

# 9.1 Intro to Dynamical Simulation



# In This Video

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- A tour of physically-inspired animation techniques

# Types of Animation

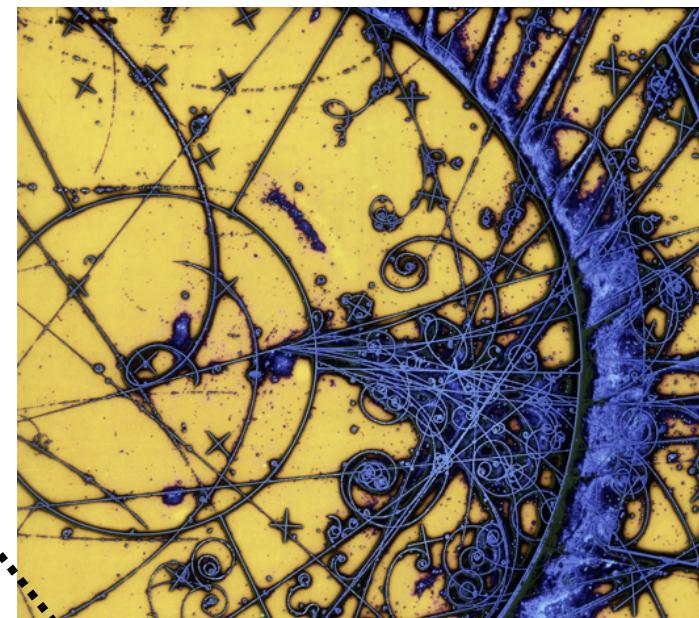
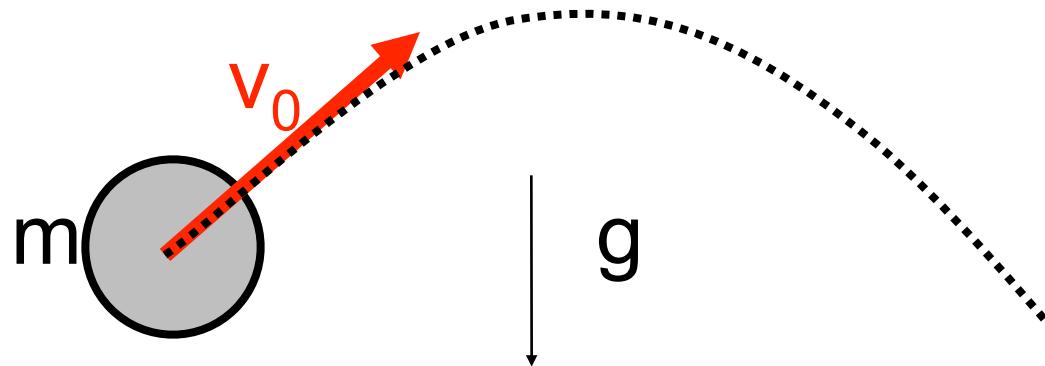
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- Keyframing
- Procedural
- **Physically-based**
  - Particle Systems
    - Smoke, water, fire, sparks, etc.
    - Usually heuristic as opposed to simulation, but not always
    - Mass-Spring Models (Cloth)
  - *Continuum Mechanics (fluids, etc.), finite elements*
    - *Not in this class*
  - *Rigid body simulation*
    - *Not in this class*

# Types of Animation: Physically-Based

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- Assign physical properties to objects
  - Masses, forces, etc.
- Also procedural forces (like wind)
- Simulate physics by solving equations of motion
  - Rigid bodies, fluids, plastic deformation, etc.
- Realistic but difficult to control



# Control (Buster Keaton)

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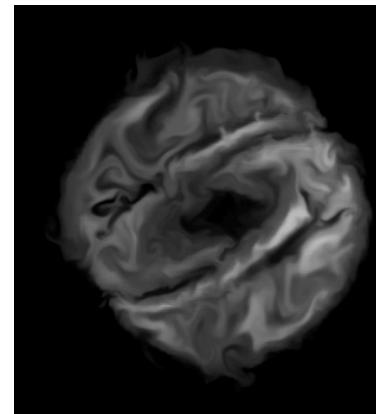


Steamboat Bill, Jr. (1928)

