

LECTURE - I

LECTURE - II

- Topics:-
- ① Mathematical modelling
 - ② Classical mechanics
 - ③ Thermodynamics
 - ④ Statistical mechanics
 - ⑤ Quantum Mechanics

Reference books:-

- 1) Concept of Modern Physics

- Arthur Compton

2) Feynmann Lectures on Physics

3) Physical Chemistry - Atkins

4) Fundamentals of statistical and thermal
Physics - F. Reif

5) Classical Mechanics - Goldstein

6) Mechanics - L D Landau & Lifschitz

7) Quantum Chemistry - I. N. Levine

8) Quantum mechanics - Griffiths

grading :-

Mid I - 20%

Mid II - 20%

End Sem - 40%

Assignments & Quizzes - 20%

LECTURE - III

Diffusion or Brownian Motion

The model we use is random walk.

→ One-Dimensional Random Walk

→ Axioms:-

- 1) It is one dimensional
- 2) Particle starts from $x=0$.
- 3) Each step ~~before it takes~~ it takes is of equal length (l).
- 4) The direction of each step is completely independent of the preceding step (i.e. it is random).
- 5) At each time, the probability of a step to be to the right is p , while the probability for step to be to the left is q .

→ Questions:- After N ~~a second~~ steps, what is the probability of it being at some x ? :-

→ ~~Analysis~~

n_1 - number of steps to the right

n_2 - number of steps to the left

$$\therefore n_1 + n_2 = N$$

Taking l as a unit,

Net Displacement = $m = (n_1 - n_2)$

$$n_1 = \frac{N+m}{2}, n_2 = \frac{N-m}{2}$$

We need to find ~~to~~ the probability ~~of~~ of taking n_1 steps to the right, out of N steps. (W_N(n))

Simple case:-

$$N=3, n_1=2, n_2=1$$

$\rightarrow \rightarrow \leftarrow, \rightarrow \leftarrow \rightarrow, \leftarrow \rightarrow \rightarrow \Rightarrow 3$ possibilities

$x \rightarrow$ number of experiments

classmate
Date _____
Page _____

$$v = \sqrt{\frac{3RT}{2m}} = \sqrt{\frac{3kT}{n}} \Rightarrow \sqrt{\frac{3X}{2 \times 10}} \frac{N!}{n!} \left(\frac{1}{2}\right)^{N/2}$$

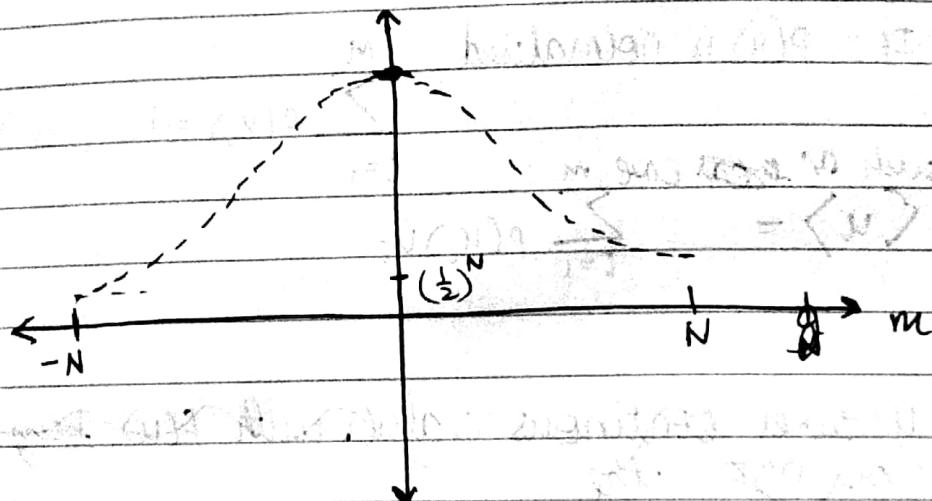
In general

$$W_N(n_1) = \frac{N!}{n_1! n_2!} \cdot p^{n_1} \cdot q^{n_2}$$

: Probability for net displacement to be m after N steps, is

$$P_N(m) = \frac{N!}{\left(\frac{N+m}{2}\right)! \left(\frac{N-m}{2}\right)!} p^{\left(\frac{N+m}{2}\right)} q^{\left(\frac{N-m}{2}\right)}$$

for unbiased random walk, $p = q = \frac{1}{2}$



Statistics :-

We find $\langle n_i \rangle$ & $\langle \text{mean } \phi_{n_i} \rangle$

$\langle n_i \rangle$ - mean value of n_i

$\langle n_i - \langle n_i \rangle \rangle$ - mean deviation σ in n_i .
(average of deviation)

$\langle (n_i - \langle n_i \rangle)^2 \rangle$ - fluctuation or second moment
(average of deviation squared)
 \propto mean-squared deviation

$\langle m \rangle, \langle m - \langle m \rangle \rangle, \langle (m - \langle m \rangle)^2 \rangle$

General statistics :-

If u is a variable that can take M discrete values u_1, u_2, \dots, u_M with respective probabilities $p(u_1), p(u_2), \dots, p(u_M)$.

Then,

$$\langle u \rangle = \sum_{i=1}^M p(u_i) u_i$$

$$\text{or } \sum_{i=1}^M p(u_i)$$

If $p(u)$ is normalised,

$$\sum_{i=1}^M p(u_i) = 1$$

In such or ~~etc~~ case,

$$\therefore \langle u \rangle = \sum_{i=1}^M p(u_i) u_i$$

If u takes continuous values with $f(u)$ being PDF, then

~~Ans~~

If $f(u)$ is any function of u , then

$$\langle f(u) \rangle = \frac{\sum_{i=1}^M p(u_i) f(u_i)}{\sum_{i=1}^M p(u_i)}$$

