



Aalto University
School of Science

CS-C2160 Theory of Computation

Lecture 11: Rice's Theorem, General Grammars

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Topics:

- Rice's Theorem
- Unrestricted grammars
- ... and their relationship to Turing machines
- Context-sensitive grammars
- * A glimpse beyond: Computational complexity

Recap

- *Church–Turing thesis*: Intuitive notion of algorithms \equiv Turing machines.
- Formal language \equiv Yes/No decision problem.
- A language is semi-decidable (also called recursively enumerable) if it can be recognised by some Turing machine.
- A language is decidable (also called recursive) if it can be recognised by some machine that halts on all inputs.
- A language is undecidable if it is not decidable.
- An undecidable language may still be semi-decidable.

- The “acceptance” decision problem for Turing machines is
*Given a Turing machine M and a string w .
Does M accept w ?*
- The formal language representing this is the universal language

$$U = \{c_M w \mid M \text{ is a TM and } M \text{ accepts } w\}.$$

- The language U is semi-decidable but not decidable.

Rice's Theorem

11.1 Rice's theorem

- Rice's Theorem states that *all* decision problems concerning the languages recognised by Turing machines¹ are undecidable.
- Let us denote the family of all semi-decidable (i.e. recursively enumerable) languages by **RE**.
- A *semantic property*² **S** of Turing machines is any family of semi-decidable languages, i.e. $\mathbf{S} \subseteq \mathbf{RE}$.
- A machine M *has property S* if $\mathcal{L}(M) \in \mathbf{S}$.
- Examples of semantic properties:
 - ▶ **NE** = $\{L \subseteq \{0,1\}^* \mid L \neq \emptyset\}$
 - ▶ **ALLSTRINGS** = $\{L \subseteq \{0,1\}^* \mid L = \{0,1\}^*\} = \{\{0,1\}^*\}$
 - ▶ **EVEN** = $\{L \subseteq \{0,1\}^* \mid |x| \text{ is even for all } x \in L\}$
 - ▶ **ONLY_w** = $\{L \subseteq \{0,1\}^* \mid x \in L \Leftrightarrow x = w\} = \{\{w\}\}$
 - ▶ **EMPTYSET** = $\{L \subseteq \{0,1\}^* \mid L = \emptyset\} = \{\emptyset\}$

¹i.e. the input-output behaviours of computer programs

²or “specification”

- A semantic property is *trivial* if
 - ▶ $S = \emptyset$ (no machine has this property) or
 - ▶ $S = \mathbf{RE}$ (all machines have this property)

- A property S is *decidable* if the language

$$\text{codes}(S) = \{c_M \mid M \text{ is a Turing machine and } \mathcal{L}(M) \in S\}$$

is decidable.

- In other words: A semantic property is decidable if one can algorithmically decide whether a given Turing machine has the property.³

Theorem 11.1 (Rice 1953)

All non-trivial semantic properties of Turing machines are undecidable.

³equivalently “a given computer program matches the specification”

Example:

- Let us consider the *non-emptiness problem* for Turing machines from Lecture 10:

Given a Turing machine M .

Does the machine accept any strings?

- The corresponding semantic property is $\mathbf{NE} = \{L \in \mathbf{RE} \mid L \neq \emptyset\}$.
- The property is non-trivial because:
 - ▶ $\mathbf{NE} \neq \emptyset$ (witness any semi-decidable language $L \neq \emptyset$)
 - ▶ $\mathbf{NE} \subsetneq \mathbf{RE}$ (since $\emptyset \in \mathbf{RE} \setminus \mathbf{NE}$)
- Thus by Rice's theorem, the language

$$\begin{aligned}\text{codes}(\mathbf{NE}) &= \{c_M \mid M \text{ is a Turing machine and } \mathcal{L}(M) \in \mathbf{NE}\} \\ &= \{c_M \mid M \text{ is a Turing machine and } \mathcal{L}(M) \neq \emptyset\}\end{aligned}$$

is undecidable. (Note that this is precisely the result in Lemma 10.5.)

Theorem 11.1

All non-trivial semantic properties of Turing machines are undecidable.

Proof

- A simple generalisation of the proof of Lemma 10.5.
- Let S be any non-trivial semantic property.
- We can assume that $\emptyset \notin S$; in other words, machines that recognise the empty language do not have the property.^a
- As S is non-trivial, there is a Turing machine M_S that has the property S , i.e. one for which $\mathcal{L}(M_S) \neq \emptyset$ and $\mathcal{L}(M_S) \in S$ hold.

