

# 8.2 The Bind Pose & Limitations

Gears of War 2



IGN.COM

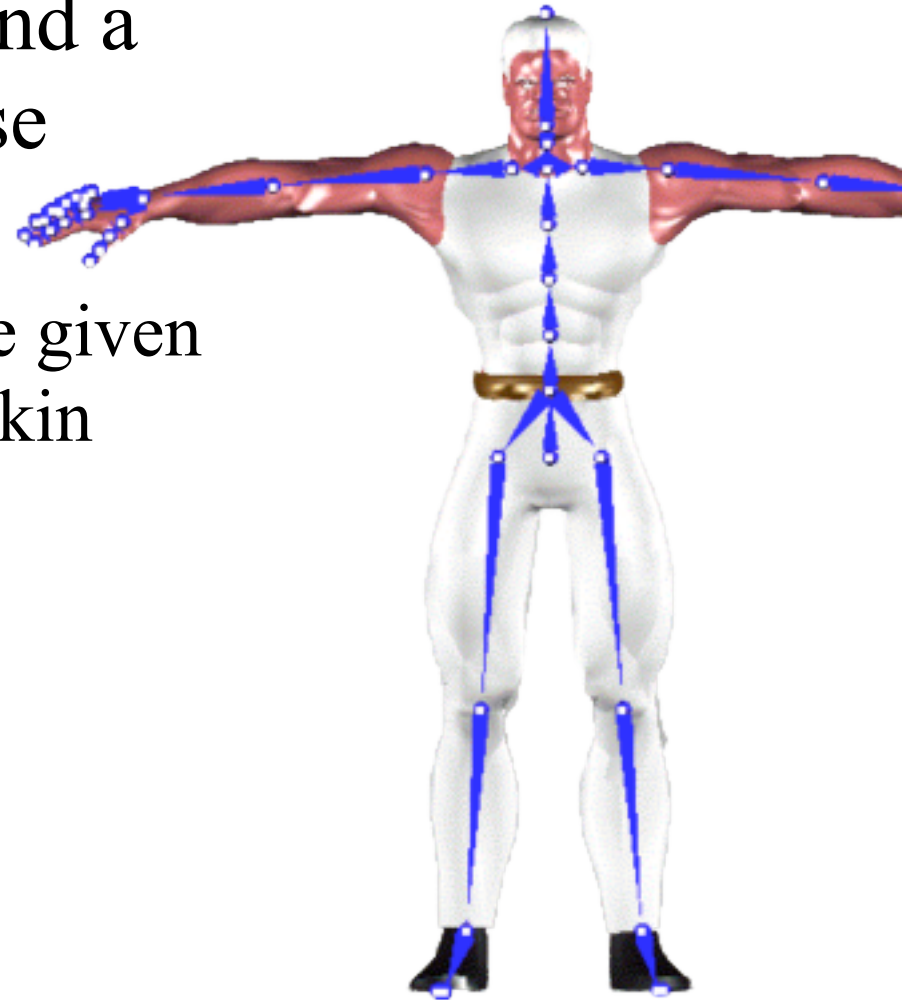
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# In This Video

- The Bind Pose: matching the skeleton to the skin
- Skinning limitations and workarounds

