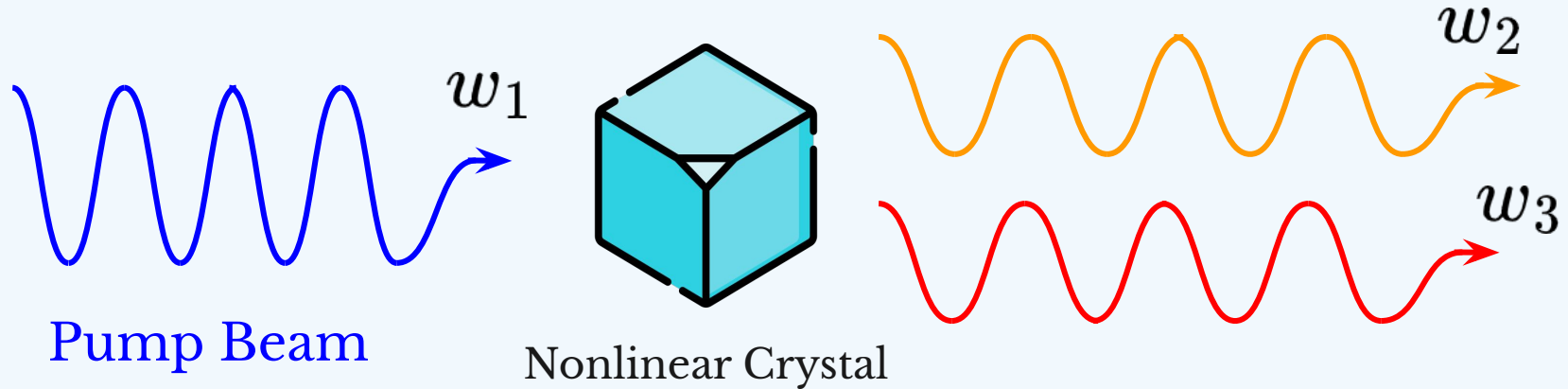


Non-classical Behaviour and Pattern Formation in DOPO

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Introduction

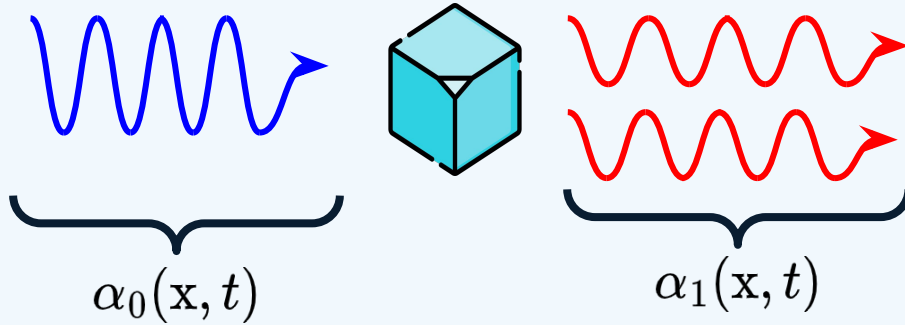
The **Optical Parametric Oscillator (OPO)** employs a nonlinear crystal in a cavity to convert a high intensity **pump beam**, in two coherent beams at lower energies.



Degenerated Optical Parametric Oscillator (DOPO): $\omega_2 = \omega_3$

DOPO: Equations in Q-representation

Objectives



- Study pattern formation in the system.
- Understand how does the pattern change with the system size.

$$\begin{cases} \partial_t \alpha_0(\mathbf{x}, t) = - \left[(1 + i\Delta_0) - i\partial_x^2 \right] \alpha_0(\mathbf{x}, t) + E - \frac{1}{2} \alpha_1^2(\mathbf{x}, t) + \sqrt{\frac{2}{d}} \frac{g}{\gamma} \xi_0(\mathbf{x}, t), \\ \partial_t \alpha_1(\mathbf{x}, t) = - \left[(1 + i\Delta_1) - 2i\partial_x^2 \right] \alpha_1(\mathbf{x}, t) + \alpha_0(\mathbf{x}, t) \alpha_1^*(\mathbf{x}, t) + \sqrt{\frac{2}{d}} \frac{g}{\gamma} \xi_1(\mathbf{x}, t) \end{cases}$$

$$\xi_1(x, t) = \left[\frac{-\alpha_{0I}(x, t)}{2\sqrt{2 + \alpha_{0R}(x, t)}} + \frac{i}{2} \sqrt{2 + \alpha_{0R}(x, t)} \right] \phi(x, t) + \sqrt{\frac{1 - \frac{|\alpha_0(x, t)|^2}{4}}{2 + \alpha_{0R}(x, t)}} \psi(x, t)$$

$\xi_0(x, t)$, $\psi(x, t)$, $\phi(x, t)$ are uncorrelated gaussian white noises in space and time.

