

Project: Assignment Week 5

Model: Beam

Date: 13/10/2021

## STRUCTURAL ANALYSIS

PROJECT

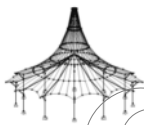
**Beam**

CLIENT

**Course code**

CREATED BY

**Nguyen Xuan Binh 887799**



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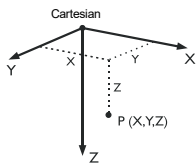
## MODEL - GENERAL DATA

	General	Model name	: Beam
		Project name	: Assignment Week 5
		Type of model	: 3D
		Positive direction of global axis Z	: Downward
		Classification of load cases and combinations	: According to Standard: EN 1990 National Annex: SFS - Finland
	Options	<input type="checkbox"/> RF-FORM-FINDING - Find initial equilibrium shapes of membrane and cable structures	
		<input type="checkbox"/> RF-CUTTING-PATTERN	
		<input type="checkbox"/> Piping analysis	
		<input type="checkbox"/> Use CQC Rule	
		<input type="checkbox"/> Enable CAD/BIM model	
		Standard Gravity	: 10.00 m/s <sup>2</sup>

## FE MESH SETTINGS

	General	Target length of finite elements	$l_{FE}$	: 0.500 m
		Maximum distance between a node and a line to integrate it into the line	$\epsilon$	: 0.001 m
		Maximum number of mesh nodes (in thousands)		: 500
	Members	Number of divisions of members with cable, elastic foundation, taper, or plastic characteristic		: 10
		<input checked="" type="checkbox"/> Activate member divisions for large deformation or post-critical analysis		
		<input checked="" type="checkbox"/> Use division for members with node lying on them		
	Surfaces	Maximum ratio of FE rectangle diagonals	$\Delta_D$	: 1.800
		Maximum out-of-plane inclination of two finite elements	$\alpha$	: 0.50 °
		Shape direction of finite elements		: Triangles and quadrangles <input checked="" type="checkbox"/> Same squares where possible

## 1.1 NODES



Node No.	Node Type	Reference Node	Coordinate System	X [m]	Y [m]	Z [m]	Comment
1	Standard	-	Cartesian	0.000	0.000	0.000	
2	Standard	-	Cartesian	4.000	0.000	0.000	
3	Standard	-	Cartesian	1.000	0.000	0.000	
4	Standard	-	Cartesian	2.000	0.000	0.000	
5	Standard	-	Cartesian	3.000	0.000	0.000	

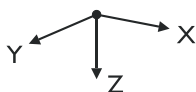
## 1.2 LINES

Line No.	Line Type	Nodes No.	Line Length L [m]		Comment
1	Polyline	3,1	1.000	X	
2	Polyline	4,3	1.000	X	
3	Polyline	5,4	1.000	X	
4	Polyline	2,5	1.000	X	

## 1.3 MATERIALS

Matl. No.	Modulus E [MN/m <sup>2</sup> ]	Modulus G [MN/m <sup>2</sup> ]	Poisson's Ratio $\nu$ [-]	Spec. Weight $\gamma$ [kN/m <sup>3</sup> ]	Coeff. of Th. Exp. $\alpha$ [1/K]	Partial Factor $\gamma_M$ [-]	Material Model
1	Steel S 235   SFS EN 1993-1-1:2005 210000.000	80769.200	0.300	78.50	1.20E-05	1.00	Isotropic Linear Elastic
2	Steel A992   ANSI/AISC 360-16:2016 199948.000	77221.300	0.295	78.49	1.20E-05	1.00	Isotropic Linear Elastic
3	E = 1000 MN/m <sup>2</sup> 1000.000	500.000	0.000	10.00	0.00E+00	1.00	Isotropic Linear Elastic

## 1.7 NODAL SUPPORTS



Support No.	Nodes No.	Axis System	Column in Z	$u_x$	$u_y$	$u_z$	$\phi_x$	$\phi_y$	$\phi_z$
1	1	User Defined X', Y', Z'	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>
2	2	User Defined X', Y', Z'	<input type="checkbox"/>	<input type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input checked="" type="checkbox"/>	<input type="checkbox"/>	<input checked="" type="checkbox"/>

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### 1.7.10 NODAL SUPPORTS - USER-DEFINED AXIS SYSTEM

Support No.	Direction Type	Sequence	Rotation [°] about X	Rotation [°] about Y	Rotation [°] about Z	Coordinate System	1st axis	Node 1 No.	Node 2 No.	2nd axis	Referen Node	Member/Line No.
1	Rotated	ZYX	-90.00	0.00	0.00							
2	Rotated	ZYX	-90.00	0.00	0.00							

### 1.13 CROSS-SECTIONS

Section No.	Matl. No.	J [cm <sup>4</sup> ] A [cm <sup>2</sup> ]	I <sub>y</sub> [cm <sup>4</sup> ] A <sub>y</sub> [cm <sup>2</sup> ]	I <sub>z</sub> [cm <sup>4</sup> ] A <sub>z</sub> [cm <sup>2</sup> ]	Principal Axes α [°]	Rotation α' [°]	Overall Dimensions [m] Width b Height h	
1	Rectangle 0.3/0.1	7902.14 300.00	2500.00 250.00	22500.00 250.00	0.00	0.00	0.300	0.100

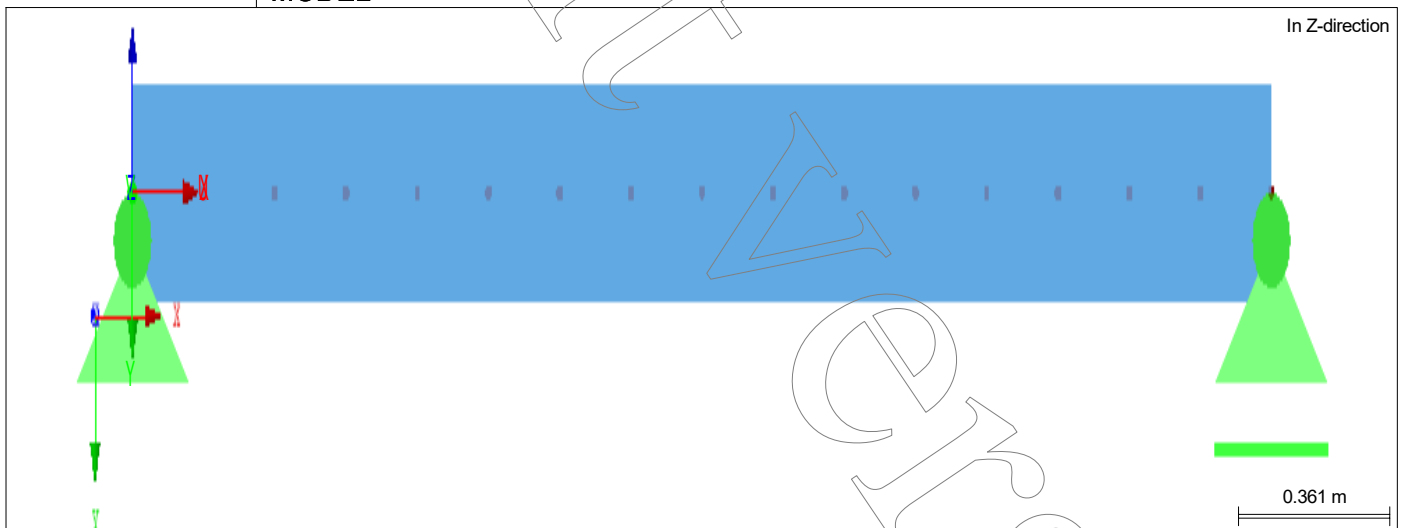
### 1.17 MEMBERS

Mbr. No.	Line No.	Member	Rotation Type	Rotation β [°/2]	Cross-Section Start	Cross-Section End	Hinge No. Start	Hinge No. End	Ecc. No.	Div. No.	Length L [m]	
1	1	Beam	Angle	0.00	1	1	-	-	-	-	1.000	X
2	2	Beam	Angle	0.00	1	1	-	-	-	-	1.000	X
3	3	Beam	Angle	0.00	1	1	-	-	-	-	1.000	X
4	4	Beam	Angle	0.00	1	1	-	-	-	-	1.000	X

### 1.23 FE MESH REFINEMENTS

Refinem. No.	FE Mesh Refinement applied to	Nodes No.	Number Divisions	Sphere Radius [m]	Target FE Length [m] Inner Outer		Comment
1	Lines via division	1-4	4				

### MODEL

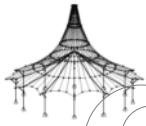


### 2.1 LOAD CASES

Load Case	Load Case Description	EN 1990   SFS Action Category	Active	Self-Weight - Factor in Direction X Y Z		
LC1	Self-weight	Permanent	<input checked="" type="checkbox"/>	0.000	1.000	0.000
LC2	Point Load	Permanent/Imposed	<input checked="" type="checkbox"/>			
LC3	Point Moment	Permanent/Imposed	<input checked="" type="checkbox"/>			

### 2.1.1 LOAD CASES - CALCULATION PARAMETERS

Load Case	Load Case Description	Calculation Parameters	
LC1	Self-weight	Method of analysis : Geometrically linear analysis Method for solving system of nonlinear algebraic equations : Newton-Raphson Activate stiffness factors of : <input checked="" type="checkbox"/> Cross-sections (factor for J, I <sub>y</sub> , I <sub>z</sub> , A, A <sub>y</sub> , A <sub>z</sub> ) : <input checked="" type="checkbox"/> Members (factor for GJ, EI <sub>y</sub> , EI <sub>z</sub> , EA, GA <sub>y</sub> , GA <sub>z</sub> )	
LC2	Point Load	Method of analysis : Geometrically linear analysis Method for solving system of nonlinear algebraic equations : Newton-Raphson Activate stiffness factors of : <input checked="" type="checkbox"/> Cross-sections (factor for J, I <sub>y</sub> , I <sub>z</sub> , A, A <sub>y</sub> , A <sub>z</sub> ) : <input checked="" type="checkbox"/> Members (factor for GJ, EI <sub>y</sub> , EI <sub>z</sub> , EA, GA <sub>y</sub> , GA <sub>z</sub> )	
LC3	Point Moment	Method of analysis : Geometrically linear analysis	