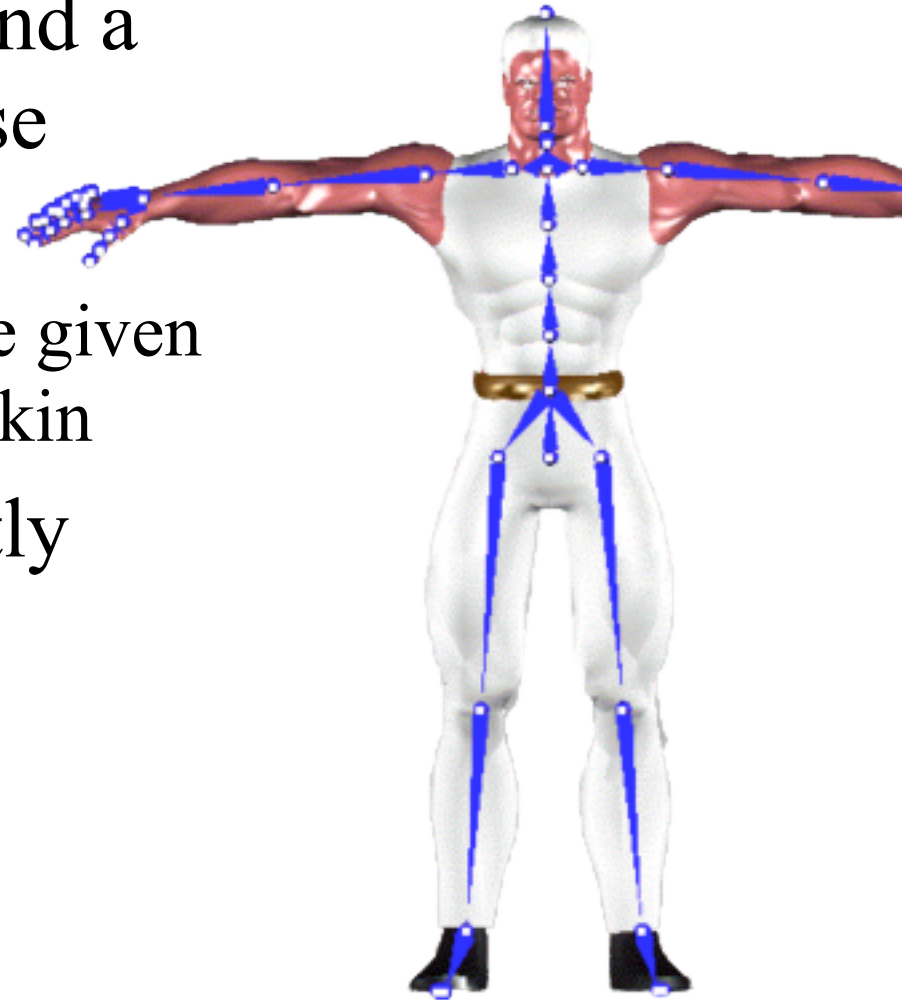
# Bind Pose

- We are given a skeleton and a skin mesh in a default pose
  - Called “bind pose”
  - Undeformed vertices  $\mathbf{p}_i$  are given in the object space of the skin



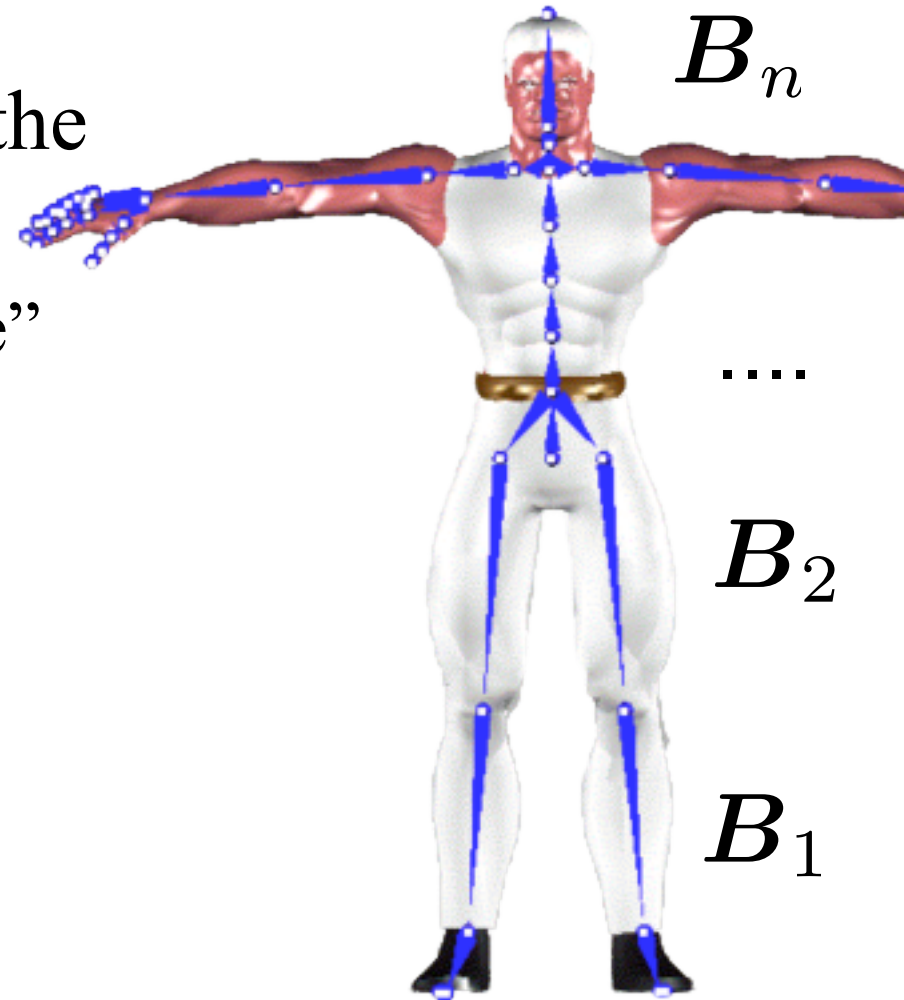
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  - Called “bind pose”
  - Undeformed vertices  $\mathbf{p}_i$  are given in the object space of the skin
- Previously we conveniently forgot that in order for  $\mathbf{p}'_{ij} = \mathbf{T}_j \mathbf{p}_i$  to make sense, coordinate systems must match up.



