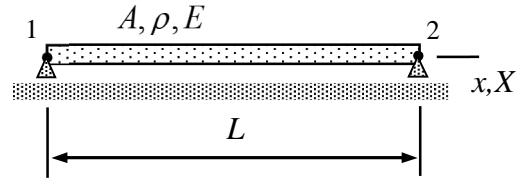


Name _____ Student number _____

Assignment 4

A bar is free to move in the horizontal direction as shown. Determine the angular velocities of the free vibrations and the corresponding modes. Use one bar element of nodes 1 and 2. Cross-sectional area A , density ρ of the material, and Young's modulus E of the material are constants.



Solution template

The non-zero displacement/rotation components of the structure are u_{X1} and u_{X2} . Let us start with the element contributions for the internal and inertia parts

$$\delta W^{\text{int}} = - \begin{Bmatrix} \delta u_{x1} \\ \delta u_{x2} \end{Bmatrix}^T \frac{EA}{h} \begin{bmatrix} 1 & -1 \\ -1 & 1 \end{bmatrix} \begin{Bmatrix} u_{x1} \\ u_{x2} \end{Bmatrix}, \quad \delta W^{\text{ine}} = - \begin{Bmatrix} \delta u_{x1} \\ \delta u_{x2} \end{Bmatrix}^T \frac{\rho Ah}{6} \begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix} \begin{Bmatrix} \ddot{u}_{x1} \\ \ddot{u}_{x2} \end{Bmatrix}.$$

As the axes of the material and structural coordinate systems coincide, virtual work expression of the structure takes the form

$$\delta W = - \begin{Bmatrix} \delta u_{X1} \\ \delta u_{X2} \end{Bmatrix}^T \left(\begin{bmatrix} \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \\ \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \end{bmatrix} \begin{Bmatrix} u_{X1} \\ u_{X2} \end{Bmatrix} + \begin{bmatrix} \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \\ \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \end{bmatrix} \begin{Bmatrix} \ddot{u}_{X1} \\ \ddot{u}_{X2} \end{Bmatrix} \right).$$

Principle of virtual work and fundamental lemma of variation calculus imply the set of ordinary differential equations

$$\begin{bmatrix} \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \\ \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \end{bmatrix} \begin{Bmatrix} u_{X1} \\ u_{X2} \end{Bmatrix} + \begin{bmatrix} \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \\ \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \end{bmatrix} \begin{Bmatrix} \ddot{u}_{X1} \\ \ddot{u}_{X2} \end{Bmatrix} = 0. \quad \leftarrow$$

The angular speeds of free vibrations can be deduced from the stiffness and mass matrix of the equation system

$$\mathbf{M} = \begin{bmatrix} \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \\ \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \end{bmatrix} \quad \text{and} \quad \mathbf{K} = \begin{bmatrix} \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \\ \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \end{bmatrix} \Rightarrow \mathbf{\Omega}^2 = \mathbf{M}^{-1} \mathbf{K} = \begin{bmatrix} \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \\ \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \end{bmatrix}.$$

The angular speeds of free vibrations are the eigenvalues of $\mathbf{\Omega}$. Let us start with the eigenvalues $\lambda = \omega^2$ of $\mathbf{\Omega}^2 = \mathbf{M}^{-1} \mathbf{K}$ to get

$$\det \left(\begin{bmatrix} \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \\ \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \right) = \det \left(\begin{bmatrix} \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \\ \underline{\hspace{1cm}} & \underline{\hspace{1cm}} \end{bmatrix} \right) = \underline{\hspace{2cm}} = 0 \Rightarrow$$

$$\lambda_1 = \underline{\hspace{2cm}} \quad \text{and} \quad \lambda_2 = \underline{\hspace{2cm}} .$$

The corresponding modes follow from the linear equation system of the eigenvalue problem when the eigenvalues are substituted there (one by one)

$$\lambda_1 = \underline{\hspace{2cm}} \quad \text{and} \quad \begin{bmatrix} \underline{\hspace{2cm}} & \underline{\hspace{2cm}} \\ \underline{\hspace{2cm}} & \underline{\hspace{2cm}} \end{bmatrix} \begin{Bmatrix} u_{X1} \\ u_{X2} \end{Bmatrix} = 0 \Rightarrow \mathbf{x}_1 = \begin{Bmatrix} u_{X1} \\ u_{X2} \end{Bmatrix} = \begin{Bmatrix} \underline{\hspace{2cm}} \\ \underline{\hspace{2cm}} \end{Bmatrix} ,$$

$$\lambda_2 = \underline{\hspace{2cm}} \quad \text{and} \quad \begin{bmatrix} \underline{\hspace{2cm}} & \underline{\hspace{2cm}} \\ \underline{\hspace{2cm}} & \underline{\hspace{2cm}} \end{bmatrix} \begin{Bmatrix} u_{X1} \\ u_{X2} \end{Bmatrix} = 0 \Rightarrow \mathbf{x}_2 = \begin{Bmatrix} u_{X1} \\ u_{X2} \end{Bmatrix} = \begin{Bmatrix} \underline{\hspace{2cm}} \\ \underline{\hspace{2cm}} \end{Bmatrix} .$$

As $\omega = \sqrt{\lambda}$, the angular velocities of the free vibrations and the associated modes are

$$(\omega_1, \mathbf{x}_1) = (\underline{\hspace{2cm}}, \underline{\hspace{2cm}}) \quad \text{and} \quad (\omega_2, \mathbf{x}_2) = (\underline{\hspace{2cm}}, \underline{\hspace{2cm}}) . \quad \leftarrow$$