PROBLEM SHEET 2

1) a) Lagrange:

$$p(x) = \sum_{j=0}^{n} q_{j} \frac{\pi}{x_{j} - x_{i}}$$

$$= \left(\frac{\pi}{x_{j}} (x - x_{i})\right) \sum_{j=0}^{n} q_{j} \frac{1}{x - x_{j}} \frac{1}{x_{j} - x_{i}}$$

$$= \varphi(x) \sum_{i=0}^{n} \frac{w_{i}}{x - x_{i}} q_{i} \qquad (3 \text{ just changed the summation order.})$$

b) Barycentric formula:

The famous observation is that f(x) = 1 (const) has the representation $1 = \sum_{i=0}^{n} L_i(x) = \varphi(x) \sum_{i=0}^{n} \frac{w_i}{x - x_i}$

So, it follows that
$$\varphi(x) = 1 / \sum_{i=0}^{n} \frac{w_i}{x - x_i}$$

c) Suppose the weights W_k for the points x_0, x_1, \dots, x_{m-1} have been computed and a new point x_m is added.

We get:

$$W_{k}^{m} = \frac{1}{x_{k} - x_{m}} W_{k}^{m-1}, k = 0, 1, ..., m-1$$

$$w_{m}^{m} = \frac{m-1}{11} \frac{1}{x_{m}-x_{j}}$$

Complexity is $\Theta(n)$. (Some textbooks have get this wrong!)

a) Since $l_p(x_i) = \delta_{pi}$ and $\overline{l}_q(y_j) = \delta_{qj}$ (δ is Kronecker's delte)

we obtain for all i, j

 $P(x_i,y_j) = \sum_{p,q} \sum_{p,q} L_p(x_i) \overline{L}_q(y_j) = \Xi_{ij}$

b) This looks complicated, but we can use the product form:

$$d_b(x) = \left[\sum_{i=1}^{d} \frac{(x-i^d)}{m^d} \sum_{i=1}^{d} \frac{1}{m^d} \right]$$

for all p , p = 0, ..., m.

Therefore, for all i,j

$$P(x_i, y_i) = \left[\sum_{P} \frac{w_P}{(x_i - x_P)} g_P(y_i) \right] / \left[\sum_{P} \frac{w_P}{x_i - x_P} \right]$$

= Z.;