^aIf $\emptyset \in S$, we can first show that the property $\tilde{S} = \mathbf{RE} \setminus S$ is undecidable and then conclude that also S is undecidable; this is because $\text{codes}(\tilde{S}) = \{0, 1\}^* \setminus \text{codes}(S)$.

- We now prove that $\text{codes}(\mathbf{S})$ is undecidable by reducing the undecidable language U to it.
- Let (M, w) be any instance of the Turing machine acceptance problem, encoded as the string $c_M w$.
- From input $c_M w$ construct (the code for) a Turing machine M^w that on any input string x works as follows:
 - ▶ First run machine M on string w , and then:
 - if M accepts w , run M_S on x
 - if M rejects w (or doesn't halt), reject x (or don't halt)
- Now M^w recognises the language

$$\mathcal{L}(M^w) = \begin{cases} \mathcal{L}(M_S) & \text{if } w \in \mathcal{L}(M) \\ \emptyset & \text{if } w \notin \mathcal{L}(M) \end{cases}$$

- Thus M accepts w if and only if M^w has the property \mathbf{S} .
That is, $c_M w \in U$ if and only if $c_{M^w} \in \text{codes}(\mathbf{S})$.
- Therefore, $\text{codes}(\mathbf{S})$ is an undecidable language.

General Grammars



11.2 Unrestricted grammars

- A generalisation of context-free grammars.
- The left-hand sides of rules can now include multiple symbols.
- As will be shown, can generate all semi-decidable languages.

Definition 11.1

An *unrestricted grammar* is a quadruple

$$G = (V, \Sigma, R, S),$$

where

- V is a finite set of *variables*;
- Σ is a finite set, disjoint from V , of *terminals*;
- $R \subseteq (V \cup \Sigma)^+ \times (V \cup \Sigma)^*$ is a finite set of *rules* (also called productions), where $(V \cup \Sigma)^+ = (V \cup \Sigma)^* \setminus \{\epsilon\}$;
- $S \in V$ is the *start variable*.

A rule $(\omega, \omega') \in R$ is usually written as $\omega \rightarrow \omega'$.

- A string $\gamma \in (V \cup \Sigma)^*$ *yields* a string $\gamma' \in (V \cup \Sigma)^*$ in the grammar G , denoted by

$$\gamma \Rightarrow_G \gamma'$$

if

- ▶ the grammar contains a rule $\omega \rightarrow \omega'$ such that $\gamma = \alpha\omega\beta$ and $\gamma' = \alpha\omega'\beta$ for some $\alpha, \beta \in (V \cup \Sigma)^*$.

- A string $\gamma \in (V \cup \Sigma)^*$ *derives* a string $\gamma' \in (V \cup \Sigma)^*$ in the grammar G , denoted by

$$\gamma \Rightarrow_G^* \gamma'$$

if there is a sequence of strings $\gamma_0, \gamma_1, \dots, \gamma_n$ for some $n \geq 0$ such that

$$\gamma = \gamma_0, \quad \gamma_0 \Rightarrow_G \gamma_1 \Rightarrow_G \dots \Rightarrow_G \gamma_n, \quad \gamma_n = \gamma'.$$

- If the grammar G is clear from the context, we can simply write $\gamma \Rightarrow \gamma'$ and $\gamma \Rightarrow^* \gamma'$ instead of $\gamma \Rightarrow_G \gamma'$ and $\gamma \Rightarrow_G^* \gamma'$, respectively.

Example:

An unrestricted grammar for the non-context-free language $\{a^k b^k c^k \mid k \geq 0\}$:

$$S \rightarrow LT \mid \varepsilon$$

$$T \rightarrow ABCT \mid ABC$$

$$BA \rightarrow AB$$

$$CB \rightarrow BC$$

$$CA \rightarrow AC$$

$$LA \rightarrow a$$

$$aA \rightarrow aa$$

$$aB \rightarrow ab$$

$$bB \rightarrow bb$$

$$bC \rightarrow bc$$

$$cC \rightarrow cc$$

A derivation of string $aabbcc$ in the grammar:

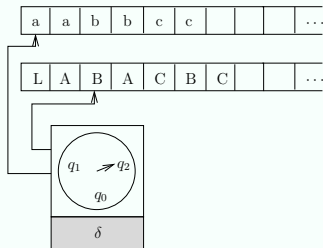
$$\begin{aligned} \underline{S} &\Rightarrow \underline{LT} \Rightarrow \underline{LABCT} \Rightarrow \underline{LABCABC} \Rightarrow \underline{LABACBC} \\ &\Rightarrow \underline{LAABCBC} \Rightarrow \underline{LAABBCC} \Rightarrow \underline{aABBCC} \\ &\Rightarrow \underline{aaBBCC} \Rightarrow \underline{aabBCC} \Rightarrow \underline{aabbCC} \\ &\Rightarrow \underline{aabbcC} \Rightarrow aabbcc \end{aligned}$$

Theorem 11.2

If a language L can be generated with an unrestricted grammar, then it can be recognised with a Turing machine.

Proof

Let $G = (V, \Sigma, R, S)$ be an unrestricted grammar generating language L . We can design a two-tape nondeterministic Turing machine M_G recognising L as follows:



- On tape 1 the machine stores a copy of the input string.
- Tape 2 holds the current string that the machine tries to rewrite to match the one on tape 1.
- In the beginning, the machine writes the start variable S on tape 2.

The computation of machine M_G is composed of stages. In each stage, the machine:

1. Moves the read/write-head of tape 2 *nondeterministically* to *some* position on the tape.
2. Chooses *nondeterministically* a rule in G that it tries to apply at the selected position. (The rules of G are encoded in the transitions of M_G .)
3. If the left-hand side of the chosen rule matches the symbols on the tape, M_G rewrites these symbols with the ones in the right-hand side of the rule. Otherwise M_G rejects.
4. At the end of the stage, M_G compares the strings on tapes 1 and 2. If they are the same, the machine accepts and halts. Otherwise, the machine executes the next stage (loops back to step 1).

Theorem 11.3

If a language L can be recognised with a Turing machine, then it can be generated with an unrestricted grammar.

Proof

Let $M = (Q, \Sigma, \Gamma, \delta, q_0, q_{\text{acc}}, q_{\text{rej}})$ be a (deterministic one-tape) Turing machine recognising language L . We can design an unrestricted grammar G_M generating L based on the following idea.

- The variables of G_M include (among others) symbols for all the states $q \in Q$ of M .
- A configuration $(q, u\underline{a}v)$ of M will be represented as a string $[uqav]$.
- Based on the transitions of M , G_M will have rules that ensure $[uqav] \xRightarrow{G_M} [u'q'a'v']$ if and only if $(q, u\underline{a}v) \vdash_M (q', u'\underline{a}'v')$.
- Thus M accepts the input x if and only if for some $u, v \in \Sigma^*$:

$$[q_0x] \xRightarrow{G_M}^* [uq_{\text{acc}}v]$$

The rules in G_M comprise three types:

1. Rules with which one can derive from the start variable S any string of form $x[q_0x]$, where $x \in \Sigma^*$ and $'[', 'q_0'$ and $']'$ are variables in G_M .
2. Rules that allow one to derive from the string $[q_0x]$ a string $[uq_{\text{acc}}v]$ if and only if M accepts x .
3. Rules that enable one to rewrite any string of form $[uq_{\text{acc}}v]$ to the empty string.

Deriving a string $x \in \mathcal{L}(M)$ can then be done as follows:

$$S \xRightarrow{(1)} x[q_0x] \xRightarrow{(2)} x[uq_{\text{acc}}v] \xRightarrow{(3)} x$$

Let us thus define the grammar $G = (V, \Sigma, R, S)$, where

$$V = (\Gamma \setminus \Sigma) \cup Q \cup \{S, T, [,], E_L, E_R\} \cup \{X_a \mid a \in \Sigma\}$$

and the rules in R include the following three sets:

1. Producing the initial configuration string:

$$\begin{array}{lll} S & \rightarrow & T[q_0] \\ T & \rightarrow & \epsilon \\ T & \rightarrow & aTX_a \quad (a \in \Sigma) \\ X_a[q_0] & \rightarrow & [q_0X_a \quad (a \in \Sigma) \\ X_ab & \rightarrow & bX_a \quad (a, b \in \Sigma) \\ X_a] & \rightarrow & a] \quad (a \in \Sigma) \end{array}$$