# “Directable Simulation”

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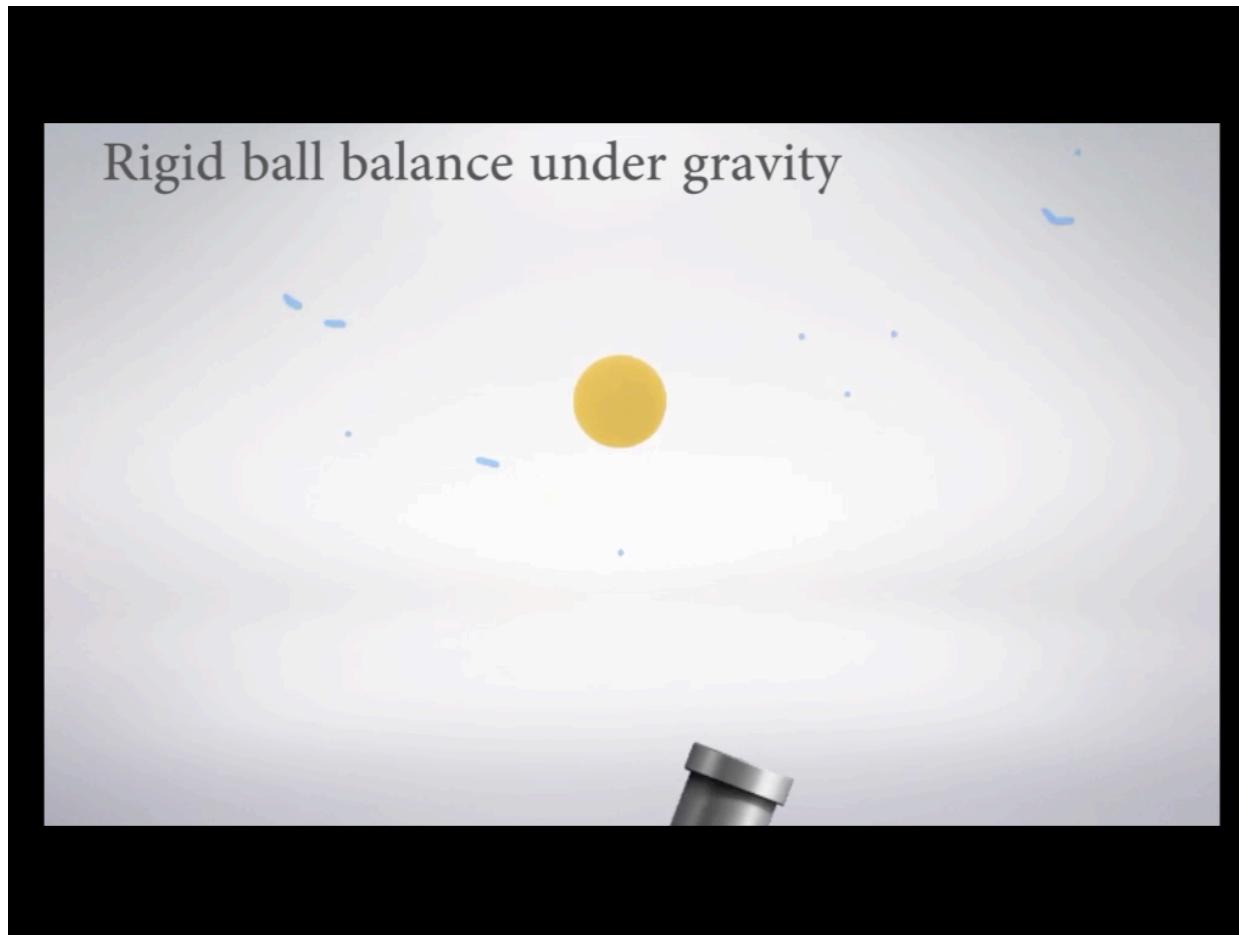
- Aim to produce simulations that obey user-specified constraints
  - Add as-small-as-possible fictitious forces to simulation to nudge it towards artist/TD needs
- Lots of cool stuff!
- See e.g. <http://www.cs.huji.ac.il/labs/cglab/projects/tdsmoke/>



# Modern: Let the AI Drive

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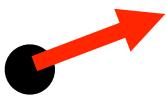
- Ma et al., SIGGRAHP 2018, Fluid directed rigid body control using deep reinforcement learning



# Types of dynamics

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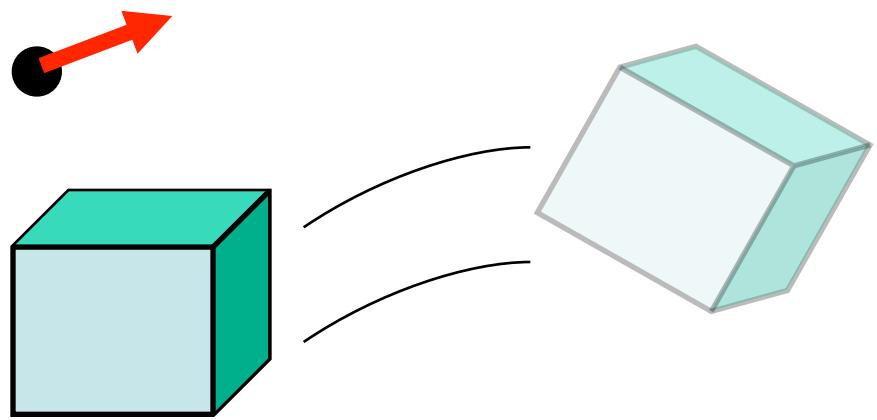
- Point



