## Assignment 4 (4p)

Derive the component forms of the membrane equilibrium equation  $\nabla \cdot \vec{N} + \vec{b} = 0$  in the spherical shell coordinate system. Assume external loading  $\vec{b} = -\Delta p \vec{e}_n$  due to a pressure difference between the inner and outer surfaces. Also assume rotation symmetry with respect to both angular coordinates so that  $\vec{N} = N_{\phi\phi}\vec{e}_{\phi}\vec{e}_{\phi} + N_{\theta\theta}\vec{e}_{\theta}\vec{e}_{\theta}$  where stress components  $N_{\phi\phi}$  and  $N_{\theta\theta}$  are constants. The basis vector derivatives and gradient of the spherical shell coordinate system are given by

$$\frac{\partial}{\partial \phi} \begin{cases} \vec{e}_{\phi} \\ \vec{e}_{\theta} \\ \vec{e}_{n} \end{cases} = \begin{cases} \sin \theta \vec{e}_{n} - \cos \theta \vec{e}_{\theta} \\ \cos \theta \vec{e}_{\phi} \\ -\sin \theta \vec{e}_{\phi} \end{cases}, \quad \frac{\partial}{\partial \theta} \begin{cases} \vec{e}_{\phi} \\ \vec{e}_{\theta} \\ \vec{e}_{n} \end{cases} = \begin{cases} 0 \\ \vec{e}_{n} \\ -\vec{e}_{\theta} \end{cases}, \quad \nabla = \frac{1}{R \sin \theta} \vec{e}_{\phi} \frac{\partial}{\partial \phi} + \frac{1}{R} \vec{e}_{\theta} \frac{\partial}{\partial \theta}.$$

## **Solution**

Membrane model is the thin-slab model in curved geometry. Equilibrium equations differ from the thin-slab ones as the non-constant basis vectors brings additional terms. Therefore, a membrane may take also external forces in the transverse direction (like pressure difference between the outer and inner surfaces of a balloon). The task is to simplify the vector equation

$$\nabla \cdot \vec{N} - \vec{b} = \frac{1}{R} \left( \frac{1}{\sin \theta} \vec{e}_{\phi} \frac{\partial}{\partial \phi} + \vec{e}_{\theta} \frac{\partial}{\partial \theta} \right) \cdot \left( N_{\phi \phi} \vec{e}_{\phi} \vec{e}_{\phi} + N_{\theta \theta} \vec{e}_{\theta} \vec{e}_{\theta} \right) - \Delta p \vec{e}_{n} = 0$$

to see the component forms. Let us start with the divergence of stress

$$\frac{1}{R\sin\theta}\,\vec{e}_{\phi}\,\frac{\partial}{\partial\phi}\cdot N_{\phi\phi}\vec{e}_{\phi}\vec{e}_{\phi} = \frac{1}{R\sin\theta}\,\vec{e}_{\phi}\cdot(\frac{\partial N_{\phi\phi}}{\partial\phi}\vec{e}_{\phi}\vec{e}_{\phi} + N_{\phi\phi}\,\frac{\partial\vec{e}_{\phi}}{\partial\phi}\vec{e}_{\phi} + N_{\phi\phi}\vec{e}_{\phi}\,\frac{\partial\vec{e}_{\phi}}{\partial\phi}) = \frac{1}{R}\,N_{\phi\phi}(\vec{e}_{n} - \cot\theta\vec{e}_{\theta})\,,$$

$$\frac{1}{R} \frac{1}{\sin \theta} \vec{e}_{\phi} \frac{\partial}{\partial \phi} \cdot N_{\theta \theta} \vec{e}_{\theta} \vec{e}_{\theta} = \frac{1}{R} \frac{1}{\sin \theta} \vec{e}_{\phi} \cdot (\frac{\partial N_{\theta \theta}}{\partial \phi} \vec{e}_{\theta} \vec{e}_{\theta} + N_{\theta \theta} \frac{\partial \vec{e}_{\theta}}{\partial \phi} \vec{e}_{\theta} + \frac{\partial}{\partial \phi} N_{\theta \theta} \vec{e}_{\theta} \frac{\partial \vec{e}_{\theta}}{\partial \phi}) = \frac{1}{R} N_{\theta \theta} \cot \theta \vec{e}_{\theta},$$

$$\frac{1}{R}\vec{e}_{\theta}\frac{\partial}{\partial\theta}\cdot(N_{\phi\phi}\vec{e}_{\phi}\vec{e}_{\phi}) = \frac{1}{R}\vec{e}_{\theta}\cdot(\frac{\partial N_{\phi\phi}}{\partial\theta}\vec{e}_{\phi}\vec{e}_{\phi} + N_{\phi\phi}\frac{\partial\vec{e}_{\phi}}{\partial\theta}\vec{e}_{\phi} + N_{\phi\phi}\vec{e}_{\phi}\frac{\partial\vec{e}_{\phi}}{\partial\theta}) = 0\,,$$

$$\frac{1}{R}\vec{e}_{\theta}\frac{\partial}{\partial\theta}\cdot(N_{\theta\theta}\vec{e}_{\theta}\vec{e}_{\theta}) = \frac{1}{R}\vec{e}_{\theta}\cdot(\frac{\partial N_{\theta\theta}}{\partial\theta}\vec{e}_{\theta}\vec{e}_{\theta} + N_{\theta\theta}\vec{e}_{n}\vec{e}_{\theta} + N_{\theta\theta}\vec{e}_{\theta}\vec{e}_{n}) = \frac{1}{R}N_{\theta\theta}\vec{e}_{n}.$$

Finally combining everything

$$\nabla \cdot \vec{N} - \vec{b} = \frac{1}{R} N_{\phi\phi} (\vec{e}_n - \cot\theta \vec{e}_\theta) + \frac{1}{R} N_{\theta\theta} \cot\theta \vec{e}_\theta + \frac{1}{R} N_{\theta\theta} \vec{e}_n - \Delta p \vec{e}_n = 0 \quad \Leftrightarrow \quad$$

$$\nabla \cdot \vec{N} - \vec{b} = [\frac{1}{R}(N_{\theta\theta} - N_{\phi\phi})\cot\theta]\vec{e}_{\theta} + [\frac{1}{R}(N_{\phi\phi} + N_{\theta\theta}) - \Delta p]\vec{e}_{n} = 0 \quad \Leftrightarrow \quad$$

$$N_{\theta\theta} - N_{\phi\phi} = 0$$
 and  $\frac{1}{R} (N_{\phi\phi} + N_{\theta\theta}) - \Delta p = 0$ .

Therefore, solution to the stress resultants is

$$N_{\phi\phi}=N_{\theta\theta}=\frac{R\Delta p}{2}\,.$$