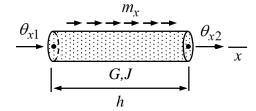
Assignment 1

Derive the virtual work expression $\delta W = \delta W^{\rm int} + \delta W^{\rm ext}$ of the bar element (length h) if the approximation is linear (a two-node element) and J, G and m_x are constants.



Solution template

Virtual work densities of the internal and external forces of the torsion bar model are

$$\delta w_{\Omega}^{\text{int}} = -\frac{d\delta\phi}{dx}GJ\frac{d\phi}{dx}$$
 and $\delta w_{\Omega}^{\text{ext}} = \delta\phi m_x$,

in which J is the second moment of area with respect to x-axis, G is the shear modulus, and m_x is the external moment per unit length.

Let us start with the linear approximation to the rotation angle. The origin of the material coordinate system is at node 1 and the length of the bar is h.

$$\phi = \begin{cases} 1 - x/h \\ x/h \end{cases}^{T} \begin{cases} \theta_{x1} \\ \theta_{x2} \end{cases}, \quad \frac{d\phi}{dx} = \left\{ \frac{1}{2} \right\}^{T} \begin{cases} \theta_{x1} \\ \theta_{x2} \end{cases},$$

$$\delta\phi = \begin{cases} 1 - x/h \\ x/h \end{cases}^{T} \begin{cases} \delta\theta_{x1} \\ \delta\theta_{x2} \end{cases}, \quad \frac{d\delta\phi}{dx} = \begin{cases} ------ \\ ------ \end{cases}^{T} \begin{cases} \delta\theta_{x1} \\ \delta\theta_{x2} \end{cases}.$$

When the approximation is substituted there, virtual works of internal and external forces per unit take the forms

$$\delta w_{\Omega}^{\text{int}} = -\frac{d\delta\phi}{dx}GJ\frac{d\phi}{dx} = -\left\{ \begin{matrix} \delta\theta_{x1} \\ \delta\theta_{x2} \end{matrix} \right\}^{\text{T}} \begin{bmatrix} \begin{matrix} & & & \\ & & & \\ \end{matrix} \end{bmatrix} \begin{cases} \theta_{x1} \\ \theta_{x2} \end{cases},$$

$$\delta w_{\Omega}^{\text{ext}} = \delta \phi m_{x} = \begin{cases} \delta \theta_{x1} \\ \delta \theta_{x2} \end{cases}^{\text{T}} \begin{cases} \underline{} \\ \underline{} \end{cases}.$$

Virtual work expressions are integrals of the densities over the length. Then, virtual work expressions of the bar element are given by

$$\delta W^{\text{int}} = \int_0^h \delta w_{\Omega}^{\text{int}} dx = -\begin{cases} \delta \theta_{x1} \\ \delta \theta_{x2} \end{cases}^{\text{T}} \begin{bmatrix} \frac{1}{2} & \frac{1}{2} \\ \frac{1}{2} & \frac{1}{2} \end{cases}, \quad \leftarrow$$

$$\delta W^{\rm ext} = \int_0^h \delta w_{\Omega}^{\rm ext} dx = \begin{cases} \delta \theta_{x1} \\ \delta \theta_{x2} \end{cases}^{\rm T} \left\{ \underline{} \right\}. \quad \blacktriangleleft$$