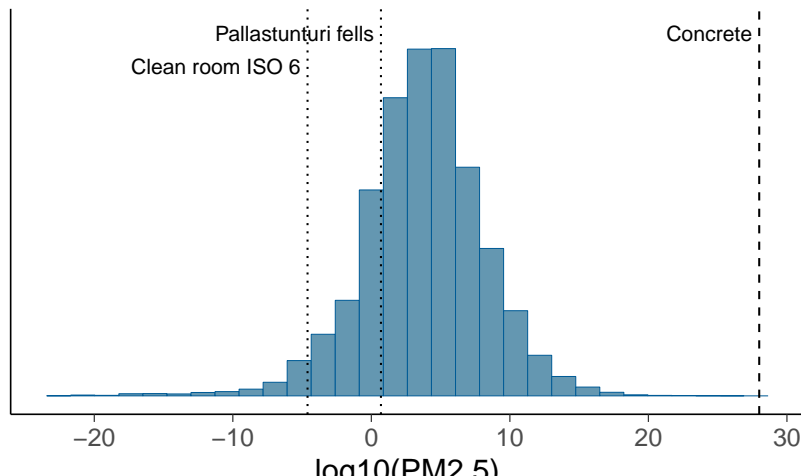




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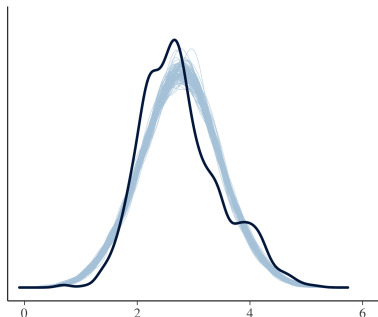
Prior predictive checking

Prior predictive distribution with weakly informative

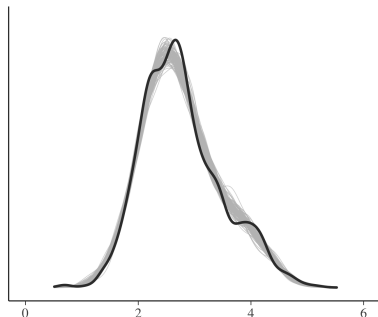


# Example: Exposure to air pollution

Posterior predictive checking – marginal predictive distributions



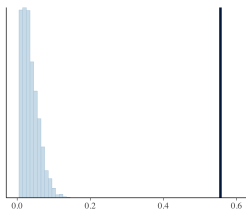
(a) Model 1



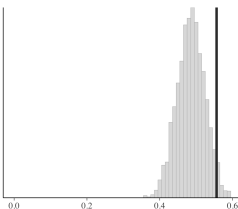
(b) Model 2

# Example: Exposure to air pollution

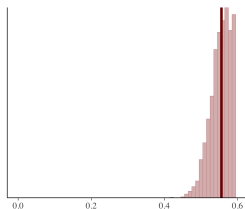
Posterior predictive checking – test statistic (skewness)



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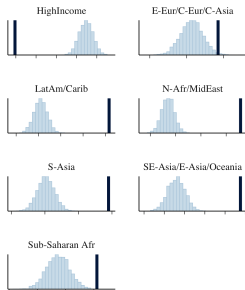
(b) Model 2



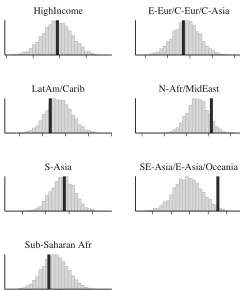
(c) Model 3

# Example: Exposure to air pollution

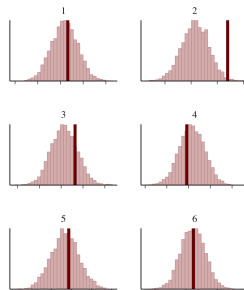
Posterior predictive checking – test statistic (median for groups)



