Assignment 2 (2p)

Derive the constitutive equations of Kirchhoff shell in cylindrical (z, ϕ, n) coordinates. Assume that all derivatives with respect to the angular coordinate ϕ and displacement and rotation components u_{ϕ} and θ_z vanish. The constitutive equations of Reissner-Mindlin shell in cylindrical (z, ϕ, n) coordinates are

$$\begin{cases} M_{zz} \\ M_{\phi\phi} \\ M_{z\phi} \\ M_{\phi z} \end{cases} = D \begin{cases} \frac{\partial \theta_{\phi}}{\partial z} - v \frac{1}{R} \frac{\partial \theta_{z}}{\partial \phi} - \frac{1}{R} \frac{\partial u_{z}}{\partial z} \\ v \frac{\partial \theta_{\phi}}{\partial z} - \frac{1}{R} \frac{\partial \theta_{z}}{\partial \phi} + \frac{1}{R^{2}} (\frac{\partial u_{\phi}}{\partial \phi} - u_{n}) \\ \frac{1}{2} (1 - v) [(\frac{1}{R} \frac{\partial \theta_{\phi}}{\partial \phi} - \frac{\partial \theta_{z}}{\partial z}) - \frac{1}{R} \frac{\partial u_{\phi}}{\partial z}] \\ \frac{1}{2} (1 - v) [(\frac{1}{R} \frac{\partial \theta_{\phi}}{\partial \phi} - \frac{\partial \theta_{z}}{\partial z}) + \frac{1}{R^{2}} \frac{\partial u_{z}}{\partial \phi}] \end{cases} , \quad M_{\phi n} = \frac{1}{2} (1 - v) D \frac{1}{R} [\frac{1}{R} (\frac{\partial u_{n}}{\partial \phi} + u_{\phi}) - \theta_{z}],$$

$$\begin{cases} N_{zz} \\ N_{\phi\phi} \\ N_{z\phi} \\ N_{\phiz} \end{cases} = \begin{cases} \frac{tE}{1-v^2} [\frac{\partial u_z}{\partial z} + v \frac{1}{R} (\frac{\partial u_\phi}{\partial \phi} - u_n)] - D \frac{1}{R} \frac{\partial \theta_\phi}{\partial z} \\ \frac{tE}{1-v^2} [\frac{1}{R} (\frac{\partial u_\phi}{\partial \phi} - u_n) + v \frac{\partial u_z}{\partial z}] - D \frac{1}{R^2} \frac{\partial \theta_z}{\partial \phi} \\ Gt(\frac{1}{R} \frac{\partial u_z}{\partial \phi} + \frac{\partial u_\phi}{\partial z}) + \frac{1}{2} (1-v) D \frac{1}{R} \frac{\partial \theta_z}{\partial z} \\ Gt(\frac{1}{R} \frac{\partial u_z}{\partial \phi} + \frac{\partial u_\phi}{\partial z}) + \frac{1}{2} (1-v) D \frac{1}{R^2} \frac{\partial \theta_\phi}{\partial \phi} \end{cases} , \begin{cases} Q_z \\ Q_\phi \end{cases} = Gt \begin{cases} \frac{\partial u_n}{\partial z} + \theta_\phi \\ \frac{1}{R} (\frac{\partial u_n}{\partial \phi} + u_\phi) - \theta_z \end{cases} .$$

Solution template

All derivatives with respect to the angular coordinate ϕ and displacement and rotation components u_{ϕ} and θ_z vanish. Kirchhoff constraints imply that

$$\theta_{\phi} =$$

When the Kirchhoff constraint is used to eliminate the rotation variable θ_{ϕ} , the constitutive equations for the non-zero stress resultants in terms of u_z and u_n simplify to

$$N_{zz} = \frac{tE}{1 - v^2} \left[\frac{\partial u_z}{\partial z} + v \frac{1}{R} \left(\frac{\partial u_\phi}{\partial \phi} - u_n \right) \right] - D \frac{1}{R} \frac{\partial \theta_\phi}{\partial z} = \frac{tE}{1 - v^2} \left[\frac{du_z}{dz} - v \frac{1}{R} u_n \right] + D \frac{1}{R} \frac{d^2 u_n}{dz^2},$$

$$N_{\phi\phi} = \frac{tE}{1 - v^2} \left[\frac{1}{R} \left(\frac{\partial u_{\phi}}{\partial \phi} - u_n \right) + v \frac{\partial u_z}{\partial z} \right] - D \frac{1}{R^2} \frac{\partial \theta_z}{\partial \phi} = \underline{\hspace{1cm}},$$

$$M_{zz} = D(\frac{\partial \theta_{\phi}}{\partial z} - v \frac{1}{R} \frac{\partial \theta_{z}}{\partial \phi} - \frac{1}{R} \frac{\partial u_{z}}{\partial z}) = \underline{\hspace{2cm}},$$

$$M_{\phi\phi} = D[v \frac{\partial \theta_{\phi}}{\partial z} - \frac{1}{R} \frac{\partial \theta_{z}}{\partial \phi} + \frac{1}{R^{2}} (\frac{\partial u_{\phi}}{\partial \phi} - u_{n})] = \underline{\hspace{1cm}}.$$