$$\widehat{A}(\widetilde{R}) = \int \frac{\mu \, \widehat{J}(\widetilde{R}') \, e^{-jk|\widetilde{R}-\widetilde{R}'|}}{4\pi \, |\widetilde{R}-\widetilde{R}'|} \, dv'$$

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$$\bar{z}$$
 \bar{z}
 \bar{z}

$$\bar{B} = \nabla x \bar{A}$$
, $\bar{H} = \frac{\nabla x \bar{A}}{M}$

$$\bar{A}(\bar{R}) = \frac{\mu I L \bar{e}^{jkR}}{4\pi R} (\bar{a}_{R} \cos \theta - \bar{a}_{\theta} \sin \theta)$$

H =
$$\frac{\nabla \times \overline{A}}{M}$$

= $\frac{1}{MR^2 \sin \theta} \begin{vmatrix} \overline{a}_{R} & R\overline{a}_{\theta} & R \sin \theta & \overline{a}_{\phi} \\ \frac{2}{3}R & \frac{2}{3}\theta & 0 \end{vmatrix}$

AR RAA 0

$$\begin{split} & \nabla f = \overline{\mathbf{a}}_R \frac{\partial}{\partial R} f + \overline{\mathbf{a}}_\theta \frac{1}{R} \frac{\partial}{\partial \theta} f + \overline{\mathbf{a}}_\phi \frac{1}{R \sin \theta} \frac{\partial}{\partial \phi} f \\ & \nabla \times \overline{f} = \frac{1}{R^2 \sin \theta} \begin{vmatrix} \overline{\mathbf{a}}_R & R \overline{\mathbf{a}}_\theta & R \sin \theta \overline{\mathbf{a}}_\phi \\ \frac{\partial}{\partial R} & \frac{\partial}{\partial \theta} & \frac{\partial}{\partial \phi} \end{vmatrix} \\ & \nabla \cdot \overline{f} = \frac{1}{R^2} \frac{\partial}{\partial R} (R^2 f_R) + \frac{1}{R \sin \theta} \frac{\partial}{\partial \theta} (\sin \theta f_\theta) + \frac{1}{R \sin \theta} \frac{\partial}{\partial \phi} f_\phi \\ & \nabla^2 f = \frac{1}{R^2} \frac{\partial}{\partial R} \left(R^2 \frac{\partial f}{\partial R} \right) + \frac{1}{R^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial f}{\partial \theta} \right) + \frac{1}{R^2 \sin^2 \theta} \frac{\partial^2 f}{\partial \phi^2} \end{split}$$

$$= \frac{1}{MR^{8} \sin \theta} R \sin \theta \left(\frac{3}{3R} \left(RA_{6} \right) - \frac{3}{3\theta} A_{R} \right)$$

$$= \frac{1}{MR^{8} \sin \theta} R \sin \theta$$

$$= \frac{3}{3R} \frac{MILe^{-ikR}}{4\pi R} \sin \theta$$

$$= +jkR \frac{MILe^{-ikR}}{4\pi R} \sin \theta$$

$$= \frac{jkR}{R \, 4\pi R} \, e^{-jkR} \, \sin\theta \, IL \, \left(1 + \frac{1}{jkR}\right)$$

$$= \frac{a_{\phi}}{a_{\phi}} \, jkLL \, \frac{e^{-jkR}}{4\pi R} \, \sin\theta \, \left(1 + \frac{1}{jkR}\right)$$

$$\nabla x H = j\omega \varepsilon \hat{\Xi}$$
 $\bar{\Xi} = \frac{\nabla x \hat{H}}{j\omega \varepsilon}$

$$\begin{split} \vec{E}(\vec{k}) &= j\omega_{\mu} \text{ TL} \quad \frac{e^{-ikR}}{4\pi R} \left[\vec{a}_{R} 2\omega_{\theta} \left(\frac{1}{jkR} + \frac{1}{(jkR)^{2}} \right) + \vec{a}_{\theta} \sin_{\theta} \left(1 + \frac{1}{jkR} + \frac{1}{(jkR)} \right) \right] \\ \vec{H}(\vec{k}) &= jk \text{ TL} \quad \frac{e^{-jkR}}{4\pi R} \sin_{\theta} \vec{a}_{\phi} \left(1 + \frac{1}{jkR} \right) \\ NEAR-FIELD \quad R &<< \lambda \qquad kR &= \frac{2\pi R}{\lambda} << 1 \qquad e^{-jkR} \simeq 1 \\ \vec{H}(\vec{k}) &\simeq jkTL \quad \frac{\sin_{\theta}}{4\pi R} \vec{a}_{\phi} \quad \frac{1}{jkR} &= \frac{TL\sin_{\theta}}{4\pi R^{2}} \vec{a}_{\phi} \\ \vec{E}(\vec{k}) &\simeq j\omega_{\mu} TL \quad \frac{1}{4\pi R} \left(\frac{1}{jkR} \right)^{s} \left(\vec{a}_{R} 2\omega_{S}\theta + \vec{a}_{\theta} \sin_{\theta} \right) \\ &- \frac{1}{j\omega_{\mu}} \frac{\pi}{L} L \qquad \frac{1}{4\pi R^{2}} \frac{1}{j\omega} \\ \vec{T}L \quad \frac{2}{j\omega_{\mu}} = \frac{P}{4\pi R^{2}} \left(\frac{2\omega_{\theta}}{a_{R}} + \frac{2\omega_{\theta}}{a_{R}} \right) \\ \vec{T}L \quad \frac{2}{j\omega_{\mu}} = \frac{2}{4\pi R^{2}} \left(\frac{2\omega_{\theta}}{a_{R}} + \frac{2\omega_{\theta}}{a_{R}} + \frac{2\omega_{\theta}}{4\pi R^{2}} \right) \end{aligned}$$

iwp = IL

$$\bar{E}(\bar{R}) = j\omega\mu IL \frac{e^{-jkR}}{4\pi R} \sin\theta \bar{\alpha}_{\theta}$$

$$\bar{H}(\bar{R}) = jk IL \frac{e^{-jkR}}{4\pi R} \sin\theta \bar{\alpha}_{\phi}$$

$$\lambda = \frac{\omega_{M}}{k} = \sqrt{\frac{\mu}{\epsilon}} = \eta$$