

Data Structures and Algorithms

Lecture 7: Quick Sort

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Outline

- Introduction to Quick Sort
- Quick Sort Components
 - Partitioning
 - Small Array Strategy
 - Picking the Pivot
- Cost Analysis

Introduction

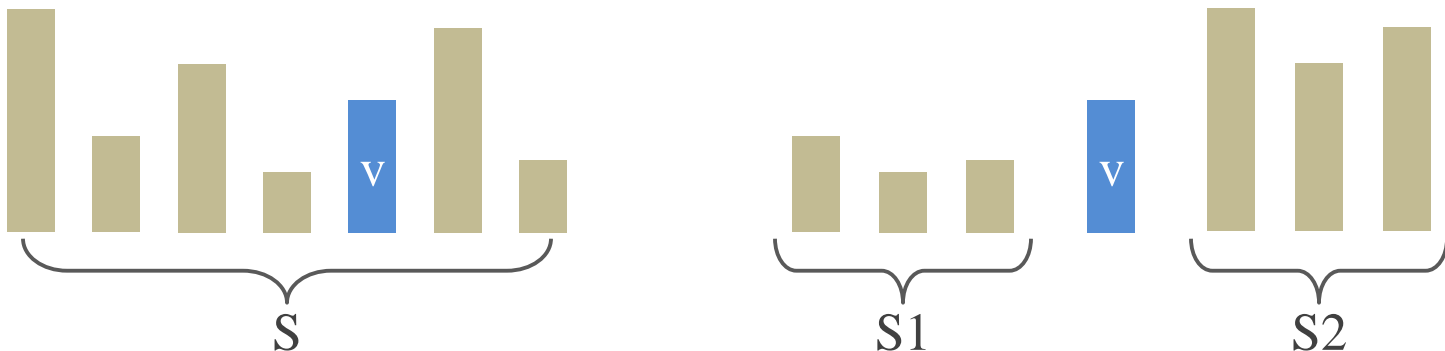
- Fastest sorting algorithm in practice
 - A lot of variations exist
- Not Stable
 - Average case cost: $O(N \log N)$
 - Worst case cost: $O(N^2)$
 - But, the worst case seldom happens.
- Another divide-and-conquer algorithm

Quick sort, another divide-and-conquer algorithm

- **DIVIDE**
- **CONQUER**
- **COMBINE**

Divide

- Pick an element v in S
 - v is called the **pivot**
 - Many ways to pick a pivot
- Partition $S - \{v\}$ into two disjoint groups
 - $S1 = \{x \in S - \{v\} \mid x \leq v\}$
 - $S2 = \{x \in S - \{v\} \mid x \geq v\}$
- Recursively divide $S1$ and $S2$



Conquer

- If there is no more than 1 element in *s*, return directly.

Combine

- No action is needed.
- The *sorted s1* (when the recursion is done) followed by *v*, followed by the *sorted s2* (when the recursion is done), make a *sorted new list*.

Example

Pick a pivot	2	6	1	4	9	5	3	0	7	8
Partition	2	3	1	0	4	5	6	9	7	8
Pick a pivot	2	3	1	0	4	5	6	9	7	8
Partition	0	1	3	2	4	5	6	9	7	8
Pick a pivot	Conquer	1	3	2	4	5	6	9	7	8
Partition		1	2	3	4	5	6	9	7	8
	Conquer									

The right half can be solved similarly

Nothing is done in conquer and combine

“DIVIDE” IS THE KEY

Animation

- Animation
- Note that
 - There are various methods to choose a pivot
 - There are various methods to partition a sub-array

Pseudo Code

```
QUICKSORT(A, left, right)
1.  IF left >= right
2.      return
3.  q = PARTITION(A, left, right)
4.  //q is the position of the pivot
5.  QUICKSORT(A, left, q-1)
6.  QUICKSORT(A, q+1, right)
```