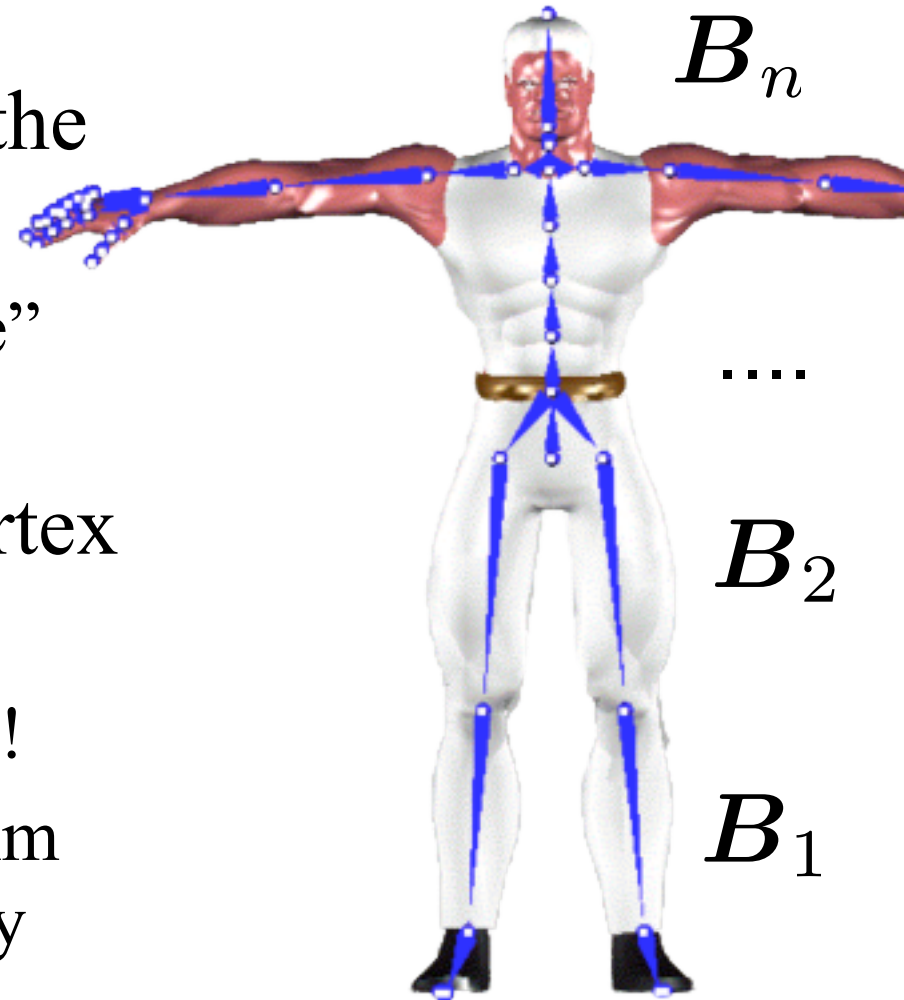
# Bind Pose cont'd

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  - This gives some “rest pose” bone transformations  $\mathbf{B}_j$



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  - This gives some “rest pose” bone transformations  $\mathbf{B}_j$
- We then figure out the vertex weights  $w_{ij}$ .
  - How? Often paint by hand!
  - Pinocchio was the algorithm that does this automatically





