

MACHINE LEARNING

LEIC IST-UL

RELATÓRIO - HOMEWORK 1

Grupo 10:

Gabriel Ferreira 107030 Irell Zane 107161

Part I: Pen and paper

1. F1-measure of a kNN.

| | | I |) | | N | | | | | |
|-----|----|----|----|----|----|----|----|----|--|--|
| | x1 | x2 | x3 | x4 | x5 | x6 | x7 | x8 | | |
| x1 | - | 2 | 1 | 0 | 1 | 1 | 1 | 2 | | |
| x2 | 2 | - | 1 | 2 | 1 | 1 | 1 | 0 | | |
| x3 | 1 | 1 | - | 1 | 2 | 2 | 0 | 1 | | |
| x4 | 0 | 2 | 1 | - | 1 | 1 | 1 | 2 | | |
| x5 | 1 | 1 | 2 | 1 | - | 0 | 2 | 1 | | |
| x6 | 1 | 1 | 2 | 1 | 0 | - | 2 | 1 | | |
| x7 | 1 | 1 | 0 | 1 | 2 | 2 | - | 1 | | |
| _x8 | 2 | 0 | 1 | 2 | 1 | 1 | 1 | _ | | |

Table 1: Hamming distance between observations

Thus with k = 5, and a leave-one-out evaluation schema, we use the closest 5 observations for each, excluding itself, to calculate the estimate using a weighted mode like so:

$$f(x_{new}) \leftarrow \underset{c \in \{P,N\}}{\operatorname{argmax}} \sum_{i=1}^{i} w_{i} \cdot \delta(c, f(x_{i}))$$
$$w_{i} = \begin{cases} \frac{1}{d(x_{n}ew, x_{i})} & \text{if } x_{new} \neq x_{i} \\ 1 & else \end{cases}$$

In this case, because the relevant observations all have distances of either 0 or 1, the weight of each is the same:

| | | I |) | | N | | | | | | |
|-----|----|----|----|----|----|----|----|----|---|---|--------------|
| | x1 | x2 | x3 | x4 | x5 | x6 | x7 | x8 | Р | N | $f(x_{new})$ |
| x1 | - | - | 1 | 0 | 1 | 1 | 1 | - | 2 | 3 | N |
| x2 | - | - | 1 | - | 1 | 1 | 1 | 0 | 1 | 4 | N |
| x3 | 1 | 1 | - | 1 | - | - | 0 | 1 | 3 | 2 | P |
| x4 | 0 | - | 1 | - | 1 | 1 | 1 | - | 2 | 3 | N |
| x5 | 1 | 1 | - | 1 | - | 0 | - | 1 | 3 | 2 | P |
| x6 | 1 | 1 | - | 1 | 0 | - | - | 1 | 3 | 2 | P |
| x7 | 1 | 1 | 0 | 1 | _ | - | - | 1 | 4 | 1 | P |
| _x8 | _ | 0 | 1 | - | 1 | 1 | 1 | - | 2 | 3 | N |

Table 2: leave-one-out evaluation kNN classifications

Now the confusion matrix:

To calculate the F1-Measure we now need Precision and Recall:

$$\begin{aligned} \text{Recall} &= \frac{TP}{TP + FN} = \frac{1}{4} \\ \text{Precision} &= \frac{TP}{TP + FP} = \frac{1}{4} \end{aligned}$$

I.1 Solution:

F1 Score =
$$\frac{2}{\frac{1}{P} + \frac{1}{R}} = \frac{2}{4+4} = \frac{1}{4}$$

2. An example of a distance and k that will improve the F1-Measure by three fold is the following:

I.2 Solution:

$$d(x_1, x_2) = 2 \cdot d_{y_1}(x_1, x_2) + d_{y_2}(x_1, x_2)$$
$$k = 3$$

Where $d_{y_j}(x_1, x_2)$ is the Hamming distance between x_1 and x_2 considering only the variable y_j .

