model

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1 Application of continuous wavelet transform to feature extraction

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Needed imports:

```
[0]: import os
    from pathlib import Path
    import numpy as np
    import pywt
    import tensorflow as tf
    from tensorflow.keras.utils import to_categorical
    from tensorflow.keras.layers import Dense, Conv2D, Flatten, MaxPooling2D
    from tensorflow.keras import Sequential
    from tensorflow.keras.optimizers import Adadelta
    from tensorflow.keras.callbacks import ModelCheckpoint
    from tqdm import tqdm
    import h5py
```

1.2 Download and unpack the data

For data description look into the README.txt file. There is a chance that you will need to change the download file. Please check UCI HAR dataset.

```
[0]: | wget https://archive.ics.uci.edu/ml/machine-learning-databases/00240/

UCI%20HAR%20Dataset.zip
```

```
--2020-03-28 22:36:15-- https://archive.ics.uci.edu/ml/machine-learning-databases/00240/UCI%20HAR%20Dataset.zip
Resolving archive.ics.uci.edu (archive.ics.uci.edu)... 128.195.10.252
Connecting to archive.ics.uci.edu (archive.ics.uci.edu)|128.195.10.252|:443...
connected.
HTTP request sent, awaiting response... 200 OK
Length: 60999314 (58M) [application/x-httpd-php]
Saving to: 'UCI HAR Dataset.zip'
```

```
UCI HAR Dataset.zip 100%[============] 58.17M 73.1MB/s
                                                                       in 0.8s
    2020-03-28 22:36:21 (73.1 MB/s) - 'UCI HAR Dataset.zip' saved
    [60999314/60999314]
[0]: | !unzip "UCI HAR Dataset.zip"
    Archive: UCI HAR Dataset.zip
       creating: UCI HAR Dataset/
      inflating: UCI HAR Dataset/.DS_Store
       creating: __MACOSX/
       creating: __MACOSX/UCI HAR Dataset/
      inflating: __MACOSX/UCI HAR Dataset/._.DS_Store
      inflating: UCI HAR Dataset/activity_labels.txt
      inflating: __MACOSX/UCI HAR Dataset/._activity_labels.txt
      inflating: UCI HAR Dataset/features.txt
      inflating: __MACOSX/UCI HAR Dataset/._features.txt
      inflating: UCI HAR Dataset/features_info.txt
      inflating: __MACOSX/UCI HAR Dataset/._features_info.txt
      inflating: UCI HAR Dataset/README.txt
      inflating: __MACOSX/UCI HAR Dataset/._README.txt
       creating: UCI HAR Dataset/test/
       creating: UCI HAR Dataset/test/Inertial Signals/
```

