$$\overline{E}(z) = \frac{Q}{4\pi\epsilon_0} \cdot \frac{z}{\sqrt{z^2 + b^2}}, \, \bar{\alpha}_2$$

$$\overline{E}(0) = 0$$

$$Z >> b$$

$$\overline{E}(z) = \frac{Q}{4\pi \epsilon_0 Z^2} \overline{q}_z$$

$$\nabla x = -\frac{3}{3} = 0$$

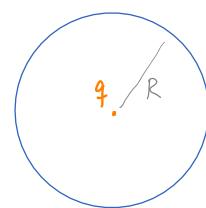
$$\oint d\vec{l} = \vec{a}_{\phi} \vec{b} d\phi$$

$$\oint d\vec{l} = b \int \vec{a}_{\phi} d\phi = 0$$

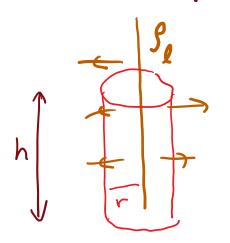
$$\oint d\vec{l} = b \int d\phi = 2\pi b$$

$$\varepsilon_{\circ}$$

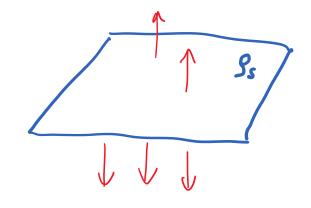
$$\bar{D}(\bar{R}) = \epsilon_0 \bar{E}(\bar{r})$$



$$\widetilde{D}(\widetilde{R}) = \frac{9}{4\pi R^2} \, \bar{a}_R$$

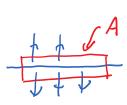


$$\overline{D} = \frac{g_{lh}}{2\pi rh} \overline{a}_{r} = \frac{g_{l}}{2\pi r} \overline{a}_{r}$$

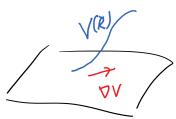


$$\frac{S_s}{D} = \frac{S_s A}{2 A} \left(\pm \bar{\alpha}_z \right) \\
= \frac{S_s}{2} \left(\pm \bar{\alpha}_z \right)$$

$$\int \nabla \cdot \overline{D} dV = \oint \overline{D} \cdot d\overline{S}$$







MONOPOLE
$$-\frac{d}{dR}R^{-1} = +R^{2}$$

$$E(\bar{R}) = -\nabla V(\bar{R})$$

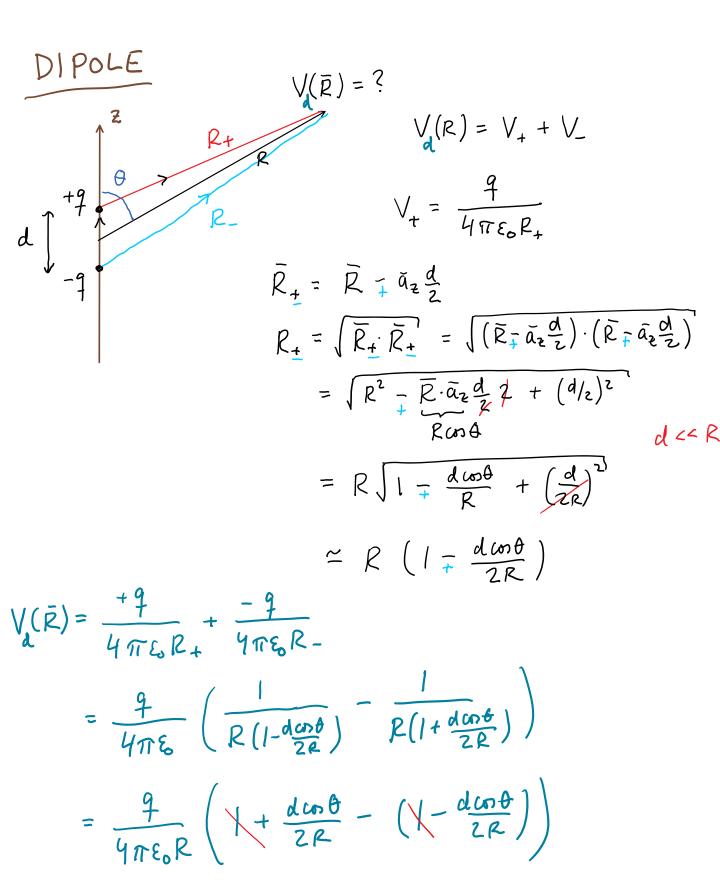
$$\int \nabla V(\bar{R}) dx$$

$$\bar{E}_{m} = \frac{q}{4\pi\epsilon R^{2}} \bar{a}_{R} = -\nabla V_{m}$$

$$= -\bar{a}_{R} \frac{dV_{m}}{dR}$$

$$V_{m} = \frac{q}{4\pi\epsilon R}$$

$$\frac{\bar{R} - \bar{R}'}{\bar{R}'} \times \sqrt{(\bar{R})} = \int \frac{g_{x'}(\bar{R}') dV'}{4\pi \varepsilon |\bar{R} - \bar{R}'|} dV'$$



$$= \frac{9 d \cos \theta}{4 \pi \epsilon_0 R^2} = V_d$$

$$\begin{split} \vec{E}_{d} &= - \nabla V_{d} = - \left(\vec{a}_{R} \frac{\partial V_{d}}{\partial R} + \frac{1}{R} \vec{a}_{\theta} \frac{\partial V_{d}}{\partial \theta} \right) \\ &= \frac{q d}{4\pi \epsilon_{o}} \left(2\vec{a}_{R} \frac{\cos \theta}{R^{3}} + \vec{a}_{\theta} \frac{\sin \theta}{R^{3}} \right) \\ &= \frac{q d}{4\pi \epsilon_{o}} \left(2 \cos \theta \vec{a}_{R} + \sin \theta \vec{a}_{\theta} \right) \end{split}$$

$$\frac{1}{1+x} \approx 1-x+x^{2}$$

$$\int \frac{1}{1+x} \approx 1+\frac{x}{2}$$

$$\int \frac{1}{1+x} = 1+\frac{x}{2}$$

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