

5. An SPI Device Driver for LED Strip and Accurate Delays in Linux

key words: SPI device driver, synchronous / asynchronous transfer, SPI-MOSI, hrtimer, rdtsc, ndelay / mdelay, bit banging.

Approach 1: SPI-based approach:

- Implement a SPI device driver which can accept pixel information from users and light up 16 RGB LEDs of a LED ring integrated with WS2812 drivers.
- The LEDs of the ring are connected serially and use a 1-wire communication protocol to receive pixel data for full color display (8 bits for each R, G, and B color).
- The data transmission speed is around 800Kbps.
- The ring should be registered as a SPI device of Galileo Gen 2 board by the probe function of the WS2812 driver once a match of device and driver is found.
- The following device file operations:

open: to open a device (the device is `"/dev/WS2812"`).

write: The write call sends n pixel data to light up the n LEDs of the ring, where $1 \leq n \leq 16$. Each pixel data consists of 3 bytes for green, red, and blue colors. The call initiates an asynchronous SPI transfer that leads to a proper 1-wire data transmission on SPI-MOSI. As a consequence, the WS2812 can receive the display data and drive the LED display accurately.

ioctl: to include one command "RESET" to reset the SPI to a suitable operation mode. Note that the SPI mode must be defined properly to make correct 1-wire data transmission. The IO pin multiplexing should also be reset to enable the connection from SPI_MOSI to Data_in of the ring.

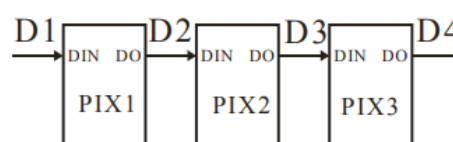
release: to close the descriptor of an opened device file.

Approach 2: bit banging

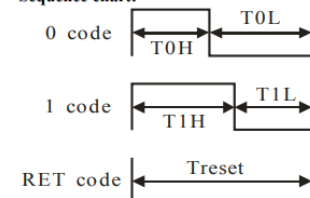
- Using software and delay loops to control a gpio output signal to generate any waveform.
- For instance, to generate a pulse of $5\mu\text{sec}$, a program can write 1 to a gpio pin, wait for $5\mu\text{sec}$, and finally write 0 to the gpio pin.
- This approach is highly dependent of the accuracy of delay functions and any possible preemptions.
- Do experiments to verify that the timing requirement of WS2812 can / cannot be met by any of the two approaches: `ndelay()` and `hrtimer`.



Cascade method:



Sequence chart:



Data transfer time($T_H + T_L = 1.25\mu\text{s} \pm 600\text{ns}$)

T0H	0 code ,high voltage time	0.35us	$\pm 150\text{ns}$
T1H	1 code ,high voltage time	0.7us	$\pm 150\text{ns}$
T0L	0 code , low voltage time	0.8us	$\pm 150\text{ns}$
T1L	1 code ,low voltage time	0.6us	$\pm 150\text{ns}$
RES	low voltage time	Above 50 μs	