inflating: UCI HAR Dataset/test/Inertial Signals/body_gyro_y_test.txt

inflating: UCI HAR Dataset/test/Inertial Signals/body_gyro_z_test.txt

inflating: __MACOSX/UCI HAR Dataset/test/Inertial

Signals/._body_gyro_y_test.txt

Signals/._total_acc_x_test.txt
 inflating: UCI HAR Dataset/test/Inertial Signals/total_acc_y_test.txt

```
inflating: __MACOSX/UCI HAR Dataset/test/Inertial
Signals/._total_acc_y_test.txt
  inflating: UCI HAR Dataset/test/Inertial Signals/total_acc_z_test.txt
  inflating: __MACOSX/UCI HAR Dataset/test/Inertial
Signals/._total_acc_z_test.txt
  inflating: __MACOSX/UCI HAR Dataset/test/._Inertial Signals
  inflating: UCI HAR Dataset/test/subject_test.txt
  inflating: __MACOSX/UCI HAR Dataset/test/._subject_test.txt
  inflating: UCI HAR Dataset/test/X_test.txt
  inflating: __MACOSX/UCI HAR Dataset/test/._X_test.txt
  inflating: UCI HAR Dataset/test/y_test.txt
  inflating: __MACOSX/UCI HAR Dataset/test/._y_test.txt
  inflating: __MACOSX/UCI HAR Dataset/._test
  creating: UCI HAR Dataset/train/
   creating: UCI HAR Dataset/train/Inertial Signals/
  inflating: UCI HAR Dataset/train/Inertial Signals/body_acc_x_train.txt
  creating: __MACOSX/UCI HAR Dataset/train/
  creating: __MACOSX/UCI HAR Dataset/train/Inertial Signals/
  inflating: __MACOSX/UCI HAR Dataset/train/Inertial
Signals/. body acc x train.txt
  inflating: UCI HAR Dataset/train/Inertial Signals/body_acc_y_train.txt
  inflating: __MACOSX/UCI HAR Dataset/train/Inertial
Signals/._body_acc_y_train.txt
  inflating: UCI HAR Dataset/train/Inertial Signals/body_acc_z_train.txt
  inflating: __MACOSX/UCI HAR Dataset/train/Inertial
Signals/._body_acc_z_train.txt
  inflating: UCI HAR Dataset/train/Inertial Signals/body_gyro_x_train.txt
  inflating: __MACOSX/UCI HAR Dataset/train/Inertial
Signals/._body_gyro_x_train.txt
  inflating: UCI HAR Dataset/train/Inertial Signals/body_gyro_y_train.txt
  inflating: __MACOSX/UCI HAR Dataset/train/Inertial
Signals/._body_gyro_y_train.txt
  inflating: UCI HAR Dataset/train/Inertial Signals/body_gyro_z_train.txt
  inflating: __MACOSX/UCI HAR Dataset/train/Inertial
Signals/. body gyro z train.txt
  inflating: UCI HAR Dataset/train/Inertial Signals/total_acc_x_train.txt
  inflating: __MACOSX/UCI HAR Dataset/train/Inertial
Signals/._total_acc_x_train.txt
  inflating: UCI HAR Dataset/train/Inertial Signals/total_acc_y_train.txt
  inflating: __MACOSX/UCI HAR Dataset/train/Inertial
Signals/._total_acc_y_train.txt
  inflating: UCI HAR Dataset/train/Inertial Signals/total_acc_z_train.txt
  inflating: __MACOSX/UCI HAR Dataset/train/Inertial
Signals/._total_acc_z_train.txt
  inflating: __MACOSX/UCI HAR Dataset/train/._Inertial Signals
  inflating: UCI HAR Dataset/train/subject_train.txt
  inflating: __MACOSX/UCI HAR Dataset/train/._subject_train.txt
  inflating: UCI HAR Dataset/train/X_train.txt
```

```
inflating: __MACOSX/UCI HAR Dataset/train/._X_train.txt
inflating: UCI HAR Dataset/train/y_train.txt
inflating: __MACOSX/UCI HAR Dataset/train/._y_train.txt
inflating: __MACOSX/UCI HAR Dataset/._train
inflating: __MACOSX/._UCI HAR Dataset
```

1.3 Load the data

Read 9 component signals from "Inertial Signals" directory and read corresponding labels from y*.txt file. Labels are from 1-6, but to use categorical features from keras library we need them to start from 0. We also transpose X array to obtain in each record 128 samples for 9 components.

```
[0]: def readData(root_directory: str):
    root_path = Path(root_directory)
    p = root_path / "Inertial Signals"
    x_paths = sorted(list(p.glob('*.txt')))
    y_path = list(root_path.glob('y*.txt'))[0]

x = []
    print(x_paths)
    for x_p in x_paths:
        x.append(np.loadtxt(x_p, dtype=np.float32))

y = to_categorical(np.loadtxt(y_path, dtype=np.int8) - 1 )
    return np.transpose(np.array(x), (1, 2, 0)), y
```

1.4 Continous wavelet transform

Below is simple example of Continous wavelet transform.

```
[0]: def myCWT(vector):
    wavelet = "morl"
    coeff, freqs = pywt.cwt(vector, np.arange(1,129), wavelet)
    return coeff
```

1.5 Create CNN input

Take the created arrays and apply CWT to each 9 components of each record. The result array shape should be (n_samples, 128, 128, 9). We're using morlet real wavelet, and scale from 1 to 128.

```
[0]: def CWT(x, size):
    records = x.shape[0]
    components = x.shape[2]

    scale = np.arange(1, size + 1)
    wavelet = 'morl'
```

