



Aalto University  
School of Engineering

# MEC-E1070

# Selection of Engineering Materials

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# Learning objectives for this Lecture

## ***Knowledge and Understanding***

Understanding of the concept of **shape efficiency**

## ***Skills and Abilities***

Ability to select efficient **material-shape combinations**

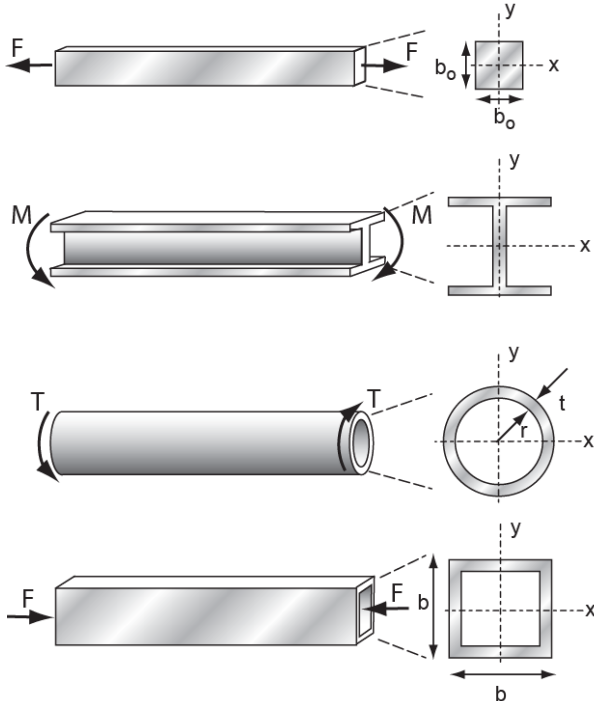
## ***Values and Attitudes***

Awareness of how materials and shape interact

## **Resources**

- Text: “***Materials: engineering, science, processing and design***” 4<sup>th</sup> edition by M.F. Ashby, H.R. Shercliff and D. Cebon, Butterworth Heinemann, Oxford, 2011, Chapters 9-10.

# Outline of Lecture



- Efficient shapes: tubes, I-beams etc
- The shape factor and shape limits
- Material indices that include shape
- Graphical ways of dealing with shape

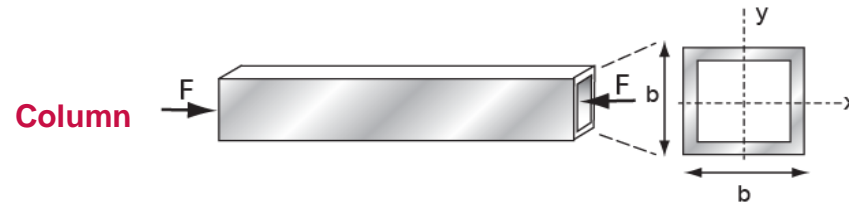
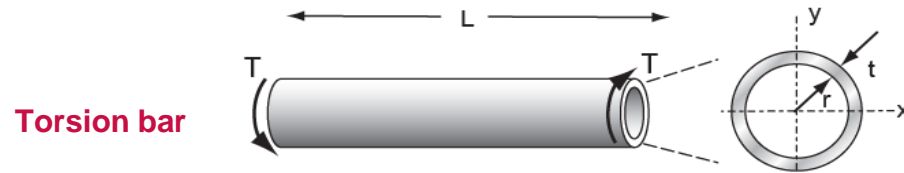
# Shape efficiency

- When materials are loaded in bending, in torsion, or are used as slender columns, section shape becomes important
- "Shape" = cross section formed to a
  - tubes
  - I-sections
  - hollow box-section
  - sandwich panels
  - ribbed panels
- "Efficient" = use least material for given stiffness or strength
- Shapes to which a material can be formed are limited by the material itself
- Goals: understand the limits to shape develop methods for co-selecting material and shape



