

The following Google Colab includes the code and description of the assignment [Threads and Synchronisation Colab link](#)

1. PThreads

Question 1 2 / 2

TODO 0: Which header files need to be included?

- ☒ stdio.h
- ☐ semaphore.h
- ☒ pthread.h
- ☐ stdlib.h

Question 2 2 / 2

TODO 1: What is the correct return type?

- ☐ void
- ☐ void&
- ☒ void*
- ☐ void**

Question 3 2 / 2

TODO 2: What is a correct way of exiting the child thread PrintHello function?

- ☒ Calling pthread_exit with any argument (e.g. NULL) as the value is not used
- ☐ Calling pthread_exit with the thread name (string) as an argument
- ☒ Just returning from the function is enough
- ☐ Using exit()

Question 4 2 / 2

TODO 3: What is the correct way of starting each thread?

- ☐ pthread_create(threads[t], NULL, PrintHello, (void *)t)
- ☒ pthread_create(&threads[t], NULL, PrintHello, (void *)t)
- ☐ pthread_create(&threads[t], NULL, *PrintHello, (void *)t)
- ☐ pthread_create(threads[t], NULL, &PrintHello, (void *)t)

Question 5 2 / 2

TODO 4: What is the correct way of exiting the main thread?

- ☒ Calling pthread_exit with any argument (e.g. NULL) as the value is not used
- ☐ Calling pthread_exit with the thread name (string) as an argument
- ☐ Just returning from the function is enough
- ☐ Using break

Question 6 2 / 2

In what order will the 5 launched threads print out their IDs to stdout?

- ☐ 1 > 2 > 3 > 4 > 5
- ☐ 5 > 4 > 3 > 2 > 1
- ☐ Only the first thread that gets a handle of stdio will print its ID out
- ☒ The order is non-deterministic

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1. More on PThreads

Question 1 2 / 2

How many critical sections are in the `hello_mutex` function?

- ☐ 0
- ☒ 1
- ☐ 2
- ☐ 3

Question 2 2 / 2

What will happen if the values of the constants `NUM_THREADS` and `NUM_ROUNDS` are swapped?

- ☒ There will be more contention for the `shared_variable`
- ☒ More threads will take part in fewer rounds
- ☐ More rounds will take place
- ☐ The `shared_variable` will be updated with higher values

Question 3 1 / 1

TODO 5: Which pair of functions will guarantee the shared variable is not accessed by more than 1 thread at the same time?

- ☐ `lock(0)` & `unlock(0)`
- ☐ `pthread_mutex_lock(PTHREAD_MUTEX_INITIALIZER)` & `pthread_mutex_unlock(PTHREAD_MUTEX_INITIALIZER)`
- ☒ `pthread_mutex_lock(mutex_object)` & `pthread_mutex_unlock(mutex_object)`
- ☐ `pthread_lock()` & `pthread_release()`

Question 4 2 / 2

TODO 6: What is true about waiting on the conditional variable?

- ☒ When the wait succeeds, the mutex will be acquired by the calling thread
- ☐ The wait is a non-blocking call
- ☒ The mutex object must already have been acquired by the calling thread when it enters the conditional wait
- ☐ The mutex object does not need to have been acquired by the calling thread when it enters the conditional wait, as it will be acquired after the wait succeeds

Question 5 2 / 2

TODO 7: What is true about signalling the conditional variable?

- ☐ It will always unblock all other threads waiting on the variable
- ☒ It is a non-blocking call
- ☐ It will block the calling thread if no other thread is waiting on the conditional variable

Question 6 1 / 1

TODO 8: Which pair of functions will guarantee semaphore-based coordination between threads calling `hello_semaphore`?

- ☒ `sem_wait(semaphore)` & `sem_post(semaphore)`
- ☐ `pthread_mutex_lock(semaphore)` & `pthread_mutex_release(semaphore)`
- ☐ `semaphore.lock()` & `semaphore.unlock()`

Question 7 2 / 2

TODO 9: What is true about initialising the semaphores and conditional variables?

- ☒ It is sufficient to initialise the semaphores as only shared between threads of this process
- ☒ To ensure all threads will wait until explicitly signalled, the initial values of the semaphores should be 0
- ☒ Initialising the conditional variable successfully will return 0

Question 8 2 / 2

TODO 10: What is the correct way of starting the first thread waiting on the semaphore?

- ☐ sem_post(-1)
- ☐ sem_post(semaphores[0])
- ☒ sem_post(&semaphores[0])
- ☐ sem_post(&semaphores[1])

Question 9 2 / 2

TODO 11: What is true about running the code with the mutex method of synchronisation compared to semaphore?

- ☒ The printed output of the program will be the same in both cases, except for the Hello World messages
- ☐ In the semaphore case, threads will not be updating the shared_variable in a deterministic order
- ☒ In the mutex case, the shared_variable will be updated up to the value of 49
- ☒ In both cases, all threads will set the shared_variable in all rounds