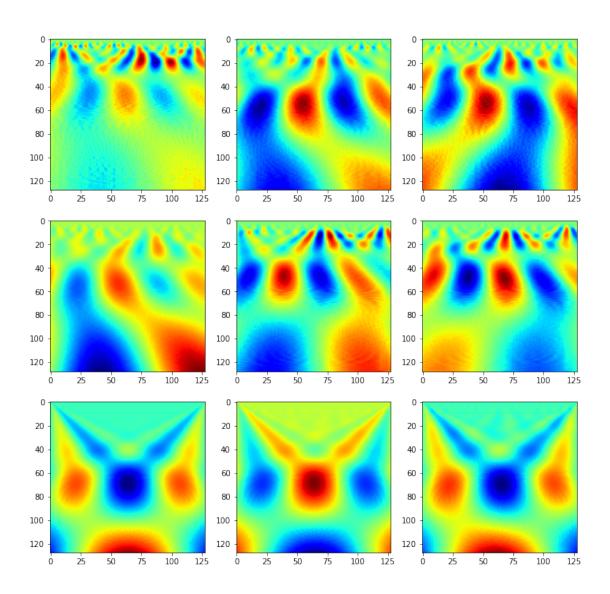
```
ret_arr = np.ndarray(shape=(records, size, size, components), dtype=np.
      →float32)
       for r in tqdm(range(records)):
         for c in range(components):
           coeffs, _ = pywt.cwt(x[r, :, c], scale, wavelet)
           ret arr[r, :, :, c] = coeffs
       return ret arr
[0]: x_train, y_train = readData("UCI HAR Dataset/train")
     x_test, y_test = readData("UCI HAR Dataset/test")
     x_train = CWT(x_train, 128)
     x_{test} = CWT(x_{test}, 128)
    [PosixPath('UCI HAR Dataset/train/Inertial Signals/body_acc_x_train.txt'),
    PosixPath('UCI HAR Dataset/train/Inertial Signals/body_acc_y_train.txt'),
    PosixPath('UCI HAR Dataset/train/Inertial Signals/body acc z train.txt'),
    PosixPath('UCI HAR Dataset/train/Inertial Signals/body gyro x train.txt'),
    PosixPath('UCI HAR Dataset/train/Inertial Signals/body_gyro_y_train.txt'),
    PosixPath('UCI HAR Dataset/train/Inertial Signals/body_gyro_z_train.txt'),
    PosixPath('UCI HAR Dataset/train/Inertial Signals/total_acc_x_train.txt'),
    PosixPath('UCI HAR Dataset/train/Inertial Signals/total_acc_y_train.txt'),
    PosixPath('UCI HAR Dataset/train/Inertial Signals/total_acc_z_train.txt')]
    [PosixPath('UCI HAR Dataset/test/Inertial Signals/body_acc_x_test.txt'),
    PosixPath('UCI HAR Dataset/test/Inertial Signals/body_acc_y_test.txt'),
    PosixPath('UCI HAR Dataset/test/Inertial Signals/body_acc_z_test.txt'),
    PosixPath('UCI HAR Dataset/test/Inertial Signals/body_gyro_x_test.txt'),
    PosixPath('UCI HAR Dataset/test/Inertial Signals/body_gyro_y_test.txt'),
    PosixPath('UCI HAR Dataset/test/Inertial Signals/body_gyro_z_test.txt'),
    PosixPath('UCI HAR Dataset/test/Inertial Signals/total_acc_x_test.txt'),
    PosixPath('UCI HAR Dataset/test/Inertial Signals/total_acc_y_test.txt'),
    PosixPath('UCI HAR Dataset/test/Inertial Signals/total_acc_z_test.txt')]
    100%1
               | 7352/7352 [13:08<00:00, 9.32it/s]
    100%|
              | 2947/2947 [05:16<00:00, 9.32it/s]
    Due to high memory usage it's good to clear the garbage at the time.
[0]: import gc
     gc.collect()
[0]: 22
[0]: print(x_train.shape, y_train.shape)
     print(x_test.shape, y_test.shape)
     print(x_train.dtype)
     print(x_train.nbytes)
```

(7352, 128, 128, 9) (7352, 6) (2947, 128, 128, 9) (2947, 6) float32 4336386048

1.6 Pick one record and see all 9 components

Here we're gonna pick one record and display all 9 components that were produced from CWT.

```
[0]: plot(x_test[4], y_test[4])
```

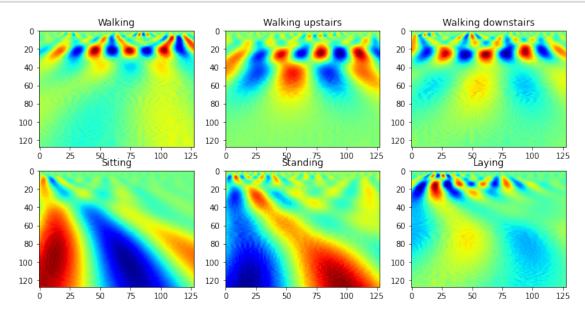


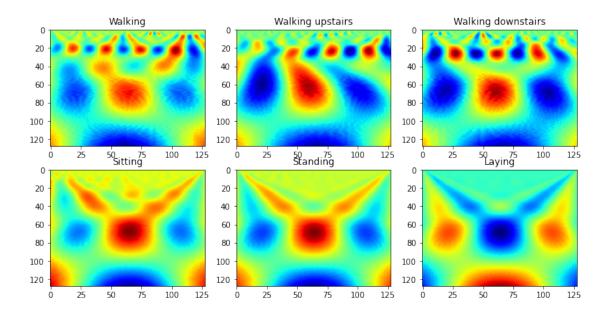
1.7 Pick one component and display for different activity