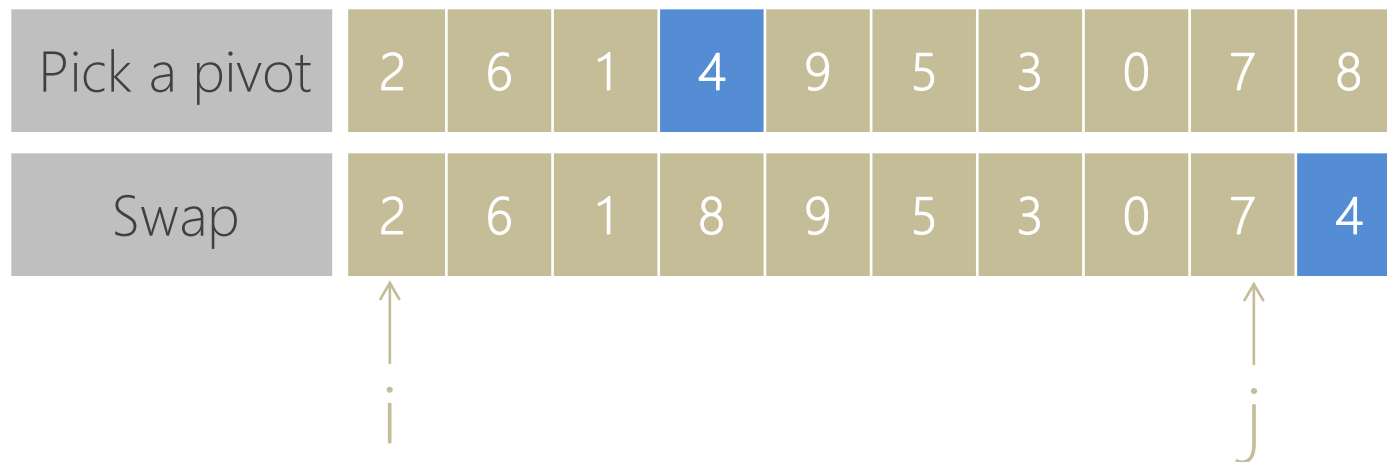
Partitioning

- Partitioning
 - This is a **key step** of the quicksort algorithm
 - **Goal:** given the picked pivot, partition the remaining elements into two smaller sets
 - Many ways to implement how to partition
 - Even the slightest deviations may cause surprisingly bad results.
- We will learn an easy and efficient partitioning strategy here.
- How to **pick a pivot** will be discussed later

Partitioning Strategy

Want to partition an array $A[\text{left} \dots \text{right}]$

1. Get the pivot element out of the way by swapping it with the last element. (Swap pivot and $A[\text{right}]$)
2. Let i start at the first element and j start at the next-to-last element
 1. $i = \text{left}, j = \text{right} - 1$



Partitioning Strategy

Goal:

- $A[\text{left}..i]$ are smaller or equal to the pivot
- $A[j..\text{right}]$ are greater or equal to the pivot

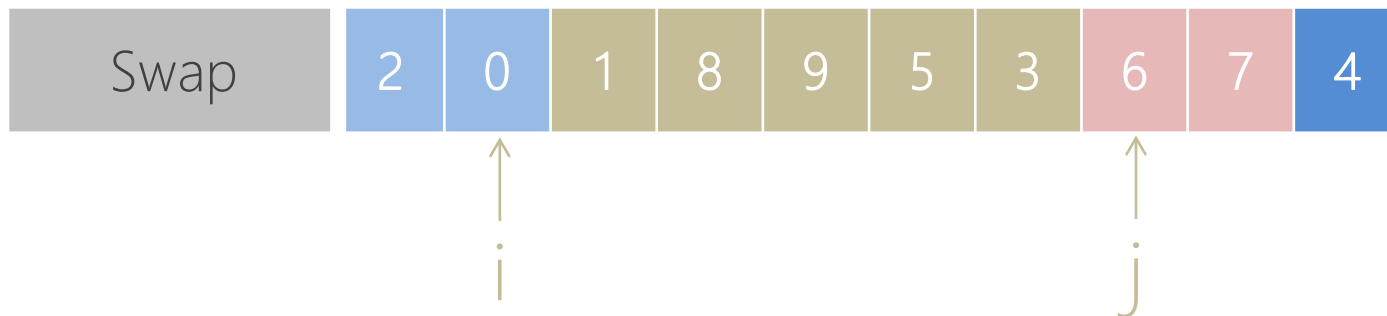
Strategy:

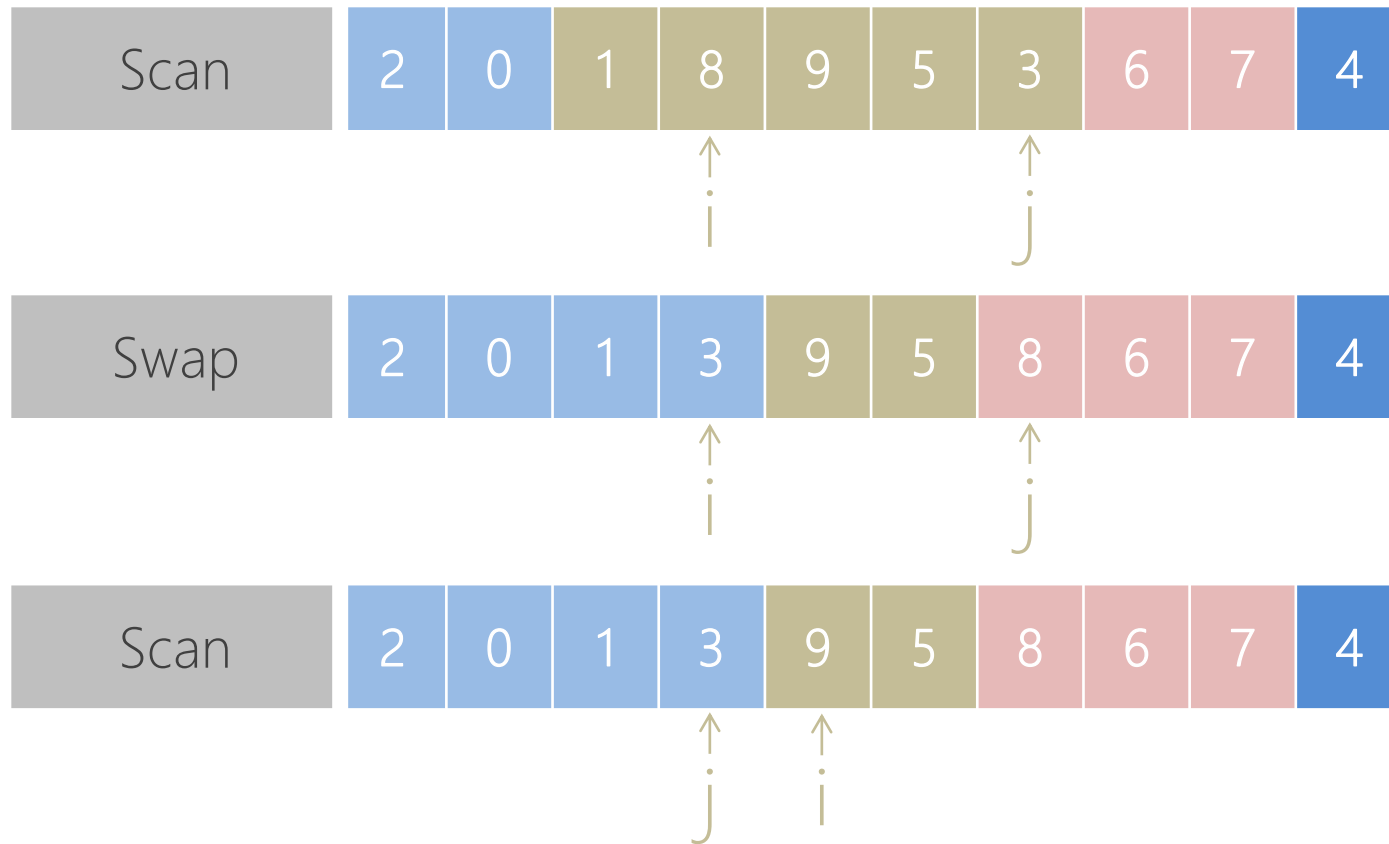
- When $i < j$
 - Move i right, skipping over elements smaller than the pivot
 - Move j left, skipping over elements greater than the pivot
 - When both i and j have stopped
 - $A[i] \geq \text{pivot}$
 - $A[j] \leq \text{pivot}$ { $A[i]$ and $A[j]$ should now be swapped }