The set of equations can be concisely written as:

$$\partial_t \alpha_k(\mathbf{x}, t) = - [z_k - a_k i \partial_x^2] \alpha_k(\mathbf{x}, t) + f_k(\alpha_0(\mathbf{x}, t), \alpha_1(\mathbf{x}, t), E) + b_k \xi_k(\mathbf{x}, t)$$

$$z_k = 1 + i\Delta_k, \quad a_0 = 1, \quad a_1 = 2, \quad b_k = \sqrt{\frac{2}{d}} \frac{g}{\gamma}, \quad k = 0, 1$$

$$f_0(\alpha_1(\mathbf{x}, t), E) = E - \frac{1}{2} \alpha_1^2(\mathbf{x}, t), \quad f_1(\alpha_0(\mathbf{x}, t), \alpha_1(\mathbf{x}, t)) = \alpha_0(\mathbf{x}, t) \alpha_1^*(\mathbf{x}, t).$$

Pattern Formation: Linear Stability

Classical equations (zero noise)

$$\begin{cases} \partial_t \alpha_0(\mathbf{x}, t) = - \left[(1 + i\Delta_0) - i\partial_x^2 \right] \alpha_0(\mathbf{x}, t) + E - \frac{1}{2} \alpha_1^2(\mathbf{x}, t) \\ \partial_t \alpha_1(\mathbf{x}, t) = - \left[(1 + i\Delta_1) - 2i\partial_x^2 \right] \alpha_1(\mathbf{x}, t) + \alpha_0(\mathbf{x}, t) \alpha_1^*(\mathbf{x}, t) \end{cases}$$

Steady and
homogeneous
solution

$$\begin{aligned} \alpha_0^{st} &= \frac{E}{1+i\Delta_0} \\ \alpha_1^{st} &= 0 \end{aligned}$$

Dispersion Relation

$$\lambda_{\pm}(k) = -1 \pm \sqrt{|\alpha_0^{st}| - (\Delta_1 + 2k^2)^2}$$

Critical values

$$k_c = \sqrt{-\Delta_1/2} \quad E_c = \sqrt{1 + \Delta_0^2}$$

Numerical Solution


- Using the centered-space Heun method, the numerical integration is given by:

$$\begin{aligned}
 A_{k,n}^{(1)}(t_j) &= A_{k,n}(t_j) + \Delta t [-z_k A_{k,n}(t_j) + D_k \delta A_{k,n}(t_j) + f_k] + b_k \sqrt{\frac{\Delta t}{\Delta x}} w_{k,n}(t_j) \\
 A_{k,n}(t_{j+1}) &= A_{k,n}(t_j) - \frac{\Delta t z_k}{2} \left(A_{k,n}(t_j) + A_{k,n}^{(1)}(t_j) \right) + \frac{\Delta t D_k}{2} \left(\delta A_{k,n}(t_j) + \delta A_{k,n}^{(1)}(t_j) \right) \\
 &\quad + \frac{\Delta t}{2} \left(f_k(A_{0,n}(t_j), E) + f_k(A_{0,n}^{(1)}(t_j), E) \right) + \frac{1}{2} b_k \sqrt{\frac{\Delta t}{\Delta x}} (w_{k,n}(t_j) + w_{k,n}^{(1)}(t_j))
 \end{aligned}$$

$$\begin{aligned}
 D_k &\equiv i \frac{a_k}{(\Delta x)^2}, \quad w_{0,n}(t_j) = w_{0,n}^{(1)}(t_j) \equiv u_n(t_j), \quad w_{1,n}(t_j) \equiv \sum_{l=1}^2 u_{l,n}(t_j) g_l(A_{0,n}(t_j)), \\
 w_{1,n}^{(1)}(t_j) &\equiv \sum_{l=1}^2 u_{l,n}(t_j) g_l(A_{0,n}^{(1)}(t_j)), \quad \delta A_{k,n}(t_j) \equiv A_{k,n+1}(t_j) - 2A_{k,n}(t_j) + A_{k,n-1}(t_j)
 \end{aligned}$$