If $\Delta u = u - \langle u \rangle$, i.e. Δu is deviation, then

$$\langle \Delta u \rangle = \langle u - \langle u \rangle \rangle = \langle u \rangle - \langle u \rangle = 0$$

$$\langle (\Delta u)^2 \rangle = \langle u^2 \rangle + \langle (\Delta u)^2 \rangle - 2\langle u \Delta u \rangle \quad \langle (u - \langle u \rangle)^2 \rangle$$

$$= \langle u^2 \rangle + \cancel{\langle (\Delta u)^2 \rangle} - \langle u \Delta u \rangle - 2\langle u \Delta u \rangle$$

$$= \langle u^2 \rangle + \langle (\Delta u)^2 \rangle - 2\langle u \Delta u \rangle$$

$$= \langle u^2 \rangle + \langle u \rangle^2 - 2\langle u \rangle^2$$

$$= \cancel{\langle u^2 \rangle} - \cancel{\langle u \rangle^2}$$

$$\langle (\Delta u)^2 \rangle = \langle u^2 \rangle - \langle u \rangle^2$$

Note that

$$\langle (\Delta u)^2 \rangle \geq 0 \Rightarrow \langle u^2 \rangle \geq \langle u \rangle^2$$

n^{th} moment of the Probability Distribution :-

$$\langle (\Delta u)^n \rangle = \langle (u - \langle u \rangle)^n \rangle$$

For our random walker,

$$\langle n_i \rangle = \sum_{n_i=0}^N P(n_i) n_i$$

$$= \sum_{n_i=0}^N \left(\frac{N!}{(n_i!) (N-n_i)!} \cdot p^{n_i} q^{N-n_i} \right) n_i$$

$$= \sum_{n_i=0}^N \left(\frac{N!}{n_i! (N-n_i)!} \cdot p^{n_i} q^{N-n_i} \right) n_i$$

$$\text{From } \sum_{n=0}^N {}^N C_n p^n q^{N-n} = (p+q)^N$$

$$\text{Let } f(p) = \sum_{n=0}^N {}^N C_n p^n q^{N-n}$$

Note that

$$p \cdot \frac{\partial(p^n)}{\partial p} = np^{n-1}$$

$$\therefore \langle n \rangle = \sum_{n_1=0}^N \frac{N!}{n_1!(N-n_1)!} p^{N-n_1} q^{n_1} \frac{\partial}{\partial p} \langle p^n \rangle$$

$$\Rightarrow \langle n \rangle = p \frac{\partial}{\partial p} \left[\sum_{n_1=0}^N \frac{N!}{n_1!(N-n_1)!} p^{N-n_1} q^{n_1} \right]$$

$$= p \frac{\partial}{\partial p} \left[(p+q)^N \right].$$

$$= p \cdot N \cdot (p+q)^{N-1}$$

$$\Rightarrow \langle n \rangle = pN(p+q)^{N-1}$$

If $p+q=1$, i.e. e.g. unbiased walk, then

$$\langle n \rangle = pN$$

Similarly,

$$\langle n_2 \rangle = qN$$

$$P = \sum_{n=0}^N C_n p^n q^{N-n}$$

classmate

date

page

4

LECTURE - IV

$$\Delta n_1 \equiv \bar{n}_1 - \langle n_1 \rangle$$

we need to find

$$\langle \Delta n_1 \rangle, \langle \Delta n_2 \rangle, \langle \Delta m \rangle \text{ & } \frac{\langle (\Delta n_1)^2 \rangle, \langle (\Delta n_2)^2 \rangle, \langle (\Delta m)^2 \rangle}{\downarrow}$$

this quantity can be measured experimentally for any solute in a solvent.

$$W_N(n_1) = \frac{N!}{(n_1!) (n_2!) \cdot n_1! \cdot n_2!} \cdot p^{n_1} \cdot q^{n_2} = \frac{N!}{n_1! \cdot n_2!} \cdot p^{n_1} q^{N-n_1}$$

$$\langle n_1 \rangle = pN, \langle n_2 \rangle = qN$$

($= \sum_{n_1=0}^N n_1 W_N(n_1)$)

$$\langle m \rangle = \langle n_1 - n_2 \rangle = \langle n_1 \rangle - \langle n_2 \rangle = pN - qN$$

$$\Rightarrow \langle m \rangle = (p-q)N$$

e.g. for unbiased random walk, $\langle m \rangle = 0$

Now,

~~$$\langle (\Delta n)^2 \rangle = \langle (n_1 - \langle n_1 \rangle)^2 \rangle$$~~

$$\langle (\Delta n)^2 \rangle = \langle n^2 \rangle - \langle n \rangle^2$$

$$\langle n_1^2 \rangle = \sum_{n_1=0}^N n_1^2 \cdot W_N(n_1) = \sum_{n_1=0}^N n_1^2 C_n p^{n_1} q^{N-n_1}$$

$$\frac{\partial^2}{\partial p^2} p^n = n(n-1) p^{n-2}$$

$$n_i p^{n_i} =$$

classmate
Date _____
Page _____

$$\langle n_i^2 \rangle = \sum_{n_i=0}^N n_i^2 \cdot {}^N C_{n_i} p^{n_i} q^{N-n_i}$$

$$\bullet n_i p \frac{\partial}{\partial p} p^n = n_i^2 p^{n_i} \neq 0 = p \frac{\partial^2}{\partial p^2} p^n$$

$$p \frac{\partial}{\partial p} (p \frac{\partial}{\partial p} p^n) = n_i^2 p^{n_i}$$

$$= \sum_{n_i=0}^N {}^N C_{n_i} \cdot n_i \cdot p \frac{\partial}{\partial p} p^{n_i} \cdot p^{n_i} q^{N-n_i}$$

$$= p \frac{\partial}{\partial p} \left[\sum_{n_i=0}^N {}^N C_{n_i} p^{n_i} q^{N-n_i} \right]$$

$$= p \frac{\partial}{\partial p} \left(n_i \right) n_i p \frac{\partial}{\partial p} p^{n_i} = n_i^2 p^{n_i}$$

$$\langle n_i^2 \rangle = \sum_{n_i=0}^N n_i^2 \cdot {}^N C_{n_i} p^{n_i} q^{N-n_i}$$

$$n_i^2 p^{n_i} = n_i \cdot$$

$$n_i p^{n_i} = p \frac{\partial}{\partial p} p^{n_i}$$

$$n_i^2 p \frac{\partial}{\partial p} p^{n_i} = p \frac{\partial}{\partial p} \left(p \frac{\partial}{\partial p} p^{n_i} \right) = p \left[p \frac{\partial^2}{\partial p^2} p^{n_i} + \frac{\partial}{\partial p} p^{n_i} \right]$$

$$= p \frac{\partial}{\partial p} p^{n_i} + p \frac{\partial}{\partial p} p^{n_i}$$

$$= p^2 \frac{\partial^2}{\partial p^2} p^{n_i} + p \frac{\partial}{\partial p} p^{n_i}$$

$$\frac{p^2}{\partial p} \frac{\partial p^n}{\partial p} = p^n n_1 (n_1 - 1) \frac{\partial^2}{\partial p^2}$$

classmate

Date _____
Page 5

$$\langle n_1^2 \rangle = \sum_{n_1=0}^N {}^N C_{n_1} q^{N-n_1} \left(\frac{p^2}{\partial p^2} \frac{\partial^2 p^n}{\partial p^n} + p \frac{\partial p^n}{\partial p} \right)$$

