

Semantic Analysis

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Outline

- The role of semantic analysis:
The need of semantic validation, examples of errors
- The basic concepts for semantic analysis
- Applications of semantic analysis
 - IR generation
 - Name and scope analysis
 - Declaration processing
 - Type analysis
- Run time support
 - Activation records
 - Stack, static, and heap allocation,
 - Function prologue, making a call, returning a call, function epilogue



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The Role of Semantic Analysis



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- Establishing semantic validity of programs
 - What kinds of errors are possible in a program?
 - What kind of analysis can check these errors?
- Generating intermediate code (AST or Three-address code)
- Generating code for run time support (procedure calls and returns)



Why Separate Semantic Analysis from Syntax Analysis?

The constraints defining semantic validity cannot be described by context free grammars

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Why Separate Semantic Analysis from Syntax Analysis?

The constraints defining semantic validity cannot be described by context free grammars

- The constraint “declare a variable before its use” can be described by a language $\{wcw \mid w \in \Sigma^*\}$ where w is the lexeme of a variable (the lexeme appearing in a use must match the lexeme appearing in the corresponding declaration)



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- The constraint “declare a variable before its use” can be described by a language $\{wcw \mid w \in \Sigma^*\}$ where w is the lexeme of a variable (the lexeme appearing in a use must match the lexeme appearing in the corresponding declaration)
- The constraint “the number of actual parameters in a call must match the number of formal parameters of the procedure” for a program with two procedures can be described by a language $\{fa^ngb^mfc^ngd^m \mid n \geq 1, m \geq 1\}$ where
 - the formal parameters of procedure f are represented by a string of a's and its actual parameters are represented by a string of c's, and
 - the formal parameters of procedure g are represented by a string of b's and its actual parameters are represented by a string of d's



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- The constraint “the number of actual parameters in a call must match the number of formal parameters of the procedure” for a program with two procedures can be described by a language $\{fa^ngb^mfc^ngd^m \mid n \geq 1, m \geq 1\}$ where
 - the formal parameters of procedure f are represented by a string of a's and its actual parameters are represented by a string of c's, and
 - the formal parameters of procedure g are represented by a string of b's and its actual parameters are represented by a string of d's

These languages are not context free and hence cannot be described by context free grammars

So How Do We Perform Semantic Analysis?



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- Using context sensitive grammars for parsing is expensive
- Practical compilers use context free grammars to admit a superset of valid sentences and prune out invalid sentences by imposing context sensitive restrictions

So How Do We Perform Semantic Analysis?

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- Practical compilers use context free grammars to admit a superset of valid sentences and prune out invalid sentences by imposing context sensitive restrictions
 - For recognizing language $\{wcw \mid w \in \Sigma^*\}$,
 - admit all sentences in $\{xcy \mid x, y \in \Sigma^*\}$,
 - enter x in a symbol table during declaration processing, and
 - when uses are processed, lookup the symbol table and check if $y = x$



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 - For language $\{fa^ngb^mfc^ngd^m \mid n \geq 1, m \geq 1\}$,
 - admit all sentences in $\{fa^ngb^mfc^igdj \mid n \geq 1, m \geq 1, i \geq 1, j \geq 1\}$,
 - enter a^n and b^m as attributes of procedures f and g in a symbol table when function declarations/definitions are processed,
 - match c^i with a^n when a call to f is encountered, and
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So How Do We Perform Semantic Analysis?



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 - match c^i with a^n when a call to f is encountered, and
 - match d^j with b^m when a call to g is encountered
 - The general strategy is to define and compute some attributes of the symbols of a context free grammar and communicate the semantic information between them through the attributes



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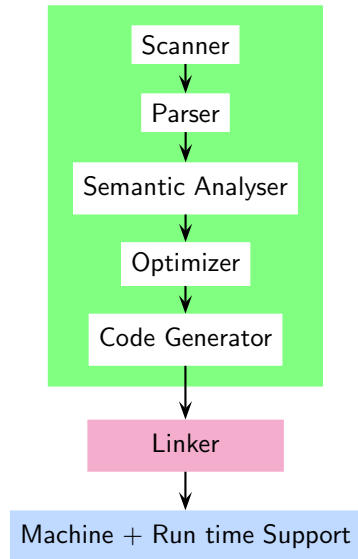
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Ensuring Validity of Programs = Detecting and Prohibiting Errors





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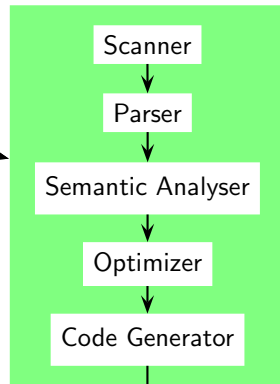
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Ensuring Validity of Programs = Detecting and Prohibiting Errors

- Compile time errors. Compilation fails

- Link time errors. Linking fails

- Run time errors. Execution fails





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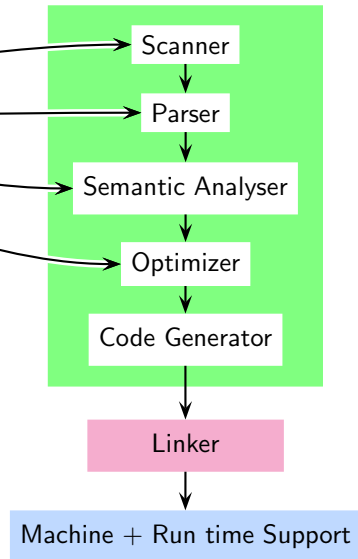
Ensuring Validity of Programs = Detecting and Prohibiting Errors

- Compile time errors. Compilation fails

- Lexical error
- Syntax error
- Semantic error

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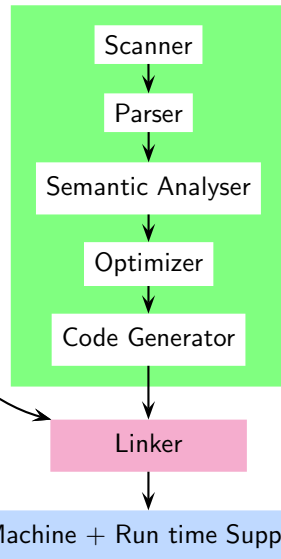
Ensuring Validity of Programs = Detecting and Prohibiting Errors

- Compile time errors. Compilation fails

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- Link time errors. Linking fails
Missing functions, global variables

- Run time errors. Execution fails





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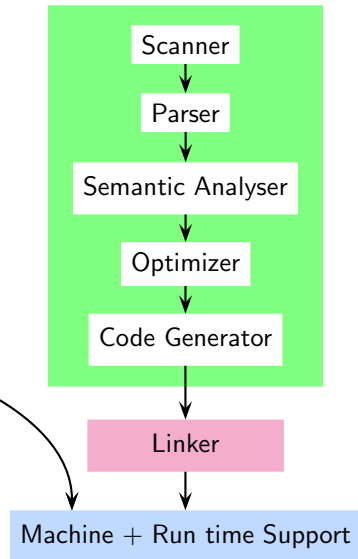
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Ensuring Validity of Programs = Detecting and Prohibiting Errors

- Compile time errors. Compilation fails
 - Lexical error
 - Syntax error
 - Semantic error
- Link time errors. Linking fails
 - Missing functions, global variables
- Run time errors. Execution fails
 - Logical error. Execution completes but gives wrong result
 - Undefined behaviour. Execution either aborts or gives wrong result





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Undefined Behaviour, Exceptions, and Unspecified Behaviour

- **Undefined behaviour.** Unchecked prohibited behaviour flagged by the language
 - No responsibility of the compiler or its run time support
 - May have unpredictable outcomes
The execution may abort or give unexpected result
 - A compiler is legally free to do anything
Including formatting your disk or launching a missile ;-)
- **Unspecified behaviour** (aka implementation-defined behaviour)
 - Valid feature whose implementation is left to the compiler
 - The available choices do not affect the result but may influence efficiency
 - Examples. The order of evaluation of arguments to a function call, or subexpressions
- **Exceptions.** Prohibited behaviour checked by the run time support



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Practical compilers try to detect them and issue warnings (and not errors)

- **Unspecified behaviour** (aka implementation-defined behaviour)
 - Valid feature whose implementation is left to the compiler
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 - Examples. The order of evaluation of arguments to a function call, or subexpressions

Practical compilers make choices based on well defined criteria

- **Exceptions.** Prohibited behaviour checked by the run time support

Practical compilers try to detect these at compile time



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Java follows the exception approach for predictability, whereas
C/C++ follows the undefined behaviour approach for efficiency

subexpressions

Practical compilers make choices based on well defined criteria

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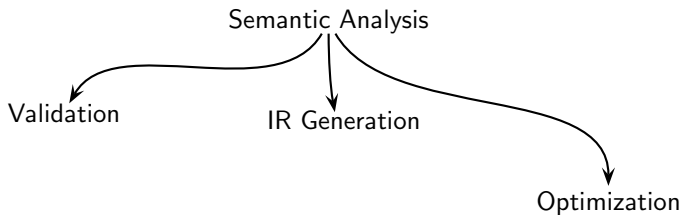
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Different Forms of Semantic Analysis