## LOADS

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### 2.1.1 LOAD CASES - CALCULATION PARAMETERS

Load Case	Load Case Description	Calculation Parameters
		Method for solving system of nonlinear algebraic equations : <input checked="" type="radio"/> Newton-Raphson
		Activate stiffness factors of: : <input checked="" type="checkbox"/> Cross-sections (factor for $J$ , $I_y$ , $I_z$ , $A$ , $A_y$ , $A_z$ )
		: <input checked="" type="checkbox"/> Members (factor for $GJ$ , $EL_y$ , $EL_z$ , $EA$ , $GA_y$ , $GA_z$ )

### 2.5 LOAD COMBINATIONS

Load Combin.	DS	Load Combination Description	No.	Factor	Load Case
CO1		Permanent Loads	1	1.00	LC1
			2	1.00	LC2
			3	1.00	LC3

### 2.5.2 LOAD COMBINATIONS - CALCULATION PARAMETERS

Load Combin.	Description	Calculation Parameters
CO1	Permanent Loads	Method of analysis : <input checked="" type="radio"/> Second order analysis (P-Delta)
		Method for solving system of nonlinear algebraic equations : <input checked="" type="radio"/> Picard
		Options : <input checked="" type="checkbox"/> Consider favorable effects due to tension
		: <input checked="" type="checkbox"/> Refer internal forces to deformed system for:
		: <input checked="" type="checkbox"/> Normal forces $N$
		: <input checked="" type="checkbox"/> Shear forces $V_y$ and $V_z$
		: <input checked="" type="checkbox"/> Moments $M_y$ , $M_z$ and $M_T$
		Activate stiffness factors of: : <input checked="" type="checkbox"/> Materials (partial factor $\gamma_M$ )
		: <input checked="" type="checkbox"/> Cross-sections (factor for $J$ , $I_y$ , $I_z$ , $A$ , $A_y$ , $A_z$ )
		: <input checked="" type="checkbox"/> Members (factor for $GJ$ , $EL_y$ , $EL_z$ , $EA$ , $GA_y$ , $GA_z$ )

### 3.1 NODAL LOADS - BY COMPONENTS - COORDINATE SYSTEM

LC2  
Point Load

LC2: Point Load

No.	On Nodes No.	Coordinate System	Force [kN] $P_x / P_U$ $P_y / P_V$ $P_z / P_W$	Moment [kNm] $M_x / M_U$ $M_y / M_V$ $M_z / M_W$
1	3	0   Global XYZ	0.000 1.000 0.000	0.000 0.000 0.000

### 3.1 NODAL LOADS - BY COMPONENTS - COORDINATE SYSTEM

LC3  
Point Moment

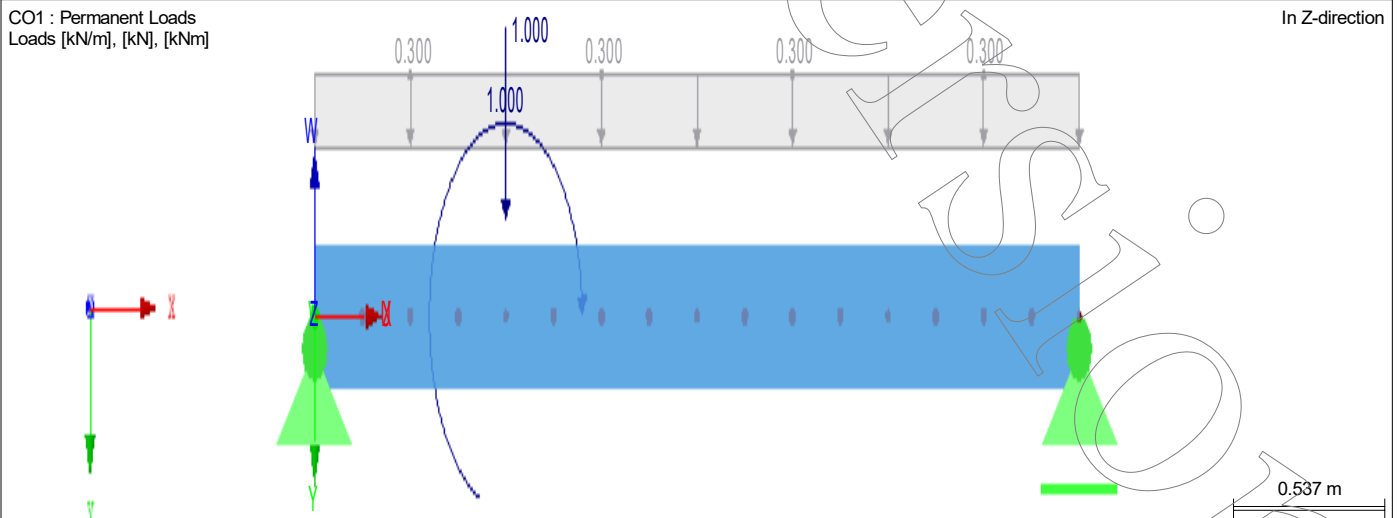
LC3: Point Moment

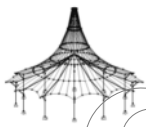
No.	On Nodes No.	Coordinate System	Force [kN] $P_x / P_U$ $P_y / P_V$ $P_z / P_W$	Moment [kNm] $M_x / M_U$ $M_y / M_V$ $M_z / M_W$
2	3	0   Global XYZ	0.000 0.000 0.000	0.000 0.000 1.000

### CO1: PERMANENT LOADS

CO1 : Permanent Loads  
Loads [kN/m], [kN], [kNm]

In Z-direction





## RESULTS

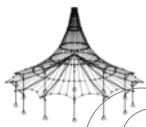
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### 4.0 RESULTS - SUMMARY

Description	Value	Unit	Comment
Load Case LC1 - Self-weight			
Sum of loads in X	0.00	kN	
Sum of support reactions in X	0.00	kN	
Sum of loads in Y	1.20	kN	
Sum of support reactions in Y	1.20	kN	Deviation 0.00%
Sum of loads in Z	0.00	kN	
Sum of support reactions in Z	0.00	kN	
Resultant of reactions about X	0.000	kNm	At center of gravity of model (X:2.000, Y:0.000, Z:0.000 m)
Resultant of reactions about Y	0.000	kNm	At center of gravity of model
Resultant of reactions about Z	0.000	kNm	At center of gravity of model
Max. displacement in X	0.00	mm	
Max. displacement in Y	4.49	mm	Member No. 2, x: 0.000 m
Max. displacement in Z	0.00	mm	
Max. vector displacement	4.49	mm	Member No. 2, x: 0.000 m
Max. rotation about X	0.0	mrاد	
Max. rotation about Y	0.0	mrاد	
Max. rotation about Z	3.6	mrاد	Member No. 1, x: 1.000 m
Maximum member strain	0.00000	-	Member No. 0, x: 0.000 m
Method of analysis	Linear		Geometrically linear analysis
Reduction of stiffness			Cross-sections, Members, Surfaces
Number of load increments	1		
Number of iterations	1		
Maximum value of element of stiffness matrix on diagonal	2.4E+08		
Minimum value of element of stiffness matrix on diagonal	3.161E+05		
Stiffness matrix determinant	1.415E+613		
Infinity Norm	4.8E+08		
Load Case LC2 - Point Load			
Sum of loads in X	0.00	kN	
Sum of support reactions in X	0.00	kN	
Sum of loads in Y	1.00	kN	
Sum of support reactions in Y	1.00	kN	Deviation 0.00%
Sum of loads in Z	0.00	kN	
Sum of support reactions in Z	0.00	kN	
Resultant of reactions about X	0.000	kNm	At center of gravity of model (X:2.000, Y:0.000, Z:0.000 m)
Resultant of reactions about Y	0.000	kNm	At center of gravity of model
Resultant of reactions about Z	-1.000	kNm	At center of gravity of model
Max. displacement in X	0.00	mm	
Max. displacement in Y	4.19	mm	Member No. 2, x: 0.250 m
Max. displacement in Z	0.00	mm	
Max. vector displacement	4.19	mm	Member No. 2, x: 0.250 m
Max. rotation about X	0.0	mrاد	
Max. rotation about Y	0.0	mrاد	
Max. rotation about Z	3.9	mrاد	Member No. 1, x: 1.000 m
Maximum member strain	0.00000	-	Member No. 0, x: 0.000 m
Method of analysis	Linear		Geometrically linear analysis
Reduction of stiffness			Cross-sections, Members, Surfaces
Number of load increments	1		
Number of iterations	1		
Maximum value of element of stiffness matrix on diagonal	2.4E+08		
Minimum value of element of stiffness matrix on diagonal	3.161E+05		
Stiffness matrix determinant	1.415E+613		
Infinity Norm	4.8E+08		
Load Case LC3 - Point Moment			
Sum of loads in X	0.00	kN	
Sum of support reactions in X	0.00	kN	
Sum of loads in Y	0.00	kN	
Sum of support reactions in Y	0.00	kN	
Sum of loads in Z	0.00	kN	
Sum of support reactions in Z	0.00	kN	
Resultant of reactions about X	0.000	kNm	At center of gravity of model (X:2.000, Y:0.000, Z:0.000 m)
Resultant of reactions about Y	0.000	kNm	At center of gravity of model
Resultant of reactions about Z	1.000	kNm	At center of gravity of model
Max. displacement in X	0.00	mm	
Max. displacement in Y	3.34	mm	Member No. 2, x: 0.125 m
Max. displacement in Z	0.00	mm	
Max. vector displacement	3.34	mm	Member No. 2, x: 0.125 m
Max. rotation about X	0.0	mrاد	
Max. rotation about Y	0.0	mrاد	
Max. rotation about Z	2.6	mrاد	Member No. 1, x: 0.000 m
Maximum member strain	0.00000	-	Member No. 0, x: 0.000 m
Method of analysis	Linear		Geometrically linear analysis
Reduction of stiffness			Cross-sections, Members, Surfaces
Number of load increments	1		
Number of iterations	1		
Maximum value of element of stiffness matrix on diagonal	2.4E+08		
Minimum value of element of stiffness matrix on diagonal	3.161E+05		
Stiffness matrix determinant	1.415E+613		
Infinity Norm	4.8E+08		
Load Combination CO1 - Permanent Loads			
Sum of loads in X	0.00	kN	
Sum of support reactions in X	0.00	kN	
Sum of loads in Y	2.20	kN	
Sum of support reactions in Y	2.20	kN	Deviation 0.00%
Sum of loads in Z	0.00	kN	
Sum of support reactions in Z	0.00	kN	