To demonstrate the same process as previous but with the new distance measure and k value:

| | | I |) | | | 1 | 1 | |
|-----|----|----|----|----|----|----|----|----|
| | x1 | x2 | x3 | x4 | x5 | x6 | x7 | x8 |
| x1 | - | 3 | 1 | 0 | 2 | 2 | 1 | 2 |
| x2 | 3 | - | 2 | 3 | 1 | 1 | 2 | 0 |
| x3 | 1 | 2 | - | 1 | 3 | 3 | 0 | 2 |
| x4 | 0 | 3 | 1 | - | 2 | 2 | 1 | 2 |
| x5 | 2 | 1 | 3 | 2 | - | 0 | 3 | 1 |
| x6 | 2 | 1 | 3 | 2 | 0 | - | 3 | 1 |
| x7 | 1 | 2 | 0 | 1 | 3 | 3 | - | 2 |
| _x8 | 3 | 0 | 2 | 3 | 1 | 1 | 2 | _ |

Table 3: New distance between observations

| | | I | | N | | | | | | | |
|-----|----|----|----|----|----|----|----|----|---|---|--------------|
| | x1 | x2 | x3 | x4 | x5 | x6 | x7 | x8 | Р | N | $f(x_{new})$ |
| x1 | - | - | 1 | 0 | - | - | 1 | - | 2 | 1 | P |
| x2 | - | - | - | - | 1 | 1 | - | 0 | 0 | 3 | N |
| x3 | 1 | - | - | 1 | - | - | 0 | - | 2 | 1 | P |
| x4 | 0 | - | 1 | - | - | - | 1 | - | 2 | 1 | P |
| x5 | - | 1 | - | - | - | 0 | - | 1 | 1 | 2 | N |
| x6 | - | 1 | - | - | 0 | - | - | 1 | 1 | 2 | N |
| x7 | 1 | - | 0 | 1 | - | - | - | - | 3 | 0 | P |
| _x8 | - | 0 | - | - | 1 | 1 | - | - | 1 | 2 | N |

Table 4: leave-one-out evaluation with new metric

This metric performs better in this data set as can be seen in the confusion matrix:

$$\begin{aligned} \text{Recall} &= \frac{TP}{TP + FN} = \frac{3}{4} \\ \text{Precision} &= \frac{TP}{TP + FP} = \frac{3}{4} \end{aligned}$$

F1 Score =
$$\frac{2}{\frac{1}{P} + \frac{1}{R}} = \frac{2}{\frac{4}{3} + \frac{4}{3}} = \frac{3}{4}$$

3. (a) Dataset:

| \overline{x} | y_1 | y_2 | y_3 | Class |
|----------------|-------|-------|-------|-------|
| 1 | A | 0 | 1.1 | Р |
| 2 | В | 1 | 0.8 | P |
| 3 | A | 1 | 0.5 | Р |
| 4 | A | 0 | 0.9 | Р |
| 5 | В | 0 | 1.0 | N |
| 6 | В | 0 | 0.9 | N |
| 7 | A | 1 | 1.2 | N |
| 8 | В | 1 | 0.9 | N |
| 9 | В | 0 | 0.8 | Р |

Table 5: Observed Values

(b) **Priors**:

• For class Positive (P):

$$p(P) = \frac{5}{9}$$

• For class Negative (N):

$$p(N) = \frac{4}{9}$$

(c) Class-conditional Probabilities:

- Calculate the probabilities of the variable set $\{y_1, y_2\}$ given each class.
- The values are calculated as follows:

$$p(y_1 = A, y_2 = 0) = \frac{2}{9}$$

$$p(y_1 = A, y_2 = 1) = \frac{2}{9}$$

$$p(y_1 = B, y_2 = 0) = \frac{2}{9}$$

$$p(y_1 = B, y_2 = 1) = \frac{3}{9}$$

$$p(y_1 = A, y_2 = 0|P) = \frac{2}{5}$$

$$p(y_1 = A, y_2 = 1|P) = \frac{1}{5}$$

$$p(y_1 = B, y_2 = 0|P) = \frac{1}{5}$$

$$p(y_1 = B, y_2 = 1|P) = \frac{1}{5}$$

$$p(y_1 = A, y_2 = 1|P) = \frac{1}{5}$$

$$p(y_1 = A, y_2 = 1|P) = \frac{1}{5}$$

$$p(y_1 = A, y_2 = 0|N) = 0$$

$$p(y_1 = A, y_2 = 1|N) = \frac{1}{4}$$

$$p(y_1 = B, y_2 = 1|N) = \frac{1}{4}$$

(d) Mean and Standard Deviation of y_3 :

