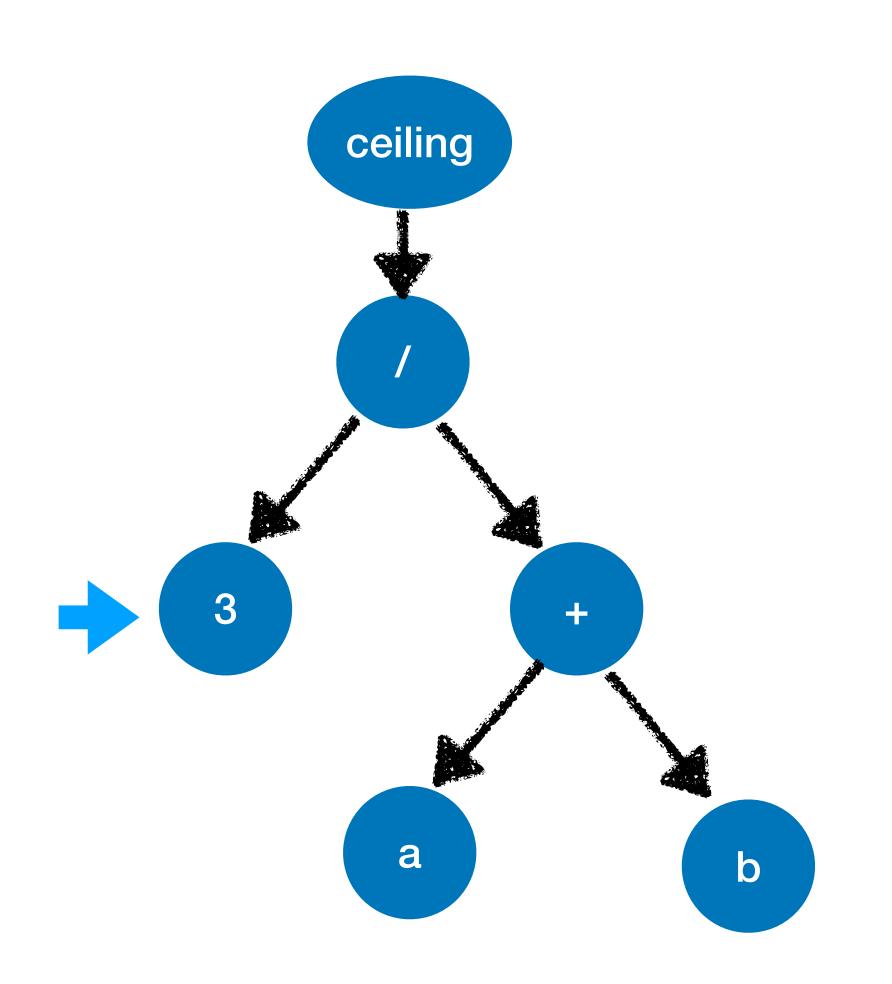
Stack-based Bytecode Design

Sharing state through an implicit stack - example

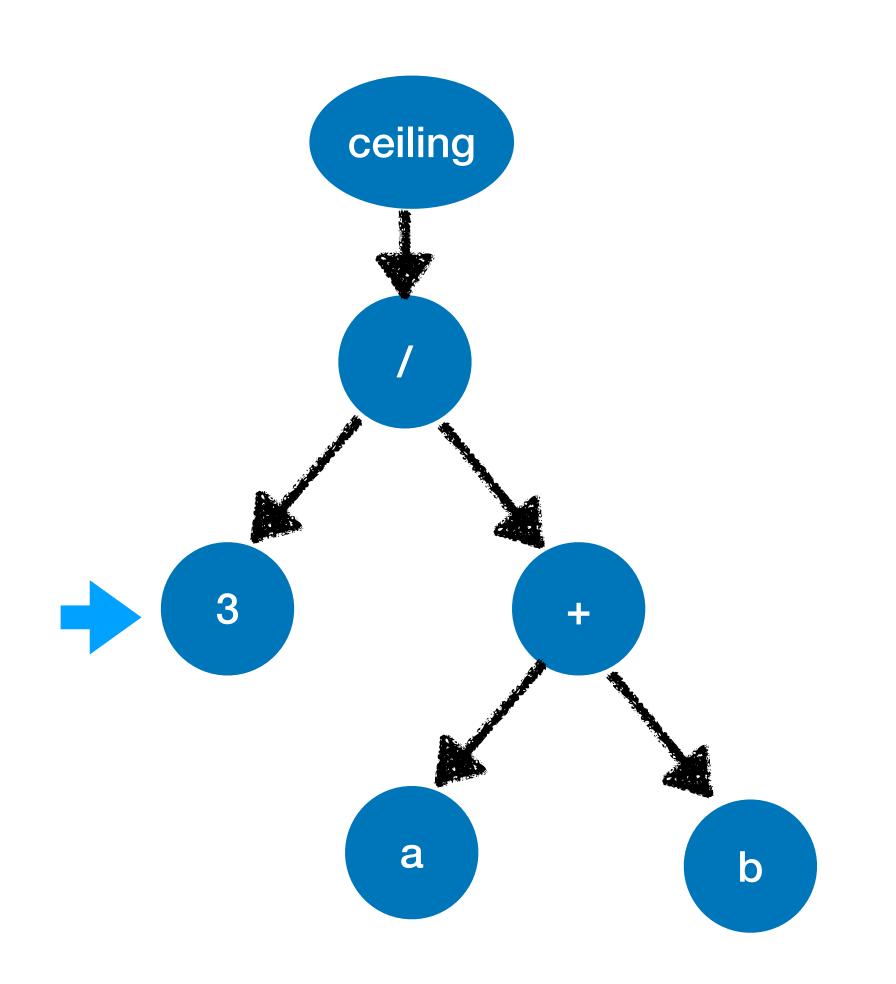


$$(3 / (a + b))$$
 . ceiling()