## RESULTS

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### 4.0 RESULTS - SUMMARY

Description	Value	Unit	Comment
Resultant of reactions about X	0.0	kNm	At center of gravity of model (X:2.0, Y:0.0, Z:0.0 m)
Resultant of reactions about Y	0.0	kNm	At center of gravity of model
Resultant of reactions about Z	0.0	kNm	At center of gravity of model
Max. displacement in X	0.00	mm	
Max. displacement in Y	11.98	mm	Member No. 2, x: 0.125 m
Max. displacement in Z	0.00	mm	
Max. vector displacement	11.98	mm	Member No. 2, x: 0.125 m
Max. rotation about X	0.0	mrاد	
Max. rotation about Y	0.0	mrاد	
Max. rotation about Z	9.5	mrاد	Member No. 1, x: 1.000 m
Maximum member strain	0.00000	-	Member No. 0, x: 0.000 m
Method of analysis	2nd Order		Second order analysis (Nonlinear, Timoshenko)
Internal forces referred to deformed system for...	<input checked="" type="checkbox"/>		N, V <sub>y</sub> , V <sub>z</sub> , M <sub>y</sub> , M <sub>z</sub> , M <sub>T</sub>
Reduction of stiffness	<input checked="" type="checkbox"/>		Materials, Cross-sections, Members, Surfaces
Consider favorable effects of tensile forces	<input checked="" type="checkbox"/>		
Divide results by CO factor	<input type="checkbox"/>		
Number of load increments	1		
Number of iterations	2		
Maximum value of element of stiffness matrix on diagonal	2.4E+08		
Minimum value of element of stiffness matrix on diagonal	3.161E+05		
Stiffness matrix determinant	1.415E+613		
Infinity Norm	4.8E+08		

#### Summary

Max. displacement in X	0.00		
Max. displacement in Y	11.98	mm	CO1, Member No. 2, x: 0.125 m
Max. displacement in Z	0.00		
Max. vector displacement	11.98	mm	CO1, Member No. 2, x: 0.125 m
Max. rotation about X	0.0		
Max. rotation about Y	0.0		
Max. rotation about Z	9.5	mrاد	CO1, Member No. 1, x: 1.000 m

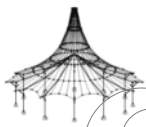
Other Settings:	
Number of 1D finite elements	16
Number of 2D finite elements	0
Number of 3D finite elements	0
Number of FE mesh nodes	17
Number of equations	102
Internal forces referred to deformed system for....	
Max. number of iterations	100
Number of divisions for member results	10
Division of cable/foundation/tapered members	10
Number of member divisions for searching maximum values	10
Subdivisions of FE mesh for graphical results	3
Percentage of iterations according to Picard method in combination with Newton-Raphson method	5 %

Options:	
Activate shear stiffness of members (A <sub>y</sub> , A <sub>z</sub> )	<input checked="" type="checkbox"/>
Activate member divisions for large deformation or post-critical analysis	<input checked="" type="checkbox"/>
Activate entered stiffness modifications	<input checked="" type="checkbox"/>
Ignore rotational degrees of freedom	<input type="checkbox"/>
Check of critical forces of members	<input checked="" type="checkbox"/>
Nonsymmetric direct solver if demanded by nonlinear model	<input type="checkbox"/>
Method for the system of equations	Direct
Plate bending theory	Mindlin
Solver version	64-bit

Precision and Tolerance:	
Change default setting	<input type="checkbox"/>

### 4.1 NODES - SUPPORT FORCES

Node No.	LC/CO	Support Forces [kN]			Support Moments [kNm]			
		P <sub>x</sub>	P <sub>y</sub>	P <sub>z</sub>	M <sub>x</sub>	M <sub>y</sub>	M <sub>z</sub>	
1*	LC1	0.00	0.00	0.60	0.00	0.00	0.00	Self-weight
	LC2	0.00	0.00	0.75	0.00	0.00	0.00	Point Load
	LC3	0.00	0.00	-0.25	0.00	0.00	0.00	Point Moment
	CO1	0.00	0.00	1.10	0.00	0.00	0.00	Permanent Loads
2*	LC1	0.00	0.00	0.60	0.00	0.00	0.00	Self-weight
	LC2	0.00	0.00	0.25	0.00	0.00	0.00	Point Load
	LC3	0.00	0.00	0.25	0.00	0.00	0.00	Point Moment
	CO1	0.00	0.00	1.10	0.00	0.00	0.00	Permanent Loads
Σ Supp.	LC1	0.00	1.20	0.00				
Σ Loads	LC1	0.00	1.20	0.00				
Σ Supp.	LC2	0.00	1.00	0.00				
Σ Loads	LC2	0.00	1.00	0.00				
Σ Supp.	LC3	0.00	0.00	0.00				
Σ Loads	LC3	0.00	0.00	0.00				
Σ Supp.	CO1	0.00	2.20	0.00				
Σ Supp.	CO1	0.00	2.20	0.00				



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## 4.12 CROSS-SECTIONS - INTERNAL FORCES

Member No.	LC/CO	Node No.	Location x [m]	Forces [kN]			Moments [kNm]			
				N	V <sub>y</sub>	V <sub>z</sub>	M <sub>T</sub>	M <sub>y</sub>	M <sub>z</sub>	
Section No. 1: Rectangle 0.3/0.1										
1	LC1	3	0.000	0.00	0.30	0.00	0.00	0.00	0.45	
		1	1.000	0.00	0.60	0.00	0.00	0.00		
	LC2	3	0.000	0.00	0.75	0.00	0.00	0.00	0.75	
		1	1.000	0.00	0.75	0.00	0.00	0.00	0.00	
	LC3	3	0.000	0.00	-0.25	0.00	0.00	0.00	-0.25	
		1	1.000	0.00	-0.25	0.00	0.00	0.00	0.00	
2	CO1	3	0.000	0.01	0.80	0.00	0.00	0.00	0.95	
		1	1.000	0.01	1.10	0.00	0.00	0.00	0.00	
	LC1	4	0.000	0.00	0.00	0.00	0.00	0.00	0.60	
		3	1.000	0.00	0.30	0.00	0.00	0.00	0.45	
	LC2	4	0.000	0.00	-0.25	0.00	0.00	0.00	0.50	
		3	1.000	0.00	-0.25	0.00	0.00	0.00	0.75	
3	LC3	4	0.000	0.00	-0.25	0.00	0.00	0.00	0.50	
		3	1.000	0.00	-0.25	0.00	0.00	0.00	0.75	
	CO1	4	0.000	0.00	-0.50	0.00	0.00	0.00	1.60	
		3	1.000	-0.00	-0.20	0.00	0.00	0.00	1.95	
	LC1	5	0.000	0.00	-0.30	0.00	0.00	0.00	0.45	
		4	1.000	0.00	0.00	0.00	0.00	0.00	0.60	
4	LC2	5	0.000	0.00	-0.25	0.00	0.00	0.00	0.25	
		4	1.000	0.00	-0.25	0.00	0.00	0.00	0.50	
	LC3	5	0.000	0.00	-0.25	0.00	0.00	0.00	0.25	
		4	1.000	0.00	-0.25	0.00	0.00	0.00	0.50	
	CO1	5	0.000	0.01	-0.80	0.00	0.00	0.00	0.95	
		4	1.000	0.00	-0.50	0.00	0.00	0.00	1.60	
5	LC1	2	0.000	0.00	-0.60	0.00	0.00	0.00	0.00	
		5	1.000	0.00	-0.30	0.00	0.00	0.00	0.45	
	LC2	2	0.000	0.00	-0.25	0.00	0.00	0.00	0.00	
		5	1.000	0.00	-0.25	0.00	0.00	0.00	0.25	
	LC3	2	0.000	0.00	-0.25	0.00	0.00	0.00	0.00	
		5	1.000	0.00	-0.25	0.00	0.00	0.00	0.25	
CO1	2	0.000	0.01	-1.10	0.00	0.00	0.00	0.00		
	5	1.000	0.01	-0.80	0.00	0.00	0.00	0.95		

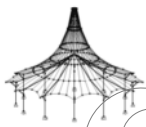
## GLOBAL DEFORMATIONS u<sub>y</sub>, SUPPORT REACTIONS

LC1 : Self-weight  
Loads [kN/m]  
Support Reactions[kN]

In Z-direction

Factor of deformations: 89.00  
Max P-Y': 0.00, Min P-Y': 0.00 kN  
Max u-Y': 4.49, Min u-Y': 0.00 mm