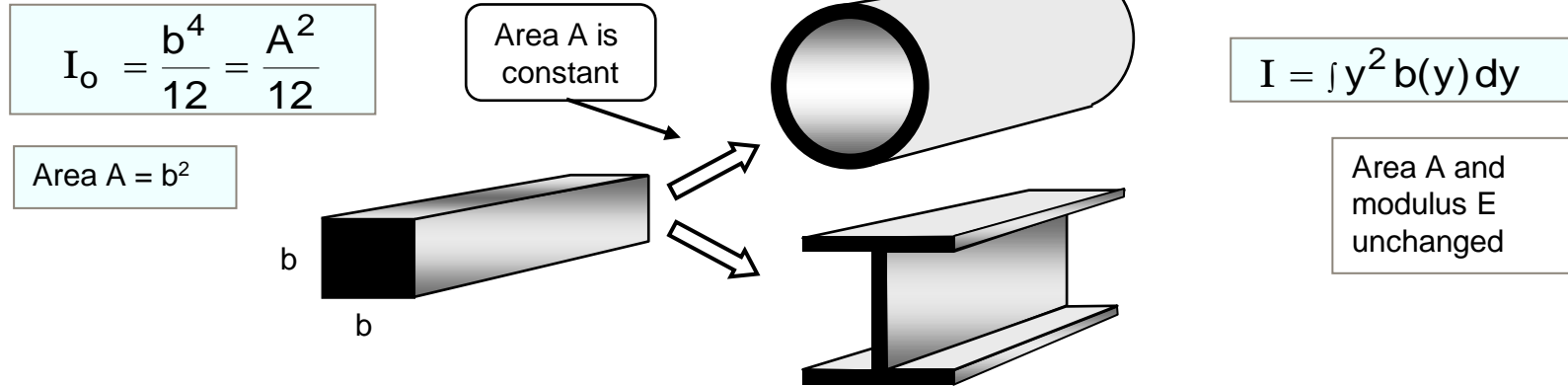
# Shape and mode of loading

## Standard structural members



# Shape efficiency: bending stiffness

- Take ratio of bending stiffness  $S$  of shaped section to that ( $S_o$ ) of a neutral reference section of the same cross-section area
- Define a standard reference section: a solid square with area  $A = b^2$
- Second moment of area is  $I$ ; stiffness scales as  $EI$ .

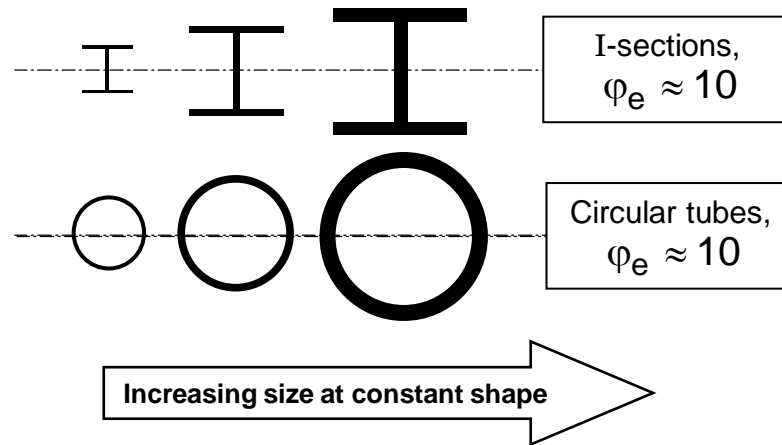


- Define **shape factor for elastic bending**, measuring efficiency, as

$$\varphi_e = \frac{S}{S_o} = \frac{EI}{EI_o} = 12 \frac{I}{A^2}$$

# Properties of the shape factor

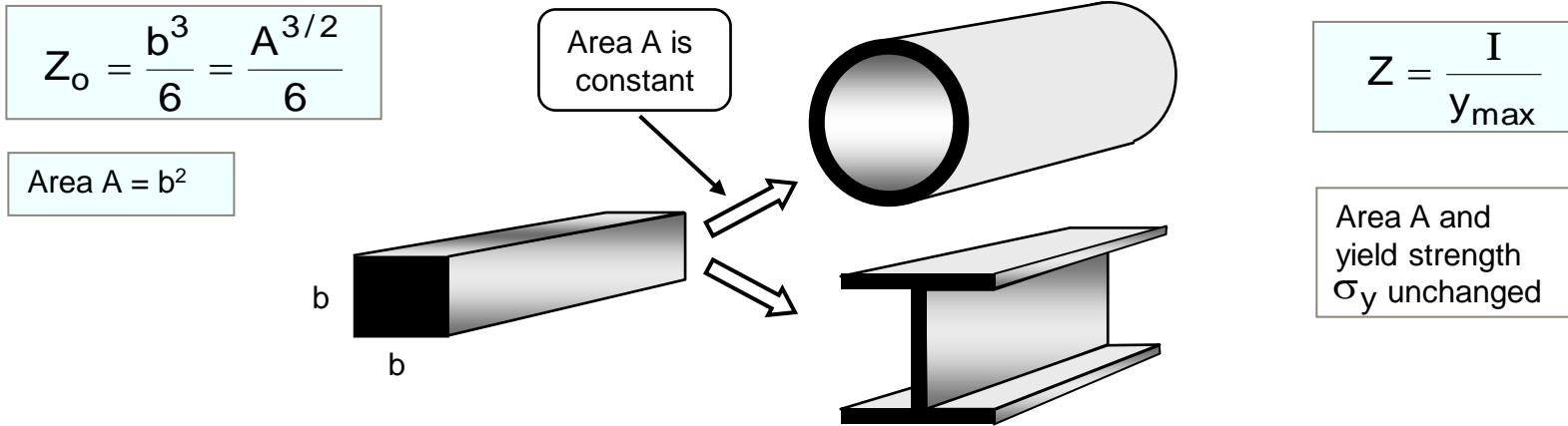
- The shape factor is dimensionless – a pure number.
- It characterizes shape.