2. Simulating the transitions of M ($a, b \in \Gamma, c \in \Gamma \cup \{ [\} \}$):

Transitions:

$$\delta(q, a) = (q', b, R)$$

$$\delta(q, a) = (q', b, L)$$

$$\delta(q, \triangleright) = (q', \triangleright, R)$$

$$\delta(q, \triangleleft) = (q', b, R)$$

$$\delta(q, \triangleleft) = (q', b, L)$$

$$\delta(q, \triangleleft) = (q', \triangleleft, L)$$

Rules:

$$qa \rightarrow bq'$$

$$cqa \rightarrow q'cb$$

$$q[\rightarrow [q'$$

$$q] \rightarrow bq']$$

$$cq] \rightarrow q'cb]$$

$$cq] \rightarrow q'c]$$

3. Erasing an accepting configuration string:

$$\begin{array}{lll} q_{\text{acc}} & \rightarrow & E_L E_R \\ q_{\text{acc}}[& \rightarrow & E_R \\ aE_L & \rightarrow & E_L \quad (a \in \Gamma) \\ [E_L & \rightarrow & \varepsilon \\ E_R a & \rightarrow & E_R \quad (a \in \Gamma) \\ E_R] & \rightarrow & \varepsilon \end{array}$$

11.3 Context-sensitive grammars

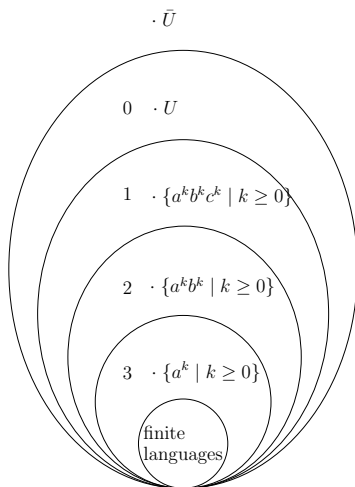
- An unrestricted grammar is *context-sensitive* if all its rules are of form $\omega \rightarrow \omega'$, where $|\omega'| \geq |\omega|$, or $S \rightarrow \epsilon$, where S is the start variable.
- In addition, it is required that if the grammar contains the rule $S \rightarrow \epsilon$, then the start variable S does not occur on the right-hand side of any rule.
- A language L is *context-sensitive* if it can be generated with some context-sensitive grammar.
- *A normal form for context-sensitive grammars:* Each context-sensitive language can be generated with a grammar whose rules are of form $S \rightarrow \epsilon$ and $\alpha A \beta \rightarrow \alpha \omega \beta$, where A is a variable and $\omega \neq \epsilon$.
- A rule $\alpha A \beta \rightarrow \alpha \omega \beta$ can be interpreted as the application of a rule $A \rightarrow \omega$ “in the context” $\alpha_ \beta$.

Theorem 11.4

A language L is context-sensitive if and only if it can be recognised with a non-deterministic Turing machine that does not use more tape space than was already allocated for the input.

- The machines in Theorem 11.4 are called *linear bounded automata*.
- It is an open problem whether the non-determinism in Theorem 11.4 is necessary or not. (The “LBA \neq DLBA” problem.)

11.4 Recap: The Chomsky hierarchy



A classification of grammars, languages generated by grammars and recogniser automata classes:

Type-0: unrestricted grammars / semi-decidable languages / Turing machines

Type-1: context-sensitive grammars / context-sensitive languages / linear bounded automata

Type-2: context-free grammars / context-free languages / pushdown automata

Type-3: right and left linear grammars / regular languages / finite automata

* A Glimpse Beyond: Computational Complexity

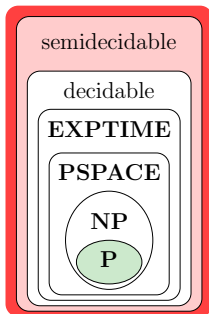
* Computational complexity

- So far: only what is decidable (solvable with computers) and what is not.
- But some problems are “more decidable than others”.
- For instance, finding a smallest element in an array is/seems much easier than solving sudokus.

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- In fact, the set of decidable problems can be divided in many smaller *complexity classes*:
- **P** — problems that can be solved in polynomial time (\approx always efficiently) with deterministic Turing machines / algorithms.
- **NP** — problems that can be solved in polynomial time with *non-deterministic Turing machines*.
- **PSPACE** — problems that can be solved with a polynomial amount of extra space (possibly in exponential time).
- **EXPTIME** — problems that can be solved in exponential time.
- and many more...