0.492 m

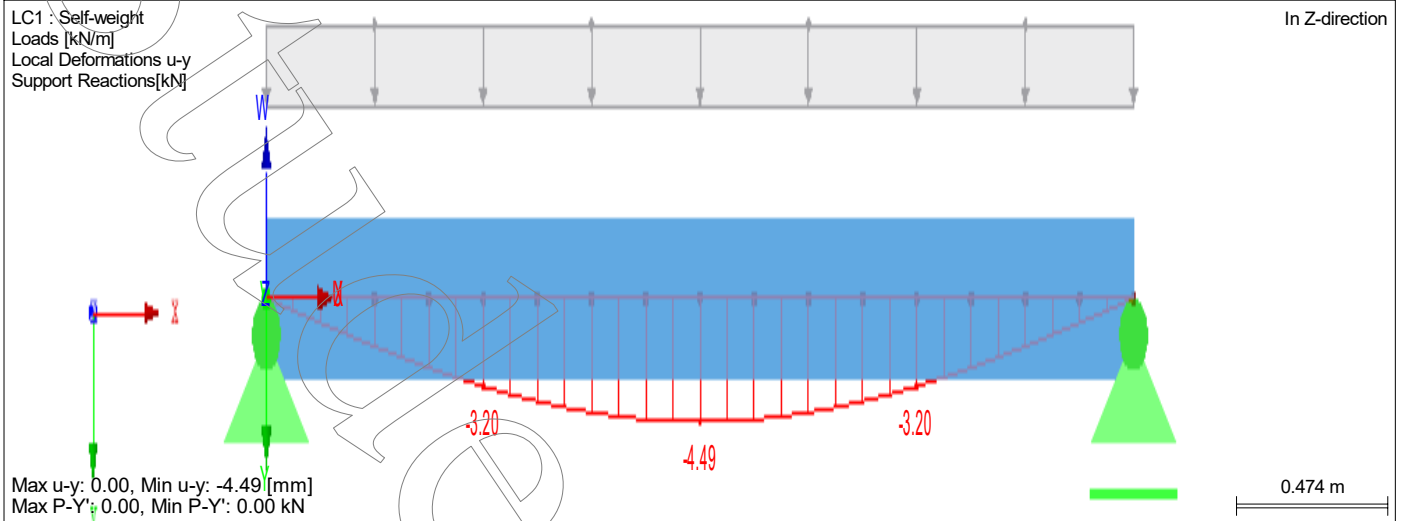


Project: Assignment Week 5

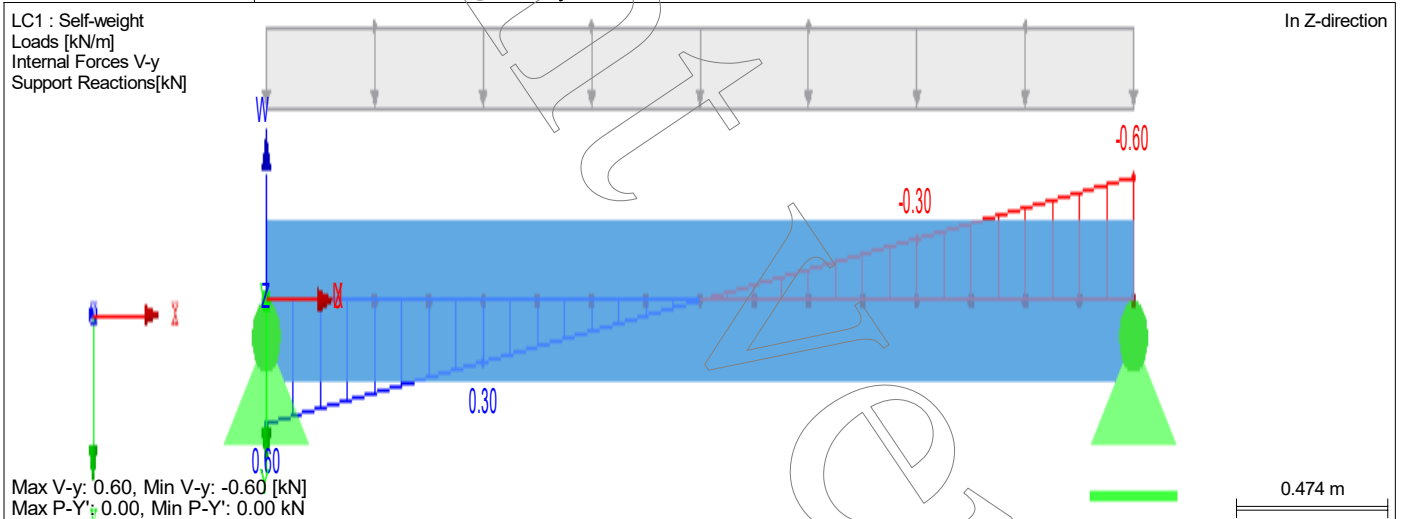
Model: Beam

Date: 13/10/2021

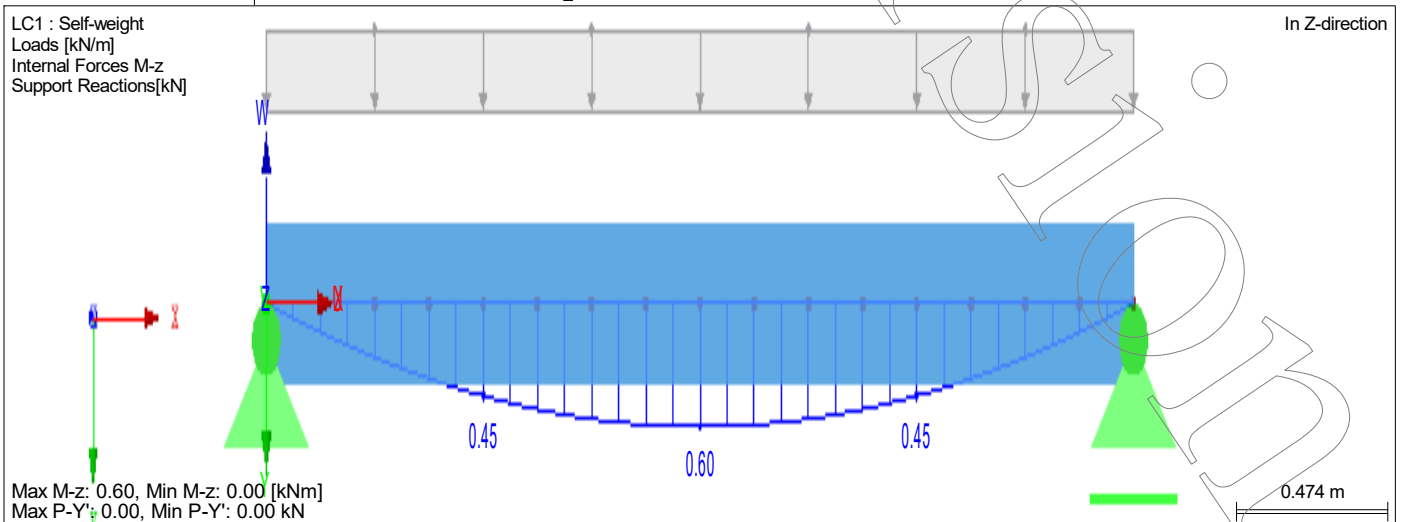
### LOCAL DEFORMATIONS $u_y$ , SUPPORT REACTIONS



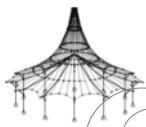
### INTERNAL FORCES $V_y$ , SUPPORT REACTIONS