• For all observations:

$$\mu_{y_3} = \frac{1.1 + 0.8 + 0.5 + 0.9 + 0.8 + 1.0 + 0.9 + 1.2 + 0.9}{9}$$
= 0.9

$$\sigma_{y_3} = \sqrt{\frac{(1.1 - 0.9)^2 + (0.8 - 0.9)^2 + (0.5 - 0.9)^2 + (0.9 - 0.9)^2 \dots}{9}}$$

$$\approx 0.2$$

4

• For Positive (P):

$$\begin{split} \mu_{y_3,P} &= \frac{1.1 + 0.8 + 0.5 + 0.9 + 0.8}{5} = 0.82 \\ \sigma_{y_3,P} &= \sqrt{\frac{(1.1 - 0.82)^2 + (0.8 - 0.82)^2 + (0.5 - 0.82)^2 + \dots}{5}} \\ &\approx 0.217 \end{split}$$

• For Negative (N):

$$\mu_{y_3,N} = \frac{1.0 + 0.9 + 1.2 + 0.9}{4} = 1.0$$

$$\sigma_{y_3,N} = \sqrt{\frac{(1.0 - 1.0)^2 + (0.9 - 1.0)^2 + (1.2 - 1.0)^2 + (0.9 - 1.0)^2}{4}}$$

$$\approx 0.1414$$

(e) Prediction of Class:

• To predict the class of a new observation (y_1, y_2, y_3) , we calculate the probability for both classes (Positive and Negative) and choose the class with the higher probability:

Predicted Class =
$$\underset{h}{\operatorname{argmax}} p(h|y_1, y_2, y_3)$$

where
$$p(h|y_1, y_2, y_3) = \frac{p(y_1, y_2, y_3|h) \cdot p(h)}{p(y_1, y_2, y_3)}$$

$$= \frac{p(y_1, y_2|h) \cdot p(y_3|h) \cdot p(h)}{p(y_1, y_2) \cdot p(y_3)}$$
where $p(y_3|h) = \frac{1}{\sigma_h \sqrt{2\pi}} \exp\left(-\frac{(y_3 - \mu_h)^2}{2\sigma_h^2}\right)$
and $p(y_3) = \frac{1}{0.2\sqrt{2\pi}} \exp\left(-\frac{(y_3 - 0.9)^2}{2 \cdot 0.2^2}\right)$

4. Under a MAP assumption we do not need to calculate the denominator, thus:

Predicted Class =
$$\underset{h}{\operatorname{argmax}} \{ p(y_1, y_2 | h) \cdot p(y_3 | h) \cdot p(h) \}$$

(a) For observation (A, 1, 0.8):

For class P:

$$p(y_3 = 0.8|P) = \frac{1}{0.217\sqrt{2\pi}} \exp\left(-\frac{(0.8 - 0.82)^2}{2 \cdot 0.217^2}\right)$$

$$= 1.83$$

$$p(y_3 = 0.8) = \frac{1}{0.2\sqrt{2\pi}} \exp\left(-\frac{(0.8 - 0.9)^2}{2 \cdot 0.2^2}\right)$$

$$= 1.76$$

$$p(P) \cdot p(y_1 = A, y_2 = 1, y_3 = 0.8|P) = \frac{5}{9} \cdot \frac{1}{5} \cdot 1.83$$

$$\approx 0.203$$

For class N:

$$p(y_3 = 0.8|N) = \frac{1}{0.1414\sqrt{2\pi}} \exp\left(-\frac{(0.8 - 1.0)^2}{2 \cdot 0.1414^2}\right)$$
$$= 1.038$$
$$p(N) \cdot p(y_1 = A, y_2 = 1, y_3 = 0.8|N) = \frac{4}{9} \cdot \frac{1}{4} \cdot 1.038$$
$$\approx 0.115$$

Since 0.203 > 0.115, the predicted class is P.