Parameters

$$\Delta_0 = 0, \quad \Delta_1 = -0.18, \quad \frac{g}{\sqrt{d}\gamma} = 10^{-4}$$


$$E_c = 1.0, \quad k_c = 0.3, \quad \lambda_c = \frac{2\pi}{k_c}$$

Initial
Conditions

$$A_{0,n}(0) = E \quad \forall n, \quad A_{1,n}(0) = 10^{-5}(\epsilon(x_n) + 10\sin(k_c x_n))$$

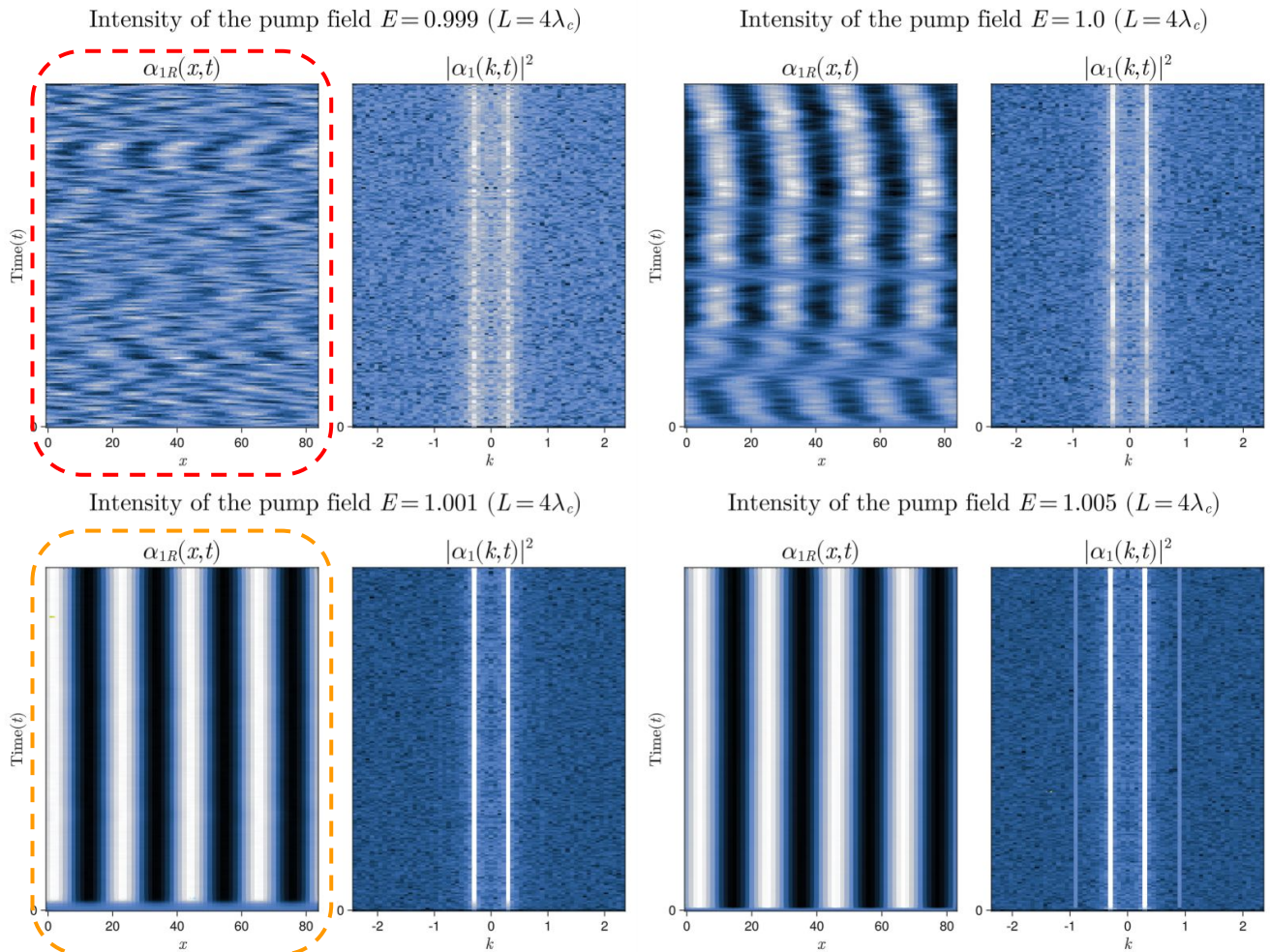