- Each of these is roughly 10 times stiffer in bending than a solid square section of the same cross-sectional area

# Shape efficiency: bending strength

- Take ratio of bending strength  $F_f$  of shaped section to that ( $F_{f,o}$ ) of a neutral reference section of the same cross-section area
- Section modulus of area is  $Z$ ; strength scales as  $\sigma_y Z$



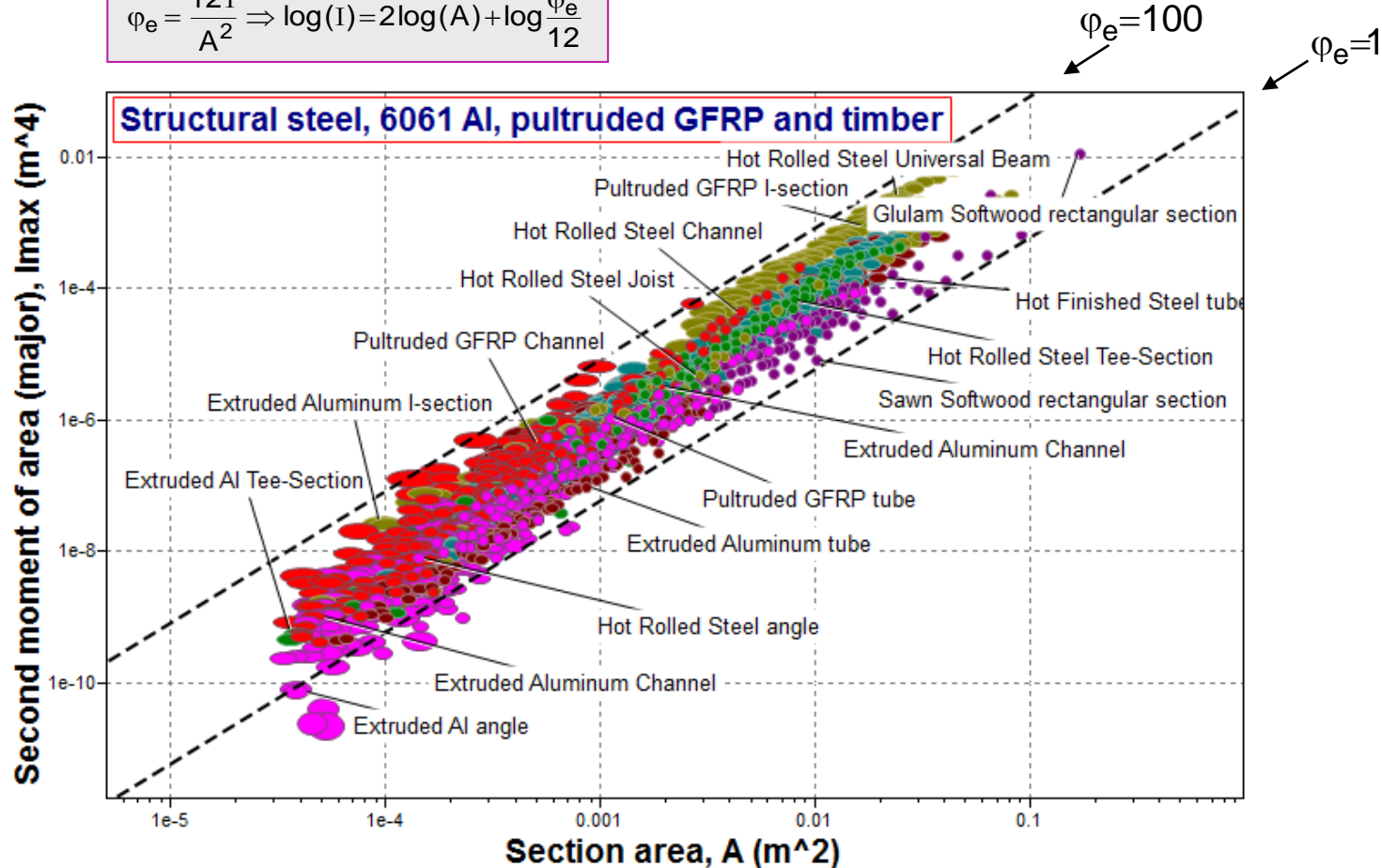
- Define **shape factor for onset of plasticity (failure)**, measuring efficiency, as