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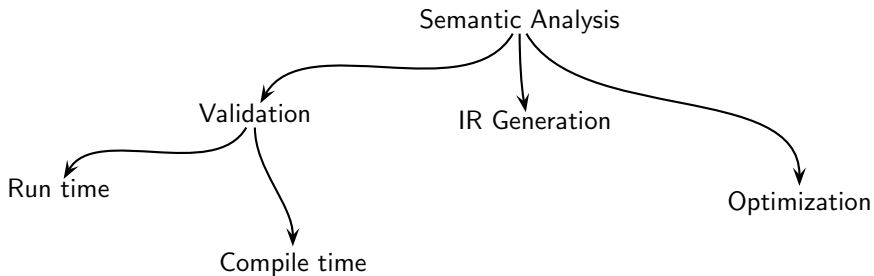
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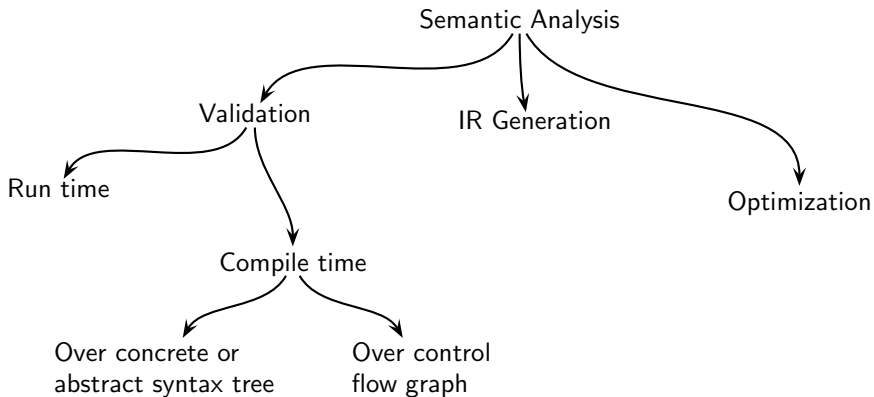
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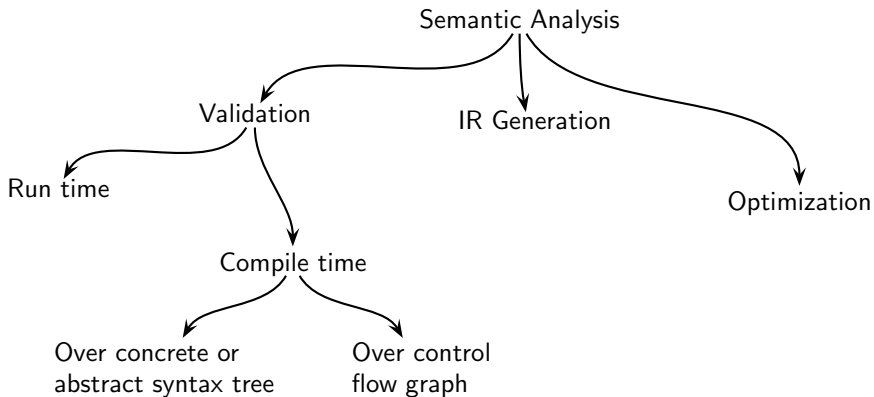
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Different Forms of Semantic Analysis





Different Forms of Semantic Analysis



declaration processing,
name & scope analysis,
type analysis,

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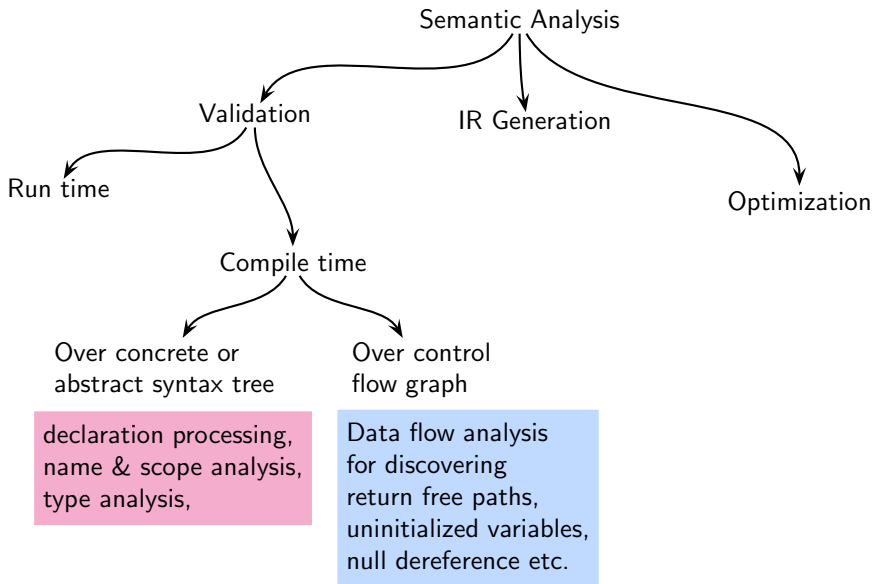
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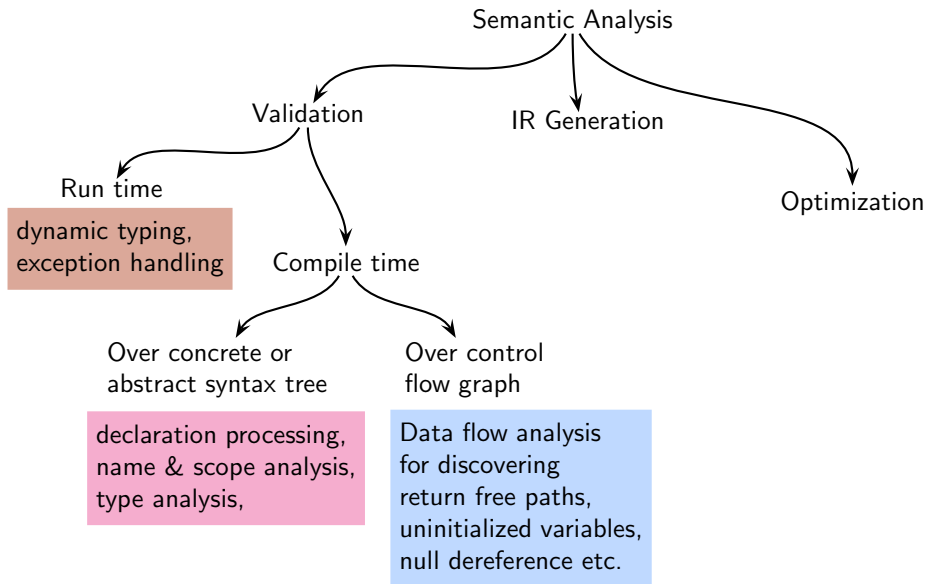
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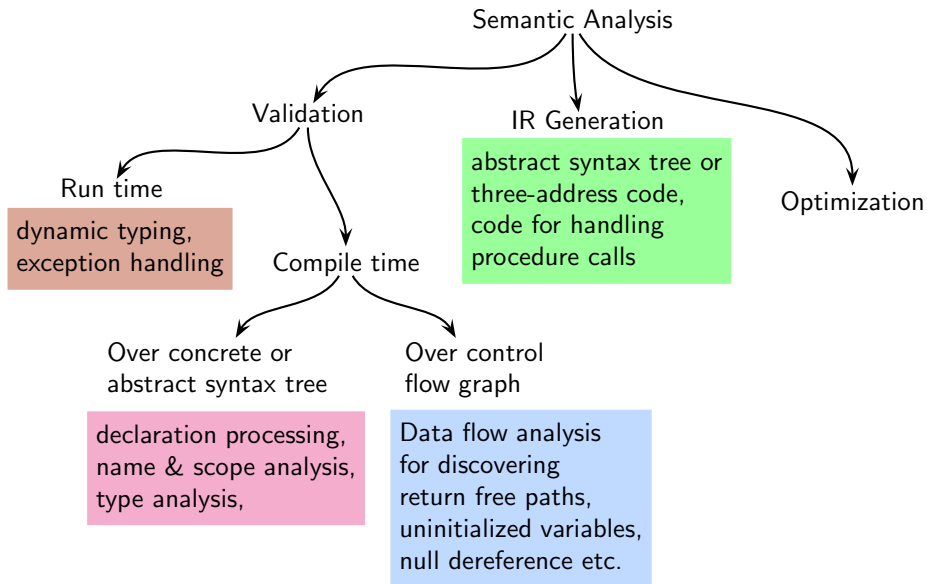
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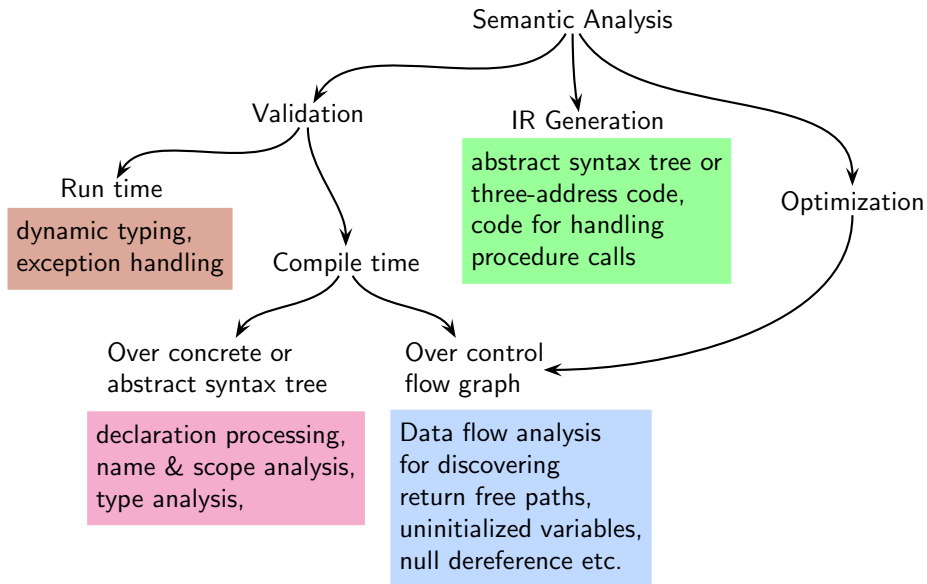
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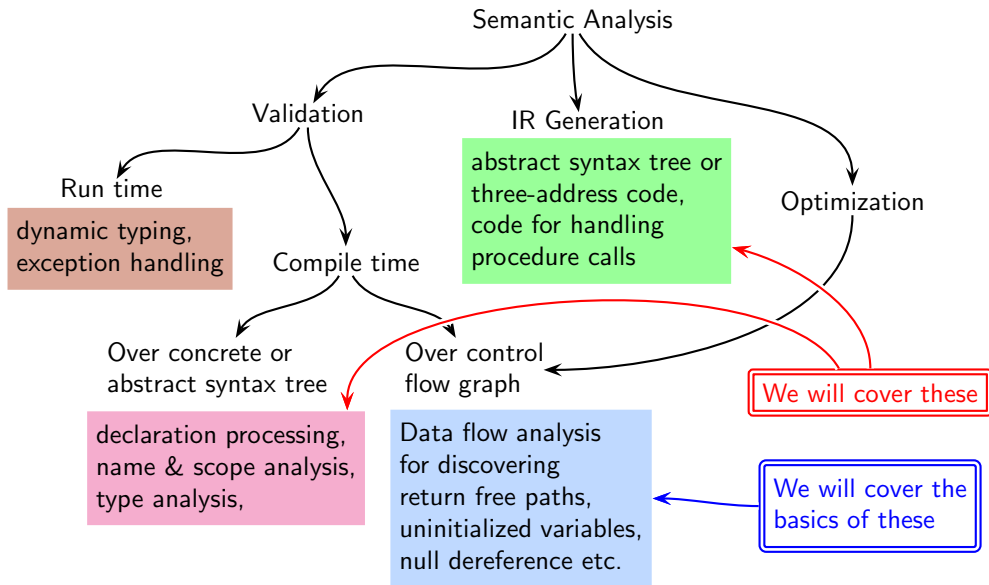
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How Can a Compiler Ensure Run Time Validation?