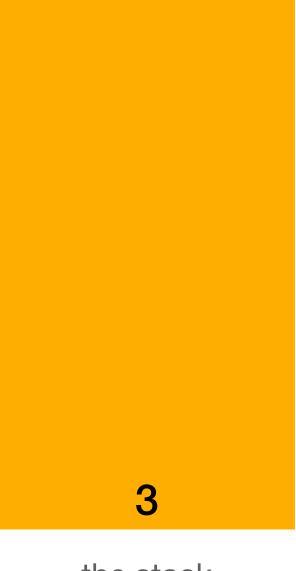


the stack

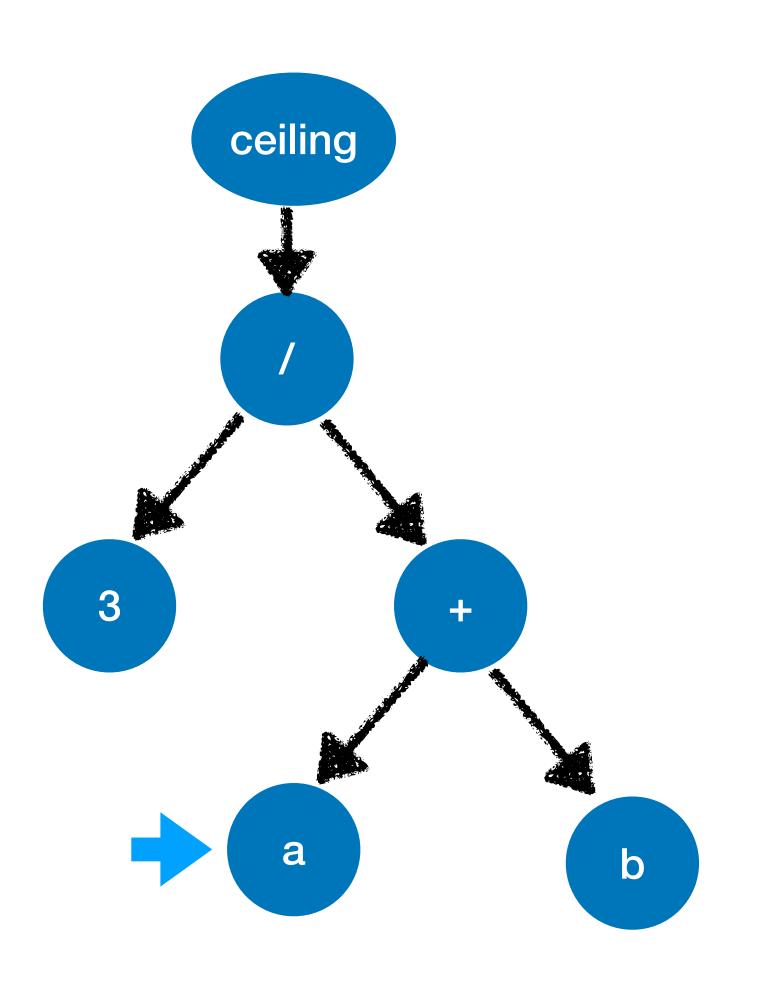
Sharing state through an implicit stack - example



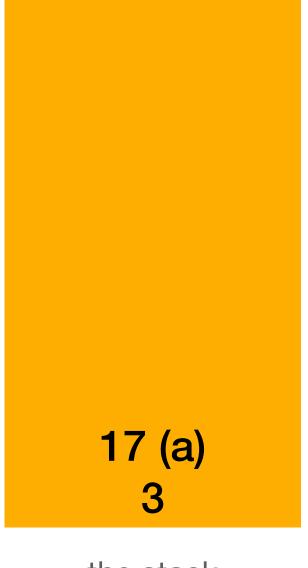
$$(3 / (a + b))$$
 . ceiling()



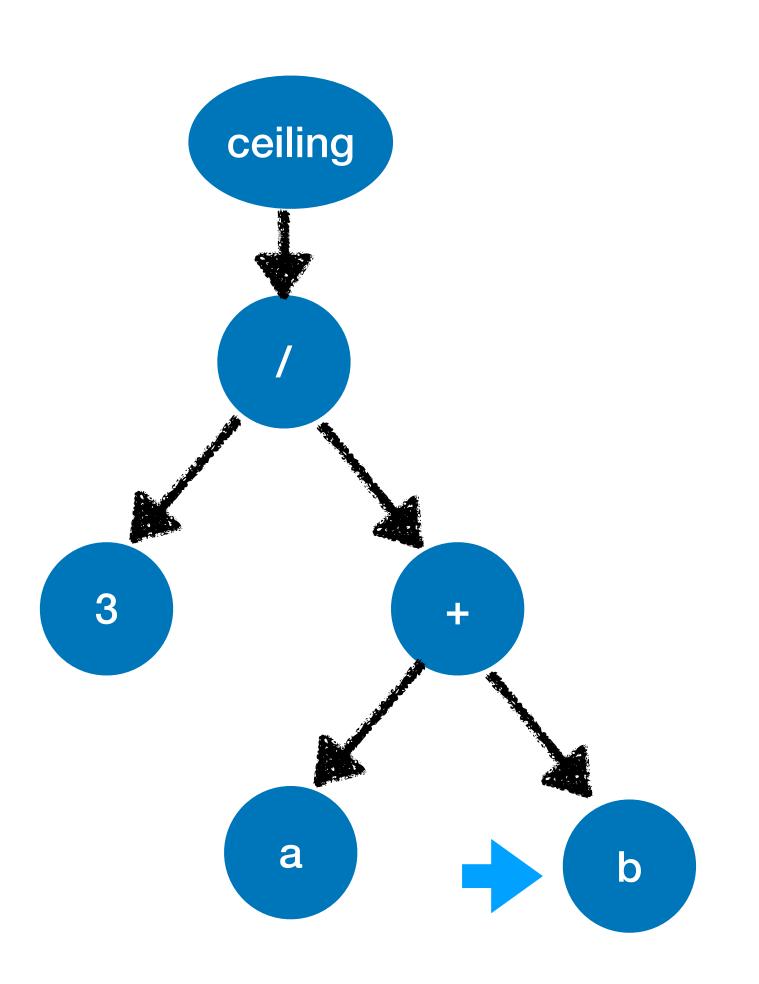
Sharing state through an implicit stack - example



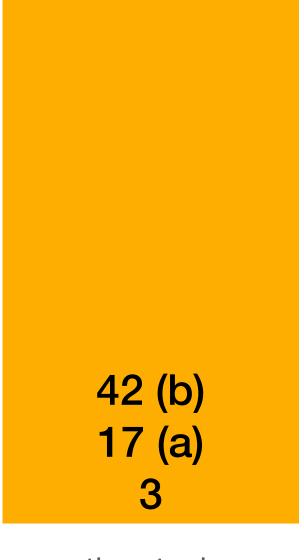
$$(3 / (a + b))$$
 . ceiling()



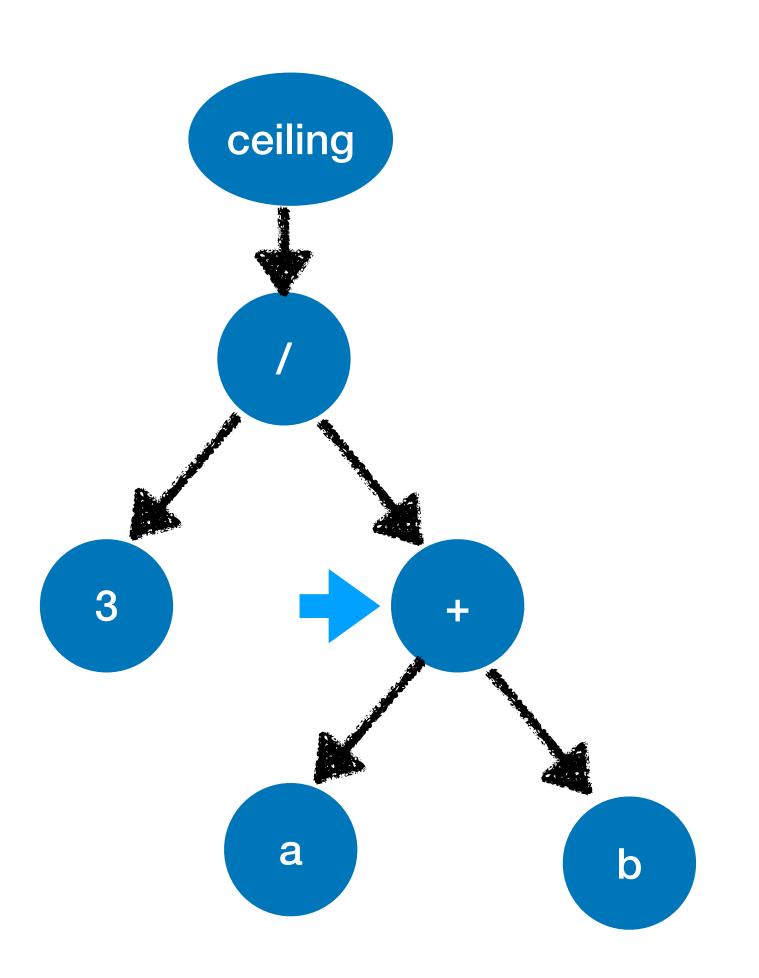
Sharing state through an implicit stack - example



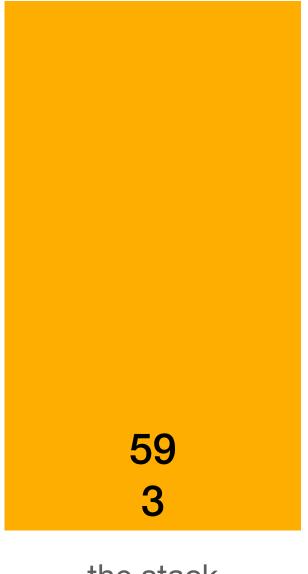
$$(3 / (a + b))$$
 . ceiling()



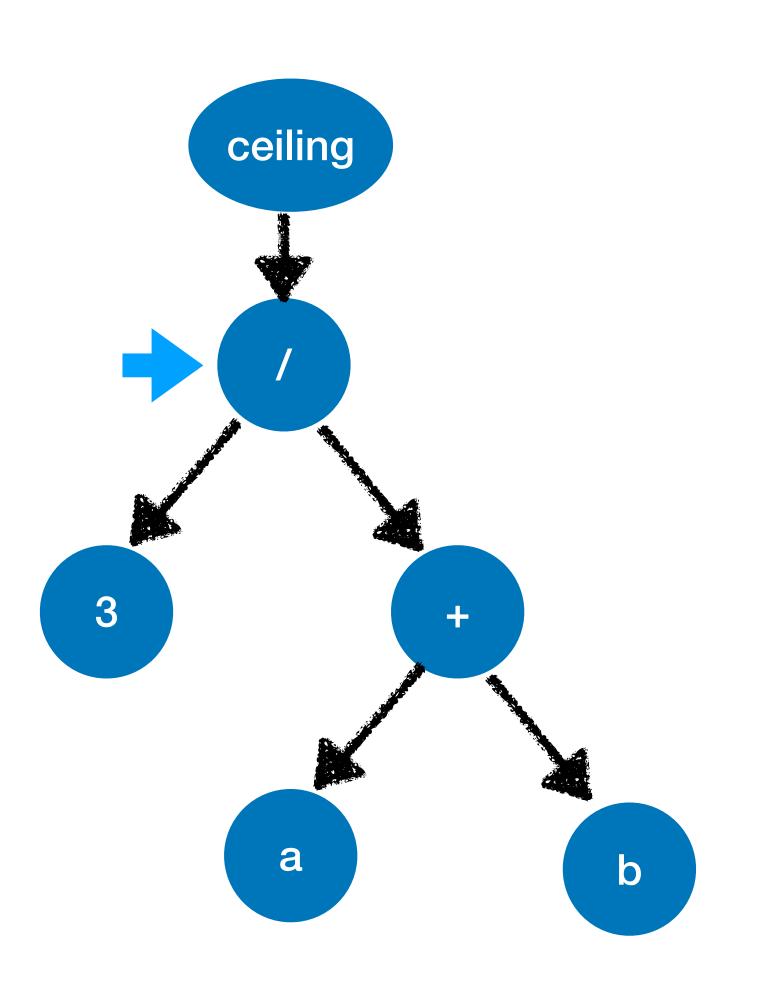
Sharing state through an implicit stack - example



$$(3 / (a + b)) \cdot ceiling()$$



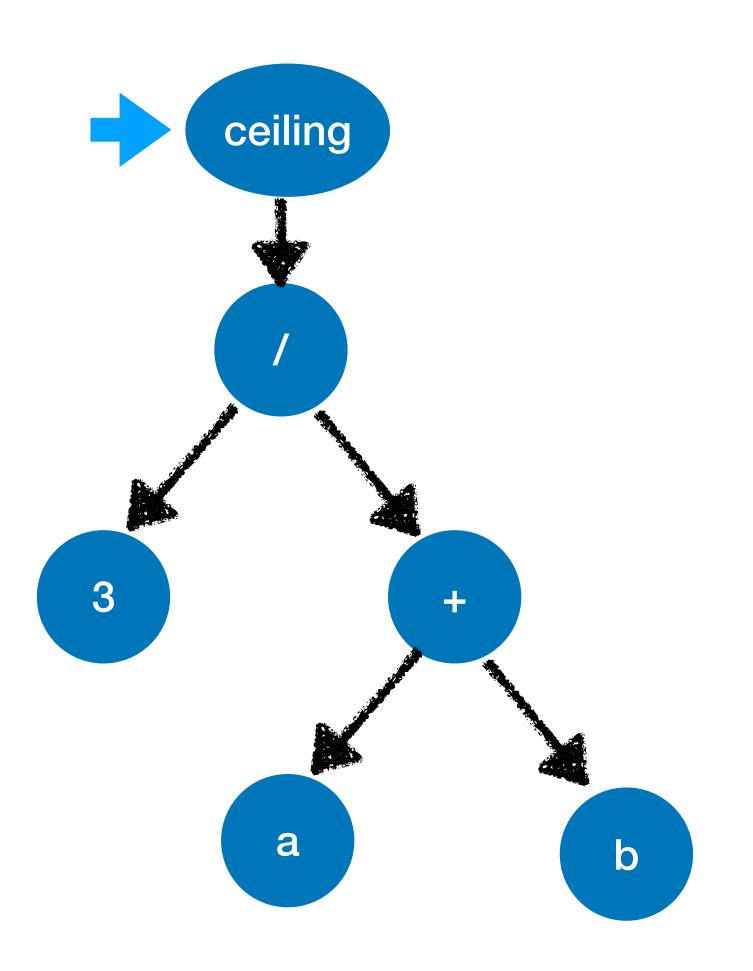
Sharing state through an implicit stack - example



$$(3 / (a + b)) \cdot ceiling()$$



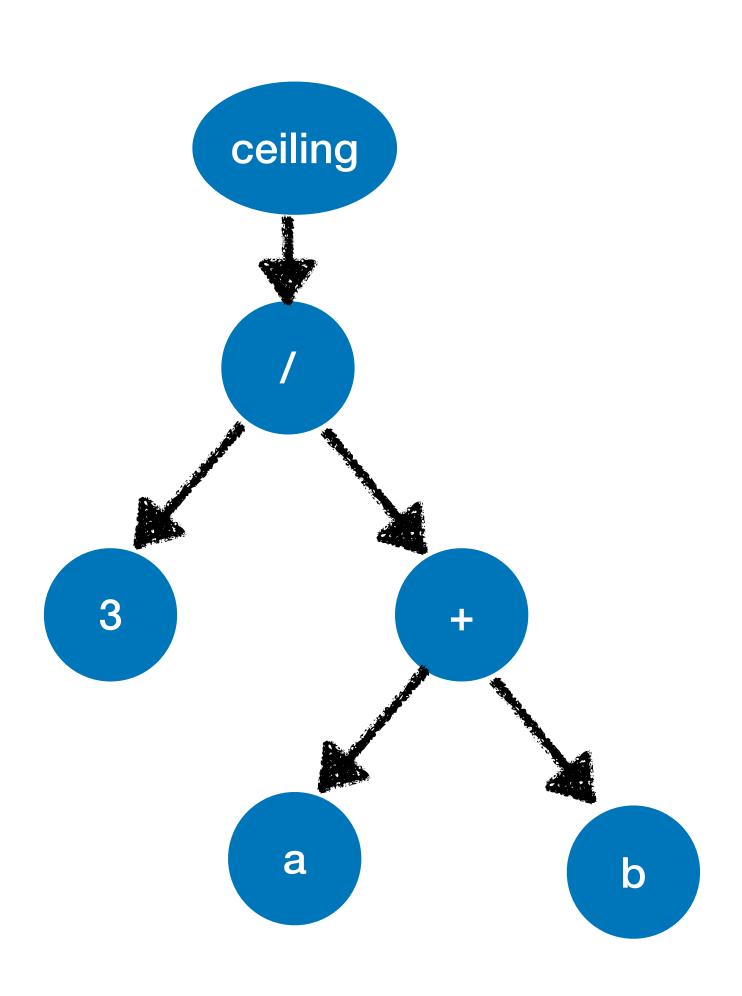
Sharing state through an implicit stack - example



$$(3 / (a + b)) \cdot ceiling()$$



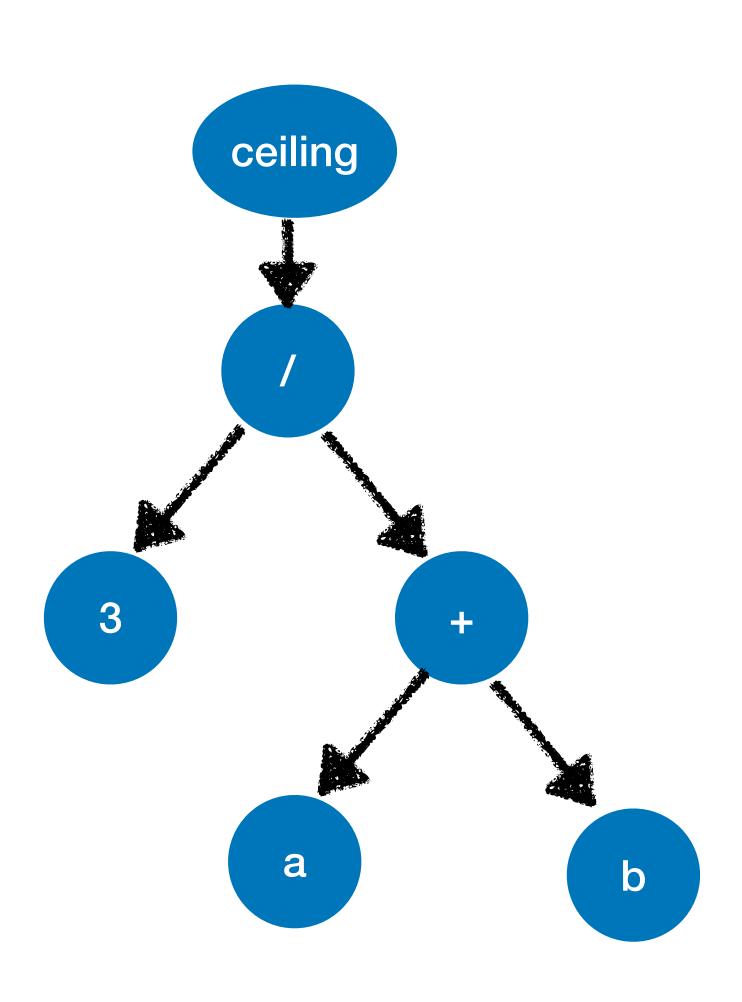
Sharing state through an implicit stack - example



$$(3 / (a + b)) \cdot ceiling()$$

- Post-order depth-first traversal of the code
- Share state through implicit stack
- Each operation pops arguments and pushes their result

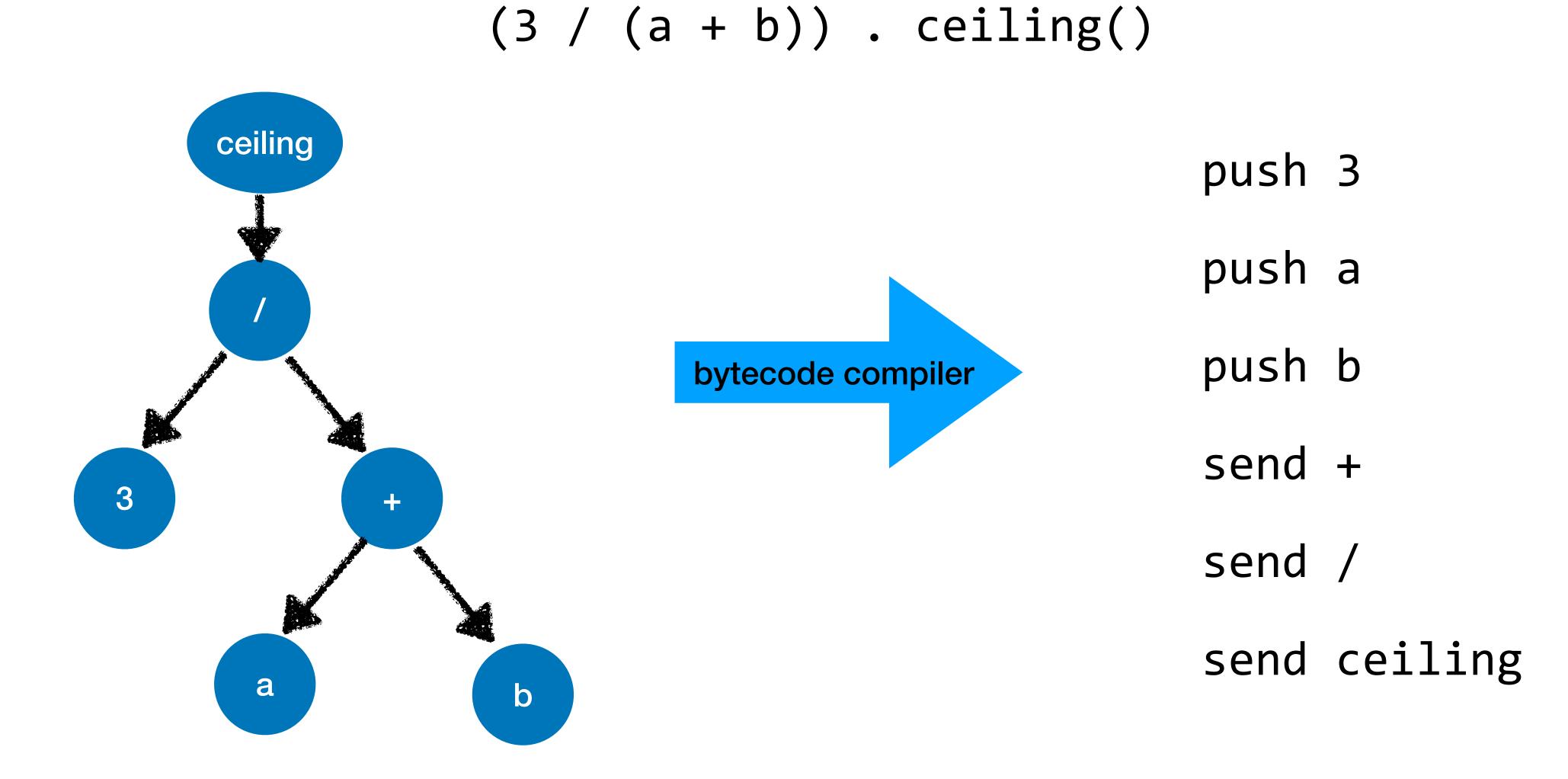
Some disadvantages



$$(3 / (a + b)) \cdot ceiling()$$

- You need an AST implementation!
- "Fat" representation
- "Decoding instructions" is expensive: Execution needs to jump here and there between nodes

Stack-based linear code



```
push 3
push a
push b
send +
send /
send ceiling
```

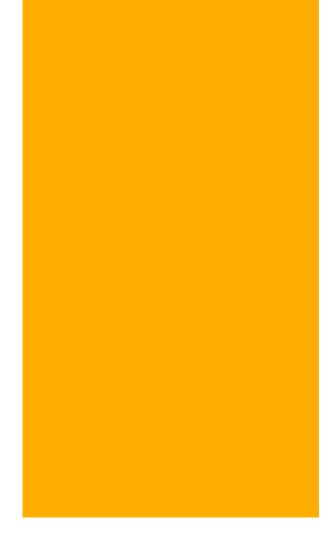
```
(3 / (a + b)) . ceiling()
```

- Each operation produces or consumes values into/from the stack
- Compact linear representation
- Execution "falls" from one instruction to the next one

send ceiling

An example

```
(3 / (a + b)) \cdot ceiling()
push 3
push a
push b
send +
send /
```

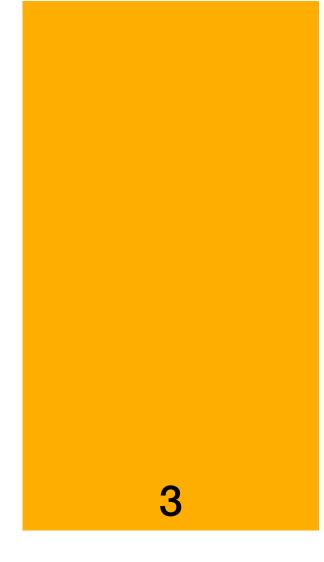


the stack

send ceiling

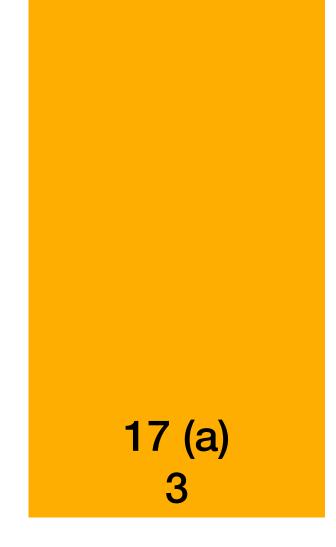
An example

```
(3 / (a + b)) \cdot ceiling()
push 3
push a
push b
send +
send /
```



```
An example
```

```
(3 / (a + b)) \cdot ceiling()
push 3
push a
push b
send +
send /
send ceiling
```



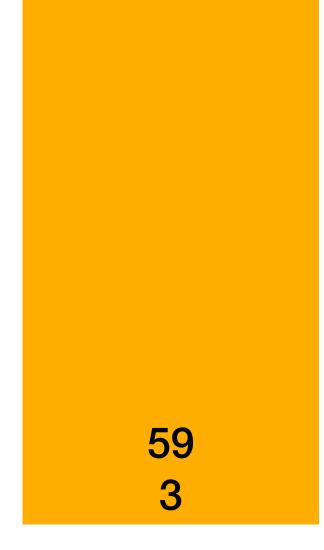
An example

```
(3 / (a + b)) \cdot ceiling()
push 3
push a
push b
send +
send /
send ceiling
```

42 (b) 17 (a) 3

```
An example
```

```
(3 / (a + b)) \cdot ceiling()
 push 3
 push a
 push b
send +
send /
send ceiling
```



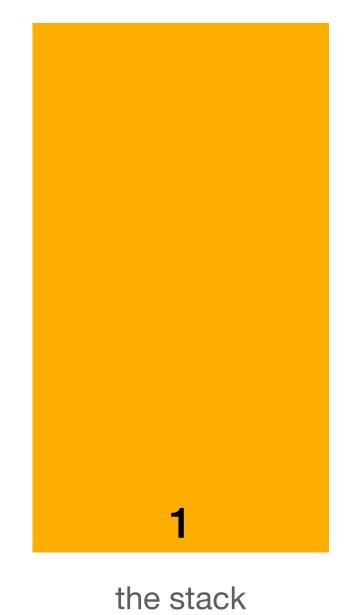
An example

```
(3 / (a + b)) \cdot ceiling()
push 3
push a
push b
send +
send /
send ceiling
```