$$= \frac{p^2}{\partial p^2} \sum_{n_1=0}^N {}^N C_{n_1} q^{N-n_1} \cdot p^{n_1} + \frac{\partial}{\partial p} \sum_{n_1=0}^N {}^N C_{n_1} \cdot p^{n_1} q^{N-n_1}$$

$$= p^2 \cdot \frac{\partial^2}{\partial p^2} [(p+q)^N] + p \frac{\partial}{\partial p} [(p+q)^N]$$

$$= p^2 [N(N-1)(p+q)^{N-2}] + p^N (p+q)^{N-1}$$

$$\langle n_1^2 \rangle = p^2 [N^2 - N] + pN$$

$$= p^2 N^2 - Np^2 + pN$$

$$= p^2 N^2 + pN(1-p)$$

$$\langle n_1^2 \rangle = (pN)^2 + pqN$$

$$\therefore \langle (\Delta n_1)^2 \rangle = \langle n_1^2 \rangle - (\langle n_1 \rangle)^2$$

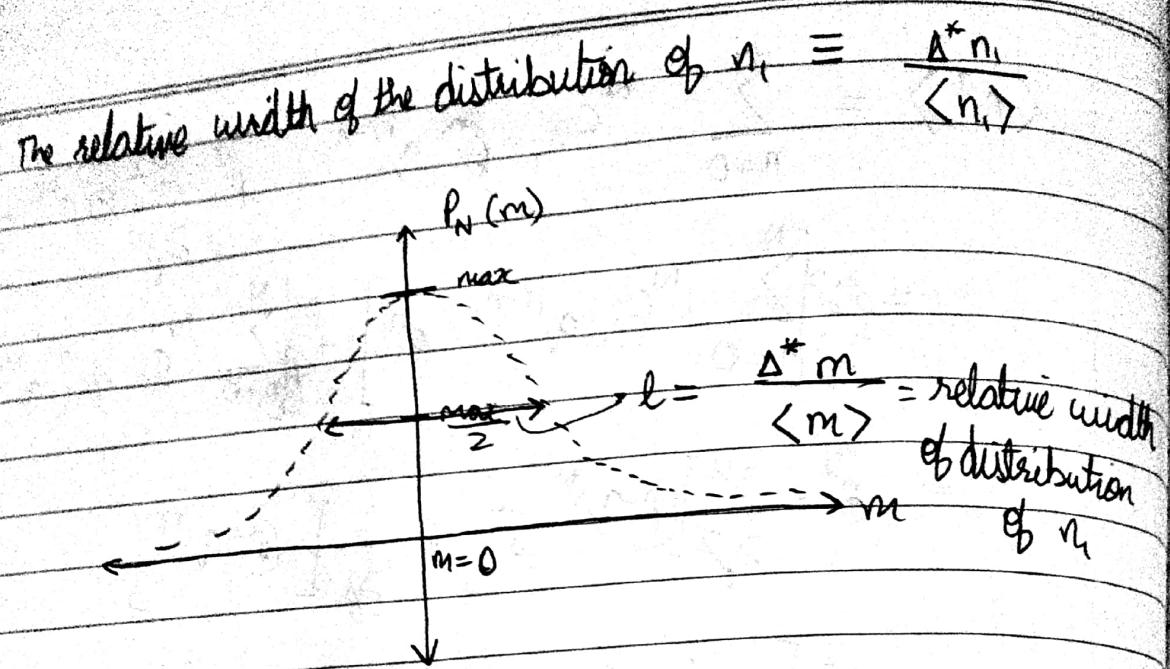
$$= (pN)^2 + pqN - (pN)^2$$

$$\boxed{\langle (\Delta n_1)^2 \rangle = pqN}$$

Root mean square deviation of $n_1 = \sqrt{\langle (\Delta n_1)^2 \rangle} = \Delta^* n_1$
 Similarly, $\langle (\Delta n_2)^2 \rangle = pqN$

$$\Rightarrow \Delta^* n_1 = \sqrt{\langle (\Delta n_1)^2 \rangle} = \sqrt{pqN}$$

$$\Delta^* n_2 = \sqrt{pqN}$$



$$\text{For } n_1, \text{ relative width of distribution} = \sqrt{\frac{pqN}{P_N}}$$

$$= \sqrt{\frac{q}{P_N}}$$

\therefore For unbiased case,

$$\text{relative width} = \sqrt{\frac{1}{N}}$$

Width measures the spread of data and is, in some sense, the error in measurement.

So here, error decreases with number of measurement.

$$\langle (\Delta m)^2 \rangle = \langle m^2 \rangle - (\langle m \rangle)^2 = 4 \langle (\Delta n)^2 \rangle$$

as

$$m = n_1 - n_2 = 2n_1 - N$$

$$\Delta m = m - \langle m \rangle$$

$$= 2n_1 - N - \langle 2n_1 - N \rangle$$

$$= 2[n_1 - \langle n_1 \rangle] = 2\Delta n$$

$$\Rightarrow (\Delta m)^2 = 4(\Delta n)^2$$

$$\langle (\Delta m)^2 \rangle = 4 \langle (\Delta n)^2 \rangle$$

$$\langle (\Delta m)^2 \rangle = 4pqN$$

$$\Delta^* m = 2\sqrt{pqN}$$

e.g. for unbiased case,

$$\Delta^* m = \sqrt{N}$$

Also, in general,

$$\langle (\Delta m)^2 \rangle \propto N$$

$$\langle (\Delta m)^2 \rangle = \langle (m^2 + \langle m \rangle^2 - 2m\langle m \rangle) \rangle = \langle m^2 \rangle + \langle m \rangle^2 - 2\langle m \rangle \langle m \rangle$$

Since $\Delta m = 0$ for unbiased random walker,

$$\Rightarrow \langle m^2 \rangle \propto N$$

\rightarrow mean square displacement

Mean square displacement of random walker increases linearly with time.

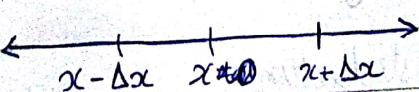
LECTURE-II

For random distribution diffusion, ①

$$\langle x^2 \rangle \propto \text{time}$$

\rightarrow random diffusion

→ Derivation of the Diffusion Equation from the random walk model
(one dimensional)



$\Delta x \rightarrow$ step length of random walker

$$\frac{d^2 f(x)}{dt^2} = \lim_{h_1 \rightarrow 0} \lim_{h_2 \rightarrow 0} \frac{f(x+h_1+h_2) - f(x+h_1) - f(x+h_2) + f(x)}{h_1 h_2}$$

$$= \lim_{h \rightarrow 0} \frac{f(x+2h) - 2f(x+h) + f(x)}{h}$$

classmate

Date _____
Page _____

$P(x,t)$ \rightarrow probability of that random walker is at x at time t .