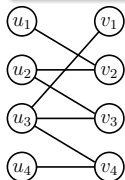


Example: a nontrivial, but efficiently solvable problem

Definition (PERFECT MATHING)

INSTANCE: Bipartite graph $B = (U, V, E)$, where $U = \{u_1, \dots, u_n\}$, $V = \{v_1, \dots, v_n\}$, and $E \subseteq U \times V$.

QUESTION: Does B have a *perfect matching*, i.e. a 1-1 pairing of vertices?

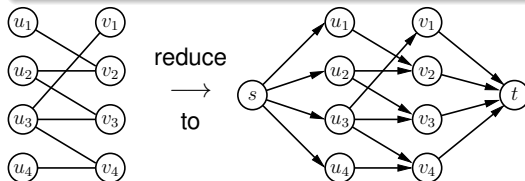


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We can solve a PERFECT MATCHING instance by

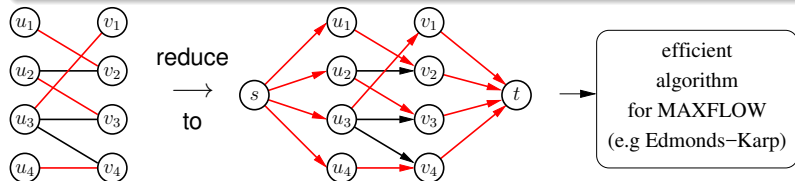
1. *Polynomial-time reducing* it to a MAXFLOW instance so that:
the MAXFLOW instance has a flow of n units if and only if
the PERFECT MATCHING instance has a perfect matching.

Example: a nontrivial, but efficiently solvable problem

Definition (PERFECT MATHING)

INSTANCE: Bipartite graph $B = (U, V, E)$, where $U = \{u_1, \dots, u_n\}$, $V = \{v_1, \dots, v_n\}$, and $E \subseteq U \times V$.

QUESTION: Does B have a *perfect matching*, i.e. a 1-1 pairing of vertices?



We can solve a PERFECT MATCHING instance by

1. *Polynomial-time reducing* it to a MAXFLOW instance so that: the MAXFLOW instance has a flow of n units if and only if the PERFECT MATCHING instance has a perfect matching.
2. Solving the resulting MAXFLOW instance.
3. The reduction is linear-time and Edmonds-Karp alg. works in $O(VE^2)$.

Example: a not-so efficiently solvable problem

Definition (propositional satisfiability, SAT)

INSTANCE: A Boolean formula ϕ in conjunctive normal form.

QUESTION: Is there a truth assignment that satisfies ϕ ?

Example

$(x) \wedge (\neg x \vee y) \wedge (\neg x \vee \neg z) \wedge (\neg x \vee \neg y \vee \neg z)$ is satisfiable
with $\{x \mapsto \mathbf{true}, y \mapsto \mathbf{true}, z \mapsto \mathbf{false}\}$.

$(x) \wedge (\neg x \vee y) \wedge (\neg x \vee \neg z) \wedge (\neg x \vee \neg y \vee z)$ is unsatisfiable.

- Even the best known SAT algorithms, with sophisticated pruning techniques can perform very badly on some instances (although they **can solve many relevant problems efficiently**).
- **No polynomial-time algorithm for SAT is known** despite several decades of effort in trying to find one.

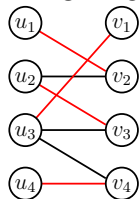
Problem class NP (Non-deterministic Polynomial time)

Two alternative ways to characterise problems in **NP**:

1. Problems that can be solved in *polynomial time* with *non-deterministic* Turing machines (\approx algorithms that can *guess perfectly*).
2. Problems whose solutions (when they exist) are
 - ▶ reasonably *small* (i.e., of polynomial size), and
 - ▶ *easy to check* (i.e., in polynomial time).

but *not necessarily easy to find* (or prove non-existent)!