### INTERNAL FORCES $M_z$ , SUPPORT REACTIONS





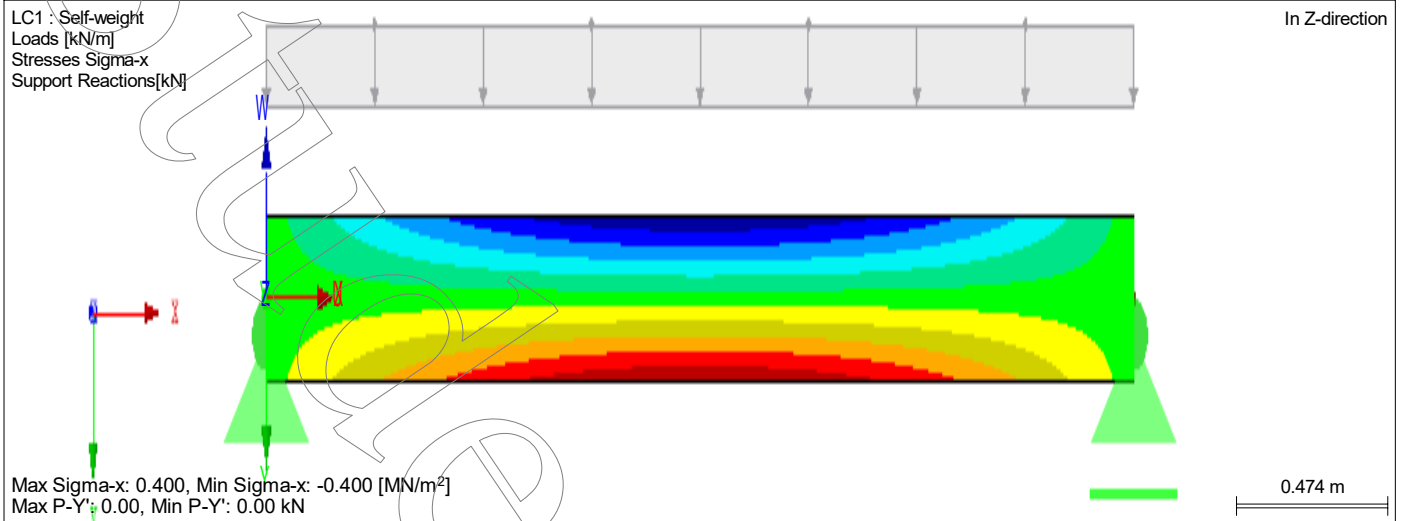


Project: Assignment Week 5

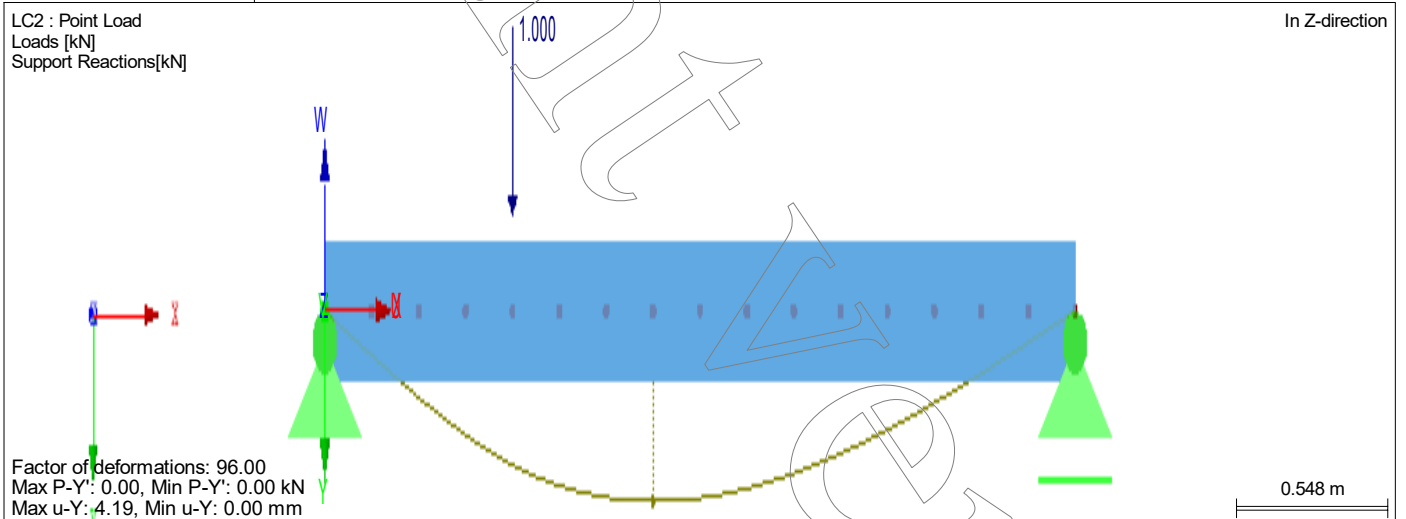
Model: Beam

Date: 13/10/2021

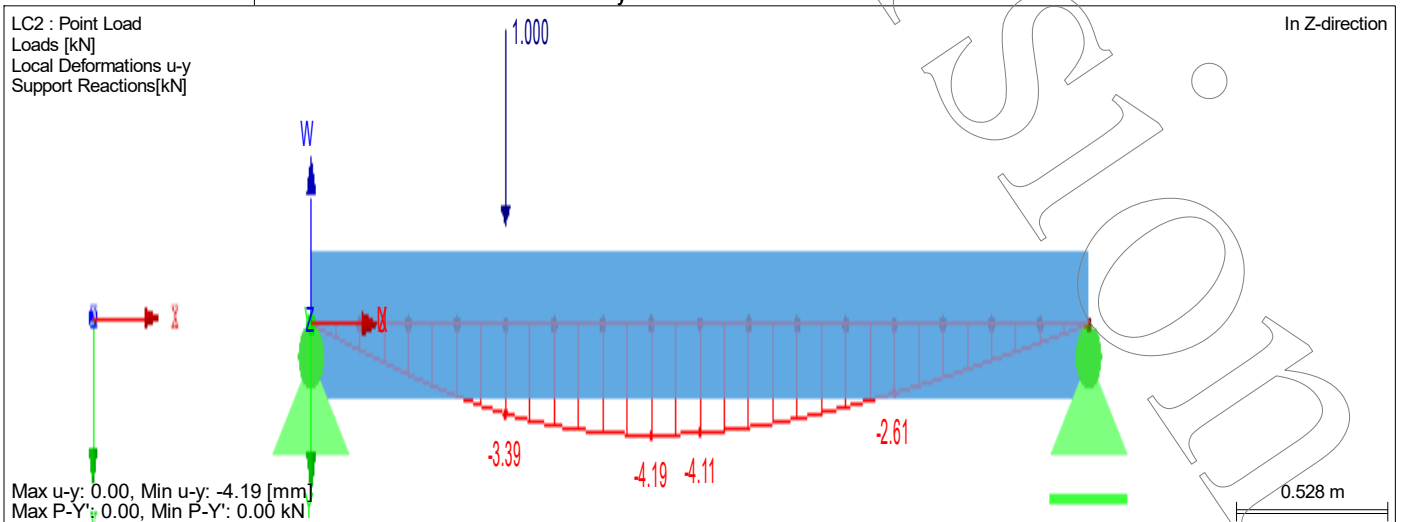
### ■ $\sigma_x$ , SUPPORT REACTIONS

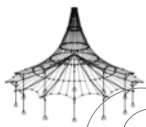


### ■ GLOBAL DEFORMATIONS $u_y$ , SUPPORT REACTIONS



### ■ LOCAL DEFORMATIONS $u_y$ , SUPPORT REACTIONS



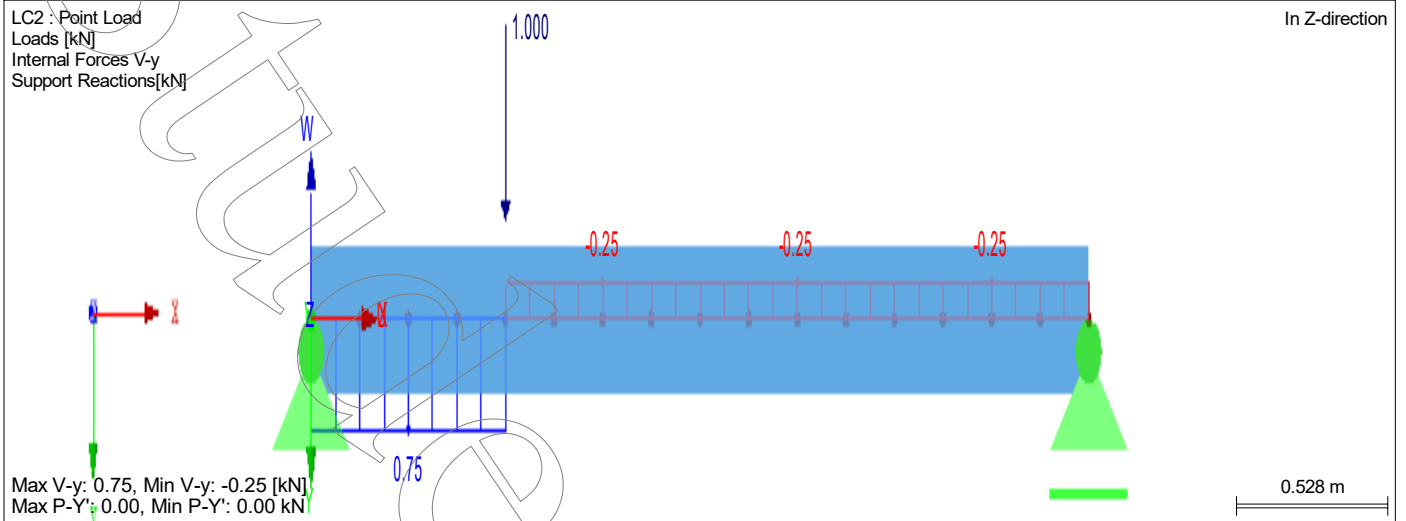


Project: Assignment Week 5

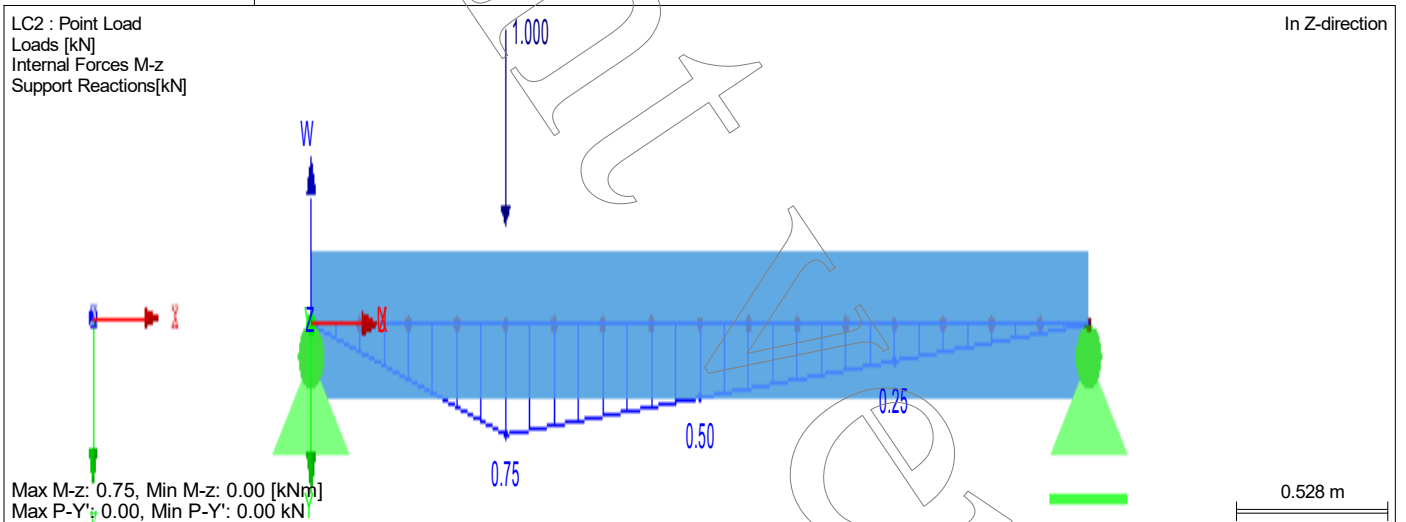