We try to find $P(x, t + \Delta t)$

$$P(x, t + \Delta t) = ?$$

Δt - the timestep

In fact

$$P(x, t + \Delta t) \approx P(x, t) \Pi$$

$$= P(x + \Delta x, t) \Pi(x + \Delta x \rightarrow x)$$

$$+ P(x - \Delta x, t) \Pi(x - \Delta x \rightarrow x) \xrightarrow{\text{transitional probability}}$$

$$- P(x, t) \Pi(x \rightarrow x + \Delta x) \text{ i.e probability to move}$$

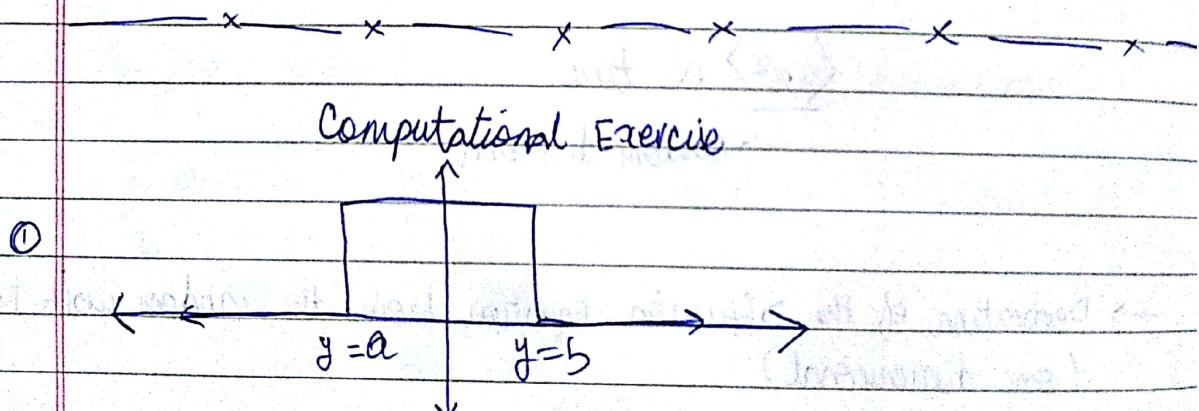
$$- P(x, t) \Pi(x \rightarrow x - \Delta x) \text{ from } x + \Delta x \rightarrow x$$

For an unbiased random walker,

$$\Pi(x \rightarrow x + \Delta x) = \Pi(x \rightarrow x - \Delta x) = \frac{1}{2}$$

i.e all transitional probabilities Π_{ab} is equal to 0.5

$$\therefore P(x, t + \Delta t) \approx P(x, t) = \frac{[P(x + \Delta x, t) - 2P(x, t)]}{2} + P(x - \Delta x, t)$$



①

$$y = a \quad y = b$$

$$P(y) = \begin{cases} 0, & y \notin [a, b] \\ \frac{1}{b-a}, & y \in [a, b] \end{cases}$$

Uniform distribution.

$$P(y) = \begin{cases} 0, & y \notin [a, b] \\ \frac{1}{b-a}, & y \in [a, b] \end{cases}$$

$$\lim_{h \rightarrow 0} \frac{f(x+h) - f(x)}{h}$$

Range: $y \in [0,1]$ i.e. $a=0, b=1$

If $y < \frac{1}{2}$, x moves left else it moves right

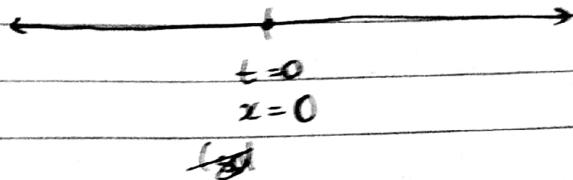
LECTURE - III

23 August 2018

Langevin Dynamics

Mathematical model for simulation of solute in a solvent.

One dimensional case:-



Solute, at $x=0$, at $t=0$, in a solvent

Two forces - viscous force, which resists motion of particle, and a random force, which acts on the particle randomly
 $m \rightarrow$ mass of particle

$x(t)$ position of particle at time t

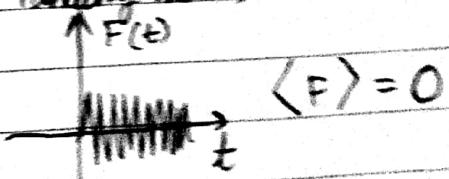
Equation of motion -

$$m \frac{dx}{dt} = -\alpha \dot{x} + F(t) \quad \text{--- (1)}$$

$\frac{dx}{dt}$ damping force
 $\underbrace{-\alpha \dot{x}}$ random force

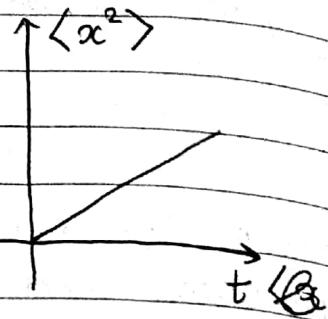
($\alpha > 0$ friction coefficient) (fluctuates randomly with t)

Q)



What is $\langle x^2 \rangle$ of the solute?

For a random walk, $\langle x^2 \rangle \propto t$



$$m \frac{d\dot{x}}{dt} = -\alpha \dot{x} + F(t)$$

Multiplying with α on both sides,

$$m \frac{d(\alpha \dot{x})}{dt} = -\alpha x \ddot{x} + \alpha F(t)$$

$$\Rightarrow m \left[\frac{d(\alpha \dot{x})}{dt} - (\dot{x})^2 \right] = -\alpha x \ddot{x} + \alpha F(t)$$

Taking average on both sides,

$$m \left[\left\langle \frac{d(\alpha \dot{x})}{dt} \right\rangle - \left\langle (\dot{x})^2 \right\rangle \right] = -\alpha \left\langle x \ddot{x} \right\rangle + \underbrace{\left\langle x F(t) \right\rangle}_{\downarrow}$$

$$= -\alpha \langle x \dot{x} \rangle + \langle x \rangle \langle F(t) \rangle$$

as $x, F(t)$ are uncorrelated
independence.
2. Since $\langle F(t) \rangle = 0$

$$m \left[\left\langle \frac{d(x\dot{x})}{dt} \right\rangle - \left\langle \dot{x}^2 \right\rangle \right] = -\alpha \left\langle x\dot{x} \right\rangle \quad \textcircled{2}$$