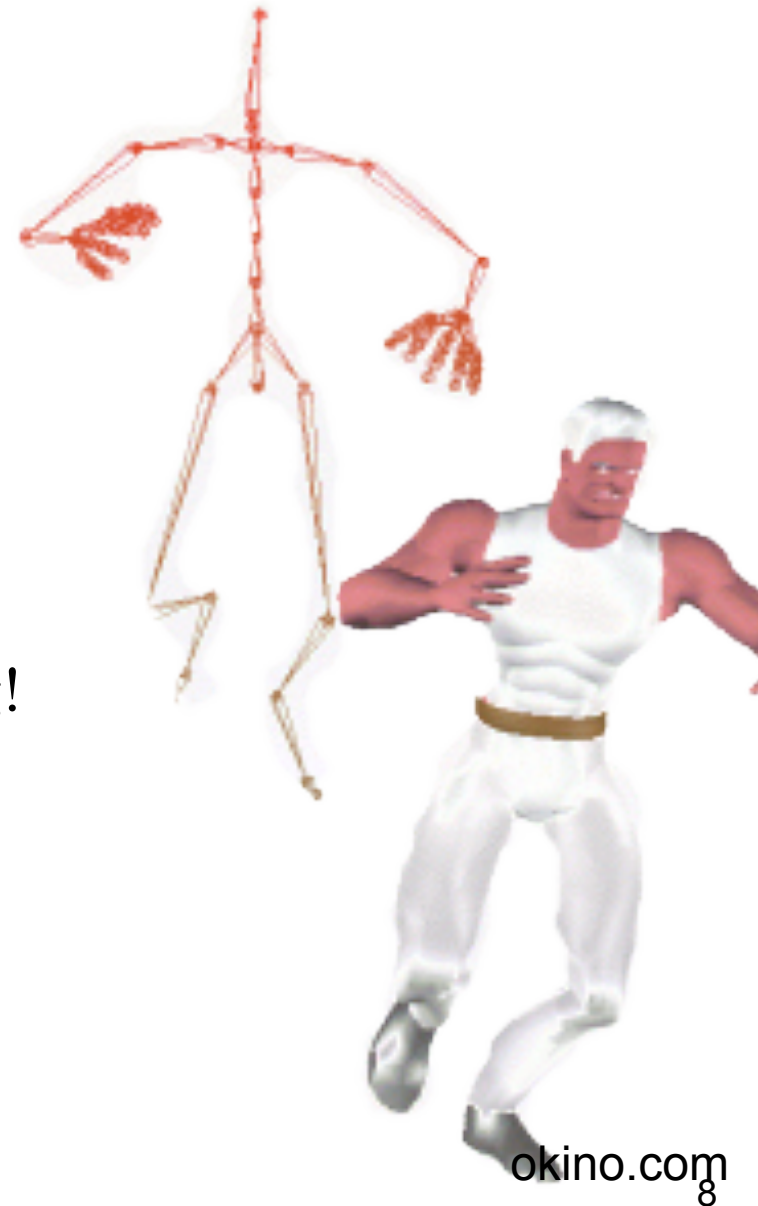
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  - What is  $T_j$ ? It maps from the local coordinate system of bone  $j$  to object space.
    - Remember hierarchical modeling!





# Bind Pose cont'd

- When we animate the model, the bone transformations  $\mathbf{T}_j$  change.
  - What is  $\mathbf{T}_j$ ? It maps from the local coordinate system of bone  $j$  to object space.
- To be able to deform  $\mathbf{p}_i$  according to  $\mathbf{T}_j$ , we must first express  $\mathbf{p}_i$  in the local coordinate system of bone  $j$ .
  - This is where the bind pose bone transformations  $\mathbf{B}_j$  come in.