- Assume that a compiler decides to guard against null pointer dereference
- Every occurrence of $*x$ can be replaced by a code that has the effect of the following expression

$(x \neq \text{NULL})? *x : \text{complain}()$

where function *complain* is a part of the run time support created by the compiler

- This is not a source level change but the IR of the program would be instrumented
- Note that this overhead slows down the program execution



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Acknowledgements

This section is based entirely on the material developed by Prof. Biswas



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Observations About Program p0.c

```
using namespace std;  
  
#include <iostream>  
/*  
 * Test Program  
 */  
int main()  
{ int a = b;  
  int b = 5;  
  return 0;  
}
```



Observations About Program p0.c

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using namespace std;
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```
#include <iostream>
```

```
/*
```

```
 * Test Program
```

```
 */
```

```
int main()
```

```
{ int a = b;
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```
  int b = 5;
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```
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```
}
```

- Unterminated comment



Observations About Program p0.c

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```
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```
int main()
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{ int a = b;
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```
  int b = 5;
```

```
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```
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```

- Unterminated comment
- Lexical error



Observations About Program p1.c

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- Declaration of **b** appears after its definition



Observations About Program p1.c

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- Declaration of **b** appears after its definition
- Cannot be identified by the scanner
- Cannot be identified by the parser
 - Our grammar is context-free
 - This needs recording and examining context
 - A variable is used in the context of its declaration



Observations About Program p1.c

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```

```
#include <iostream>
```

```
int main()  
{ int a = b;  
  int b = 5;  
  return 0;  
}
```

- Declaration of **b** appears after its definition
- Cannot be identified by the scanner
- Cannot be identified by the parser
 - Our grammar is context-free
 - This needs recording and examining context
 - A variable is used in the context of its declaration
- Semantic error (name and scope analysis)



Observations About Program p2.c

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```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ int a = b, b = 5;  
  return 0;  
}
```



Observations About Program p2.c

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```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ int a = b, b = 5;  
  return 0;  
}
```

- Declaration of **b** appears after its use even if it is within the same declaration statement



Observations About Program p2.c

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```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ int a = b, b = 5;  
  return 0;  
}
```

- Declaration of **b** appears after its use even if it is within the same declaration statement
- Semantic error (name and scope analysis)



Observations About Program p3.c

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```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ float b;  
  int b = 5;  
  return 0;  
}
```



Observations About Program p3.c

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```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ float b;  
  int b = 5;  
  return 0;  
}
```

- Redeclaration of **b** with different types



Observations About Program p3.c

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```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ float b;  
  int b = 5;  
  return 0;  
}
```

- Redeclaration of **b** with different types
- Not allowed even with the same type



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Observations About Program p3.c

```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ float b;  
  int b = 5;  
  return 0;  
}
```

- Redclaration of **b** with different types
- Not allowed even with the same type
- Semantic error (name and scope analysis)



Observations About Program p4.c

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```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ int &i;  
  cout << i << endl;  
  return 0;  
}
```



Observations About Program p4.c

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```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ int &i;  
  cout << i << endl;  
  return 0;  
}
```

- C++ requires references to be initialized



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Observations About Program p4.c

```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ int &i;  
  cout << i << endl;  
  return 0;  
}
```

- C++ requires references to be initialized
- Cannot be identified by the scanner
- Identified by the parser
 - Token '=' must appear after ID



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Observations About Program p4.c

```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ int &i;  
  cout << i << endl;  
  return 0;  
}
```

- C++ requires references to be initialized
- Cannot be identified by the scanner
- Identified by the parser
 - Token '=' must appear after ID
- Syntax error and not a semantic error



Observations About Program p5.c

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```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ short s = 1234567890;  
  cout << s << endl;  
  return 0;  
}
```



Observations About Program p5.c

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```
using namespace std;
```

- Overflow

```
#include <iostream>
```

```
int main()  
{ short s = 1234567890;  
  cout << s << endl;  
  return 0;  
}
```



Observations About Program p5.c

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```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ short s = 1234567890;  
  cout << s << endl;  
  return 0;  
}
```

- Overflow
- Cannot be identified by the scanner
- Cannot be identified by the parser
 - Needs the knowledge of types
 - Needs recording and examining context



Observations About Program p5.c

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```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ short s = 1234567890;  
  cout << s << endl;  
  return 0;  
}
```

- Overflow
- Cannot be identified by the scanner
- Cannot be identified by the parser
 - Needs the knowledge of types
 - Needs recording and examining context
- Semantic error (type matching)
Reported as a warning



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Observations About Program p6.c

```
using namespace std;

#include <iostream>

int main()
{ int i = 40;
  if ( 1 <= i <= 5)
    cout << " In range\n";
  else
    cout << " Out of Range\n";
  return 0;
}
```



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Observations About Program p6.c

```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ int i = 40;  
  if ( 1 <= i <= 5)  
    cout << " In range\n";  
  else  
    cout << " Out of Range\n";  
  return 0;  
}
```

- Relational operators are left-associative in C++
They are non-associative in scanf



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Observations About Program p6.c

```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ int i = 40;  
  if ( 1 <= i <= 5)  
    cout << " In range\n";  
  else  
    cout << " Out of Range\n";  
  return 0;  
}
```

- Relational operators are left-associative in C++
They are non-associative in sc1p
- `1 <= i` evaluated to `true` whose value is taken as 1 by the compiler



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Observations About Program p6.c