We know that, mean K.E $\langle \text{K} \rangle$ is

$$\langle \text{K} \rangle = \frac{1}{2} k_B T = \frac{1}{2} m \langle \dot{x}^2 \rangle$$



k_B - Boltzmann Constant
 T - Temperature

From \textcircled{2},

$$m \left[\left\langle \frac{d(x\dot{x})}{dt} \right\rangle - \frac{k_B T}{m} \right] = -\alpha \left\langle x\dot{x} \right\rangle$$

$$\Rightarrow m \left\langle \frac{d(x\dot{x})}{dt} \right\rangle = \alpha k_B T - \alpha \left\langle x\dot{x} \right\rangle$$

$$\text{Also, } \left\langle \frac{du}{dt} \right\rangle = \frac{d}{dt} \langle u \rangle$$

$$\therefore m \frac{d}{dt} \langle x\dot{x} \rangle = k_B T - \alpha \langle x\dot{x} \rangle \quad \textcircled{3}$$

This is a linear differential equation in $\langle x\dot{x} \rangle$

∴ Solution is

$$\langle x\dot{x} \rangle = \cancel{C} + \frac{k_B T}{\alpha} + ce^{-\alpha t} \quad \textcircled{4}$$

Here, C is the constant of integration.

$$\cancel{C} = \frac{a}{m}$$

Note at $t=0$,

Note that,

$$\langle \dot{x}^2 \rangle = \frac{1}{2} \frac{d}{dt} \langle x^2 \rangle$$

equation 4 implies

$$\frac{1}{2} \frac{d}{dt} \langle x^2 \rangle = cc^{-\alpha t} - \frac{k_BT}{\alpha} \cancel{x}$$

According to initial condition at $t=0, x=0$

$$c = - \frac{k_BT}{\alpha} \text{ (at } t=0, \langle x^2 \rangle = 0)$$

i.e. ④ becomes

$$\frac{1}{2} \frac{d}{dt} \langle x^2 \rangle = \frac{k_BT}{\alpha} \left(1 - c^{-\alpha t} \right) \quad ⑤$$

∴

Integrating from $t=0$ to $t=t$,

$$\langle x^2 \rangle = 2 \frac{k_BT}{\alpha} \left[t - \left(\frac{e^{-\alpha t}}{\alpha} + \frac{1}{\alpha} \right) \right]$$

$$\Rightarrow \boxed{\langle x^2 \rangle = \frac{2k_BT}{\alpha} \left[t - \left(\frac{1 - e^{-\alpha t}}{\alpha} \right) \right]}$$

$$+ \frac{e^{-\alpha t}}{2} \Big|_0^t \quad \frac{d}{dt} \langle x^2 \rangle = \langle \frac{d}{dt} (x^2) \rangle$$

classmate

Date _____
Page 9

Limiting cases -

D) When $t \ll \frac{1}{\alpha} \Rightarrow 0 < \alpha t \ll 1$ (short time diffusion)

$$\therefore e^{-\alpha t} \approx 1$$

$$\therefore \langle x^2 \rangle = \frac{2k_B T}{\alpha} \sqrt{t} = \textcircled{a}$$

$$\therefore e^{-\alpha t} = 1 - \alpha t + \frac{\alpha^2 t^2}{2} + \dots$$

neglecting higher powers

as $\alpha t \ll 1$,

$$e^{-\alpha t} = 1 - \alpha t + \frac{1}{2} \alpha^2 t^2$$

$$\langle px^2 \rangle = \frac{2k_B T}{\alpha} \left(t - \frac{1}{2} \frac{\alpha t}{\alpha} \right) \neq 0$$

$$\therefore \langle x^2 \rangle = \frac{2k_B T}{\alpha} \left[t - \frac{1}{2} \left(t - (1 - \alpha t + \frac{1}{2} \alpha^2 t^2) \right) \right]$$

$$= \frac{2k_B T}{\alpha} \left[t - \frac{1}{2} \left(\alpha t - \frac{1}{2} \alpha^2 t^2 \right) \right]$$

$$\langle x^2 \rangle = \frac{2k_B T}{\alpha} \alpha t^2 = \left(\frac{k_B T}{m} \right) t^2$$

This is similar to a free particle with no force as

$$\frac{dx}{dt} = 0 \Rightarrow x \propto t \Rightarrow x^2 \propto t^2 \Rightarrow \langle x^2 \rangle \propto t^2$$

\therefore Solute behaves like a free particle for a short period of time

$$\sum_{n_1=0}^{\infty} w_N^2(n_1) = \sum_{n_1=0}^{\infty} \left[\frac{(N!)^2}{(n_1)(N-n_1)!} \left(\frac{1}{2}\right)^N \right]$$

2.70 Long time limit i.e.
 $t \gg \frac{1}{\gamma} \Rightarrow \gamma t \gg 1$

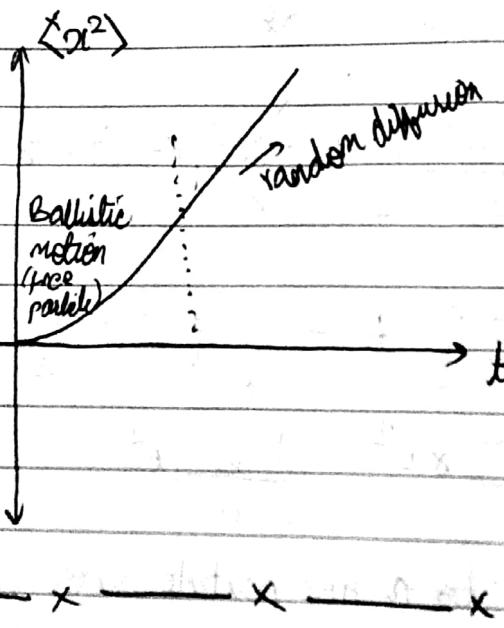
$$\therefore e^{-\gamma t} \approx 0$$

Ans:-

$$\langle x^2 \rangle = \frac{2k_B T}{\alpha} \left(t - \left(1 - \frac{e^{-\gamma t}}{\gamma}\right) \right)$$

$$= \frac{2k_B T}{\alpha} \left(t - \frac{1}{\gamma} \right)$$

\therefore After a very long time it tends to linear time dependence
 i.e. it tends to a random walk.

