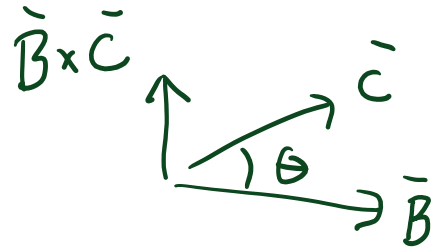


$$\vec{B} \cdot \vec{B} = |\vec{B}|^2 = B^2$$

$$\frac{\vec{B}}{|\vec{B}|} = \frac{\vec{B}}{\sqrt{\vec{B} \cdot \vec{B}}} = \vec{a}_B$$

$$|\vec{B} \times \vec{C}| = |\vec{B}| |\vec{C}| \sin \theta$$

$$\vec{C} \times \vec{B} = -\vec{B} \times \vec{C}$$

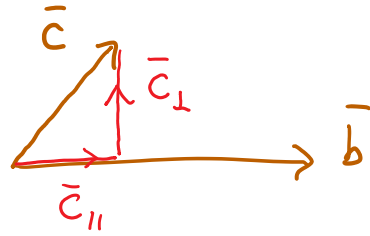


$$\vec{A} \cdot \vec{B} \times \vec{C} = \vec{A} \times \vec{B} \cdot \vec{C} = \vec{C} \cdot \vec{A} \times \vec{B}$$

$$\vec{A} \times (\vec{B} \times \vec{C}) = \vec{B}(\vec{A} \cdot \vec{C}) - \vec{C}(\vec{A} \cdot \vec{B})$$

$$(\vec{A} \times \vec{B}) \times \vec{C} = \vec{B}(\vec{A} \cdot \vec{C}) - \vec{A}(\vec{B} \cdot \vec{C})$$

\bar{b}, \bar{c}



$$\bar{c} = \bar{c}_{||} + \bar{c}_{\perp}$$

$$= \alpha \bar{b} + \beta (\bar{b} \times \bar{c}) \times \bar{b}$$

$$\bar{b} \cdot \bar{c} = \alpha \bar{b} \cdot \bar{b} + \beta \underbrace{[(\bar{b} \times \bar{c}) \times \bar{b}] \cdot \bar{b}}_{(\bar{b} \times \bar{c}) \cdot \underbrace{\bar{b} \times \bar{b}}_{=0}} = \alpha \bar{b} \cdot \bar{b} \Rightarrow \alpha = \frac{\bar{b} \cdot \bar{c}}{\bar{b} \cdot \bar{b}}$$

$$\begin{aligned} \bar{b} \times \bar{c} &= \alpha \underbrace{\bar{b} \times \bar{b}}_0 + \beta \bar{b} \times [(\bar{b} \times \bar{c}) \times \bar{b}] = \beta [(\bar{b} \times \bar{c}) \bar{b} \cdot \bar{b} - \bar{b} \underbrace{(\bar{b} \cdot \bar{b} \times \bar{c})}_0] \\ &= \beta \underbrace{\bar{b} \cdot \bar{b}}_1 \bar{b} \times \bar{c} \end{aligned}$$

$$\bar{c} = \frac{\bar{b} \cdot \bar{c}}{\bar{b} \cdot \bar{b}} \bar{b} + \frac{(\bar{b} \times \bar{c}) \times \bar{b}}{\bar{b} \cdot \bar{b}}$$