# Types of dynamics

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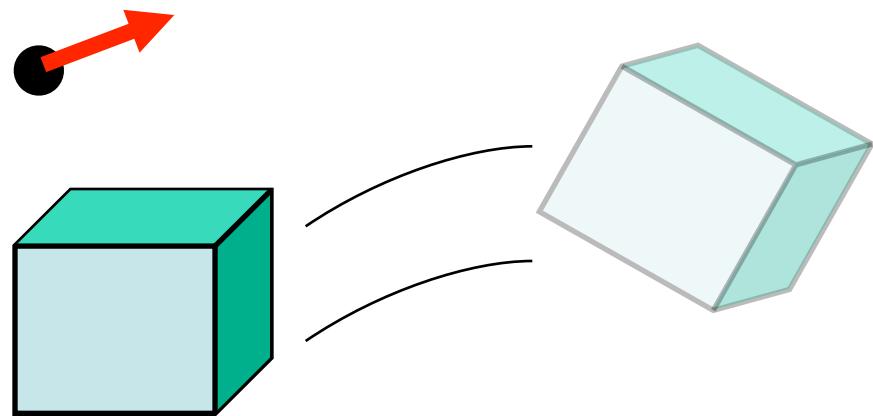
- Point
- Rigid body



# Types of dynamics

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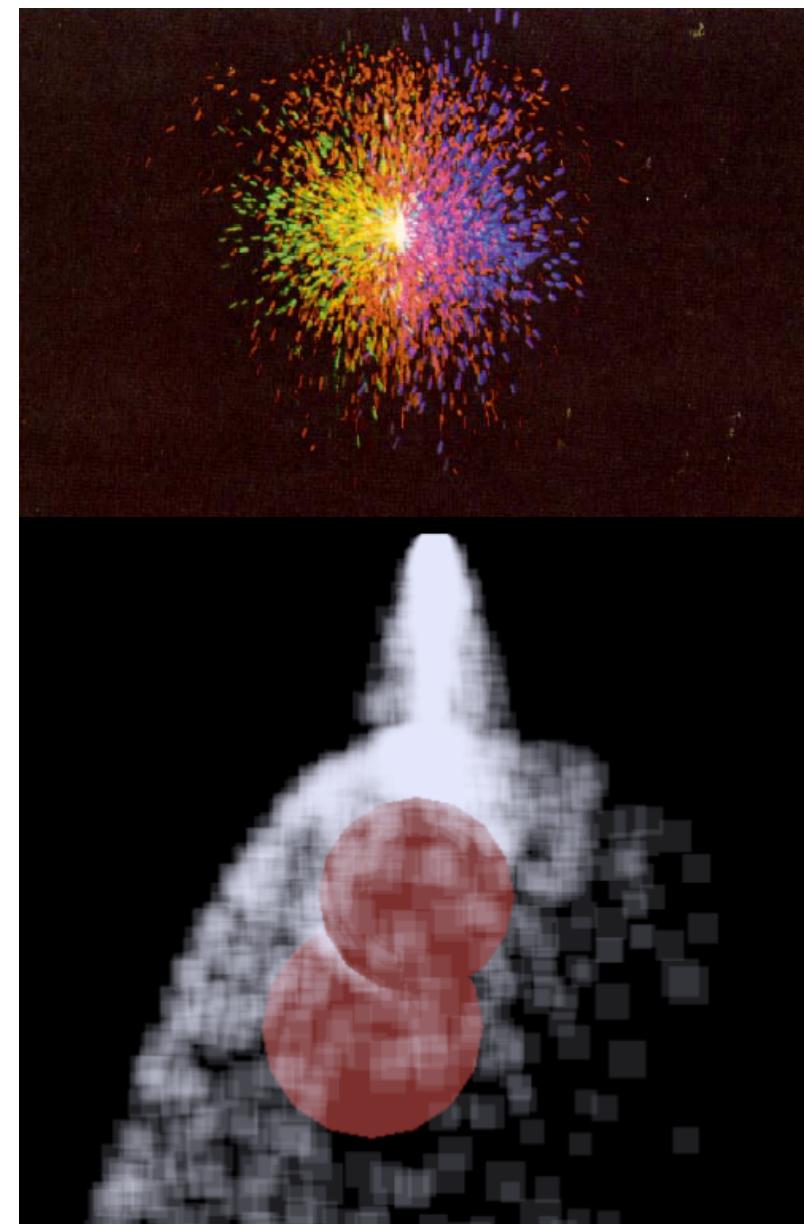
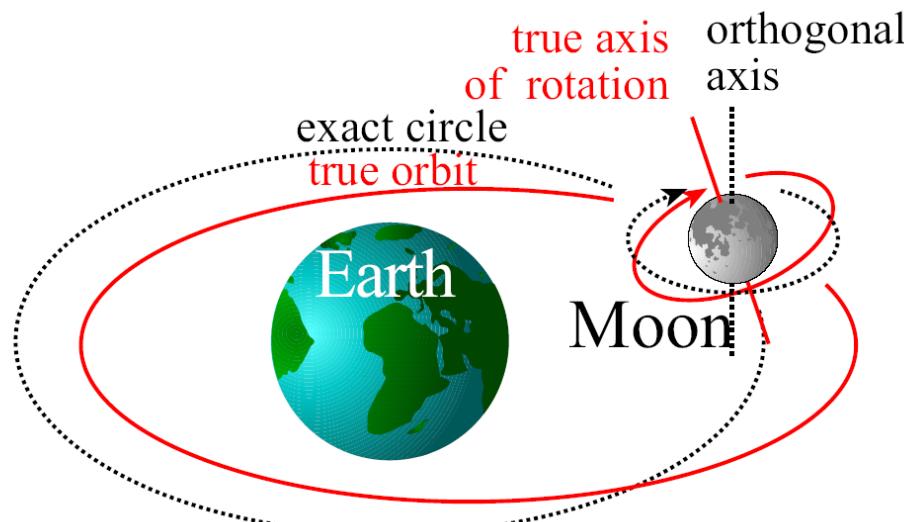
- Point
- Rigid body
- Deformable body  
(include clothes, fluids, smoke, etc.)



