



Aalto University

MS-C1350 Partial differential equations

Chapter 1 – Introduction

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Official learning outcomes

- ▶ how to solve partial differential equations using separation of variables and Fourier techniques
- ▶ the physical interpretations of the equations
- ▶ the equations in the spherical and cylindrical coordinates
- ▶ the role of the fundamental solutions
- ▶ the maximum and comparison principles
- ▶ the variational forms of the equations.

Goal: to have more detailed learning goals biweekly this fall (work in progress → also already published parts might be edited during the fall)

What we will do in this course

- ▶ We study three prototype equations: Laplace, heat and wave equation.
- ▶ First, we learn how to solve PDEs using Fourier series and Fourier transform.
- ▶ In the second part, we study each of the three equations one-by-one in more detail.
- ▶ We learn techniques that are useful in the study of also more general equations.

Lecture 1

- ▶ What is a PDE?
- ▶ What is a solution to PDE?
- ▶ Well posed problem.
- ▶ Function spaces C , C_0 , C^k and C^∞ . Difference of $C((0, 1))$ and $C([0, 1])$?
- ▶ Introduction to Fourier series:
 - ▶ periodic functions,
 - ▶ L^p (and especially L^2) functions,
 - ▶ (complex) inner product, orthonormal basis and representing an element of a vector space using a basis.

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- ▶ In this course, we study special cases, in which explicit solutions and representation formulas are available, but focus on features that are present also in more general situations.
- ▶ Qualitative aspects are also important in numerical solutions of PDE. Without **existence, uniqueness and stability**, numerical methods may give inaccurate or completely wrong solutions.

Introduction – types of equations

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There are also PDEs that are in none of the above classes.

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A PDE problem is **well posed**, if

1. **EXISTENCE**: the problem has a solution,
2. **UNIQUENESS**: there exists only one solution and
3. **STABILITY**: the solution depends continuously on the data given in the problem.

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⇒ We can verify by direct computation that a function solves the PDE.
- ▶ Weak solution: less regularity, e.g. saw tooth wave.

Many PDEs do not have any classical solutions, but some type of weak solutions might be physically meaningful.