Here we're gonna plot CWT coefficients for different activities to just one choosen component.

```
[0]: def find_indexes(y):
    indexes = []
    y_n = np.argmax(y, axis=-1)
    for label in sorted(np.unique(y_n)):
        indexes.append(np.where(y_n == label)[0][0])
    return indexes
```

```
[0]: indxs = find_indexes(y_test)
plot2(x_test, 1, indxs)
plot2(x_test, 7, indxs)
```





1.8 Create CNN model

As in the task description we're creating the simple CNN with 2 convolutional and 2 MaxPooling layers. After that we're adding flat classificator with 2 fully connected layers. On the output layer we have 6 neurons.

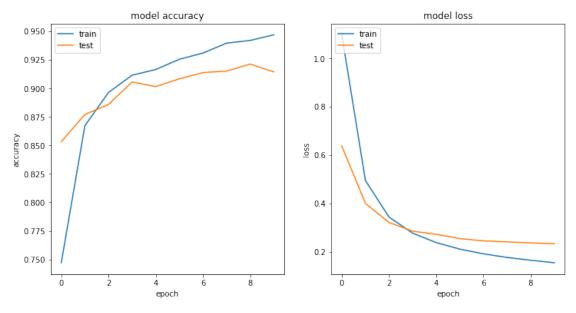
```
[0]: import gc gc.collect()
```

[0]: 0

This is classification to 6 different classes, so at the end of our classificator we have **softmax** activation function. We're gonna use Adadelta optimizer and *categorical crossentropy* as a loss function.

```
[0]: model.compile(loss='categorical_crossentropy',
            optimizer=tf.keras.optimizers.Adadelta(),
            metrics=['accuracy'])
[0]: history = model.fit(
      x_train, y_train,
      validation_split=0.2,
      batch_size=16, epochs=10, verbose=1,
      shuffle=True,
   Epoch 1/10
   accuracy: 0.7472 - val_loss: 0.6372 - val_accuracy: 0.8532
   Epoch 2/10
   368/368 [============= ] - 8s 20ms/step - loss: 0.4945 -
   accuracy: 0.8672 - val_loss: 0.3999 - val_accuracy: 0.8770
   Epoch 3/10
   368/368 [============= ] - 8s 20ms/step - loss: 0.3432 -
   accuracy: 0.8963 - val_loss: 0.3210 - val_accuracy: 0.8858
   Epoch 4/10
   368/368 [============= ] - 7s 20ms/step - loss: 0.2768 -
   accuracy: 0.9114 - val_loss: 0.2850 - val_accuracy: 0.9055
   Epoch 5/10
   accuracy: 0.9163 - val_loss: 0.2720 - val_accuracy: 0.9014
   accuracy: 0.9254 - val_loss: 0.2544 - val_accuracy: 0.9082
   accuracy: 0.9308 - val_loss: 0.2448 - val_accuracy: 0.9137
   Epoch 8/10
   368/368 [============= ] - 7s 20ms/step - loss: 0.1762 -
   accuracy: 0.9395 - val_loss: 0.2408 - val_accuracy: 0.9150
   Epoch 9/10
   accuracy: 0.9418 - val_loss: 0.2363 - val_accuracy: 0.9211
   Epoch 10/10
   accuracy: 0.9468 - val_loss: 0.2332 - val_accuracy: 0.9143
   Plot the loss and accuracy.
```

```
[0]: def plot_graphs(history):
       # summarize history for accuracy
       acc_key = "accuracy"
       fig, (ax1, ax2) = plt.subplots(1,2, figsize=(12,6))
       ax1.plot(history.history[acc_key])
       ax1.plot(history.history['val_' + acc_key])
       ax1.set_title('model accuracy')
       ax1.set_ylabel('accuracy')
       ax1.set_xlabel('epoch')
       ax1.legend(['train', 'test'], loc='upper left')
       # summarize history for loss
       ax2.plot(history.history['loss'])
       ax2.plot(history.history['val_loss'])
       ax2.set_title('model loss')
       ax2.set_ylabel('loss')
       ax2.set_xlabel('epoch')
       ax2.legend(['train', 'test'], loc='upper left')
      plt.show()
     plot_graphs(history)
```



We see that during training our validation accuracy reaches 91% and is not far away from the training accuracy. This means that the model generalize well. Now lets check what is the estimation of the real accuracy:

```
[0]: test_score = model.evaluate(x_test, y_test, verbose=0)
print('Test loss: {}, Test accuracy: {}'.format(test_score[0], test_score[1]))
```

Test loss: 0.2667182981967926, Test accuracy: 0.9049881100654602

[0]: