



$$\nabla f$$

gradient

$$\nabla \cdot \vec{D}$$

divergence

$$\nabla \times \vec{H}(x)$$

curl

$\uparrow$

$$x \bar{a}_y = H_y \bar{a}_y$$

$$\nabla \times (x \bar{a}_y) = \begin{vmatrix} \bar{a}_x & \bar{a}_y & \bar{a}_z \\ \partial/\partial x & \partial/\partial y & \partial/\partial z \\ 0 & x & 0 \end{vmatrix} = \bar{a}_z$$

$$\vec{E} \quad \vec{D}$$

$$\vec{D} = \epsilon_0 \vec{E}$$

FREE SPACE

PERMITTIVITY

$$\epsilon_0 = 8.854 \cdot 10^{-12} \frac{As}{Vm}$$

$$\cdot [q] \quad C = As$$

$$\rho_l \quad \frac{As}{m}$$

$$\rho_s \quad \frac{As}{m^2}$$

$$\rho_v \quad As/m^3$$

COULOMB'S LAW

$$q_1 \cdot \frac{q_2}{D} \cdot \vec{a}_{12}$$

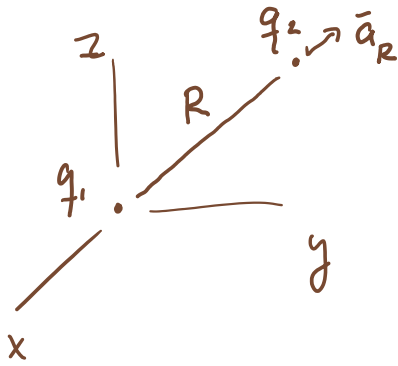
$$\vec{F}_{12} = \frac{q_1 q_2}{4\pi\epsilon_0 D^2} \vec{a}_{12}$$

$$q_1 = q_2 = 1 As$$

$$D = 1m$$

$$|\vec{F}| = \frac{1 As \cdot 1 As}{4\pi \cdot 8.854 \cdot 10^{-12} \frac{As}{Vm} \cdot (1m)^2} = 10^{10} N \times 10^9 kg$$

$$UNITS \quad \frac{As \cdot As}{As \cdot m^2} Vm = \frac{\overbrace{VA}^W s}{m} = \frac{J}{m} = N$$



$$\vec{F}_{12} = \frac{q_1 q_2}{4\pi\epsilon_0 R^2} \vec{a}_R$$

$$\frac{\vec{F}_{12}}{q_2} = \frac{q_1}{4\pi\epsilon_0 R^2} \vec{a}_R = \vec{E}_1(\vec{R})$$

$$\nabla \times \vec{E}_1 = ?$$

UNIT:  $\frac{\text{As V}_m}{\text{As m}^2} = \frac{\text{V}}{\text{m}}$

$$\nabla \times (\vec{a}_R E_{1R}) = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \vec{a}_R & R\vec{a}_\theta & R\sin\theta \vec{a}_\phi \\ \frac{\partial}{\partial R} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ \frac{q_1}{4\pi\epsilon_0} R^{-2} & 0 & 0 \end{vmatrix}$$

$$= 0$$

Spherical coordinates

$$\nabla f = \vec{a}_R \frac{\partial}{\partial R} f + \vec{a}_\theta \frac{1}{R} \frac{\partial}{\partial \theta} f + \vec{a}_\phi \frac{1}{R \sin \theta} \frac{\partial}{\partial \phi} f$$

$$\nabla \times \vec{f} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \vec{a}_R & R\vec{a}_\theta & R\sin\theta \vec{a}_\phi \\ \frac{\partial}{\partial R} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \\ f_R & Rf_\theta & R\sin\theta f_\phi \end{vmatrix}$$

$$\nabla \cdot \vec{f} = \frac{1}{R^2} \frac{\partial}{\partial R} (R^2 f_R) + \frac{1}{R \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta f_\theta) + \frac{1}{R \sin \theta} \frac{\partial}{\partial \phi} f_\phi$$

$$\nabla^2 f = \frac{1}{R^2} \frac{\partial}{\partial R} \left( R^2 \frac{\partial f}{\partial R} \right) + \frac{1}{R^2 \sin \theta} \frac{\partial}{\partial \theta} \left( \sin \theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{R^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \phi^2}$$

$$\nabla \times \vec{E} = - \frac{\partial \vec{B}}{\partial t} = 0 \quad \left( \frac{\partial}{\partial t} = 0 \quad (\text{STATICS}) \right)$$

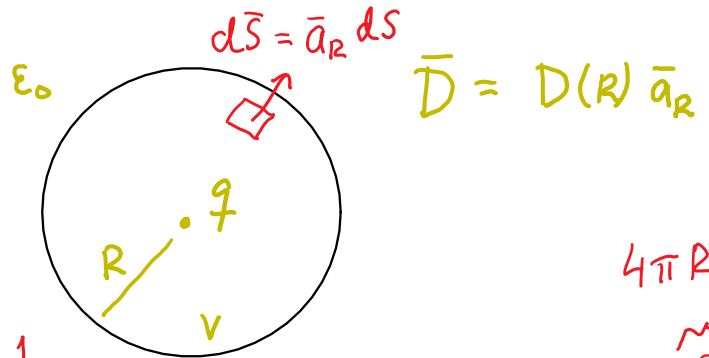
$$\nabla \cdot \vec{D} = \rho_v \quad \leftarrow$$