Model: Beam

Date: 13/10/2021

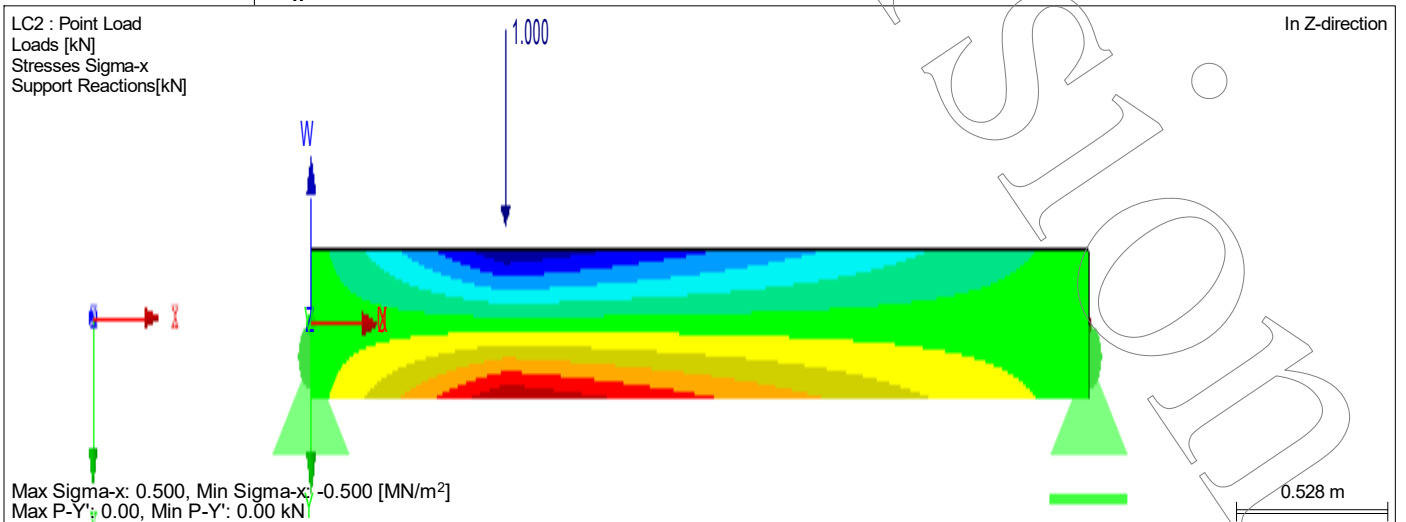
### INTERNAL FORCES $V_y$ , SUPPORT REACTIONS

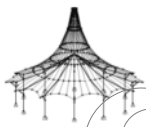


### INTERNAL FORCES $M_z$ , SUPPORT REACTIONS



### $\sigma_x$ , SUPPORT REACTIONS



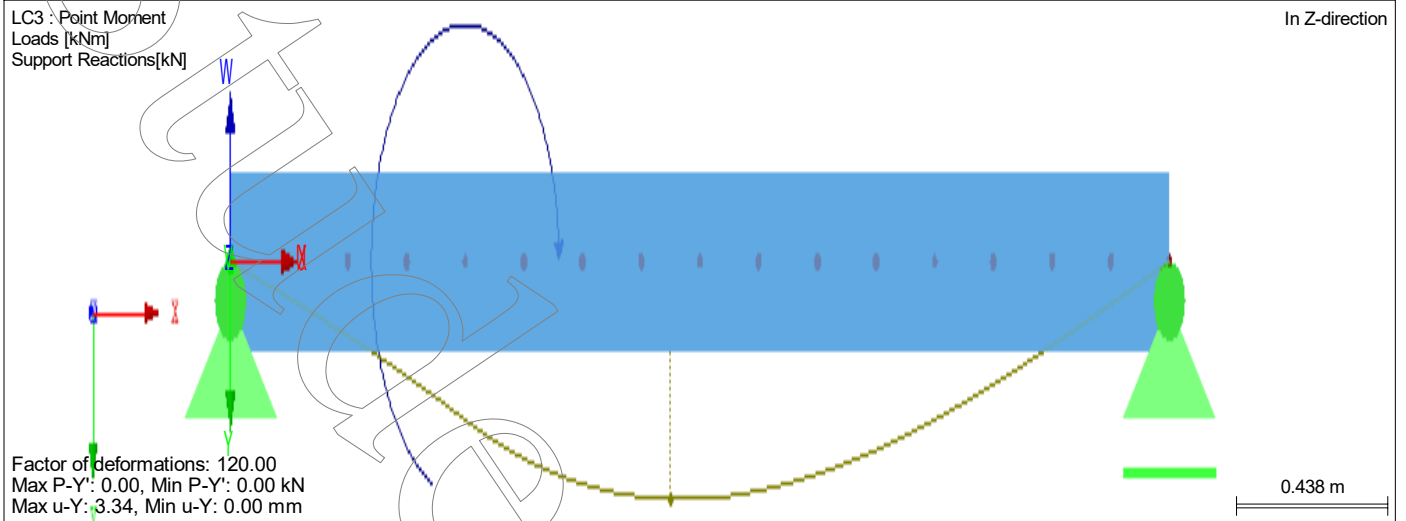


Project: Assignment Week 5

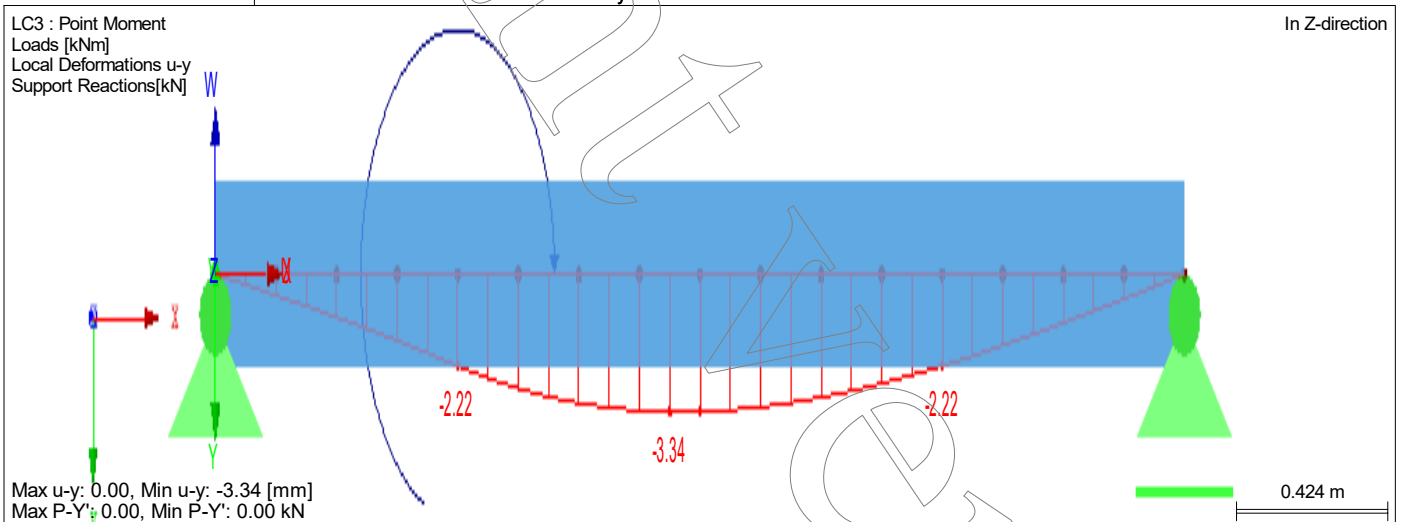
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Date: 13/10/2021

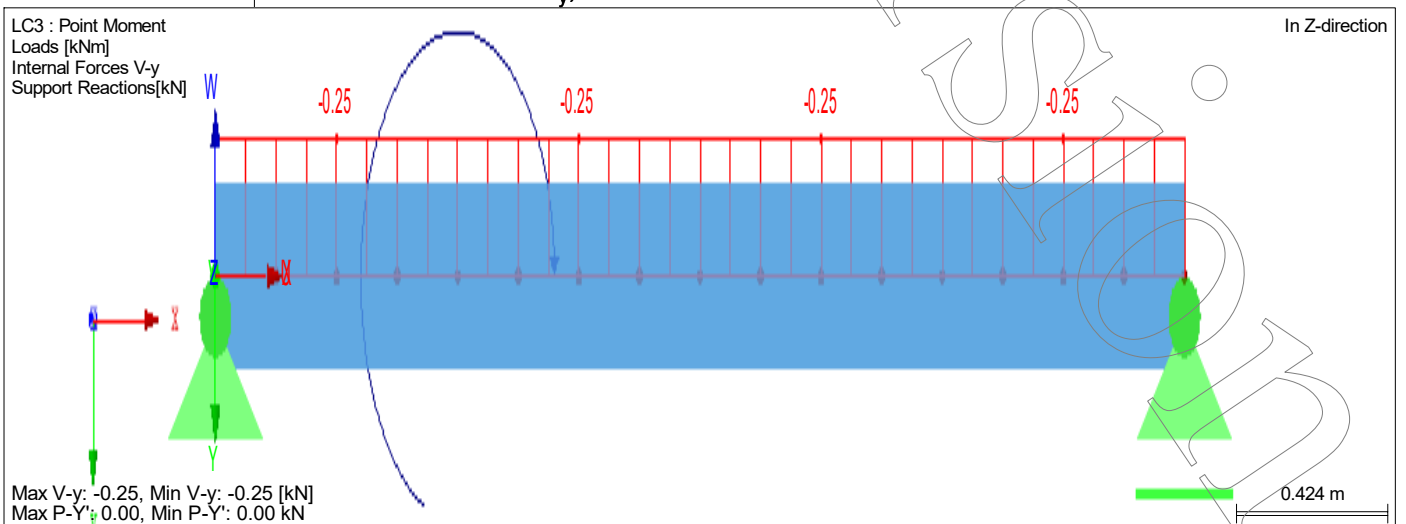
### GLOBAL DEFORMATIONS $u_y$ , SUPPORT REACTIONS



### LOCAL DEFORMATIONS $u_y$ , SUPPORT REACTIONS



### INTERNAL FORCES $V_y$ , SUPPORT REACTIONS

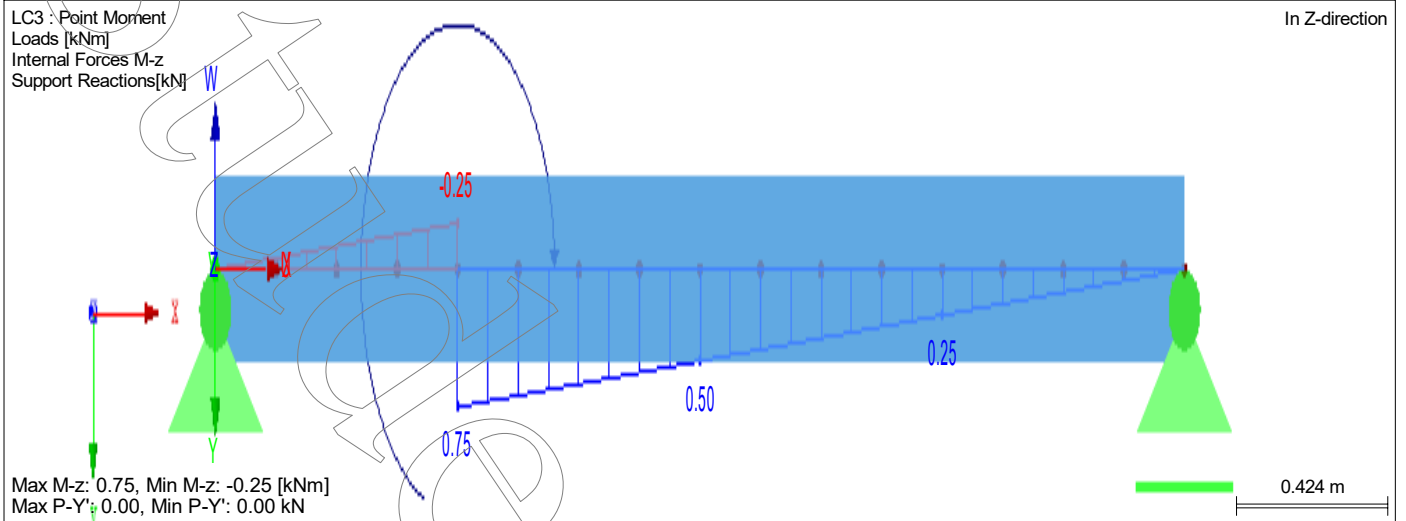


Project: Assignment Week 5

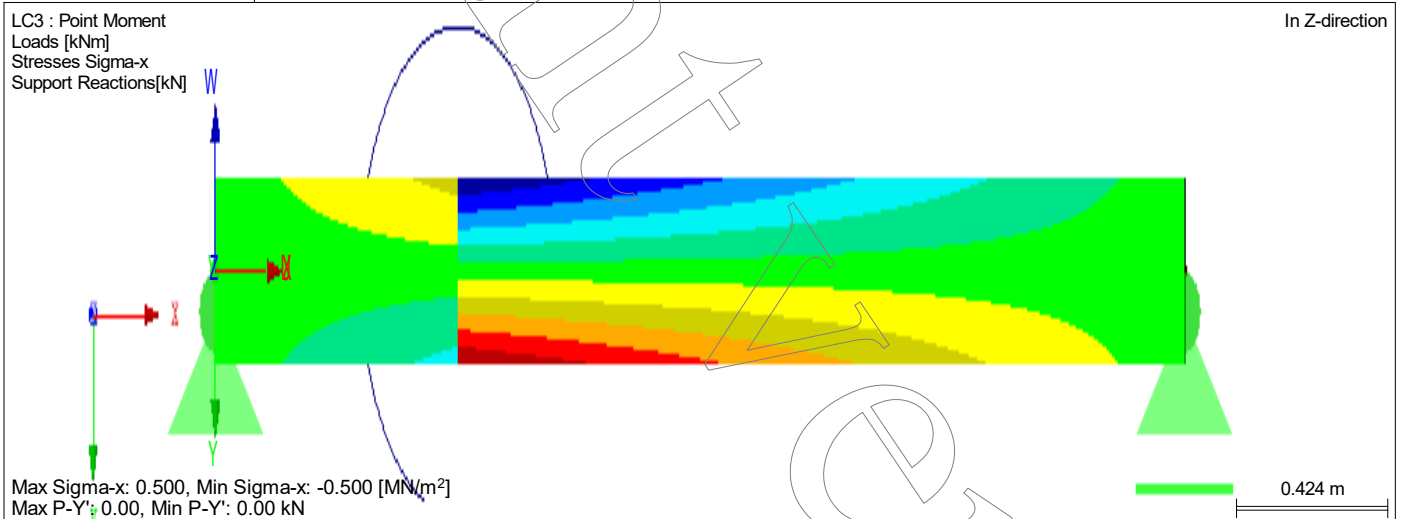
Model: Beam

Date: 13/10/2021

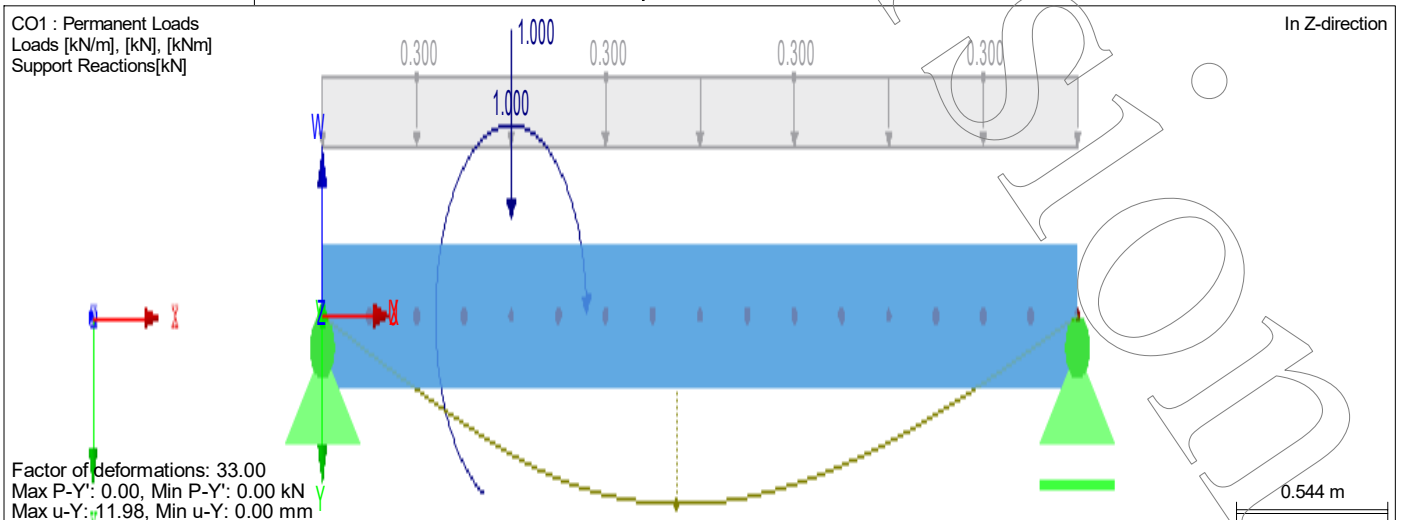
### INTERNAL FORCES $M_z$ , SUPPORT REACTIONS

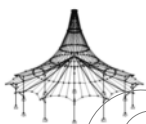


### $\sigma_x$ , SUPPORT REACTIONS



### GLOBAL DEFORMATIONS $u_y$ , SUPPORT REACTIONS





Project: Assignment Week 5

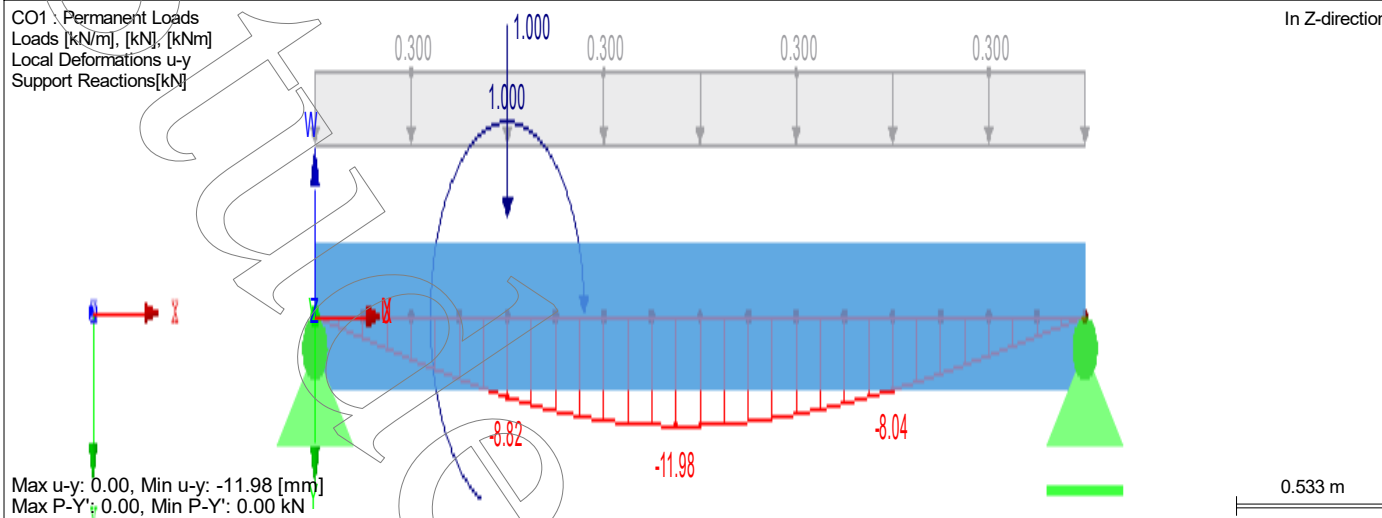
Model: Beam

Date: 13/10/2021

### LOCAL DEFORMATIONS $u_y$ , SUPPORT REACTIONS

CO1 : Permanent Loads  
Loads [kN/m], [kN], [kNm]  
Local Deformations  $u_y$   
Support Reactions[kN]

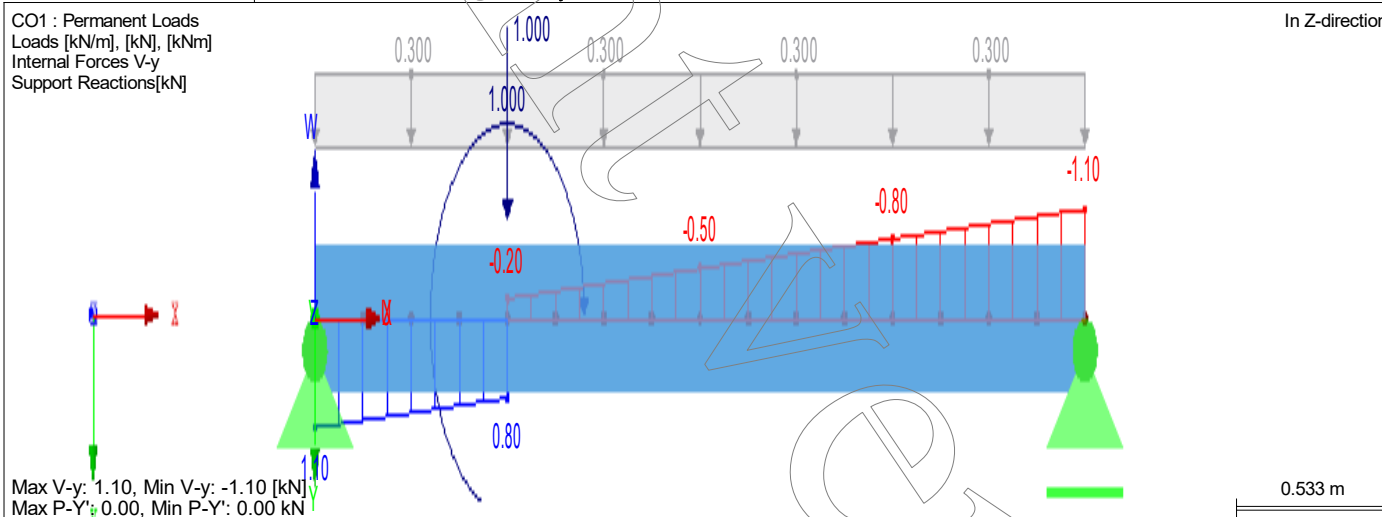
In Z-direction



### INTERNAL FORCES $V_y$ , SUPPORT REACTIONS

CO1 : Permanent Loads  
Loads [kN/m], [kN], [kNm]  
Internal Forces  $V_y$   
Support Reactions[kN]

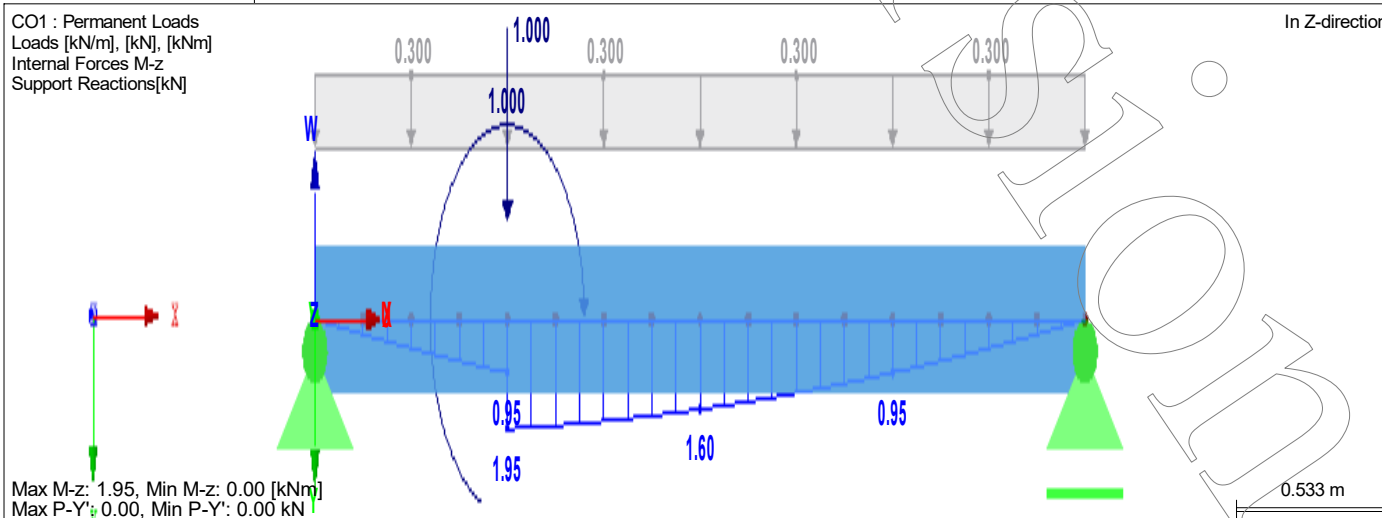
In Z-direction

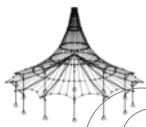


### INTERNAL FORCES $M_z$ , SUPPORT REACTIONS

CO1 : Permanent Loads  
Loads [kN/m], [kN], [kNm]  
Internal Forces  $M_z$   
Support Reactions[kN]

In Z-direction





Project: Assignment Week 5

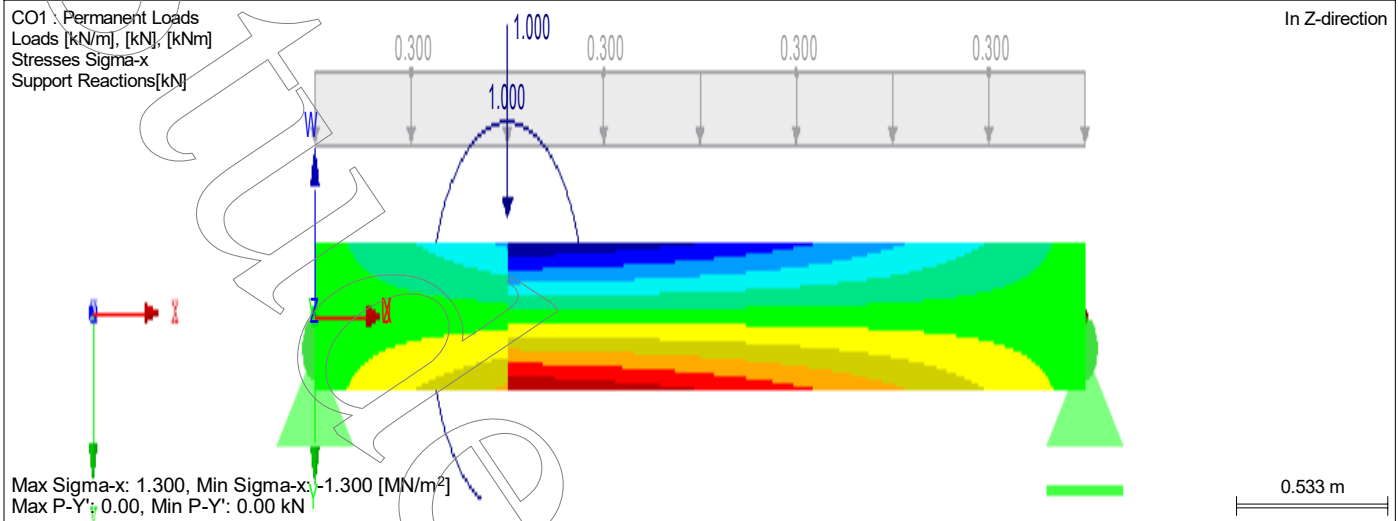
Model: Beam

Date: 13/10/2021

## ■ $\sigma_x$ , SUPPORT REACTIONS

CO1 : Permanent Loads  
Loads [kN/m], [kN], [kNm]  
Stresses  $\sigma_x$   
Support Reactions[kN]

In Z-direction



## ■ NOTES OF BENDING MOMENTS

Bending moment graphs have opposite signs than in Finnish practice