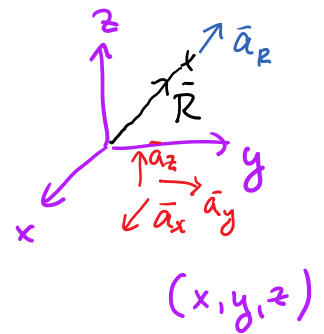


CARTESIAN COORDINATE SYSTEM

$$\vec{R} = x\vec{a}_x + y\vec{a}_y + z\vec{a}_z$$

$$|\vec{R}| = \sqrt{\vec{R} \cdot \vec{R}} = \sqrt{x^2 + y^2 + z^2}$$

$$\vec{a}_R = \frac{\vec{R}}{|\vec{R}|}$$



$$\vec{a}_x \cdot \vec{a}_x = 1$$

$$\vec{a}_x \cdot \vec{a}_y = 0$$

$$d\vec{r} = dx\vec{a}_x + dy\vec{a}_y + dz\vec{a}_z$$



$$dV = dx dy dz$$

CYLINDRICAL C. SYSTEM

$$(r, \phi, z)$$

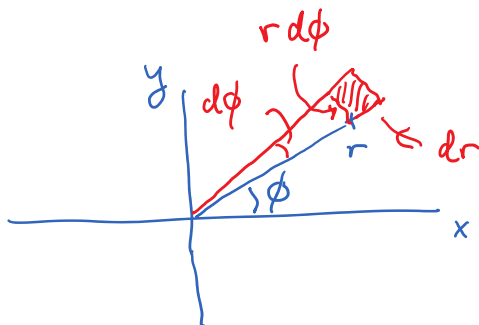
$$\vec{a}_r \quad \vec{a}_\phi \quad \vec{a}_z$$

$$\vec{a}_r = \cos\phi \vec{a}_x + \sin\phi \vec{a}_y$$

$$\vec{a}_\phi = -\sin\phi \vec{a}_x + \cos\phi \vec{a}_y$$

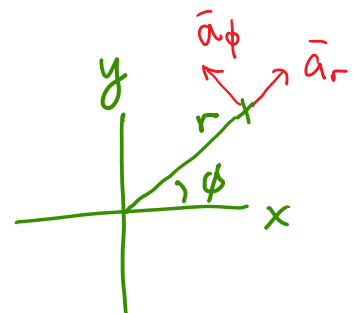
$$r = \sqrt{x^2 + y^2}$$

$$\tan\phi = y/x$$



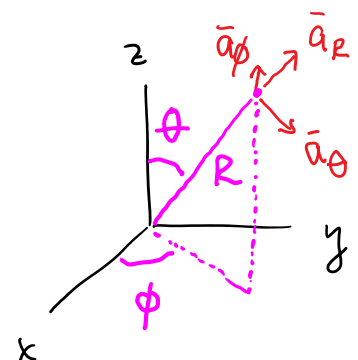
$$dS = r d\phi dr$$

$$dV = dS dz$$

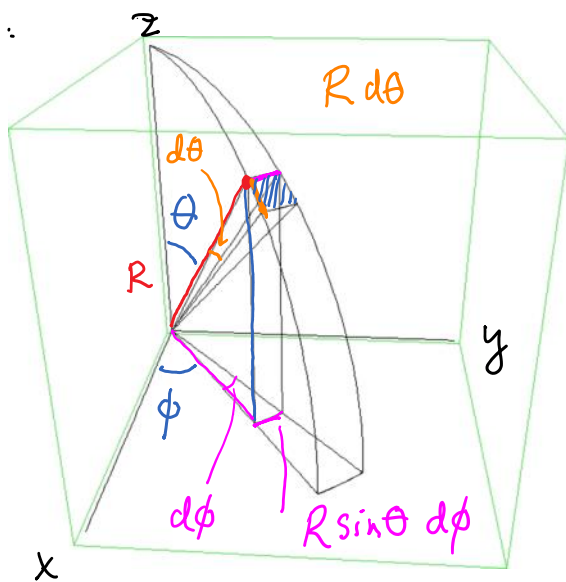


SPHERICAL C. SYSTEM

$$(R, \theta, \phi)$$



$$\vec{a}_R \cdot \vec{a}_R = 1$$



$$\bar{a}_R \cdot \bar{a}_\theta = 0$$

$$\bar{a}_R \times \bar{a}_\theta = \bar{a}_\phi \quad \dots$$

$$dS = R d\theta \quad R \sin\theta d\phi$$

$$= \sin\theta R^2 d\theta d\phi$$

$$dV = dR \cdot dS$$