(b) For observation (B, 1, 1):

For class P:

$$p(y_3 = 1|P) = \frac{1}{0.217\sqrt{2\pi}} \exp\left(-\frac{(1 - 0.82)^2}{2 \cdot 0.217^2}\right)$$

$$= 1.304$$

$$p(y_3 = 1) = \frac{1}{0.2\sqrt{2\pi}} \exp\left(-\frac{(1 - 0.9)^2}{2 \cdot 0.2^2}\right)$$

$$= 1.76$$

$$p(P) \cdot p(y_1 = B, y_2 = 1, y_3 = 1|P) = \frac{5}{9} \cdot \frac{1}{5} \cdot 1.304$$

$$\approx 0.145$$

For class N:

$$p(y_3 = 1|N) = \frac{1}{0.1414\sqrt{2\pi}} \exp\left(-\frac{(1-1.0)^2}{2\cdot 0.1414^2}\right)$$
$$= 2.82$$
$$p(N) \cdot p(y_1 = B, y_2 = 1, y_3 = 1|N) = \frac{4}{9} \cdot \frac{1}{4} \cdot 2.82$$
$$\approx 0.313$$

Since 0.145 < 0.313, the predicted class is N.

(c) For observation (B, 0, 0.9):

For class P:

$$p(y_3 = 0.9|P) = \frac{1}{0.217\sqrt{2\pi}} \exp\left(-\frac{(0.9 - 0.82)^2}{2 \cdot 0.217^2}\right)$$

$$= 1.72$$

$$p(y_3 = 0.9) = \frac{1}{0.2\sqrt{2\pi}} \exp\left(-\frac{(0.9 - 0.9)^2}{2 \cdot 0.2^2}\right)$$

$$= 1.99$$

$$p(P) \cdot p(y_1 = B, y_2 = 0, y_3 = 0.9|P) = \frac{5}{9} \cdot \frac{1}{5} \cdot 1.72$$

$$\approx 0.191$$

For class N:

$$p(y_3 = 0.9|N) = \frac{1}{0.1414\sqrt{2\pi}} \exp\left(-\frac{(0.9 - 1.0)^2}{2 \cdot 0.1414^2}\right)$$
$$= 2.20$$
$$p(N) \cdot p(y_1 = B, y_2 = 0, y_3 = 0.9|N) = \frac{4}{9} \cdot \frac{2}{4} \cdot 2.20$$
$$\approx 0.489$$

Since 0.191 < 0.489, the predicted class is N.

5. Class-conditional frequency of each word in the training vocabulary.

| c | "Amazing" | "run" | "I" | "like" | "it" | "Too" | "tired" | "bad" | N_c | V |
|---|-----------|-------|-----|--------|------|-------|---------|-------|-------|---|
| Р | 1 | 1 | 1 | 1 | 1 | 0 | 0 | 0 | 5 | 0 |
| N | 0 | 1 | 0 | 0 | 0 | 1 | 1 | 1 | 4 | 8 |

Under a ML assumption, for the word w:

Predicted Class =
$$\underset{c}{\operatorname{argmax}} \{ p(c|w) \}$$
$$= \underset{c}{\operatorname{argmax}} \{ \frac{p(w|c) \cdot p(c)}{p(w)} \}$$
$$= \underset{c}{\operatorname{argmax}} \{ \prod_{c} p(t_i|c) \}$$

Since 0.000280 > 0.000096, the predicted class is P.

I.5 Solution:
Since
$$0.000280 > 0.000096$$
, the predicted class is P.

Part II: Programming

1. Solution to the programming questions here.

End note: do not forget to also submit your Jupyter notebook