```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ int i = 40;  
  if ( 1 <= i <= 5)  
    cout << " In range\n";  
  else  
    cout << " Out of Range\n";  
  return 0;  
}
```

- Relational operators are left-associative in C++

They are non-associative in sclp

- `1 <= i` evaluated to `true` whose value is taken as 1 by the compiler
 - All non-zero integers map to true but true maps only to 1



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Observations About Program p6.c

```
using namespace std;

#include <iostream>

int main()
{ int i = 40;
  if ( 1 <= i <= 5)
    cout << " In range\n";
  else
    cout << " Out of Range\n";
  return 0;
}
```

- Relational operators are left-associative in C++
They are non-associative in sclp
- `1 <= i` evaluated to `true` whose value is taken as 1 by the compiler
 - All non-zero integers map to true but true maps only to 1
- The compiler and run time support cannot know the programmer's intent (Does the value of `i` lie between 1 and 5?)



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Observations About Program p6.c

```
using namespace std;

#include <iostream>

int main()
{ int i = 40;
  if ( 1 <= i <= 5)
    cout << " In range\n";
  else
    cout << " Out of Range\n";
  return 0;
}
```

- Relational operators are left-associative in C++
They are non-associative in scilp
- `1 <= i` evaluated to `true` whose value is taken as 1 by the compiler
 - All non-zero integers map to true but true maps only to 1
- The compiler and run time support cannot know the programmer's intent (Does the value of `i` lie between 1 and 5?)
- Logical error and not a semantic error



Observations About Program p7.c

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```
using namespace std;
```

```
#include <iostream>
```

```
int main()
```

```
{ int a[5] = {1, 2, 3, 4,  
              5, 6, 7, 8
```

```
};
```

```
    return 0;
```

```
}
```



Observations About Program p7.c

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```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ int a[5] = {1, 2, 3, 4,  
              5, 6, 7, 8  
              };  
  return 0;  
}
```

- More elements in the initialization than the declared size of the array



Observations About Program p7.c

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```
using namespace std;
```

```
#include <iostream>
```

```
int main()
```

```
{ int a[5] = {1, 2, 3, 4,  
              5, 6, 7, 8  
};
```

```
    return 0;
```

```
}
```

- More elements in the initialization than the declared size of the array
- Cannot be identified by the scanner
- Cannot be identified by the parser
 - Requires the knowledge of the size of the array



Observations About Program p7.c

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```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ int a[5] = {1, 2, 3, 4,  
              5, 6, 7, 8  
              };  
  return 0;  
}
```

- More elements in the initialization than the declared size of the array
- Cannot be identified by the scanner
- Cannot be identified by the parser
 - Requires the knowledge of the size of the array
- Semantic error (declaration processing)



Observations About Program p8.c

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```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ int a[5] = {1, 2, 3};  
  int sum;  
  for (int i=0; i<10000; i++)  
    sum = sum + a[i];  
  cout << sum << endl;  
  return 0;  
}
```



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Observations About Program p8.c

- Segmentation fault
Memory access violation

```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ int a[5] = {1, 2, 3};  
  int sum;  
  for (int i=0; i<10000; i++)  
    sum = sum + a[i];  
  cout << sum << endl;  
  return 0;  
}
```



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Observations About Program p8.c

```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ int a[5] = {1, 2, 3};  
  int sum;  
  for (int i=0; i<10000; i++)  
    sum = sum + a[i];  
  cout << sum << endl;  
  return 0;  
}
```

- Segmentation fault
Memory access violation
- This is a run time activity and the error cannot be identified by a compiler



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Observations About Program p8.c

```
using namespace std;
```

```
#include <iostream>
```

```
int main()  
{ int a[5] = {1, 2, 3};  
  int sum;  
  for (int i=0; i<10000; i++)  
    sum = sum + a[i];  
  cout << sum << endl;  
  return 0;  
}
```

- Segmentation fault
Memory access violation
- This is a run time activity and the error cannot be identified by a compiler
- Run time error (undefined behaviour)



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Observations About Program p8.c

```
using namespace std;

#include <iostream>

int main()
{ int a[5] = {1, 2, 3};
  int sum;
  for (int i=0; i<10000; i++)
    sum = sum + a[i];
  cout << sum << endl;
  return 0;
}
```

- Segmentation fault
Memory access violation
- This is a run time activity and the error cannot be identified by a compiler
- Run time error (undefined behaviour)
- If we change the loop bound to 5 or 10, memory violation may go undetected, program may not abort, but the result would be unpredictable
(undefined behaviour)



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Observations About Program p8.c

```
using namespace std;

#include <iostream>

int main()
{ int a[5] = {1, 2, 3};
  int sum;
  for (int i=0; i<10000; i++)
    sum = sum + a[i];
  cout << sum << endl;
  return 0;
}
```

- Segmentation fault
Memory access violation
- This is a run time activity and the error cannot be identified by a compiler
- Run time error (undefined behaviour)
- If we change the loop bound to 5 or 10, memory violation may go undetected, program may not abort, but the result would be unpredictable
(undefined behaviour)
- If we change the loop bound to 2, it will be a logical error because it is not a memory violation



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Observations About Program p9.c

```
using namespace std;
#include <iostream>

int f(int x)
{
    if (x>10) return x;
    else
        if (x>5) return x+5;
}

int main()
{ int i = -5;
  int j = f(i);

  cout << j << endl;
  return 0;
}
```



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Observations About Program p9.c

```
using namespace std;  
#include <iostream>
```

```
int f(int x)  
{  
    if (x>10) return x;  
    else  
        if (x>5) return x+5;  
}
```

```
int main()  
{ int i = -5;  
  int j = f(i);  
  
  cout << j << endl;  
  return 0;  
}
```

- Existence of a control flow path along which no value is returned
- Semantic analysis over control flow graph



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Observations About Program p9.c

```
using namespace std;  
#include <iostream>
```

```
int f(int x)  
{  
    if (x>10) return x;  
    else  
        if (x>5) return x+5;  
}
```

```
int main()  
{ int i = -5;  
  int j = f(i);  
  
  cout << j << endl;  
  return 0;  
}
```

- Existence of a control flow path along which no value is returned
- Semantic analysis over control flow graph
- A warning to flag a possible undefined behaviour



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Observations About Program p9.c

```
using namespace std;  
#include <iostream>
```

```
int f(int x)  
{  
    if (x>10) return x;  
    else  
        if (x>5) return x+5;  
}
```

```
int main()  
{ int i = -5;  
  int j = f(i);  
  
  cout << j << endl;  
  return 0;  
}
```

- Existence of a control flow path along which no value is returned
- Semantic analysis over control flow graph
- A warning to flag a possible undefined behaviour
- What does a language definition say?
A variable must be *declared* before its use but may not be *defined* before its use
The latter leads to undefined behaviour



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Observations About Program p9.c

```
using namespace std;
#include <iostream>

int f(int x)
{
    if (x>10) return x;
    else
        if (x>5) return x+5;
}

int main()
{ int i = -5;
  int j = f(i);

  cout << j << endl;
  return 0;
}
```

- Existence of a control flow path along which no value is returned
- Semantic analysis over control flow graph
- A warning to flag a possible undefined behaviour
- What does a language definition say?
A variable must be *declared* before its use but may not be *defined* before its use
The latter leads to undefined behaviour
- Observe the run time consequences by
 - Add cout statement in f
 - Add $x = x + 200$ in f
 - Add a call $g(y)$ returning a value in f
 - Change the argument of f to $i+2$



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```
using namespace std;
#include <iostream>

int main()
{ float inc = 0.1;
  float sum = 0;
  while (inc != 1.0)
  { sum = sum + inc;
    inc = inc + 0.1;
  }
  cout << sum << endl;
  return 0;
}
```



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Observations About Program p10.c

```
using namespace std;  
#include <iostream>
```

- Infinite loop?