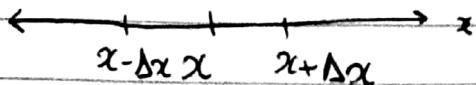


Class Assignment 8-I :-

Two drunks start out at the origin, each having equal probability of making a step to the left or right along the x-axis. Find the probability that they meet again after N steps. It is to be understood that the men take their steps simultaneously.

LECTURE - VII

Derivation of the ~~different~~ diffusion equation from random walk Model (one-dimensional case) -



$\Delta x \rightarrow$ step length in a given time step Δt

It is an unbiased random walker.

Transition Probabilities -

$$\text{P}(\text{x} + \Delta x \rightarrow \text{x}) = 1/2$$

$$\text{P}(\text{x} - \Delta x \rightarrow \text{x}) = 1/2$$

$$\text{P}(\text{x} \rightarrow \text{x} + \Delta x) = 1/2$$

or

$$\text{P}(\text{x} \rightarrow \text{x} - \Delta x) = 1/2$$

$P(x, t)$ \Rightarrow probability of finding the random walker at x at time t .

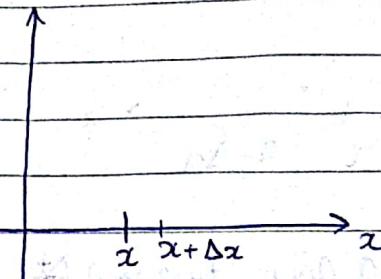
The change in probability can be written as

$$\begin{aligned} P(x, t + \Delta t) &= P(x, t) - P(x, t) \\ &= -\text{P}(x \rightarrow x + \Delta x) \cdot P(x, t) \\ &\quad - \text{P}(x \rightarrow x - \Delta x) \cdot P(x, t) \\ &\quad + \text{P}(x + \Delta x \rightarrow x) \cdot P(x + \Delta x, t) \\ &\quad + \text{P}(x - \Delta x \rightarrow x) \cdot P(x - \Delta x, t) \end{aligned}$$

$$(\alpha) \quad P(x, t + \Delta t) = P(x + \Delta x, t) \text{P}(x + \Delta x \rightarrow x) + P(x - \Delta x, t) \text{P}(x - \Delta x \rightarrow x)$$

$$P(x, t + \Delta t) - P(x, t) = \frac{1}{2} [P(x + \Delta x, t) - 2P(x, t) + P(x - \Delta x, t)]$$

Taylor's Series expansion:-



We know $f(x), f'(x), f''(x), f'''(x)$ at x

i.e we know

$$f(x), \left. \frac{df(x)}{dx} \right|_x, \left. \frac{d^2 f}{dx^2} \right|_x, \dots, \left. \frac{d^n f}{dx^n} \right|_x$$

Then, for sufficiently small Δx ,

$$f(x + \Delta x)$$

$$f(x + \Delta x) = \cancel{f(x)} + \cancel{\left. \frac{df}{dx} \right|_x \Delta x} + \frac{1}{2!} \left. \frac{d^2 f}{dx^2} \right|_x (\Delta x)^2 + \dots + \frac{1}{n!} \left. \frac{d^n f}{dx^n} \right|_x (\Delta x)^n$$

$$\therefore P(x + \Delta x, t) = P(x, t) + \frac{\partial P(x, t)}{\partial x} \Delta x + \frac{1}{2!} \frac{\partial^2 P(x, t)}{\partial x^2} (\Delta x)^2 + \dots$$

similarly,

$$P(x - \Delta x, t) = P(x, t) - \frac{\partial P(x, t)}{\partial x} \Delta x + \frac{1}{2!} \frac{\partial^2 P(x, t)}{\partial x^2} (\Delta x)^2$$

For sufficiently small $\Delta x \neq 0$, we ignore $(\Delta x)^n$ for $n > 2$.

\therefore For $\Delta x \rightarrow 0$,

$$P(x+\Delta x, t) + P(x-\Delta x, t) = 2P(x, t) + \frac{\partial^2}{\partial x^2} P(x, t) (\Delta x)^2$$

$$\Rightarrow P(x+\Delta x, t) - 2P(x, t) + P(x-\Delta x, t) = \left[\frac{\partial^2}{\partial x^2} P(x, t) \right] (\Delta x)^2$$

\hookrightarrow

Putting in ①,

$$\therefore P(x, t+\Delta t) - P(x, t) = \frac{1}{2} \left[\frac{\partial^2}{\partial x^2} P(x, t) \right] (\Delta x)^2$$

Note:-

② Can also be derived in the following way

$$g(x) = \frac{d}{dx} f(x) = \lim_{\Delta x \rightarrow 0} \frac{f(x+\Delta x) - f(x)}{\Delta x}$$

$$h(x) = \frac{d}{dx} g(x) = \frac{d^2}{dx^2} f(x) = \lim_{\Delta x \rightarrow 0} \frac{g(x+\Delta x) - g(x)}{\Delta x}$$

$$= \lim_{\Delta x \rightarrow 0} \frac{f(x+2\Delta x) - 2f(x) + f(x-\Delta x)}{(\Delta x)^2}$$

$$= \lim_{\Delta x \rightarrow 0} \frac{f(x+\Delta x) - 2f(x) + f(x-\Delta x)}{(\Delta x)^2}$$

\therefore For small Δx ,

$$f(x+\Delta x) - 2f(x) + f(x-\Delta x) = (\Delta x)^2 \cdot \frac{d^2}{dx^2} f(x)$$

$$BC e^{\alpha x + \beta t} = D \alpha^2 e^{\alpha x + \beta t}$$

$$BC = \alpha^2 D$$

\therefore for $\Delta x \rightarrow 0$

$$P(x+\Delta x, t+\Delta t) - P(x, t) = \frac{1}{2} \left(\frac{\partial^2 P(x, t)}{\partial x^2} \right) (\Delta x)^2$$

$$\Rightarrow P(x, t+\Delta t) - P(x, t) = \frac{1}{2} \left(\frac{\partial^2 P(x, t)}{\partial x^2} \right) \cdot \frac{(\Delta x)^2}{\Delta t}$$

Now, for $\Delta t \rightarrow 0$,

$$\frac{\partial P(x, t)}{\partial t} = \frac{1}{2} \frac{(\Delta x)^2}{\Delta t} \cdot \frac{\partial^2 P(x, t)}{\partial x^2}$$

↓ time derivative

↓ spatial derivative

$$\text{let } D = \frac{(\Delta x)^2}{\Delta t}$$

D is called the diffusion constant or diffusion coefficient

$$\frac{\partial P(x, t)}{\partial t} = D \frac{\partial^2 P(x, t)}{\partial x^2}$$

Diffusion equation

In general, if we solve the diffusion equation, we can determine $P(x, t)$ (given the initial condition).