Partitioning Strategy

- When i and j have stopped and i is to the left of j (thus legal)
 - Swap $A[i]$ and $A[j]$
 - And then both elements are on the “correct” side
 - After swapping
 - $A[i] \leq \text{pivot}$
 - $A[j] \geq \text{pivot}$
 - Repeat the process until i and j cross

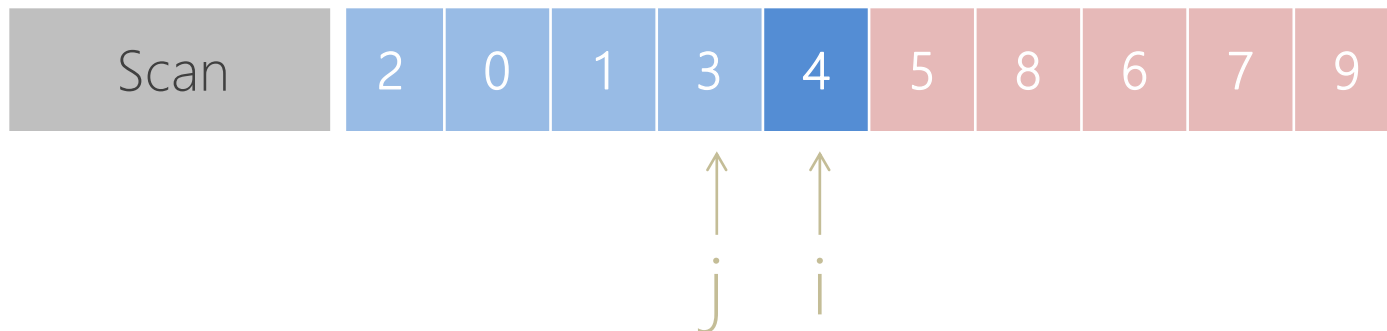




i and j cross now!

Partitioning Strategy

- When i and j have crossed
 - Swap $A[i]$ and pivot
- Result:
 - $A[p] \leq \text{pivot}$, for $p < i$
 - $A[p] \geq \text{pivot}$, for $p > i$
- Partition complete



Pseudo Code

```
PARTITION(A, left, right)
1.  p = PIVOT(A, left, right)
2.  //p is the position of the pivot
3.  swap A[p] and A[right]
4.  i = left, j = right-1, pivot = A[right]
5.  WHILE true
6.      WHILE i < right AND A[i] < pivot
7.          i++
8.      WHILE j >= left AND A[j] > pivot
9.          j--
10.     IF i < j
11.         swap A[i] and A[j]
12.     ELSE
13.         BREAK
14. swap A[i] and A[right]
```

Small arrays

- For very small arrays, quicksort does not perform as well as [insertion sort](#)
 - how small depends on many factors, such as the time spent making a recursive call, the compiler, etc
- Do not use quicksort recursively for small arrays
 - Instead, use a sorting algorithm that is efficient for small arrays, such as insertion sort

Quick Sort + Small Array Strategy

```
QUICKSORT(A, left, right)
1.  IF left >= right - 10
2.      INSERTIONSORT(A, left, right)
3.      RETURN
4.  q = PARTITION(A, left, right)
5.  //q is the position of the pivot
6.  QUICKSORT(A, left, q-1)
7.  QUICKSORT(A, q+1, right)
```

Picking the **PIVOT**

Strategy I

- Use the **first element** as pivot
 - if the input is **random**, ok
 - if the input is **presorted** (or in reverse order)
 - all the elements go into S2 (or S1)
 - this happens consistently throughout the recursive calls
 - Results in $O(n^2)$ behavior

Strategy II

- Choose the pivot randomly
 - generally safe
 - random number generation can be expensive

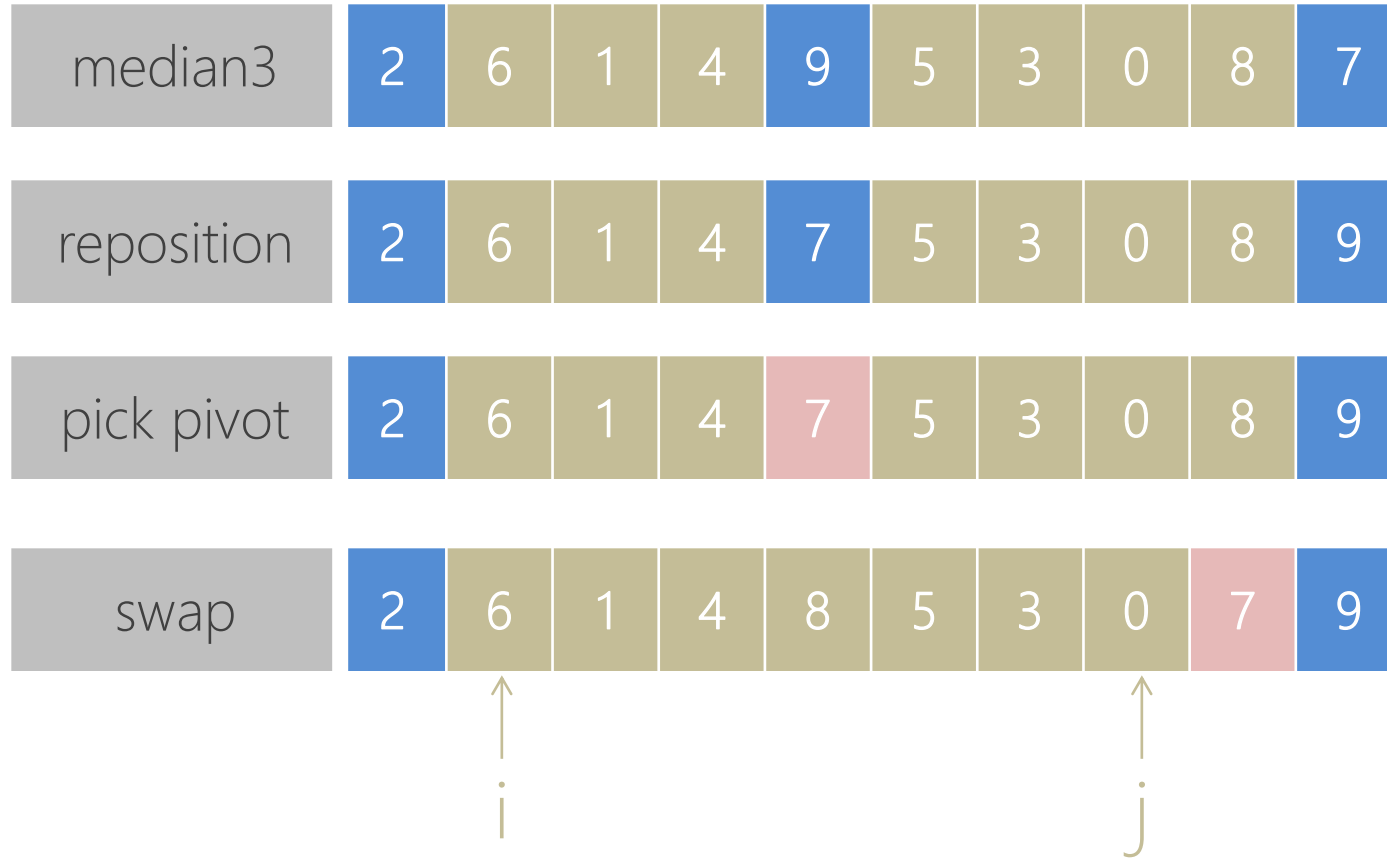
Strategy III

- Use the **median** of the array
 - The median is the **middle element** if the array is **sorted**. For example, if there are 9 elements in the array, the median is the 5th largest one.
 - Partitioning always cuts the array into roughly half
 - An **optimal** quicksort: $O(N \log N)$
 - However, **expensive** to find the exact median
 - e.g., sort an array to pick the value in the middle