```
int main()  
{ float inc = 0.1;  
  float sum = 0;  
  while (inc != 1.0)  
  { sum = sum + inc;  
    inc = inc + 0.1;  
  }  
  cout << sum << endl;  
  return 0;  
}
```



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```
using namespace std;
#include <iostream>

int main()
{ float inc = 0.1;
  float sum = 0;
  while (inc != 1.0)
  { sum = sum + inc;
    inc = inc + 0.1;
  }
  cout << sum << endl;
  return 0;
}
```

- Infinite loop?
- Print values in the loop and observe



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Observations About Program p10.c

```
using namespace std;
#include <iostream>

int main()
{ float inc = 0.1;
  float sum = 0;
  while (inc != 1.0)
  { sum = sum + inc;
    inc = inc + 0.1;
  }
  cout << sum << endl;
  return 0;
}
```

- Infinite loop?
- Print values in the loop and observe
- Change ! to < and observe



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```
using namespace std;  
#include <iostream>  
  
int main()  
{ float inc = 0.1;  
  float sum = 0;  
  while (inc != 1.0)  
  { sum = sum + inc;  
    inc = inc + 0.1;  
  }  
  cout << sum << endl;  
  return 0;  
}
```

- Infinite loop?
- Print values in the loop and observe
- Change ! to < and observe
- Floating point values are not exact



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```
using namespace std;
#include <iostream>

int main()
{ float inc = 0.1;
  float sum = 0;
  while (inc != 1.0)
  { sum = sum + inc;
    inc = inc + 0.1;
  }
  cout << sum << endl;
  return 0;
}
```

- Infinite loop?
- Print values in the loop and observe
- Change ! to < and observe
- Floating point values are not exact
- This is a run time activity and the error cannot be identified by a compiler



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```
using namespace std;
#include <iostream>

int main()
{ float inc = 0.1;
  float sum = 0;
  while (inc != 1.0)
  { sum = sum + inc;
    inc = inc + 0.1;
  }
  cout << sum << endl;
  return 0;
}
```

- Infinite loop?
- Print values in the loop and observe
- Change ! to < and observe
- Floating point values are not exact
- This is a run time activity and the error cannot be identified by a compiler
- Logical error and not a semantic error



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Observations About Program p11.c

```
using namespace std;  
#include <iostream>  
short f(short a)  
{ cout << " short\n";  
  return a;}
```

```
long f(long x)  
{ cout << " long\n";  
  return x;}
```

```
char f (char c)  
{ cout << " char\n";  
  return c;}
```

```
int main()  
{  
  f(100);  
}
```



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Observations About Program p11.c

```
using namespace std;  
#include <iostream>  
short f(short a)  
{ cout << " short\n";  
  return a;}
```

```
long f(long x)  
{ cout << " long\n";  
  return x;}
```

```
char f (char c)  
{ cout << " char\n";  
  return c;}
```

```
int main()  
{  
  f(100);  
}
```

- Difficulty in resolving function overloading



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```
using namespace std;  
#include <iostream>  
short f(short a)  
{ cout << " short\n";  
  return a;}
```

```
long f(long x)  
{ cout << " long\n";  
  return x;}
```

```
char f (char c)  
{ cout << " char\n";  
  return c;}
```

```
int main()  
{  
  f(100);  
}
```

- Difficulty in resolving function overloading
- Value 100 fits into types `char`, `short`, and `long`



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```
using namespace std;  
#include <iostream>  
short f(short a)  
{ cout << " short\n";  
  return a;}
```

```
long f(long x)  
{ cout << " long\n";  
  return x;}
```

```
char f (char c)  
{ cout << " char\n";  
  return c;}
```

```
int main()  
{  
  f(100);  
}
```

- Difficulty in resolving function overloading
- Value 100 fits into types `char`, `short`, and `long`
- Add a function with type `int` and observe



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Observations About Program p11.c

```
using namespace std;
#include <iostream>
short f(short a)
{ cout << " short\n";
  return a;}
```

```
long f(long x)
{ cout << " long\n";
  return x;}
```

```
char f (char c)
{ cout << " char\n";
  return c;}
```

```
int main()
{
  f(100);
}
```

- Difficulty in resolving function overloading
- Value 100 fits into types `char`, `short`, and `long`
- Add a function with type `int` and observe
- Cannot be identified by the parser
- Semantic error (type matching)



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Observations About Program p12.c

```
using namespace std;
#include <iostream>
long f(long a)
{ cout << " long\n"; return a;}
int f(int x)
{ cout << " int\n"; return x;}
char f (char c)
{ cout << " char\n"; return c;}
int main()
{  short d = 25;
   char ch = '$';
   f(10000000000000);
   f(1234);
   f(ch);
   f(d);
}
```



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Observations About Program p12.c

```
using namespace std;
#include <iostream>
long f(long a)
{ cout << " long\n"; return a;}
int f(int x)
{ cout << " int\n"; return x;}
char f (char c)
{ cout << " char\n"; return c;}
int main()
{  short d = 25;
   char ch = '$';
   f(10000000000000);
   f(1234);
   f(ch);
   f(d);
}
```

- Type casting for resolving function overloading



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Observations About Program p12.c

```
using namespace std;
#include <iostream>
long f(long a)
{ cout << " long\n"; return a;}
int f(int x)
{ cout << " int\n"; return x;}
char f (char c)
{ cout << " char\n"; return c;}
int main()
{ short d = 25;
  char ch = '$';
  f(10000000000000);
  f(1234);
  f(ch);
  f(d);
}
```

- Type casting for resolving function overloading
- A `short` value is treated as an `int` value



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```
using namespace std;
#include <iostream>
long f(long a)
{ cout << " long\n"; return a;}
int f(int x)
{ cout << " int\n"; return x;}
char f (char c)
{ cout << " char\n"; return c;}
int main()
{ short d = 25;
  char ch = '$';
  f(10000000000000);
  f(1234);
  f(ch);
  f(d);
}
```

- Type casting for resolving function overloading
- A `short` value is treated as an `int` value
- Semantic analysis (type analysis)



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Observations About Program p13.c

```
using namespace std;
```

```
#include<iostream>
```

```
template <class T>
```

```
int countzeros (T a[], int size)
```

```
{ int count = 0;
```

```
  for (int i = 0; i < size; i++)
```

```
    if (a[i] == 0) count ++;
```

```
  return count;
```

```
}
```

```
int main()
```

```
{ int x[5]={7, 0 , 5, 1, 0};
```

```
  float y[6]={0.0, 1.5, 0.0, 2.5,  
              9.5, 0.0005};
```

```
  int a=20, b=50, c=-100, d=1000;
```

```
  int * p[5]={&a, &b, &c, &d, 0};
```

```
  char ch[5]={'a', '0', ',', ',', '0',  
              '9'};
```

```
  string str[4]={"12", "0", "abc",  
                 "0"};
```

```
  cout << countzeros(x,5) << endl;
```

```
  cout << countzeros(y,6) << endl;
```

```
  cout << countzeros(p,5) << endl;
```

```
  cout << countzeros(ch,5) << endl;
```

```
  cout << countzeros(str,4) << endl;
```

```
  return 0;
```

```
}
```



Observations About Program p13.c

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- Comparison between `string` and `int` not defined
- No zero in array `ch`



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```
using namespace std;
```

```
#include<iostream>
```

```
template <class T>  
int countzeros (T a[], int size)  
{ int count = 0;  
  for (int i = 0; i < size; i++)  
    if (a[i] == 0) count ++;  
  return count;  
}
```




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```
using namespace std;
```

```
#include<iostream>
```

```
template <class T>  
int countzeros (T a[], int size)  
{ int count = 0;  
  for (int i = 0; i < size; i++)  
    if (a[i] == 0) count ++;  
  return count;  
}
```

- No main



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```
using namespace std;
```

```
#include<iostream>
```

```
template <class T>  
int countzeros (T a[], int size)  
{ int count = 0;  
  for (int i = 0; i < size; i++)  
    if (a[i] == 0) count ++;  
  return count;  
}
```

- No main
- General error: missing external data function or variable
- Identified by the linker



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```
using namespace std;
```

```
#include<iostream>
```

```
template <class T>  
int countzeros (T a[], int size)  
{ int count = 0;  
  for (int i = 0; i < size; i++)  
    if (a[i] == 0) count ++;  
  return count;  
}
```

- No main
- General error: missing external data function or variable
- Identified by the linker
- Using -c option with compilation suppresses the error



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```
using namespace std;
```