# We Focus on Point Dynamics

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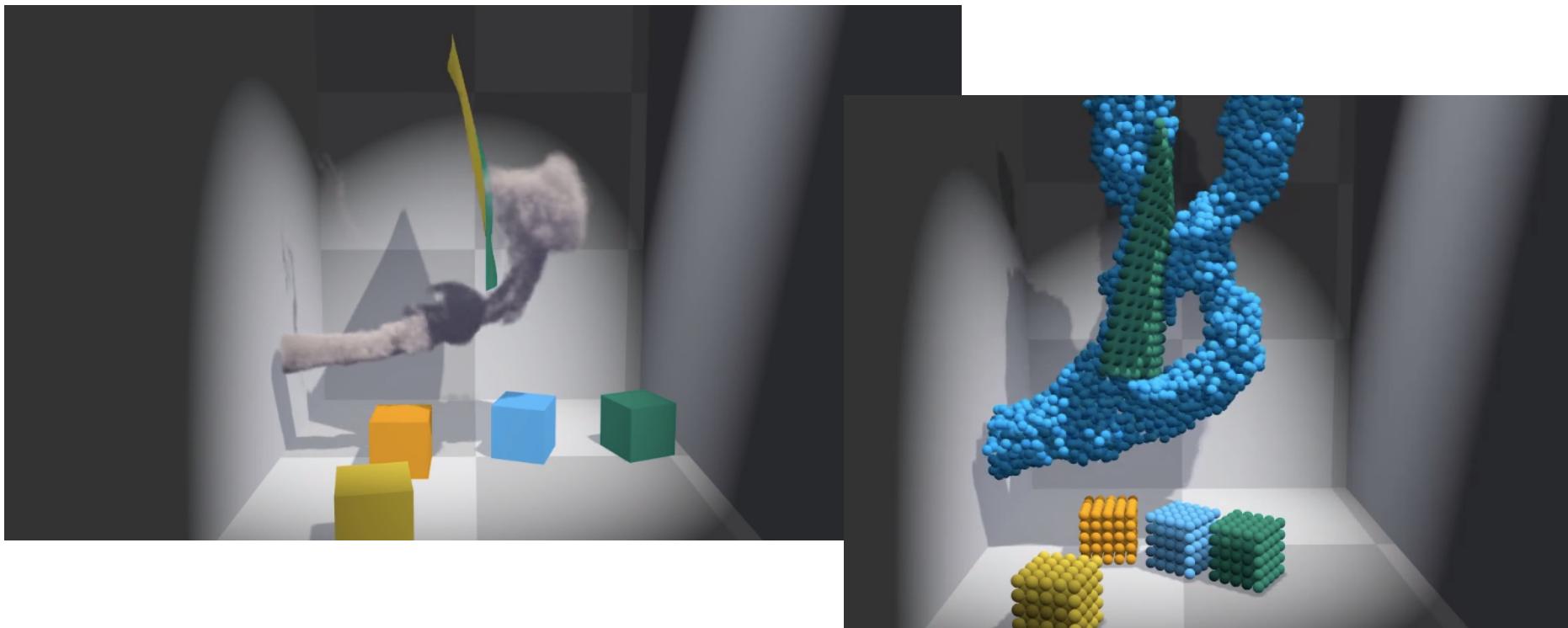
- Lots of points!
- “Particle systems”
  - Borderline between procedural and physically-based

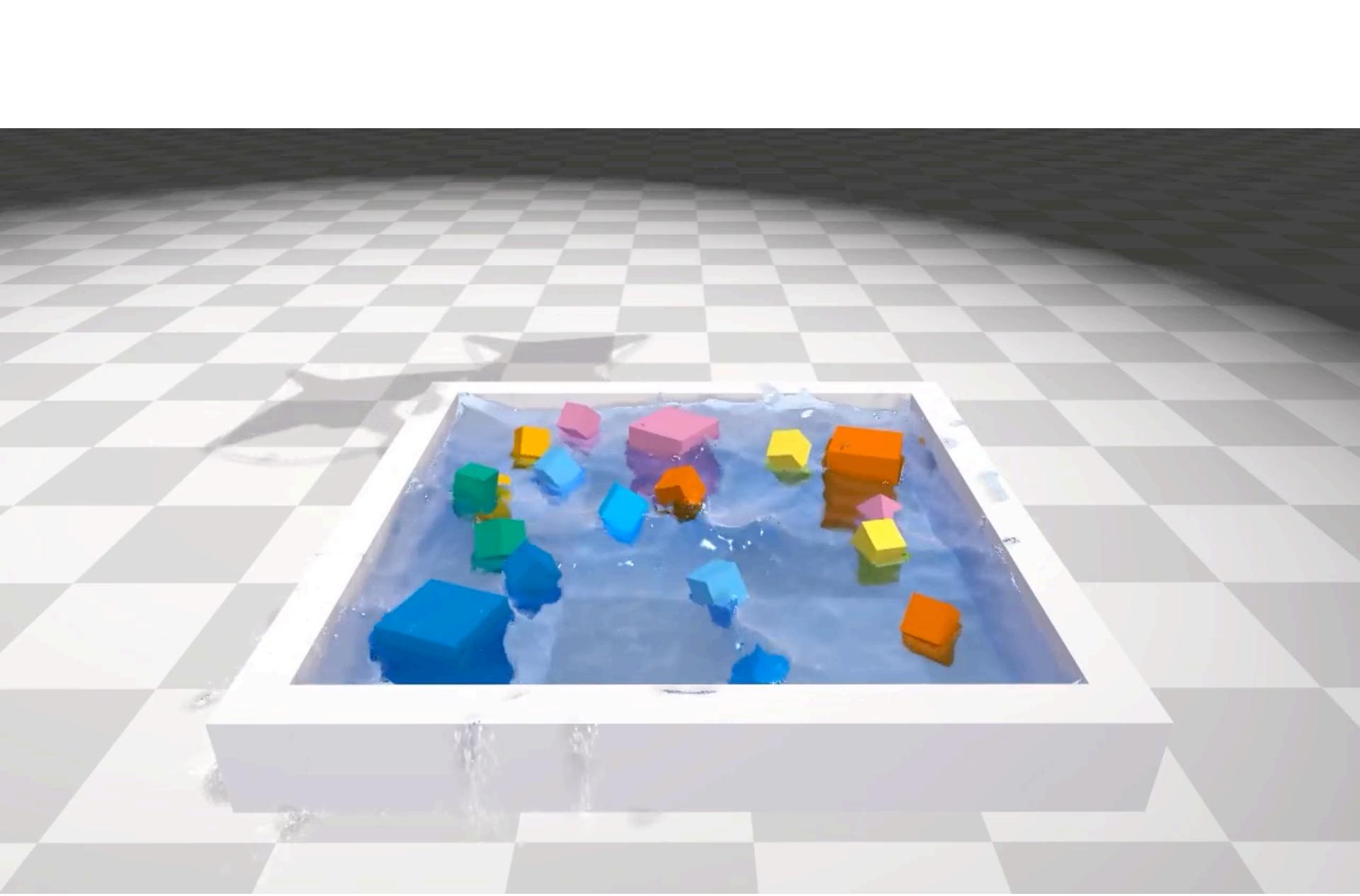


# Can Model Everything using Particles!

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- Unified Particle Physics for Real-Time Applications  
(Chantanez et al. SIGGRAPH 2014)
  - video





# Real-Time Particles Demo (3DMark03)

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Futuremark Corp., used with permission

3DMARK®



# Generalizations (later)

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- Mass-spring and deformable surface dynamics
  - surface represented as a set of points
  - forces between neighbors keep the surface coherent

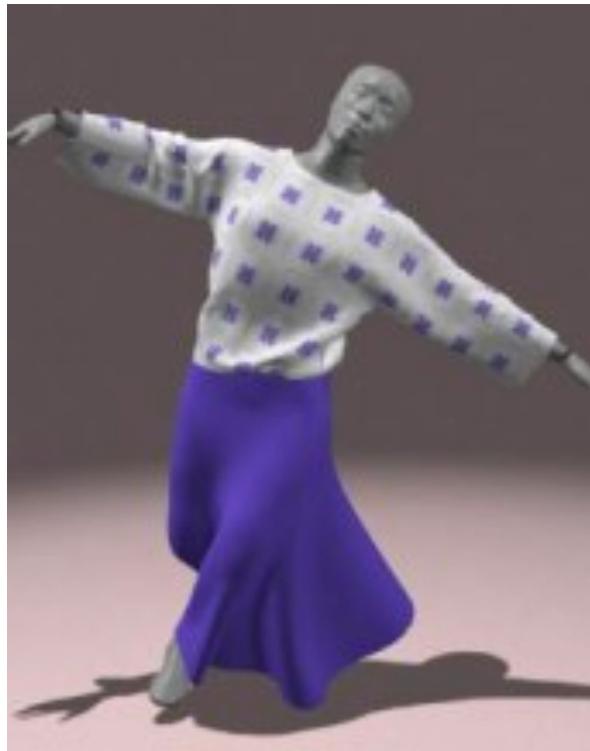


Image Witkin & Baraff

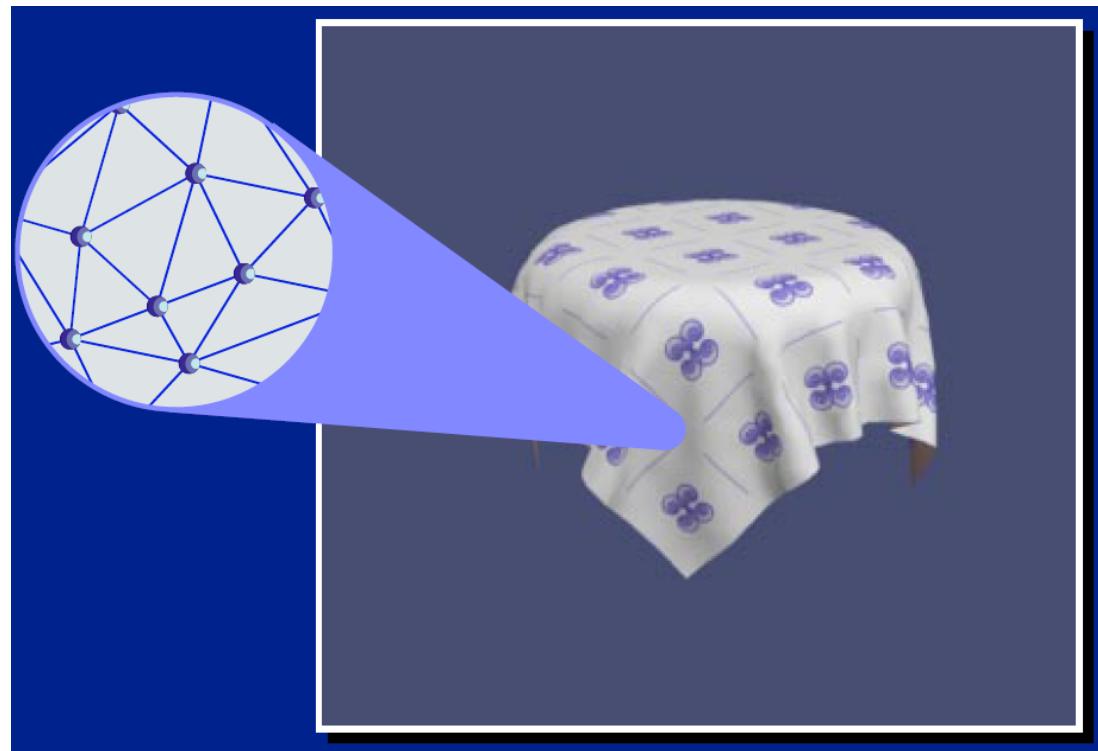


Image Michael Kass 16

# Take-Home Message

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- Particle-based methods can range from pure heuristics (hacks that happen to look good) to “real” simulation
- Basics are the same:  
**Things always boil down to integrating ODEs!**
  - Also in the case of grids/computational meshes

Andrew Selle et al.