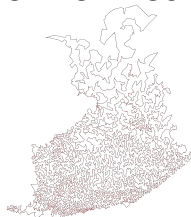
PERFECT
MATCHING



SAT

$$\begin{aligned} &(\textcolor{red}{x} \vee y \vee \neg z) \wedge \\ &(\neg x \vee \neg \textcolor{red}{y} \vee v) \wedge \\ &(\textcolor{red}{x} \vee w \vee \textcolor{red}{z}) \wedge \\ &(y \vee \neg \textcolor{red}{w} \vee \neg z) \wedge \\ &\dots \end{aligned}$$

TRAVELLING
SALESPERSON

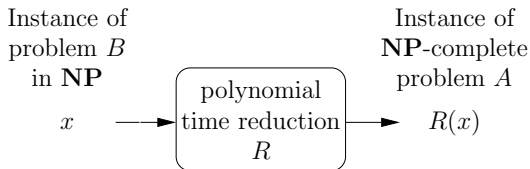


GENERALISED
SUDOKUS

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NP-complete problems

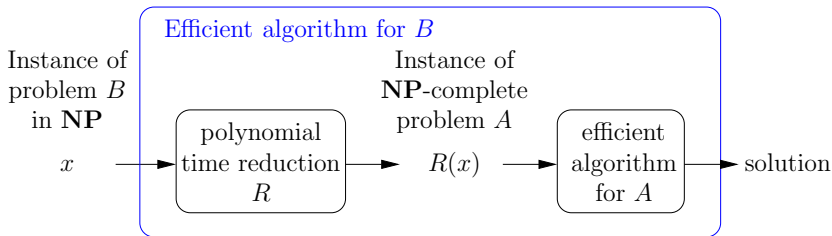
- A problem A in **NP** is **NP-complete** if *every* other problem B in **NP** can be reduced **to it** with a polynomial time computable reduction.



Property: x has a solution in B if and only if $R(x)$ has a solution in A .

NP-complete problems

- A problem A in **NP** is **NP-complete** if *every* other problem B in **NP** can be reduced *to it* with a polynomial time computable reduction.



Property: x has a solution in B if and only if $R(x)$ has a solution in A .

- 👉 If an **NP-complete** problem A can be solved in polynomial time, then *all the problems in **NP** can*.
- 👉 **NP-complete** problems are the *most difficult ones* in **NP**!
- 👉 We *do not know*(!!!) whether **NP-complete** problems can be solved efficiently or not.

The Cook–Levin theorem

Theorem (S. A. Cook 1971, L. Levin 1973)

*SAT is **NP**-complete.*



Stephen Cook (1939–)



Leonid Levin (1948–)



Richard Karp (1935–)

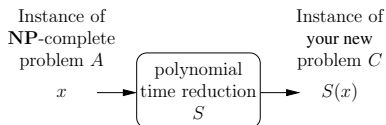
- R. Karp soon (1972) listed the next 21 **NP**-complete problems.
- Since then, 1000's of problems have been shown **NP**-complete.
- E.g. TRAVELLING SALESPERSON, GENERALISED SUDOKUS etc. are **NP**-complete.
- Classic text: Garey and Johnson (1979): *Computers and Intractability: A Guide to the Theory of NP-Completeness*.

How to prove a new problem NP-complete?

Given: a new problem C that you suspect **NP**-complete.

To prove that C is **NP**-complete:

1. show that C is in **NP**,
2. take any *existing NP-complete problem* A , and
3. reduce A *to your problem* C .

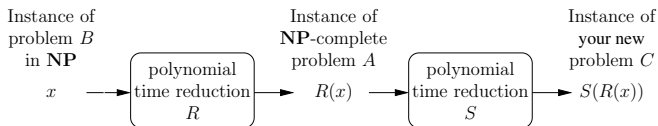


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Polynomial time reductions compose: any B in **NP** reduces to C !

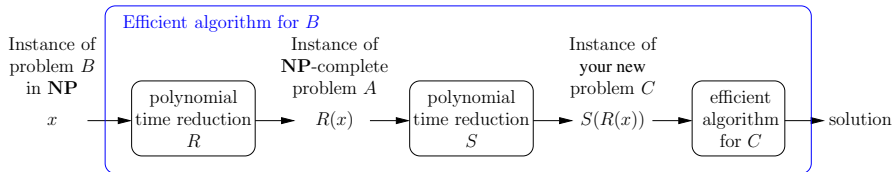
 Your problem C is **NP**-complete.