(a) Model 1



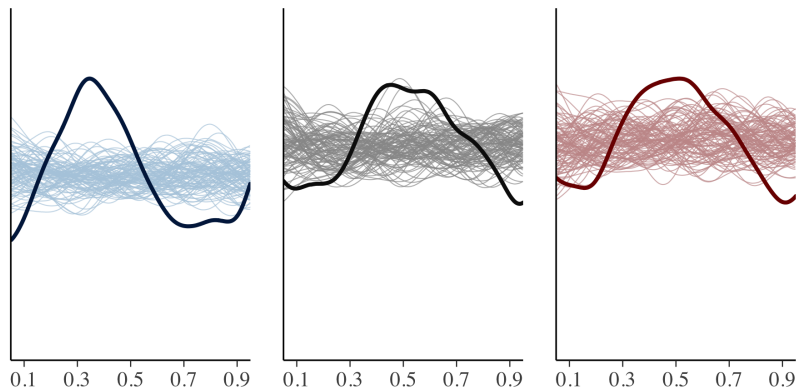
(b) Model 2



(c) Model 3

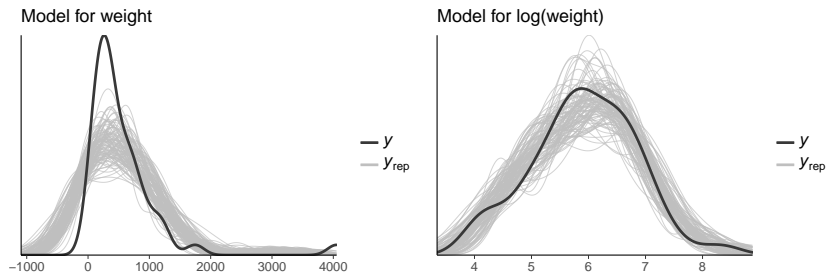
# Example: Exposure to air pollution

LOO predictive checking – LOO-PIT



EDIT 2020: These plots use boundary corrected KDE which is a better choice than the non-boundary corrected KDE used in the plots in the paper and the 2019 lecture

# Example of posterior predictive checking

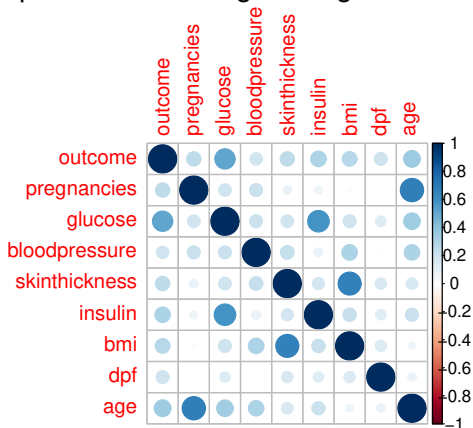


Predicting the yields of mesquite bushes.

Gelman, Hill & Vehtari (2020): Regression and Other Stories, Chapter 11.

# Example of posterior predictive checking

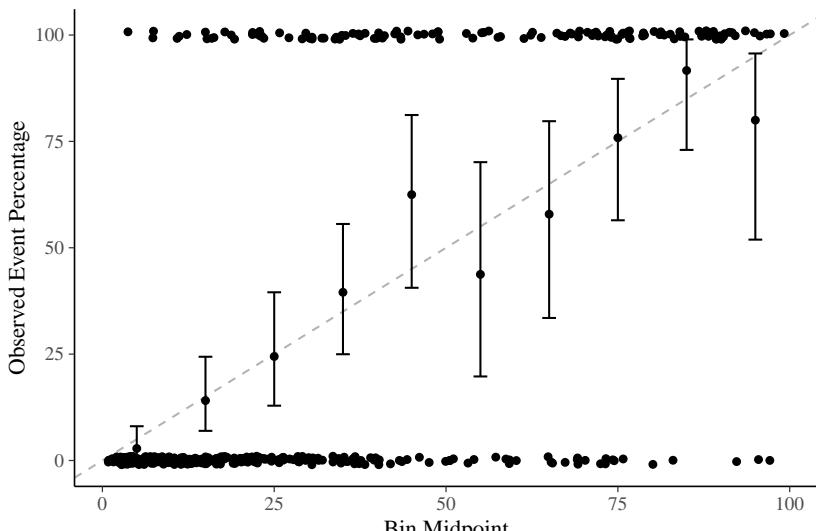
Diabetes prediction with logistic regression - diabetes demo