```
#include<iostream>
```

```
template <class T>  
int countzeros (T a[], int size)  
{ int count = 0;  
  for (int i = 0; i < size; i++)  
    if (a[i] == 0) count ++;  
  return count;  
}
```

- No main
- General error: missing external data function or variable
- Identified by the linker
- Using -c option with compilation suppresses the error
- Linking error



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Syntax Directed Definitions



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- Practical compilers use context free grammars to admit a superset of valid sentences and prune out invalid sentences by imposing context sensitive restrictions
- The general strategy is to define and compute some attributes of the symbols of a context free grammar and communicate the semantic information between them through the attributes

Syntax directed attribute evaluation



Syntax Directed Definitions (SDDs)

- A context free grammar augmented with attributes of grammar symbols and semantic rules for evaluating the attributes

$$A \rightarrow \alpha \quad b = f(c_1, c_2, \dots, c_k)$$

where b is an attribute of A and $c_i, 1 \leq i \leq k$ are attributes of the symbols in α

- The semantic rules are evaluated when the corresponding grammar rule is used for derivation (in a top down parser) or reduction (in a bottom up parser)
- Notations and conventions
 - For simplicity, we will show attribute evaluation on a parse tree
 - $X.attribute$ refers to the attribute named “attribute” of grammar symbol X
 - Multiple occurrences of a grammar symbol within the same production are distinguished using subscripts

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Syntax Directed Definition for Expression Evaluation

- The parser uses the attributes called *value* and *name*
- The attribute values for *id* and *num* are supplied by the scanner

$E_1 \rightarrow E_2 * E_3$	$E_1.value = E_2.value * E_3.value$
$E_1 \rightarrow E_2 / E_3$	$E_1.value = E_2.value / E_3.value$
$E_1 \rightarrow E_2 + E_3$	$E_1.value = E_2.value + E_3.value$
$E_1 \rightarrow E_2 - E_3$	$E_1.value = E_2.value - E_3.value$
$E_1 \rightarrow - E_2$	$E_1.value = -E_2.value$
$E_1 \rightarrow (E_2)$	$E_1.value = E_2.value$
$E \rightarrow num$	$E.value = num.value$

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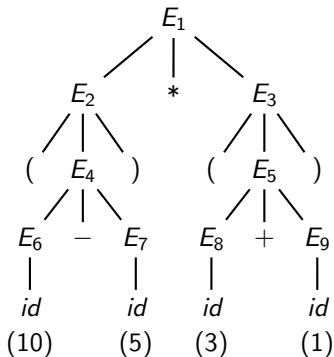
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Example of Expression Evaluation

Input expression: $(10 - 5) * (3 + 1)$



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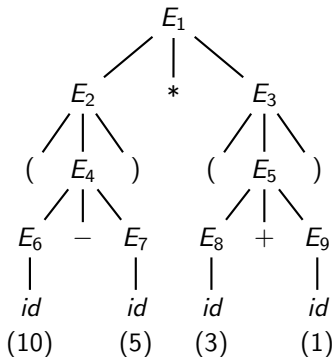
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Example of Expression Evaluation

Input expression: $(10 - 5) * (3 + 1)$

$E_6.value$	10
$E_7.value$	5
$E_8.value$	3
$E_9.value$	1



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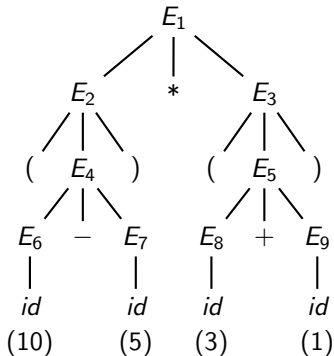
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Example of Expression Evaluation

Input expression: $(10 - 5) * (3 + 1)$



$E_6.value$	10
$E_7.value$	5
$E_8.value$	3
$E_9.value$	1
$E_4.value$	5

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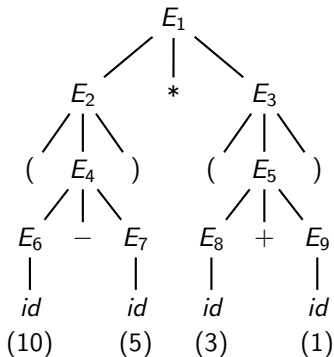
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Example of Expression Evaluation

Input expression: $(10 - 5) * (3 + 1)$



$E_6.value$	10
$E_7.value$	5
$E_8.value$	3
$E_9.value$	1
$E_4.value$	5
$E_2.value$	5

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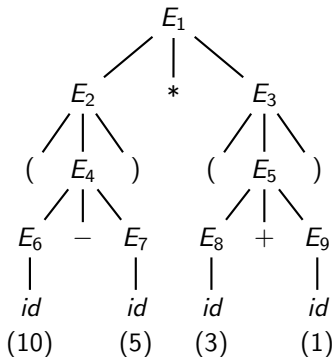
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Example of Expression Evaluation

Input expression: $(10 - 5) * (3 + 1)$



$E_6.value$	10
$E_7.value$	5
$E_8.value$	3
$E_9.value$	1
$E_4.value$	5
$E_2.value$	5
$E_5.value$	4

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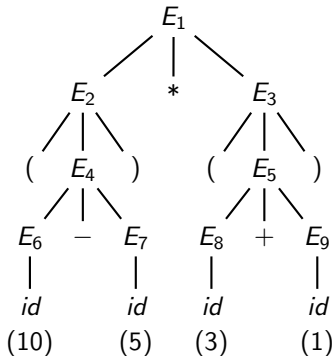
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Example of Expression Evaluation

Input expression: $(10 - 5) * (3 + 1)$



$E_6.value$	10
$E_7.value$	5
$E_8.value$	3
$E_9.value$	1
$E_4.value$	5
$E_2.value$	5
$E_5.value$	4
$E_3.value$	4

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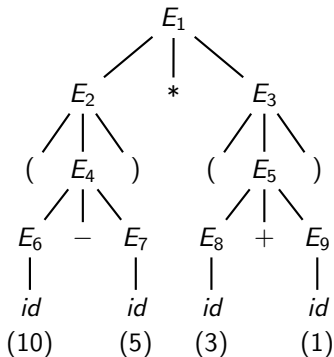
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Example of Expression Evaluation

Input expression: $(10 - 5) * (3 + 1)$



$E_6.value$	10
$E_7.value$	5
$E_8.value$	3
$E_9.value$	1
$E_4.value$	5
$E_2.value$	5
$E_5.value$	4
$E_3.value$	4
$E_1.value$	20

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SDDs for Generating IR



SDDs for Generating IR

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- Generating IR for unary and binary expressions
- Generating IR for ternary expression
- Generating IR for WHILE loop
- Generating IR for array accesses
- Generating IR for field accesses in structures
- Generating IR for field accesses through pointers



SDD for Generating IR for Expression

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- Input statement. $x = (a - b) * (c + d)$
- Desired output

$$t_0 = a - b$$

$$t_1 = c + d$$

$$t_2 = t_0 * t_1$$

$$x = t_2$$



SDD for Generating IR for Expression

- We use attributes called *name* (value supplied by the scanner), *place* (the source or the temporary variable that holds the result), and *code*
- Function *gen* generates code for an assignment statement, function *expr* generates the code for an expression, function *getNewTemp* returns the name of a new temporary, and operator `||` concatenates code

$S \rightarrow id = E$	$c_1 = gen(id.place, =, E.place)$ $S.code = E.code c_1$
$E_1 \rightarrow E_2 op E_3$	$t_1 = getNewTemp();$ $c_1 = E_2.code; c_2 = E_3.code$ $c_3 = gen(t_1, =, expr(E_2.place, op, E_3.place))$ $E_1.code = c_1 c_2 c_3$ $E_1.place = t_1$
$E_1 \rightarrow (E_2)$	$E_1.code = E_2.code$ $E_1.place = E_2.place$
$E \rightarrow id$	$E.code = NULL$ $E.place = id.name$



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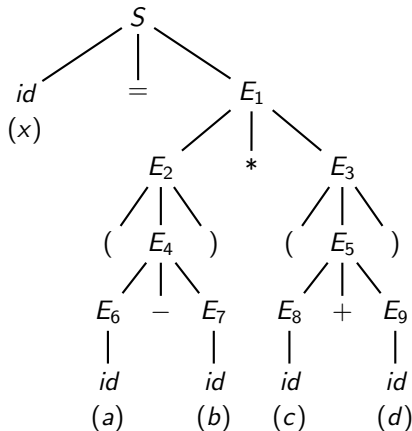
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Example of Generating IR for Expression

Input statement: $x = (a - b) * (c + d)$





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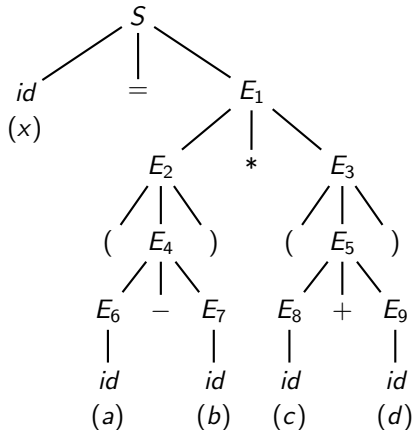
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Example of Generating IR for Expression

Input statement: $x = (a - b) * (c + d)$

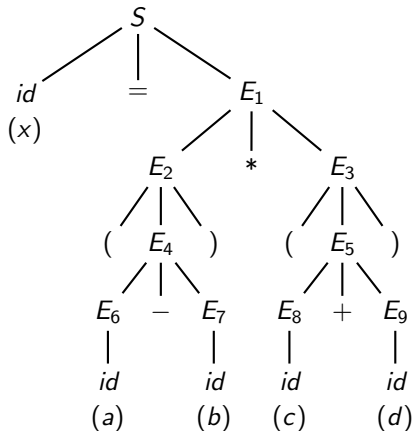


$E_6.place$	a
$E_7.place$	b
$E_8.place$	c
$E_9.place$	d



Example of Generating IR for Expression

Input statement: $x = (a - b) * (c + d)$



$E_6.place$	a
$E_7.place$	b
$E_8.place$	c
$E_9.place$	d
$E_4.place, E_2.place$	t_0
$E_4.code, E_2.code$	$t_0 = a - b$

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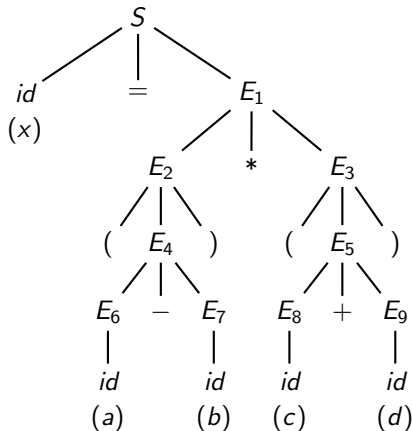
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Example of Generating IR for Expression

Input statement: $x = (a - b) * (c + d)$



$E_6.place$	a
$E_7.place$	b
$E_8.place$	c
$E_9.place$	d
$E_4.place, E_2.place$ $E_4.code, E_2.code$	t_0 $t_0 = a - b$
$E_5.place, E_3.place$ $E_5.code, E_3.code$	t_1 $t_1 = c + d$

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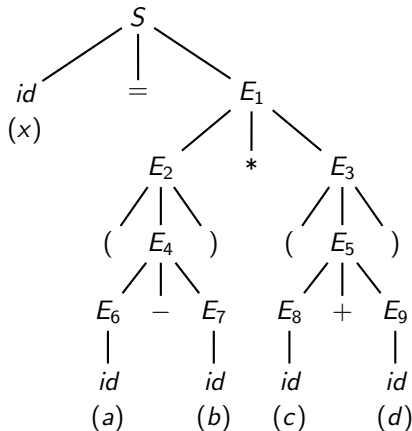
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Example of Generating IR for Expression

Input statement: $x = (a - b) * (c + d)$

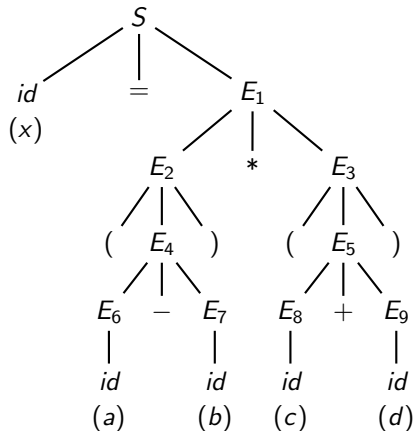


$E_6.place$	a
$E_7.place$	b
$E_8.place$	c
$E_9.place$	d
$E_4.place, E_2.place$ $E_4.code, E_2.code$	t_0 $t_0 = a - b$
$E_5.place, E_3.place$ $E_5.code, E_3.code$	t_1 $t_1 = c + d$
$E_1.place$ $E_1.code$	t_2 $t_0 = a - b$ $t_1 = c + d$ $t_2 = t_0 * t_1$



Example of Generating IR for Expression

Input statement: $x = (a - b) * (c + d)$



$E_6.place$	a
$E_7.place$	b
$E_8.place$	c
$E_9.place$	d
$E_4.place, E_2.place$ $E_4.code, E_2.code$	t_0 $t_0 = a - b$
$E_5.place, E_3.place$ $E_5.code, E_3.code$	t_1 $t_1 = c + d$
$E_1.place$ $E_1.code$	t_2 $t_0 = a - b$ $t_1 = c + d$ $t_2 = t_0 * t_1$
$S.code$	$t_0 = a - b$ $t_1 = c + d$ $t_2 = t_0 * t_1$ $x = t_2$

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Designing SDD for Generating IR for Ternary Expression



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$$E_1 \rightarrow E_2 ? E_3 : E_4$$

$E_1.place = t_2$

$E_1.code$

$E_2.code$

$t_1 = \neg E_2.place$

if t_1 goto l_1

$E_3.code$

$t_2 = E_3.place$

goto l_2

$l_1:$ $E_4.code$

$t_2 = E_4.place$

$l_2:$



SDD for Generating IR for Ternary Expression

For simplicity, we view the IR as strings and arguments of *gen* as strings without showing the construction of strings explicitly

$E_1 \rightarrow E_2 ? E_3 : E_4$