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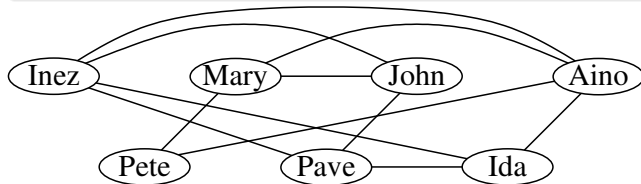
- 👉 Your problem C is **NP**-complete.
- 👉 If your problem C can be solved in polynomial time, then so can A and all the problems in **NP**.

Proving NP-completeness: an example

Definition (PARTYING WITH STRANGERS)

INSTANCE: A network of students and a positive integer K , where a network consists of (i) a finite set of students and (ii) a symmetric, binary “X knows Y” relation among them.

QUESTION: Is it possible to arrange a party with (at least) K students, none of whom know each other?



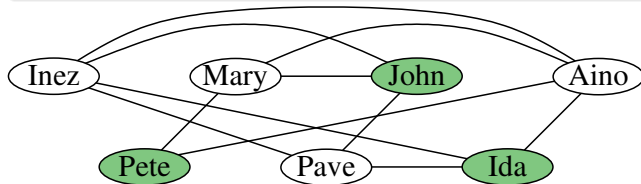
with $K = 3$?

Proving NP-completeness: an example

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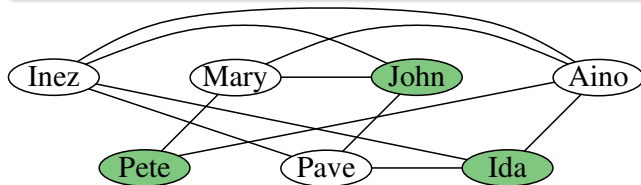
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with $K = 3$?

Definition (INDEPENDENT SET)

INSTANCE: An undirected graph $G = (V, E)$ and an integer K .

QUESTION: Is there an independent set $I \subseteq V$ with $|I| = K$?

Theorem

INDEPENDENT SET is **NP-complete**.

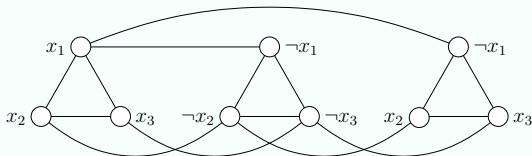
Proof

Reduction *from* 3SAT.

The SAT formula ϕ :

$$(x_1 \vee x_2 \vee x_3) \wedge \\ (\neg x_1 \vee \neg x_2 \vee \neg x_3) \wedge \\ (\neg x_1 \vee x_2 \vee x_3)$$

The corresponding graph G with $K = 3$:



1. If ϕ is satisfiable, then G has an independent set of size K .
 2. If G has an independent set of size K , then ϕ is satisfiable.
- $\Rightarrow \phi$ is satisfiable if and only if G has an independent set of size K .

☞ If we can solve **INDEPENDENT SET** efficiently, then we can solve **SAT** and all other problems in **NP** efficiently as well.

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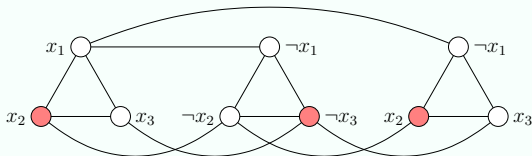
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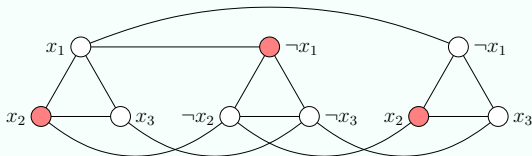
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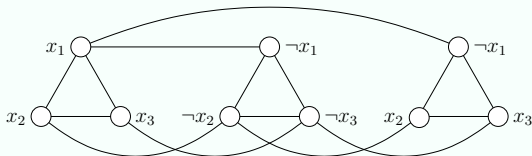
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NP-completeness: Significance

- *Can **NP**-complete problems be solved in polynomial time?*

One of the seven 1M\$ Clay Mathematics Institute Millennium Prize problems, see

<http://www.claymath.org/millennium-problems/>

- What to do when a problem is **NP**-complete?
 - ▶ Attack special cases that occur in practice
 - ▶ Develop backtracking search algorithms with efficient heuristics and pruning techniques
 - ▶ Develop approximation algorithms
 - ▶ Apply incomplete local search methods
 - ▶ ...

Some further courses:

- CS-E3190 Principles of Algorithmic Techniques
- CS-E4530 Computational Complexity Theory
- CS-E4340 Cryptography
- and so on...