# Example of posterior predictive checking

Diabetes prediction with logistic regression - diabetes demo

PPC with binning for binary data

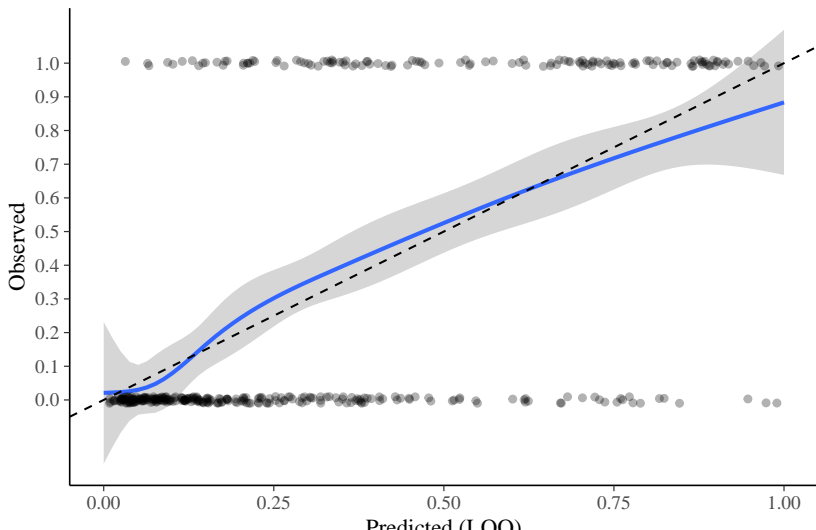




# Example of posterior predictive checking

Diabetes prediction with logistic regression - diabetes demo

PPC with non-linear regression for binary data



# Posterior predictive checking

- demo demos\_rstan/ppc/poisson-ppc.Rmd

```
data {  
  int<lower=1> N;  
  int<lower=0> y[N];  
}  
parameters {  
  real<lower=0> lambda;  
}  
model {  
  lambda ~ exponential(0.2);  
  y ~ poisson(lambda);  
}  
generated quantities {  
  real log_lik[N];  
  int y_rep[N];  
  for (n in 1:N) {  
    y_rep[n] = poisson_rng(lambda);  
    log_lik[n] = poisson_lpmf(y[n] | lambda);  
  }  
}
```

## Further reading and examples

- Jonah Gabry, Daniel Simpson, Aki Vehtari, Michael Betancourt, and Andrew Gelman (2019). Visualization in Bayesian workflow. <https://doi.org/10.1111/rssa.12378>.
- Graphical posterior predictive checks using the bayesplot package  
<http://mc-stan.org/bayesplot/articles/graphical-ppcs.html>
- Another demo `demos_rstan/ppc/poisson-ppc.Rmd`
- Michael Betancourt's workflow case study with prior and posterior predictive checking
  - for RStan [https://betanalpha.github.io/assets/case\\_studies/principled\\_bayesian\\_workflow.html](https://betanalpha.github.io/assets/case_studies/principled_bayesian_workflow.html)
  - for PyStan  
[https://github.com/betanalpha/jupyter\\_case\\_studies/blob/master/principled\\_bayesian\\_workflow/principled\\_bayesian\\_workflow.ipynb](https://github.com/betanalpha/jupyter_case_studies/blob/master/principled_bayesian_workflow/principled_bayesian_workflow.ipynb)