$$\varphi_f = \frac{F_f}{F_{fo}} = \frac{\sigma_y Z}{\sigma_y Z_o} = 6 \frac{Z}{A^{3/2}}$$



# What values of $\varphi_e$ exist in reality?

$$\varphi_e = \frac{12I}{A^2} \Rightarrow \log(I) = 2\log(A) + \log \frac{\varphi_e}{12}$$



# Limits for Shape Factors $\varphi_e$ and $\varphi_f$

- There is an upper limit to shape factor for each material

Material	Max $\varphi_e$	Max $\varphi_f$
Steels	65	13
Aluminum alloys	44	10
GFRP and CFRP	39	9
Unreinforced polymers	12	5
Woods	8	3
Elastomers	<6	-
Other materials	...can calculate	

- Limit set by: (a) manufacturing constraints  
(b) local buckling

- Theoretical limit:

$$\varphi_e \approx 2 \sqrt{\frac{E}{\sigma_y}}$$

Modulus

Yield strength

# Indices that include shape

Function *Beam* (shaped section).

Constraint *Bending stiffness = S:*

$$S = \frac{CEI}{L^3}$$

*I* is the second moment of area:

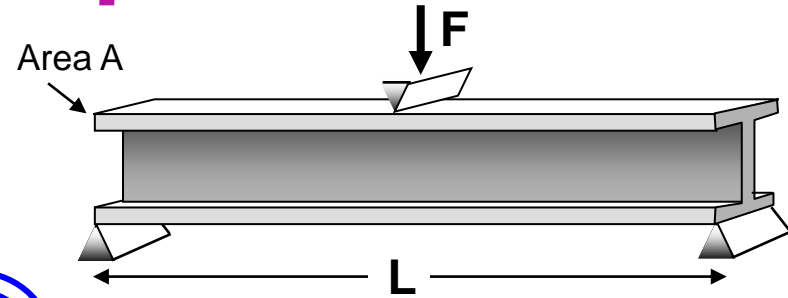
$$\varphi_e = 12 \frac{I}{A^2} \quad A = \left( \frac{12I}{\varphi_e} \right)^{1/2}$$

Objective *Minimise mass, m, where:*

$$m = AL\rho$$



$$m = \left( \frac{12 S L^5}{C} \right)^{1/2} \left( \frac{\rho}{(\varphi_e E)^{1/2}} \right)$$



m = mass  
A = area  
L = length  
 $\rho$  = density  
b = edge length  
S = stiffness  
I = second moment of area  
E = Young's Modulus

Chose materials with smallest  $\left( \frac{\rho}{(\varphi_e E)^{1/2}} \right)$

# Selecting material-shape combinations

Materials for stiff, *shaped* beams of minimum weight

- Fixed shape ( $\varphi_e$  fixed): choose materials with low  $\frac{\rho}{E^{1/2}}$
- Shape  $\varphi_e$  a variable: choose materials with low  $\frac{\rho}{(\varphi_e E)^{1/2}}$