GAUSS

$$\int_V \nabla \cdot \vec{D} \, dV = \oint_S \vec{D} \cdot d\vec{S}$$

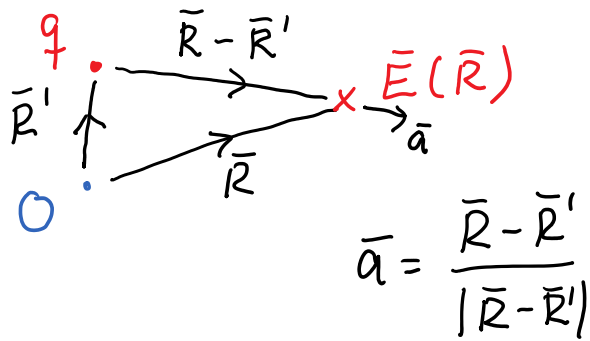
$$= \int \rho_v \, dV = q$$

$$\oint D(R) \vec{a}_R \cdot \vec{a}_R \, dS = \oint D(R) \, dS = D(R) \oint dS = D(R) 4\pi R^2$$

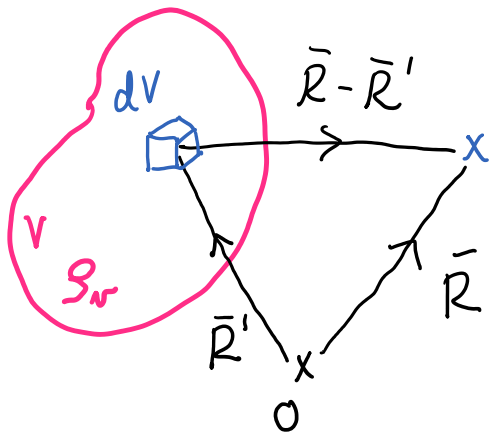


$$\vec{D}(\vec{R}) = \vec{a}_R \frac{q}{4\pi R^2} = \epsilon_0 \vec{E}(\vec{R}) \quad (\text{COULOMB!})$$

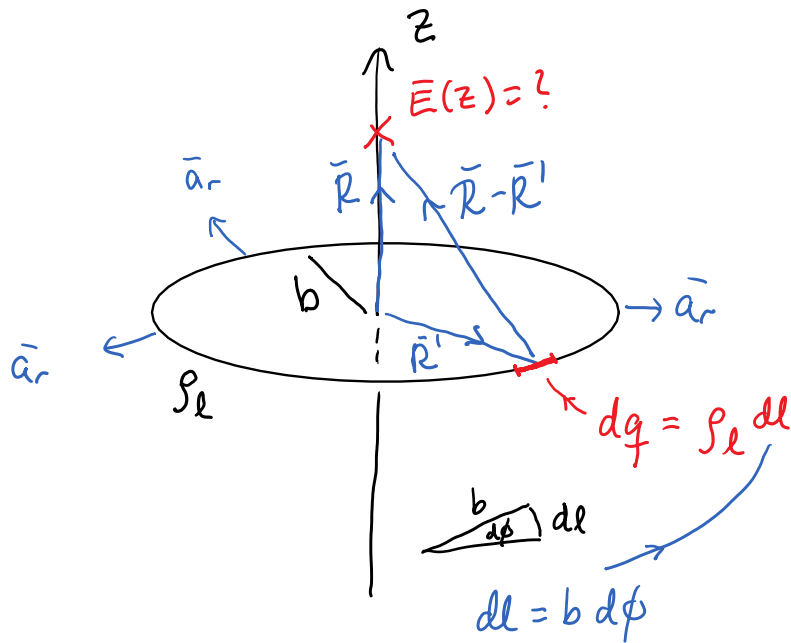
## SHIFT OF ORIGIN



$$\begin{aligned}\vec{E}(\vec{r}) &= \frac{q}{4\pi\epsilon_0 |\vec{r} - \vec{r}'|^2} \vec{a} \\ &= \frac{q (\vec{r} - \vec{r}')}{4\pi\epsilon_0 |\vec{r} - \vec{r}'|^3}\end{aligned}$$



$$\vec{E}(\vec{r}) = \int_V \frac{\rho_v(\vec{r}') (\vec{r} - \vec{r}') dV'}{4\pi\epsilon_0 |\vec{r} - \vec{r}'|^3}$$



$$\vec{r} = z \vec{a}_z \quad (r, \phi, z)$$

$$\vec{r}' = b \vec{a}_r$$

$$\vec{r} - \vec{r}' = z \vec{a}_z - b \vec{a}_r$$

$$\begin{aligned} (\vec{r} - \vec{r}') \cdot (\vec{r} - \vec{r}') &= (z \vec{a}_z - b \vec{a}_r) \cdot (z \vec{a}_z - b \vec{a}_r) \\ &= z^2 + b^2 - 2zb \underbrace{\vec{a}_z \cdot \vec{a}_r}_0 \end{aligned}$$

$$|\vec{r} - \vec{r}'| = \sqrt{z^2 + b^2}$$

$$\vec{E}(z) = \int_0^{2\pi} \frac{\rho_l (z \vec{a}_z - b \vec{a}_r) b d\phi}{4\pi \epsilon_0 \sqrt{z^2 + b^2}^3} = \frac{\rho_l b}{4\pi \epsilon_0 \sqrt{z^2 + b^2}^3} \int_0^{2\pi} (z \vec{a}_z - b \vec{a}_r) d\phi$$

$$= \frac{\overbrace{\rho_l 2\pi b}^Q z}{4\pi \epsilon_0 (z^2 + b^2)^{3/2}} \vec{a}_z$$

$$\begin{aligned} & \int_0^{2\pi} \vec{a}_r d\phi = 0 \\ & \text{Note: } \int_0^{2\pi} \vec{a}_r d\phi = 0 \end{aligned}$$

$$\vec{a}_r = \vec{a}_x \cos \phi + \vec{a}_y \sin \phi$$

$$\int_0^{2\pi} \vec{a}_x \cos \phi d\phi = \vec{a}_x \int_0^{2\pi} \cos \phi d\phi = 0$$