Discretization

$$\Delta t = 0.01, \quad \Delta x = \frac{L}{n-1}, \quad n = 64$$

Results for $L = 4\lambda_c$

Noisy precursor
produced by
quantum
fluctuations

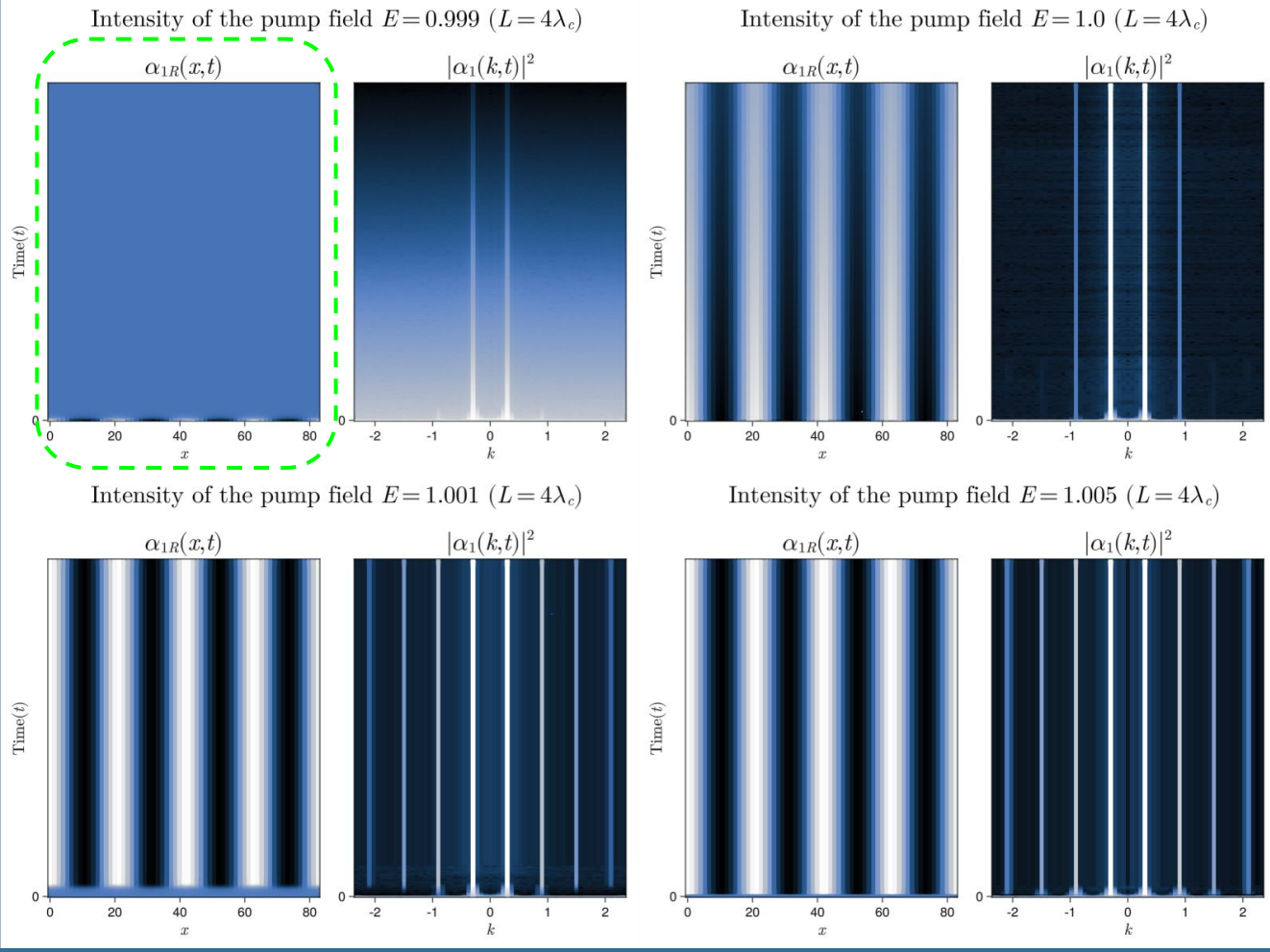
By slightly
increasing the
intensity of the
pump field above
threshold, the
pattern becomes
fully formed