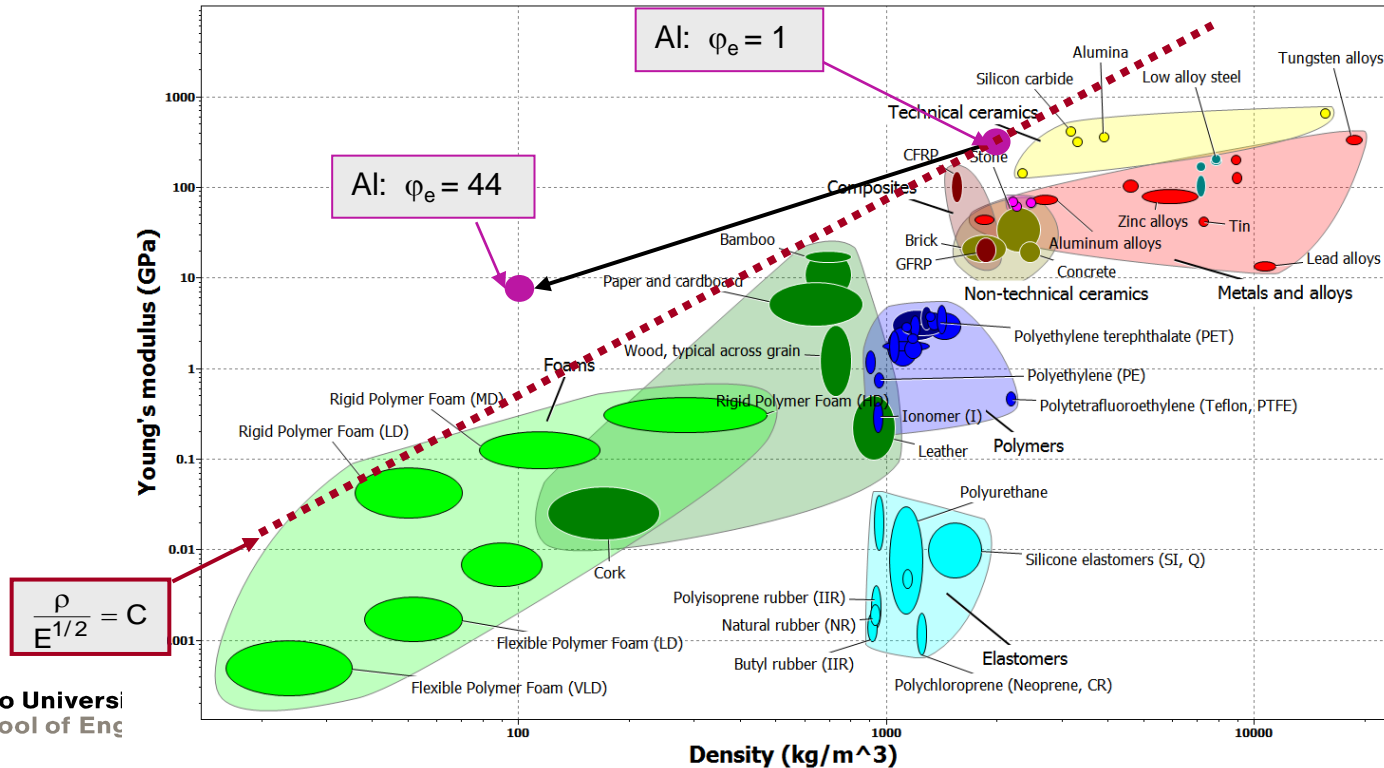
Material	$\rho$ , Mg/m <sup>3</sup>	E, GPa	$\varphi_{e,\max}$	$\rho/E^{1/2}$	$\rho/(\varphi_{e,\max} E)^{1/2}$
1020 Steel	7.85	205	65	0.55	0.068
6061 T4 Al	2.70	70	44	0.32	0.049
GFRP	1.75	28	39	0.35	0.053
Wood (oak)	0.9	13	8	0.25	0.088

- Commentary: Fixed shape (up to  $\varphi_e = 8$ ): wood is best  
Maximum shape ( $\varphi_e = \varphi_{e,\max}$ ): Al-alloy is best  
Steel recovers some performance through high  $\varphi_{e,\max}$



# Shape on selection charts

- Note that  $\frac{\rho}{(\varphi_e E)^{1/2}} = \frac{\rho/\varphi_e}{(E/\varphi_e)^{1/2}}$  New material with  $\begin{cases} \rho^* = \rho/\varphi_e \\ E^* = E/\varphi_e \end{cases}$



# Remarks

- When materials carry bending, torsion or axial compression, the section shape becomes important.
- The “shape efficiency” is the amount of material needed to carry the load. It is measured by the shape factor,  $\phi$ .
- If two materials have the *same* shape, the standard indices for bending (e.g.  $\rho/E^{1/2}$  ) guide the choice.
- If materials can be made -- or are available -- in different shapes, then indices which include the shape (e.g.  $\rho/(\phi E)^{1/2}$  ) guide the choice.