```
t1 = getNewTemp(); t2 = getNewTemp()  
l1 = getNewLabel(); l2 = getNewLabel()  
c1 = E2.code || gen(t1 = ¬E2.place) || gen(if t1 goto l1)  
c2 = E3.code || gen(t2 = E3.place) || gen(goto l2)  
c3 = gen(l1:) || E4.code || gen(t2 = E4.place)  
c4 = gen(l2:)  
E1.code = c1 || c2 || c3 || c4  
E1.place = t2
```

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Example of Generating IR for Ternary Expression

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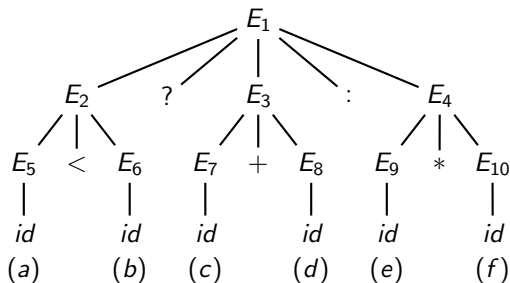
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$E_5.place$	a
$E_6.place$	b
$E_7.place$	c
$E_8.place$	d
$E_9.place$	e
$E_{10}.place$	f

$E_2.place$	t_0
$E_2.code$	$t_0 = a < b$
$E_3.place$	t_1
$E_3.code$	$t_1 = c + d$
$E_4.place$	t_2
$E_4.code$	$t_2 = e * f$

$E_1.place$	t_4	
$E_1.code$	c_1	$t_0 = a < b$ $t_3 = !t_0$ if t_3 goto l_1
	c_2	$t_1 = c + d$ $t_4 = t_1$ goto l_2
	c_3	$l_1:$ $t_2 = e * f$ $t_4 = t_2$
	c_4	$l_2:$



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SDD for Generating IR for WHILE loop

$$S_1 \rightarrow \text{WHILE } (E) S_2$$

$S_1.code$

```

 $l_1$ :  $E.code$ 
       $t_1 = \neg E.place$ 
      if  $t_1$  goto  $l_2$ 
       $S_2.code$ 
      goto  $l_1$ 
 $l_2$ :
```

$$S_1 \rightarrow \text{WHILE } (E) S_2$$

```

 $t_1 = getNewTemp()$ ;
 $l_1 = getNewLabel()$ ;  $l_2 = getNewLabel()$ 
 $c_1 = gen(l_1:) || E.code$ 
 $c_2 = gen(t_1 = \neg E.place) || gen(\text{if } t_1 \text{ goto } l_2)$ 
 $c_3 = S_2.code || gen(\text{goto } l_1)$ 
 $c_4 = gen(l_2:)$ 
 $S_1.code = c_1 || c_2 || c_3 || c_4$ 
```



Representing Arrays in Memory

A 2-D Array

Row Major
Representation

Column Major
Representation

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A(0,0)	A(0,1)	A(0,2)
A(1,0)	A(1,1)	A(1,2)
A(2,0)	A(2,1)	A(2,2)

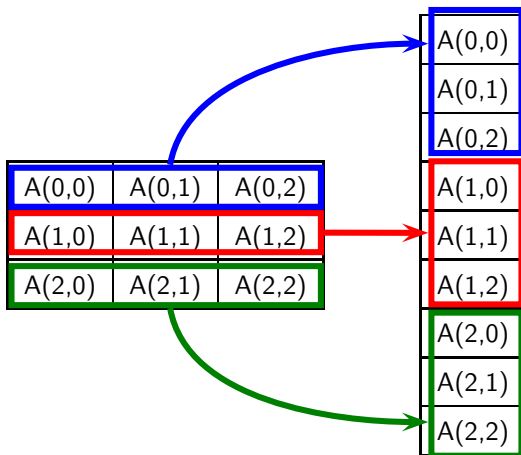


Representing Arrays in Memory

A 2-D Array

Row Major
Representation

Column Major
Representation



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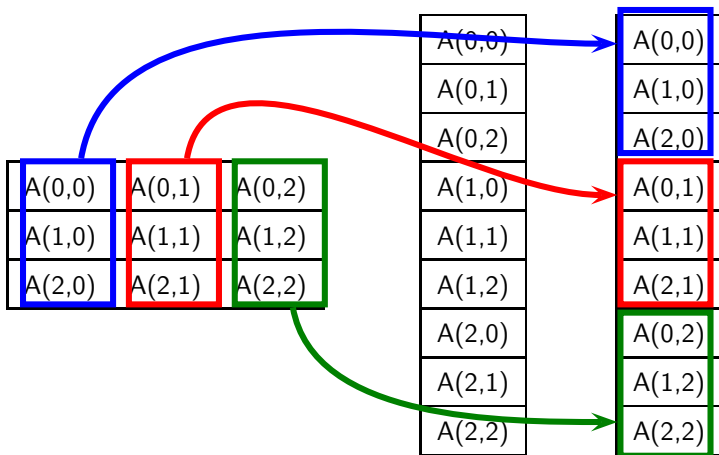


Representing Arrays in Memory

A 2-D Array

Row Major
Representation

Column Major
Representation



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Array Address Calculation

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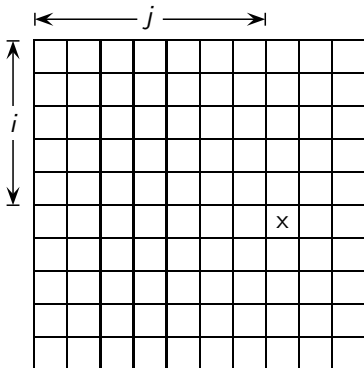
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Cell (i, j)





Array Address Calculation

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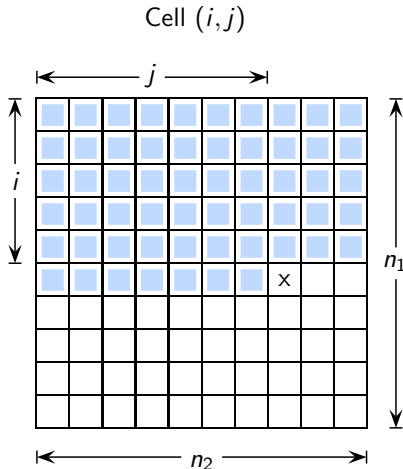
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- Indices begin at 0 (0, 1, 2, ...)
- Array is stored in the row major form
- The starting address of the cell is

$$\text{Base} + (i \times n_2) + j$$

- The number of cells in the first dimension does not matter



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Array Address Calculation

- Consider a 2-D array with limits (n_1, n_2)
 - The offset (i.e., starting address) of an element (i_1, i_2) is

$$i_1 \times n_2 + i_2$$



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Array Address Calculation

- Consider a 2-D array with limits (n_1, n_2)
 - The offset (i.e., starting address) of an element (i_1, i_2) is

$$i_1 \times n_2 + i_2$$

- Consider a k -D array with limits (n_1, n_2, \dots, n_k)
 - The offset (i.e., starting address) of an element (i_1, i_2, \dots, i_k) is

$$((((i_1 \times n_2 + i_2) \times n_3 + i_3) \times n_4 + i_4) \dots) \times n_k + i_k$$

Note that n_1 does not appear in the expression



Array Address Calculation

- Consider a 2-D array with limits (n_1, n_2)
 - The offset (i.e., starting address) of an element (i_1, i_2) is

$$i_1 \times n_2 + i_2$$

- Consider a k -D array with limits (n_1, n_2, \dots, n_k)
 - The offset (i.e., starting address) of an element (i_1, i_2, \dots, i_k) is

$$((((i_1 \times n_2 + i_2) \times n_3 + i_3) \times n_4 + i_4) \dots) \times n_k + i_k$$

Note that n_1 does not appear in the expression

- It can be obtained from the recurrence

$$\begin{aligned} O_1 &= i_1 \\ O_{j+1} &= O_j \times n_{j+1} + i_{j+1} \end{aligned}$$

where O_m gives the expression for dimension $1 \leq m \leq k$



Example of Array Address Calculation

Address calculation formula

$$\begin{aligned} O_1 &= i_1 \\ O_{j+1} &= O_j \times n_{j+1} + i_{j+1} \end{aligned}$$

Declaration