Strategy IV

- We will use median of three
 - Compare just three elements: the left most, right most and center
 - Swap these elements if necessary so that
 - $A[\text{left}] = \text{Smallest}$
 - $A[\text{right}] = \text{Largest}$
 - $A[\text{center}] = \text{Median of three}$
 - Pick $A[\text{center}]$ as the pivot
 - Swap $A[\text{center}]$ and $A[\text{right} - 1]$ so that pivot is at second last position
 - **WHY?**

Median3 Example



Partition With Median3

```
PARTITION(A, left, right)
1.  MEDIAN3(A, left, right)
2.  // MEDIAN3 repositions the left, center
3.  // and the right elements
4.  i = left+1, j = right-2, pivot = A[right-1]
5.  WHILE true
6.      WHILE A[i] < pivot
7.          i++
8.      WHILE A[j] > pivot
9.          j--
10.     IF i < j
11.         swap A[i] and A[j]
12.         i++, j--
13.     ELSE
14.         BREAK
15.  Swap A[i] and A[right-1]
```

No boundary
check. Why?

Quicksort **Faster** than Mergesort

- Both quicksort and mergesort take $O(N \log N)$ in the *average case*.
- Why is quicksort *faster* than mergesort?
 - The inner loop consists of an increment/decrement (by 1, which is fast), a test and a jump.
 - There is no extra juggling as in mergesort.

Analysis

- Assumptions
 - Pivot Selection: Median of 3
 - Base Case: Array size ≤ 10
- Running time $T(n)$
 - Divide
 - Pivot selection: $O(1)$
 - Partitioning: $O(n)$
 - Recursive calls: $T(i) + T(n-i-1)$
 - i : number of elements in S_1
 - Conquer and Combine: $O(1)$

$$T(n) = T(i) + T(n-i-1) + O(n)$$

Worst-Case Analysis

- What will be the worst case?
 - The pivot is the **smallest** element, all the time
 - Partition is always **unbalanced**

$$T(N) = T(N - 1) + cN$$

$$T(N - 1) = T(N - 2) + c(N - 1)$$

$$T(N - 2) = T(N - 3) + c(N - 2)$$

$$\vdots$$

$$T(2) = T(1) + c(2)$$

$$T(N) = T(1) + c \sum_{i=2}^N i = O(N^2)$$

Best-case Analysis

- What will be the best case?
 - Partition is **perfectly balanced**
 - Pivot is always in the middle (median of the array)

$$\begin{aligned}T(n) &= 2T(n/2) + n \\&= 2[2T(n/2^2) + n/2] + n \\&= 2^2T(n/2^2) + 2n \\&= 2^3T(n/2^3) + 3n \\&= 2^iT(n/2^i) + i*n\end{aligned}$$

$$\begin{aligned}\text{Let } i &= \log(n), \\&= nT(n/n) + n*\log(n) \\&= O(n*\log(n))\end{aligned}$$

Average-Case Analysis

- Assume
 - Each of the sizes for S_1 is equally likely
- This assumption is valid for our pivoting (median-of-three) strategy
- On average, the running time is $O(N \log N)$

Covered in

**DESIGN AND ANALYSIS OF
ALGORITHMS**

Consider special cases

- When all elements are the same?
- Other cases?

Analysis of Quick Sort

Best-case Running Time	$O(n \log(n))$
Worst-case Running Time	$O(n^2)$
Average Running Time	$O(n \log(n))$

- Quick sort is **not stable**
- But it is the **fastest** in practice
- The worst case **seldom** happens