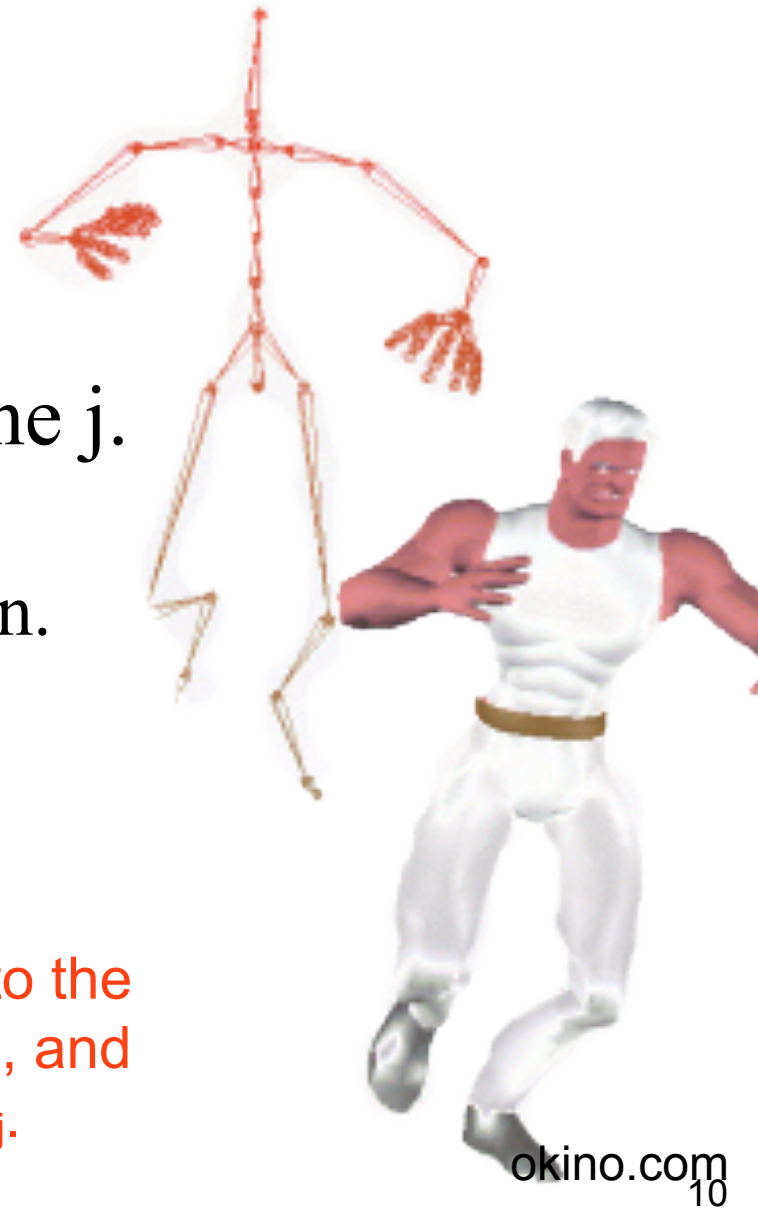


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$$\mathbf{p}'_{ij} = \mathbf{T}_j \mathbf{B}_j^{-1} \mathbf{p}_i$$

This maps  $\mathbf{p}_i$  from bind pose object space to the local coordinate system of bone  $j$  using  $\mathbf{B}_j^{-1}$ , and then to deformed object space using  $\mathbf{T}_j$ .



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What is  $\mathbf{T}_j \mathbf{B}_j^{-1}$ ? It is the relative change between the bone transformations between the current and the bind pose.

# Bind Pose cont'd

What is the transformation when the model is still in bind pose?

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The identity!

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# Skinning Pseudocode

- Do the usual forward kinematics
  - maybe quaternion interpolation for rotations
  - get a matrix  $\mathbf{T}_j(t)$  per bone
- For each skin vertex  $\mathbf{p}_i$

$$\mathbf{p}'_i = \sum_j w_{ij} \mathbf{T}_j(t) \mathbf{B}_j^{-1} \mathbf{p}_i$$



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**Remember from Lecture 2:  
Normals must be treated differently!**

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$$\mathbf{p}'_i = \sum_j w_{ij} \mathbf{T}_j(t) \mathbf{B}_j^{-1} \mathbf{p}_i$$

- Inverse transpose for normals!

$$\mathbf{n}'_i = \left( \sum_j w_{ij} \mathbf{T}_j(t) \mathbf{B}_j^{-1} \right)^{-T} \mathbf{n}_i$$

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- Note that the weights are constant over time
  - Only a small number of matrices change
  - This enables implementation on GPU “vertex shaders” (little information to update for each frame)

# Hmmh...

- This is what we do to get deformed positions

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- This is *exactly* what I warned you of earlier:  
blending matrices entry-by-entry (!!!)



# Indeed... Limitations

- Rotations really need to be combined differently (quaternions!)

