

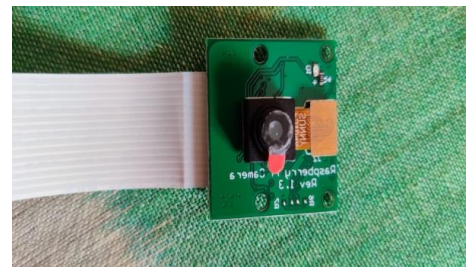
# Images of the project and the components used.

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Motor drive controller



Pi Camera



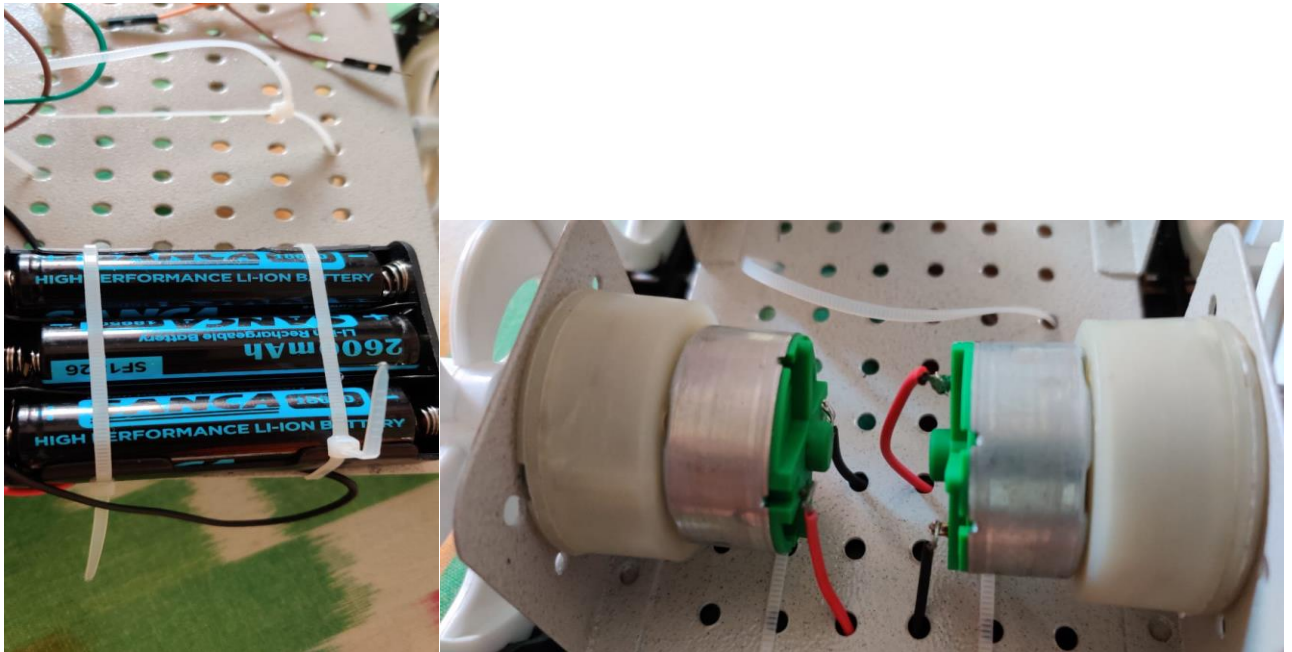
Servo Motor



Raspberry Pi3



Motors fixed to rover wheels and battery power supply for components



Camera and componenets fixed on rover