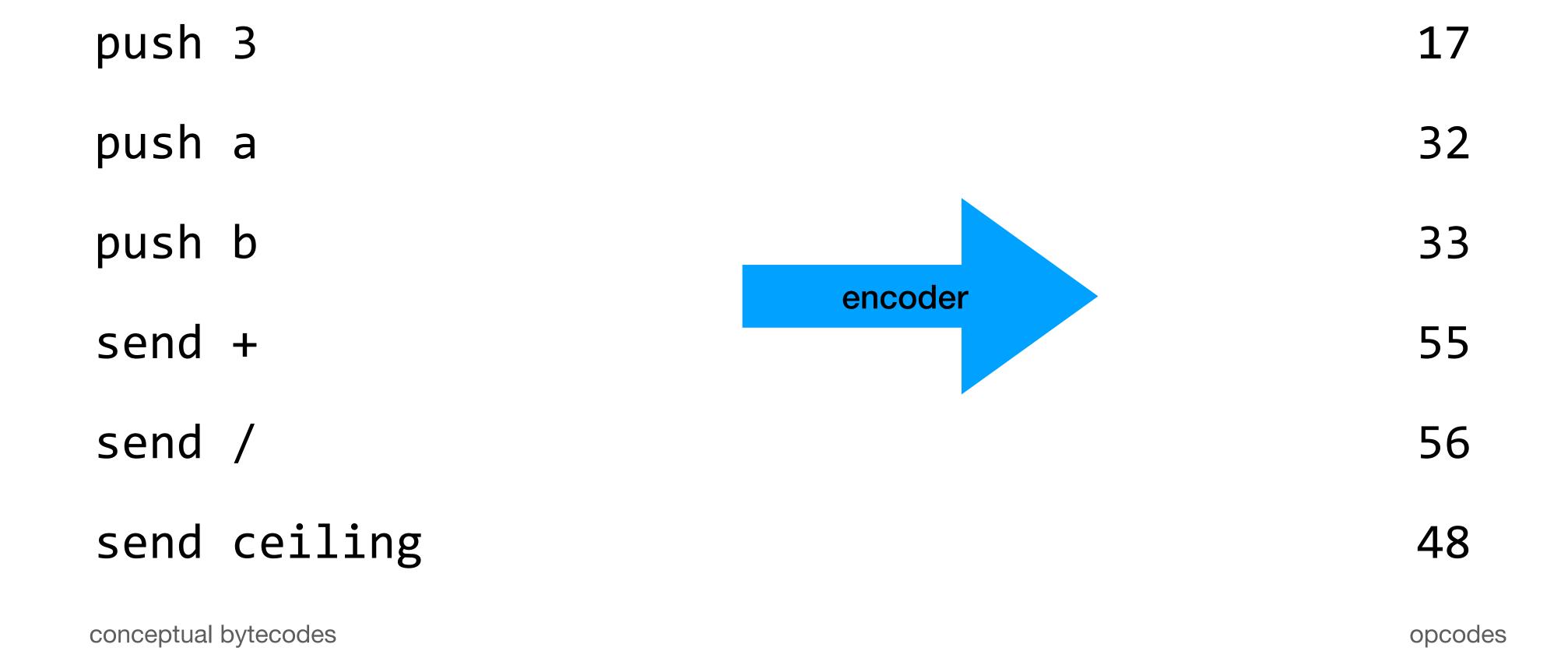


```
An example
```

```
(3 / (a + b)) \cdot ceiling()
  push 3
  push a
  push b
  send +
  send /
send ceiling
```



Binary Bytecode Representation



Encoding bytecodes

- Each kind of bytecode will have an opcode or "operation code"
- Opcodes may be of fixed size (e.g., all 1 byte) or variable size (e.g., all different)
- Important! They must be non-ambiguous => the bytecode interpreter should be able to determine what to do from an opcode

Representing Control Flow

- Conditionals and loops alter the order of execution
- Both can be represented with two kind of instructions:
 - conditional jumps: move the program counter to some other point
 - unconditional jumps: move the program counter if some condition is met

- Jumps may have an absolute program counter to jump to, or a relative offset
- Loops are generally modelled with backward jumps, or "backjumps"

Representing Control Flow

Example if

```
if (cond) {
  //A
} else {
  //B
}
//C
```

```
1: push cond
2: jumpIfFalseTo 5
3: // code for A
4: jumpTo 6
5: // code for B 4/6: // code for C
```

Representing Control Flow

Example loop

```
while (cond) {
  //A
}
// B
```

```
1: push cond
2: jumpIfFalseTo 5
3: // code for A
4: jumpTo 1
5: // code for B
```

Bytecode Families

- Many bytecodes will do the same but with different parametrization
- E.g., push constant 1, push constant 2, push constant 'my string'

- This means we could have an operation "push constant" with a parameter
- These can be encoded as
 - one byte for the opcode and one byte for the parameter or;
 - one byte that has the opcode (5 bits) and the parameter (3 bits)

Generic vs Specific Bytecodes

- Case: reading a variable should look it up in the scope chain
 - But! this lookup can be pre-computed at compile-time
- Option 1: have a generic bytecode "read variable"
 - then let the interpreter lookup variables at runtime
- Option 2: have many specific bytecodes
 - read local, read field/instance variable, read global ...
 - decide what opcode to use at compile time

There is more than the bytecode

Meta-data

- We need a binary format including class declarations, method declarations...
- The "bytecode" will be only inside the methods
- This means meta-data needs to be encoded too
 - (and be non-ambiguous)

```
beginClass Person
  beginMethod sumThree
    pushConstant 1
    pushConstant 2
    send +
    returnTop
  endMethod
...
endClass
```

There is more than the bytecode

Literals

- Literals in the code need to be encoded somehow
- One possibility:
 - put all the literals in a table
 - have a bytecode pushLiteral indexInTheTable

• Literal tables can be stored per method, per class, per file...

```
literal table
1 "my String"
2 42.75007
```

•••

```
beginMethod foo
  pushLiteral 1
  send size
  pushLiteral 2
  send +
  returnTop
endMethod
```

Common bytecode optimisations

- Common long bytecodes could have shorter versions
 - Compact bytecodes and literals tables
 - e.g., pushTrue instead of pushConstant true
- Common sequences can have a special combined bytecode
 - Compact size of methods + less bytecode fetch overhead
 - e.g., a bytecode storeAndPop combining (store, pop) sequence
 - e.g., a bytecode returnTrue combining (push true, returnTop) sequence

Conclusion

- Bytecode is generally used to represent a stack-based linear code
- Compact and linear representation
- Execution falls through
- Except for conditionals and loops that modify the control-flow => rely on jumps
- Different designs lead play with complexity to achieve compactness, speed...
- Moreover, in general bytecode needs to have associated meta-data