# Further reading

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# Cloth Video

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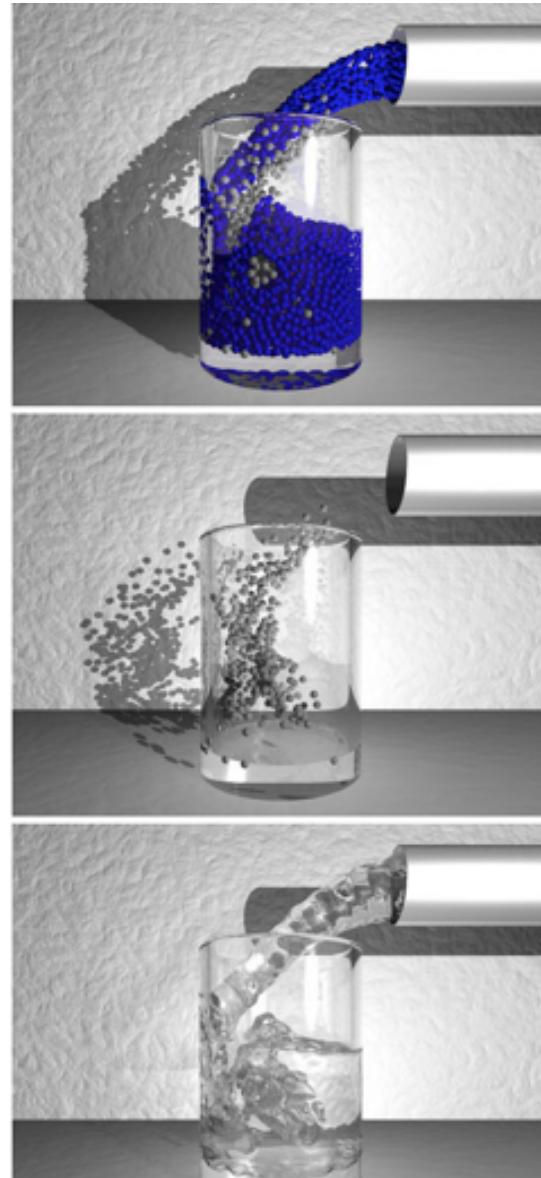


Selle, A., Su, J., Irving, G. and Fedkiw, R., "Robust High-Resolution Cloth Using Parallelism, History-Based Collisions, and Accurate Friction," IEEE TVCG 15, 339-350 (2009).