Results for $L = 4\lambda_c$

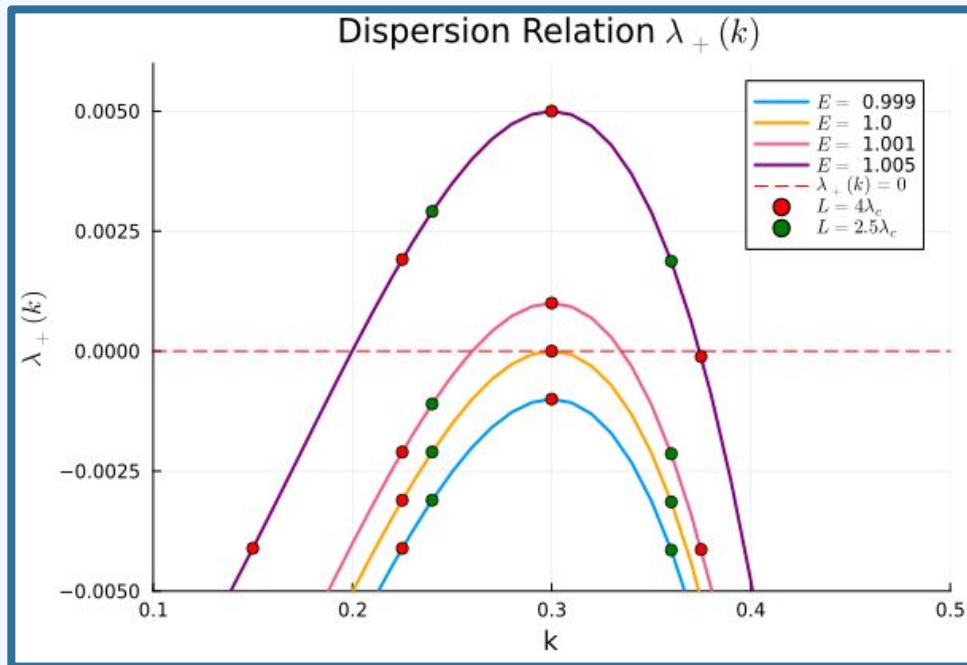
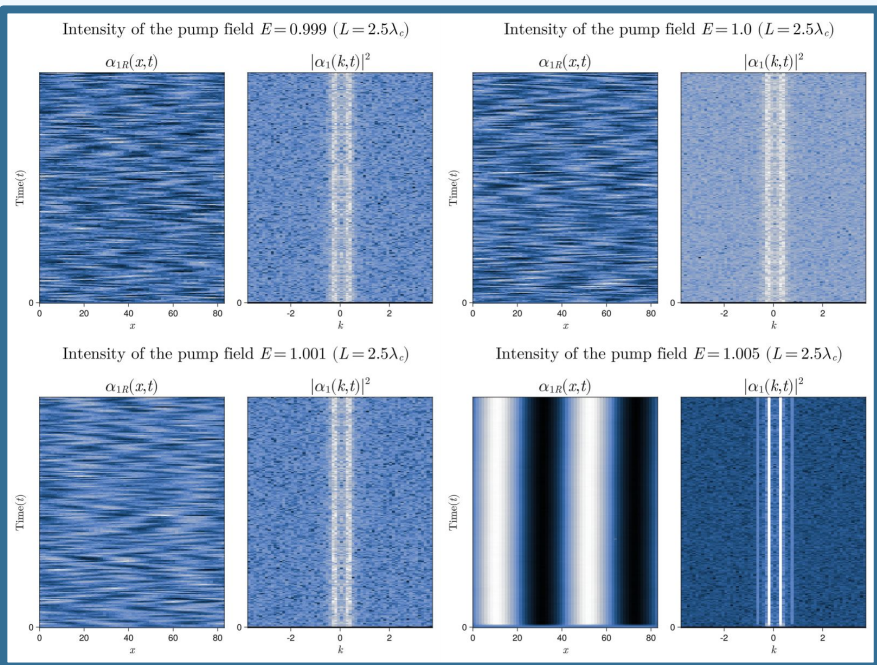
Zero noise
 $b_k = 0$

