

CS-E3190 Principles of Algorithmic Techniques

06. Randomized Algorithms – Tutorial Exercise

1. **Revisiting Quicksort.** In the lectures we proved that paranoid Quicksort has an expected runtime of $O(n \log n)$. Here we prove that the runtime is $O(n \log^2 n)$ *with high probability*. Let us recap what paranoid Quicksort does. Recall that A is an array of n *unique* integer elements and l, r are indices of A . We call an index p of A a pivot. Given a pair A, p we can *partition* A on p such that all elements of A smaller than $A[p]$ are put to the left of p , and all elements of A larger than $A[p]$ are to the right of p . A pivot p (and the corresponding partition) is called *good* if at least $|A|/10$ elements are larger and at least $|A|/10$ are smaller than $A[p]$, or $|A| < 10$. The algorithms are shown below.

Algorithm 1: QUICKSORT(A, l, r)

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if  $l \geq r$  then
  return  $A$ ;
repeat
  Randomly select  $p$  in  $\{l, \dots, r\}$ ;
  PARTITION( $A[l, r], p$ )
until PARTITION( $A[l, r], p$ ) is good;
QUICKSORT( $A, l, p - 1$ )
QUICKSORT( $A, p + 1, r$ )
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Algorithm 2: PARTITION(A, p)

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SWAP( $A[0], A[p]$ )
 $i \leftarrow 1$ 
for  $j = i, i + 1, \dots$  do
  if  $A[j] < A[0]$  then
    SWAP( $A[i], A[j]$ );
     $i \leftarrow i + 1$ ;
end
SWAP( $A[i - 1], A[0]$ )
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Let $T(k)$ be the randomized runtime of QUICKSORT($A, 0, k - 1$) on array A of length k . Define a new random variable $N(k)$ as the number of partition-calls during one call of Quicksort on array A of size k ; $N(k)$ does not include the time of recursive calls. Because the runtime of one Partition call on array A of size k takes $O(k)$ time, we have

$$T(k) \leq T(k - i) + T(i) + O(k) \cdot N(k)$$

for any i . In the lectures we studied the expectation of $T(n)$ and used $\mathbb{E}[N(n)] \leq 2$ to prove that $\mathbb{E}[T(n)] = O(n \log n)$. To prove the high probability result we want to bound $N(n)$ with high probability, as opposed to bounding its expectation.

- (a) Consider the nodes of the recursion tree of the algorithm. Each node is associated with one Quicksort call. Take any node i in the tree. Let k_i be the size of the subarray of A at i . Say the node i is *bad* if $N(k_i) > 3 \log n$. Recall that $N(k_i)$ is the number of partition-calls during one call of Quicksort on an array of size k_i . Prove that the probability of node i being bad satisfies the following bound.

$$\mathbb{P}[\text{node } i \text{ is bad}] \leq (2/5)^{3 \log n}.$$

Solution. First, note that if the number of elements in the subarray A at node i is $k_i < 10$ the bound is trivially true; when $k_i < 10$ any pivot is good, so only one Partition call is made and the probability of i being bad is 0. Suppose now that $k_i \geq 10$. The probability of picking a good pivot is bounded by

$$\mathbb{P}[p \text{ is good}] \geq 6/10 = 3/5.$$

To see this, consider $k_i = 11$. There are only 7/11 entries that give good pivots¹. The probability is never lower than this; we use a conservative bound of 3/5.

¹This is a technical detail. The reason we do not use 4/5 is that $|A|$ is not generally divisible by 10. To ensure that at least $|A|/10$ elements are larger than $A[p]$ we may need to round the value $|A|/10$ up. We can lose up to two elements to rounding.

Thus the probability of choosing a bad pivot is at most $1 - 3/5 = 2/5$. Each successive choice of pivot is independent. To observe t or more attempts one must pick a bad pivot t times in a row. This occurs with probability

$$\begin{aligned} P[N(k) > t] &= P[(1^{st} \text{ pivot bad}) \cap (2^{nd} \text{ pivot bad}) \cap \dots \cap (t^{th} \text{ pivot bad})] \\ &= \prod_{j=1}^t P[(j^{th} \text{ pivot bad})] \leq (2/5)^t \end{aligned}$$

The second equality follows from independence, and the inequality from our bound. You can also argue the random variable $N(k)$ follows a geometric distribution. Finally, plugging in $3 \log n$ for t gives the desired bound.

- (b) Observe that there are at most $n \log n$ nodes in the recursion tree (note that this is a very loose bound). Prove that

$$P[\text{at least one node is bad}] \leq n \log n \cdot (2/5)^{3 \log n}.$$

Solution. We can use the union bound and part (a). Let M be the number of nodes.

$$\begin{aligned} P[\text{at least one node is bad}] &= P\left[\bigcup_{i=1}^M (i^{th} \text{ node is bad})\right] \\ &\leq \sum_{i=1}^M P[(i^{th} \text{ node is bad})] \\ &\leq M(2/5)^{3 \log n} = n \log n \cdot (2/5)^{3 \log n}. \end{aligned}$$

Note that the union bound here is particularly useful because we do not know whether events $(i^{th} \text{ node is bad})$ and $(j^{th} \text{ node is bad})$ are independent.

- (c) Prove that the probability of having no bad nodes is at least $1 - n^{-1}$.

Solution. We can use what we derived in part (b).

$$\begin{aligned} P[\text{no nodes are bad}] &= 1 - P[\text{at least one node is bad}] \\ &= 1 - n \log n \cdot (2/5)^{3 \log n} \\ &\geq 1 - n \log n \cdot (1/2)^{3 \log n} \\ &= 1 - n \log n \cdot n^{-3} \\ &\geq 1 - n^{-1}, \end{aligned}$$

where the last inequality follows from $n \geq \log n$, where we assume $n > 1$.

- (d) Explain why we have a runtime of $O(n \log^2 n)$ with high probability.

Solution. We have established in part (c) that with high probability, no nodes are bad and hence $N(k_i) = 3 \log k_i = O(\log n)$ for an array of size k_i . So the cost per recursion level is $O(n) \cdot O(\log n) = O(n \log n)$. Since the recursion tree depth is $O(\log n)$, the total cost is $O(\log n) \cdot O(n \log n) = O(n \log^2 n)$ with high probability.

2. **Partitioning, Union Bound.** Consider partitioning the vertex set of a tree $T = (V, E)$ into two sets V_1 and V_2 (i.e., $V = V_1 \cup V_2$ and $V_1 \cap V_2 = \emptyset$) such that each vertex belongs to either V_1 or V_2 with a probability of $1/2$, independently of the other vertices. Let $T[V_1]$ and $T[V_2]$ denote the subgraphs induced by node sets V_1 and V_2 respectively. Show that the partitioning leads to each connected component of $T[V_1]$ and $T[V_2]$ having a diameter of $O(\log n)$, with high probability.

Solution. Each path of length $\omega(\log n)$ is present in $T[V_1]$ or $T[V_2]$ with probability $1/2^{\omega(\log n)}$, which is less than $1/\text{poly}(n)$. As there are at most $O(n^2)$ distinct paths in the tree, we can union bound over all of them and conclude that no path of length $\omega(\log n)$ will be present in $T[V_1]$ or $T[V_2]$, with probability $1 - O(n^2)/\text{poly}(n) = 1 - 1/\text{poly}(n)$. This is equivalent to each connected component of $T[V_1]$ and $T[V_2]$ having a diameter of $O(\log n)$, with high probability.