For 3-D, the diffusion equation is, given that $\vec{r} = \begin{bmatrix} x \\ y \\ z \end{bmatrix}$

$$\frac{\partial P}{\partial t} = D \nabla^2 P$$

$$\frac{\partial^2 f(x,y)}{\partial x^2} = 0$$

$$\Rightarrow \frac{\partial^2 f(x,y)}{\partial x^2} - g(y) = f(x,y) - g(y) \Rightarrow f(x,y) = g(y)$$

$$\frac{\partial^2 f(x,y)}{\partial y^2} = 0$$

$$\Rightarrow \frac{\partial^2 f(x,y)}{\partial y^2} - g(x) = f(x,y) - g(x) \Rightarrow f(x,y) = g(x)$$

$$\frac{\partial P(r,t)}{\partial t} = D_x \frac{\partial^2 P(r,t)}{\partial x^2} + D_y \frac{\partial^2 P(r,t)}{\partial y^2} + D_z \frac{\partial^2 P(r,t)}{\partial z^2}$$

D_x, D_y, D_z - diffusion coefficient along 3 axes

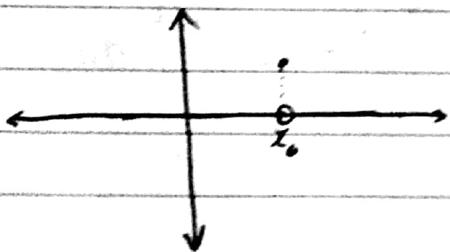
For a homogeneous medium

$$D_x = D_y = D_z \Rightarrow$$

→ Solving the diffusion equation (1-D)

Initial condition - $P(x, t=0) = \delta(x - x_0)$, where

$\delta(x)$ is a function 0 everywhere but $x=0$



For our case, take $x_0 = 0$

$$\therefore P(x, 0) = \delta(x)$$

LECTURE VIII

Diffusion equation :-

$$\frac{\partial P(x,t)}{\partial t} = D \frac{\partial^2 P(x,t)}{\partial x^2}$$

Initial condition :-

$$P(x, 0) = S(x)$$

$$\int u v dx = u \int v dx - \int \frac{du}{dx} \left(\int v dx \right) dx$$

We use Fourier Transformation technique to solve the problem.

Fourier Transformation :-

$$\tilde{P}(k, t) \stackrel{\text{def'd as}}{=} \int_{-\infty}^{\infty} P(x, t) e^{-ikx} dx$$

k = element in inverse space of x -space angular
e.g. we can move from time domain t to frequency
space.

Here we move from ~~real~~ space to inverse space.

Laplace Transform: similar to Fourier transform, but we use s

Inverse Fourier Transform:-

$$P(x, t) \stackrel{\text{def'd as}}{=} \frac{1}{2\pi} \int_{-\infty}^{\infty} \tilde{P}(k, t) e^{ikx} dk$$

Now

We calculate the Fourier transform of $\frac{\partial^2 P(x, t)}{\partial t^2}$ and $\frac{\partial^2 P(x, t)}{\partial x^2}$

$$\frac{\partial^2 \tilde{P}(k, t)}{\partial t^2} = \int_{-\infty}^{\infty} \frac{\partial^2 P(x, t)}{\partial t^2} e^{ikx} dx$$

top

$$\frac{\partial^2 P(x, t)}{\partial x^2} = \frac{\partial^2}{\partial t^2} \int_{-\infty}^{\infty} P(x, t) e^{ikx} dx$$

$$\frac{\partial^2 \tilde{P}(k, t)}{\partial x^2} = \frac{\partial^2}{\partial t^2} \tilde{P}(k, t) \quad \text{--- (1)}$$

$$\int_{\text{boundary}} \psi \partial_x \psi = \frac{1}{2\pi} \int_{-\infty}^{\infty} \left(\int_{-\infty}^{\infty} B(x, t) e^{ikx} dx \right) e^{-ikx} dk$$

classmate

Date _____

Page _____

13

$$\tilde{\frac{\partial^2 P(k, t)}{\partial x^2}} = \int_{-\infty}^{\infty} \frac{2}{2\pi} P(x, t) e^{ikx} dx$$

By now by integration by parts,

$$= \int \left[e^{ikx} \cdot \frac{\partial}{\partial x} P(x, t) \right]_{-\infty}^{\infty}$$

$$- i \int_{-\infty}^{\infty} P(x, t) e^{ikx} dx$$

For $x \rightarrow \pm\infty$, and finite t , $P(x, t) \rightarrow 0$, $\frac{\partial P(x, t)}{\partial x} \rightarrow 0$

$$\therefore \tilde{\frac{\partial^2 P(k, t)}{\partial x^2}} = -ik \cdot \tilde{P}(k, t) \quad \text{--- (1)}$$

$$\text{Now, } \tilde{\frac{\partial^2 P(k, t)}{\partial x^2}} = \int_{-\infty}^{\infty} \frac{2^2}{2\pi} P(x, t) e^{ikx} dx$$

$$= \int \left[e^{ikx} \cdot \frac{2}{2\pi} P(x, t) \right]_{-\infty}^{\infty} - e^{ikx} \int_{-\infty}^{\infty} \frac{2}{2\pi} P(x, t) e^{ikx} dx$$

As $\frac{2}{2\pi} P(x, t) \rightarrow 0$ as $x \rightarrow \pm\infty$,

$$\tilde{\frac{\partial^2 P(k, t)}{\partial x^2}} = -ik \tilde{\frac{\partial P(k, t)}{\partial k}} = -ik(-ik \tilde{P}(k, t))$$

(from (1))

$$\Rightarrow \tilde{\frac{\partial^2 P(k, t)}{\partial x^2}} = -k^2 \tilde{P}(k, t)$$

\therefore In ~~real space~~ ^{k-space}, diffusion equation becomes

$$\frac{\partial P(x, t)}{\partial t} = D \frac{\partial^2 P(x, t)}{\partial x^2}$$

Taking Fourier transform on both sides, and simplifying

$$\frac{\partial}{\partial t} (\mathcal{F} \tilde{P}(k, t)) = D \cdot (-k^2) \tilde{P}(k, t)$$

$$\frac{\partial \tilde{P}(k, t)}{\partial t} = -Dk^2 \tilde{P}(k, t)$$

First order D.E,

Solving this, we get

$$\tilde{P}(k, t) = C \cdot e^{-Dk^2 t}$$

From initial condition

$$P(x, 0) = S(x) = \begin{cases} \infty & \text{at } x=0 \\ 0 & \text{elsewhere} \end{cases}$$

$$P(x=0, t=0) = 1$$

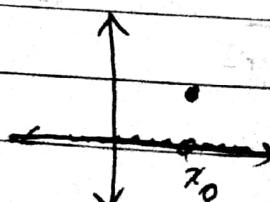
$$P(x, 0) = \underbrace{S(x)}_{\infty}$$