Turning off the
noise, we obtain
an homogeneous
field



Results for $L = 2.5\lambda_c$

The threshold can change due to the finite size of the system.



Conclusions

- The noisy precursor produced by quantum fluctuations has been obtained as well as the striped pattern that appears above threshold.
- We have shown that the threshold can change due to the finite size effects.

Thanks for your attention

Reference

- Roberta Zambrini et al. “Non-classical behavior in multimode and disordered transverse structures in OPO: Use of the Q-representation”. In: Springer 22 (2003), pp. 461–471. DOI: <https://doi.org/10.1140/epjd/e2003-00019-7>

Appendix: Generalized Stochastic Heun Method

$$\frac{d\mathbf{x}}{dt} = q(\mathbf{x}(t), t) + \sum_{j=1}^d g_j(\mathbf{x}(t), t) \xi_j(t)$$

$$\mathbf{x}^{(1)}(t_i) = \mathbf{x}(t_i) + \Delta t q(\mathbf{x}(t_i), t_i) + \Delta t \sum_{j=1}^d u_j(t_i) g(\mathbf{x}(t_i), t_i)$$

$$\begin{aligned} \mathbf{x}(t_{i+1}) = & \mathbf{x}(t_i) + \frac{\Delta t}{2} \left[q(\mathbf{x}(t_i), t_i) + q(\mathbf{x}^{(1)}(t_i), t_{i+1}) \right] \\ & + \frac{\sqrt{\Delta t}}{2} \sum_{j=1}^d u_j(t_i) \left[g(\mathbf{x}(t_i), t_i) + g(\mathbf{x}^{(1)}(t_i), t_{i+1}) \right] \end{aligned}$$

Appendix: Finite differences, Centered-Space Method

$$A_{k,n}(t) = \frac{1}{\sqrt{\Delta x}} \int_{x_n}^{x_{n+1}} \alpha_k(x, t) dx, \quad \xi_{k,n}^{cg}(t) = \frac{1}{\sqrt{\Delta x}} \int_{x_n}^{x_{n+1}} \xi_k(x, t) dx$$

$$\begin{aligned} \frac{dA_{k,n}(t)}{dt} = & -z_k A_{k,n}(t) + a_k i \left[\frac{A_{k,n+1}(t_i) - 2A_{k,n}(t_i) + A_{k,n-1}(t_i)}{(\Delta x)^2} \right] \\ & + f_k(A_{k,0}(t), A_{k,1}(t), t, E) + \frac{b_k}{\sqrt{\Delta x}} \xi_{k,n}(t) \end{aligned}$$

Appendix: Code Implementation

$$\lambda_{k,n}(t_j) = \Delta t \left[-z_k A_{k,n}(t_j) + i \frac{a_k}{(\Delta \mathbf{x})^2} \delta A_{k,n}(t_j) + f_k(A_{0,n}(t_j), A_{1,n}(t_j), E) \right] + b_k \sqrt{\frac{\Delta t}{\Delta x}} w_{k,n},$$

$$A_{k,n}^{(1)}(t_j) = A_{k,n}(t_j) + \lambda_{k,n}(t_j),$$

$$\begin{aligned} A_{k,n}(t_{j+1}) = & A_{k,n}(t_j) + \frac{1}{2} \lambda_k + \frac{\Delta t}{2} \left(-z_k A_{1,n}^{(1)}(t_j) + D_k \delta A_{1,n}^{(1)}(t_j) + f_k(A_{0,n}^{(1)}(t_i), A_{1,n}^{(1)}(t_i), E) \right) \\ & + \frac{1}{2} b_k \sqrt{\frac{\Delta t}{\Delta x}} w_{k,n}^{(1)} \end{aligned}$$