# Generalizations

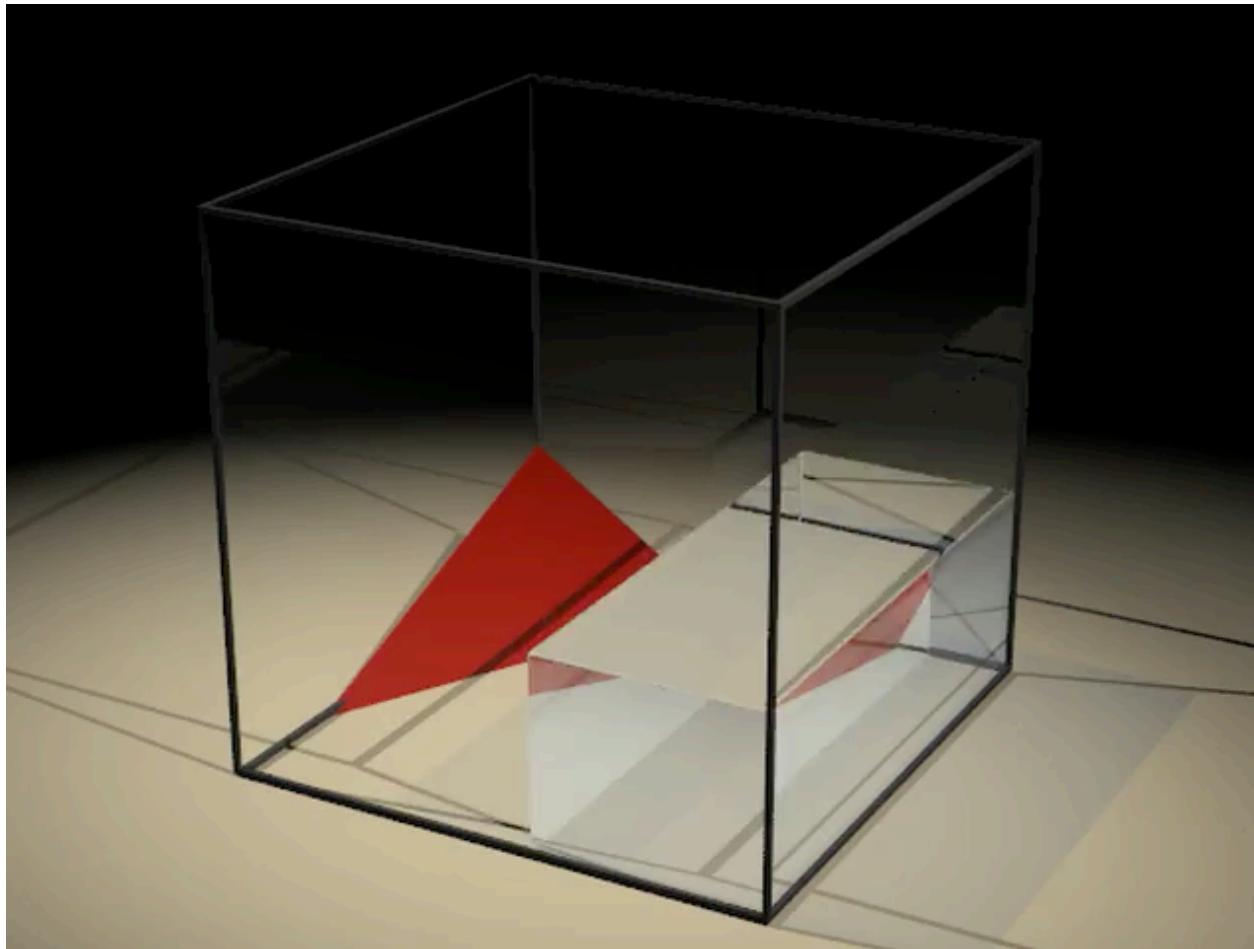
Müller et al. 2005

- It's not all hacks:  
Smoothed Particle Hydrodynamics  
(SPH)
  - A family of “real” particle-based fluid simulation techniques.
  - Fluid flow is described by the Navier-Stokes Equations, a nonlinear partial differential equation (PDE)
    - SPH discretizes the fluid as small packets (particles!), and evaluates pressures and forces based on them.



# SPH Example

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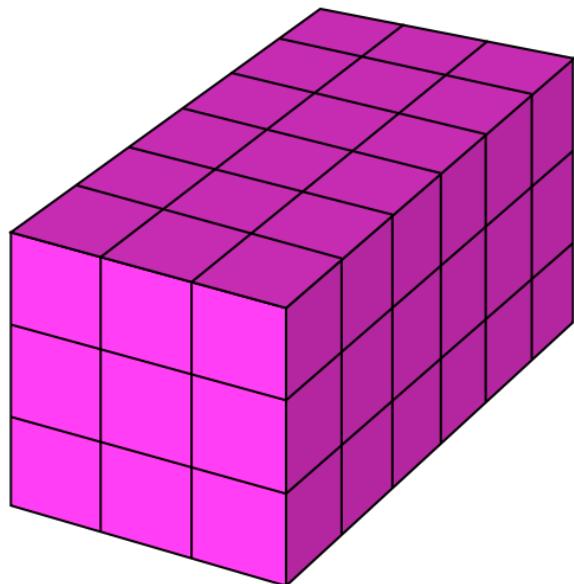


Predictive-Corrective Incompressible SPH. Barbara Solenthaler,  
Renato Pajarola. ACM Transactions on Graphics (SIGGRAPH), 2009

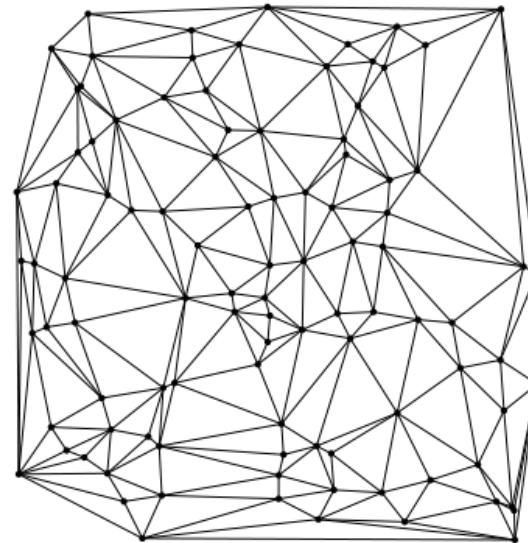
# Meshless Techniques

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- Most simulation techniques work on either regular grids or meshes constructed from triangles/tets
- PDEs defined on space are discretized on the grid.



Regular 3D grid

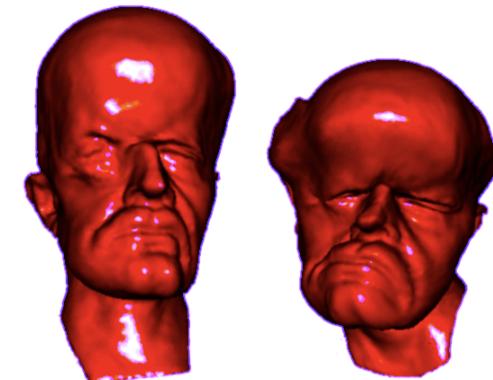


Irregular 2D grid

# Meshless Techniques

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- Most simulation techniques work on either regular grids or meshes constructed from triangles/tets
- In contrast, so-called *meshless methods* do not require the underlying space to be discretized
  - Instead, represent things using points (particles!)
  - They can still be “well-founded”: SPH is an example.
  - Another example: Point-Based Animation of Elastic, Plastic and Melting Objects (Müller, Keiser, Nealen, Pauly, Gross, Alexa, SCA 2004)



Müller et al.

# That's all!

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- Next time: particle systems