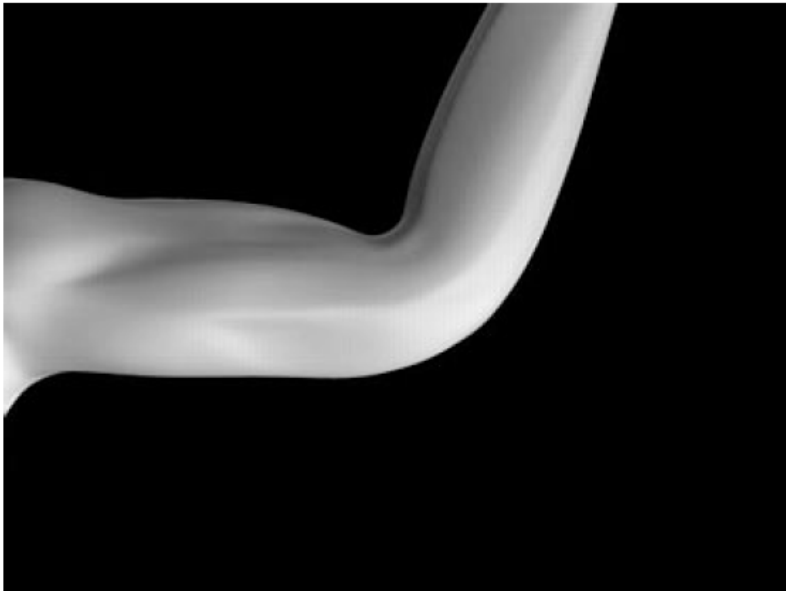


Figure 2: The 'collapsing elbow' in action, c.f. Figure 1.

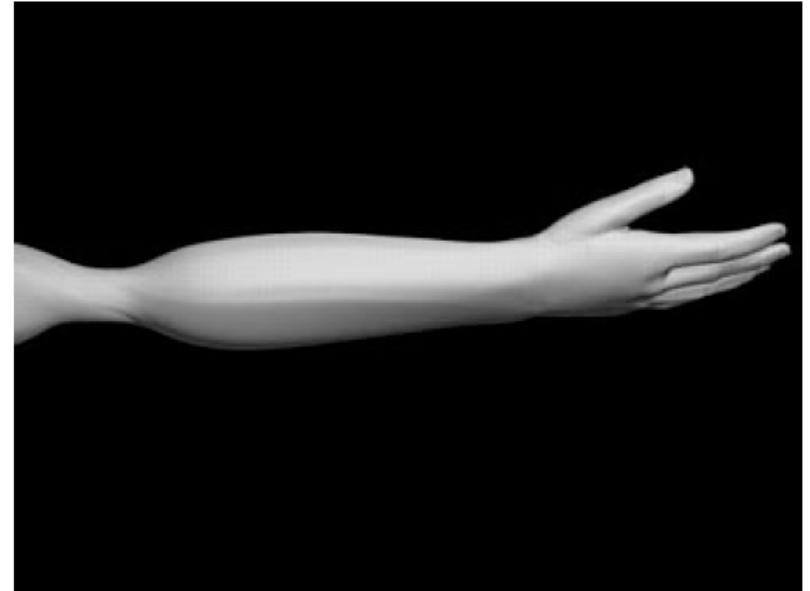


Figure 3: The forearm in the 'twist' pose, as in turning a door handle, computed by SSD. As the twist approaches  $180^\circ$  the arm collapses.

- From: Pose Space Deformation: A Unified Approach to Shape Interpolation and
- Skeleton-Driven Deformation
- J. P. Lewis, Matt Cordner, Nickson Fong

# Dual Quaternion Skinning

The common skin deformation technique (linear blend skinning) sometimes produces non-natural results, such as below.



Several more advanced methods exist, but lead to slower run-time performance and require a more expensive character setup. Our approach, based on dual quaternions, removes the skinning artifacts at a small cost in computational efficiency and no cost at all in character setup. The result of our method is pictured below (using the same model files as above).