Dirac Delta function

$$\therefore \tilde{P}(k, 0) = \int_{-\infty}^{\infty} \delta(x) \cdot C e^{ikx} dx = C$$

$$\Rightarrow C = \int_{-\infty}^{\infty} \delta(x) \cdot C e^{ikx} dx, x_0 = 0$$

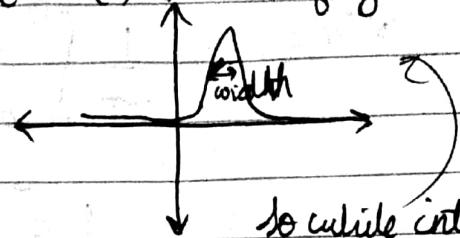
$$S(x-x_0)$$



$$\frac{\partial f(k,t)}{\partial t} = -D k^2 f(k,t)$$

$\therefore C = e^{ik_0 x_0}$ (this is because $\delta(x)$ is limit of Gaussian as width $\rightarrow 0$)
 since $x_0 = 0$,

$$C = 1$$



$$\therefore \hat{P}(k,t) = e^{-Dk^2 t}$$

To calculate integrating
 we integrate Gaussian and then
 take the limit.

Q:

Now, we apply the inverse Fourier transform.

$$\therefore P(x,t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} \hat{P}(k,t) \cdot e^{-ikx} dk$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-ik^2 t} \cdot e^{ikx} dk$$

$$= \sqrt{\frac{1}{2\pi}} \int_{-\infty}^{\infty} e^{-ik^2 t + ikx} dk$$

$$\Rightarrow P(x,t) = \sqrt{\frac{1}{2\pi}} \int_{-\infty}^{\infty} e^{-k^2 t + ikx} dk$$

$$= \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-(Dk^2 t + ikx)} dk$$

$$\text{let } a^2 = Dk^2 t, 2ab = ikx$$

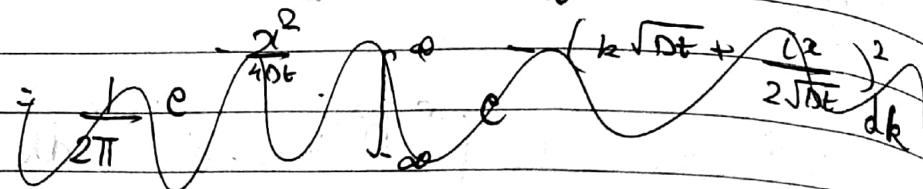
$$\Rightarrow b = \frac{ikx}{2\sqrt{Dt}}$$

Adding and subtracting b^2 in exponent,

$$P(x,t) = \frac{1}{2\pi} \int_{-\infty}^{\infty} e^{-[Dt + ikx + \frac{(ix)^2}{2Dt}]} + \frac{(ix)^2}{2\pi Dt} dk$$

$$= \frac{1}{2\pi} e^{-\frac{(ix)^2}{2Dt}} \cdot \int_{-\infty}^{\infty} e^{-(a+b)^2} dk$$

$$\Rightarrow P(x,t) = \frac{1}{2\pi} e^{-\frac{x^2}{4Dt}} \cdot \int_{-\infty}^{\infty} e^{-(a+b)^2} dk$$



$$\text{Let } y = a+b = k\sqrt{Dt} + \frac{ix}{2\sqrt{Dt}}$$

$$\Rightarrow dy = \sqrt{Dt} dk$$

$$\therefore P(x,t) = \frac{1}{2\pi} e^{-\frac{x^2}{4Dt}} \cdot \int_{-\infty}^{\infty} \frac{e^{-y^2}}{\sqrt{Dt}} dy$$

$$= \frac{1}{2\pi\sqrt{Dt}} \int_{-\infty}^{\infty} e^{-y^2} dy$$

Gaussian

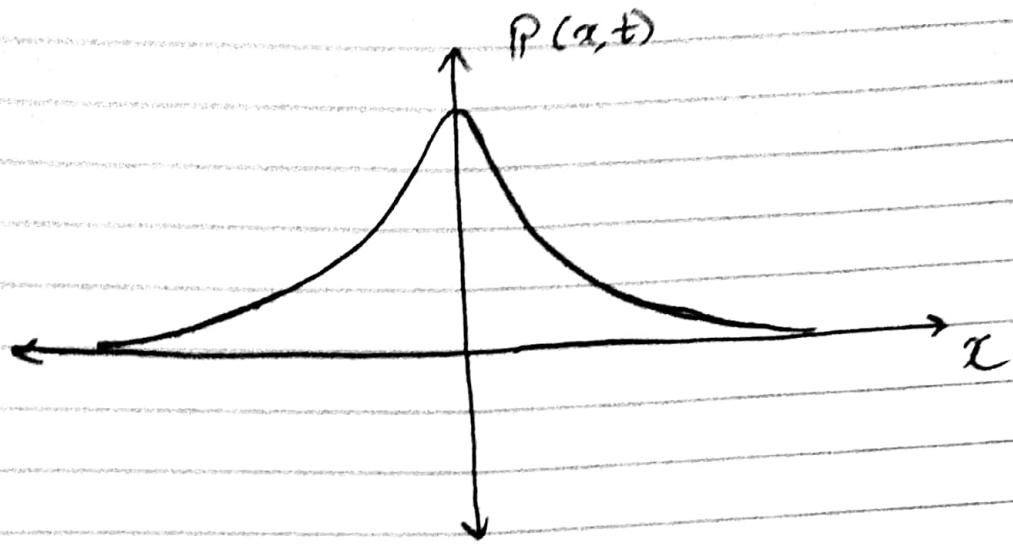
$$\int_{-\infty}^{\infty} y e^{-y^2} dy = \sqrt{\pi}$$

$$\therefore P(x,t) = \boxed{\frac{1}{2\sqrt{\pi Dt}} e^{-\frac{x^2}{4Dt}}}$$



Chesnute

Chalk
Page 15



For the 3-D case, solving equation yields

$$P(\vec{r}, t) = \frac{1}{(4\pi D t)^{3/2}} e^{-\frac{(x^2+y^2+z^2)}{4Dt}}$$