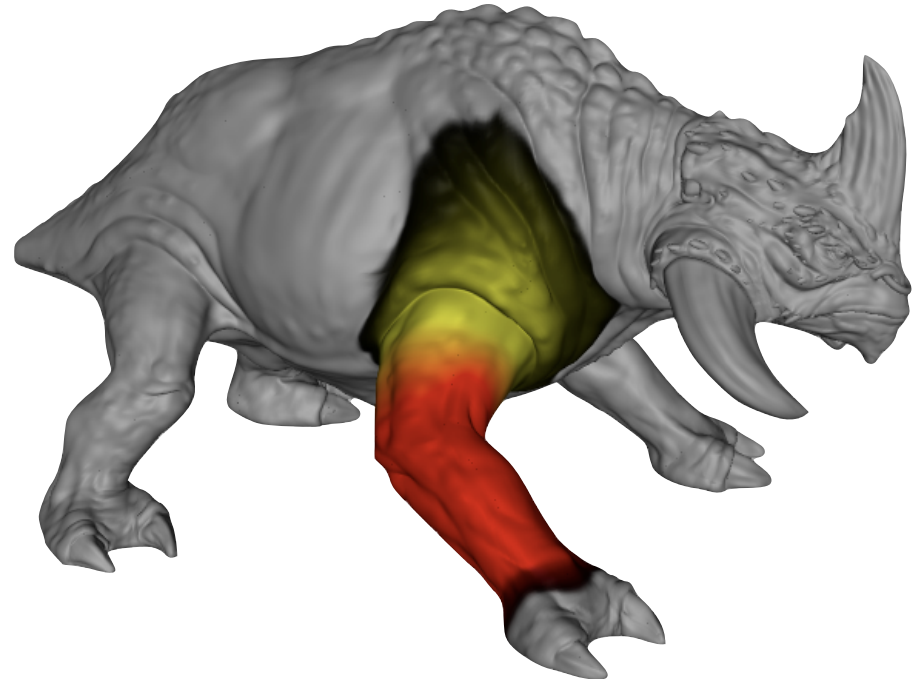


# Usual Solution

- Have the artists deal with it O:-)
- In practice, build a rig that has extra bones near joints that move in sync to counter the artifacts.
  - Tedious, but this is what people often do.
  - Need sophisticated animation controls to drive this.
- Cool paper that does this automatically:  
Kavan, Collins, O'Sullivan: Automatic Linearization of Nonlinear Skinning, I3D 2009

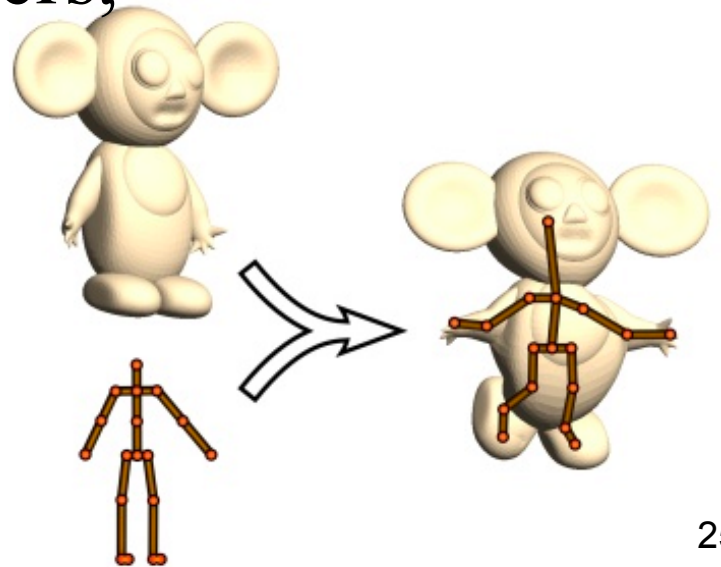
# Figuring out the Weights

- Usual approach: Paint them on the skin.
- Can also find them by optimization from example poses and deformed skins.
  - Wang & Phillips, SCA 2002



# Super Cool: Automatic Rigging

- When you just have some reference skeleton animation (perhaps from motion capture) and a skin mesh, figure out the bone transformations and vertex weights!
- Ilya Baran, Jovan Popovic: Automatic Rigging and Animation of 3D Characters, SIGGRAPH 2007
  - <http://www.mit.edu/~ibaran/autorig/>
- You saw this earlier



# The Other Direction

- When you have no skeleton, but a source animation for the full mesh (not so common)

## Skinning Mesh Animations

Doug L. James

Christopher D. Twigg

Carnegie Mellon University



Figure 1: **Stampede!** Ten thousand skinned mesh animations (SMAs) synthesized in graphics hardware at interactive rates. All SMAs are reformed using only traditional matrix palette skinning with well-chosen nonrigid bone transforms. Distant SMAs are simplified.



# That's All!

- Further reading
  - <http://www.okino.com/conv/skinning.htm>
- Take a look at any video game – basically all the characters are animated using SSD/skinning.