```
int b[10][20][30];
```

Access

```
a = b[c][d*e][f+g];
```

Generated code

```
t1 = c * 20    // O1 × n2
t2 = d * e     // i2
t3 = t1 + t2  // O2 = O1 × n2 + i2
t4 = t3 * 30   // O2 × n3
t5 = f + g     // i3
t6 = t4 + t5  // O3 = O2 × n3 + i3
t7 = t6 * 4    // O3 × sizeof(int)
t8 = b[t7]
a = t8
```

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We use the following attributes

- $S.code$, $E.place$, $E.code$, $id.name$, and $num.value$
- $A.name$: name of the array
- $A.offset$: name of the variable holding the offset of A
- $A.code$: code that access array element
- $A.ndim$: dimension number being considered

We use the following functions apart from $gen(\cdot)$ and $getNewTemp()$ functions

- $width(A)$ gives the number of bytes required an element in the array
- $dimLimit(A, i)$ gives the number of elements in dimension i (i.e., n_i)

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$S \rightarrow id = E$ $E \rightarrow id$ $E \rightarrow num$ $E \rightarrow \dots$	

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$S \rightarrow id = E$ $E \rightarrow id$ $E \rightarrow num$ $E \rightarrow \dots$	
$E \rightarrow A$	



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$S \rightarrow id = E$ $E \rightarrow id$ $E \rightarrow num$ $E \rightarrow \dots$	
$E \rightarrow A$	
$A \rightarrow id[E]$	

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$S \rightarrow id = E$ $E \rightarrow id$ $E \rightarrow num$ $E \rightarrow \dots$	
$E \rightarrow A$	
$A \rightarrow id[E]$	
$A_1 \rightarrow A_2[E]$	



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$S \rightarrow id = E$ $E \rightarrow id$ $E \rightarrow num$ $E \rightarrow \dots$	// The usual rules
$E \rightarrow A$	
$A \rightarrow id[E]$	
$A_1 \rightarrow A_2[E]$	



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$S \rightarrow id = E$ $E \rightarrow id$ $E \rightarrow num$ $E \rightarrow \dots$	// The usual rules
$E \rightarrow A$	$t_1 = getNewTemp(); t_2 = getNewTemp()$ $c_1 = gen(t_1, =, A.offset \times width(A.name))$ $c_2 = gen(t_2, =, A.name, [, t_1,])$ $E.code = A.code \parallel c_1 \parallel c_2$ $E.place = t_2$
$A \rightarrow id[E]$	
$A_1 \rightarrow A_2[E]$	



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$S \rightarrow id = E$ $E \rightarrow id$ $E \rightarrow num$ $E \rightarrow \dots$	// The usual rules
$E \rightarrow A$	$t_1 = getNewTemp(); t_2 = getNewTemp()$ $c_1 = gen(t_1, =, A.offset \times width(A.name))$ $c_2 = gen(t_2, =, A.name, [, t_1,])$ $E.code = A.code \parallel c_1 \parallel c_2$ $E.place = t_2$
$A \rightarrow id[E]$	$A.name = id.name; A.ndim = 1$ $A.offset = E.place; A.code = E.code$
$A_1 \rightarrow A_2[E]$	



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Declaration
Processing

$S \rightarrow id = E$ $E \rightarrow id$ $E \rightarrow num$ $E \rightarrow \dots$	// The usual rules
$E \rightarrow A$	$t_1 = getNewTemp(); t_2 = getNewTemp()$ $c_1 = gen(t_1, =, A.offset \times width(A.name))$ $c_2 = gen(t_2, =, A.name, [, t_1,])$ $E.code = A.code \parallel c_1 \parallel c_2$ $E.place = t_2$
$A \rightarrow id[E]$	$A.name = id.name; A.ndim = 1$ $A.offset = E.place; A.code = E.code$
$A_1 \rightarrow A_2[E]$	$t_1 = getNewTemp(); t_2 = getNewTemp()$ $A_1.name = A_2.name; A_1.ndim = A_2.ndim + 1$ $c_1 = gen(t_1, =, A_2.offset \times dimLimit(A_1.name, A_1.ndim))$ $c_2 = gen(t_2, =, t_1, +, E.place)$ $A_1.code = A_2.code \parallel E.code \parallel c_1 \parallel c_2$ $A_1.offset = t_2$



Example of Generating Code for Array Accesses

Declaration	<code>int b[10][20][30];</code>
Access	<code>a = b[c][d*e][f+g];</code>

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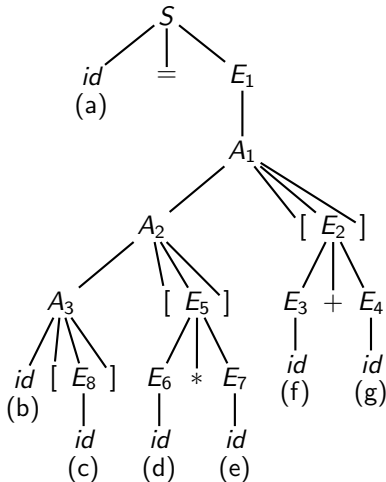
Declaration
Processing



Example of Generating Code for Array Accesses

Declaration `int b[10][20][30];`

Access `a = b[c][d*e][f+g];`



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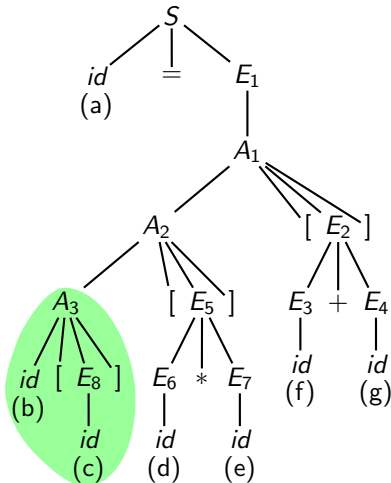
Declaration
Processing



Example of Generating Code for Array Accesses

Declaration `int b[10][20][30];`

Access `a = b[c][d*e][f+g];`



$E_8.code$ `NULL`

$E_8.place$ `c`

$A_3.name$ `b`

$A_3.ndim$ `1`

$A_3.code$ `NULL`

$A_3.offset$ `c`

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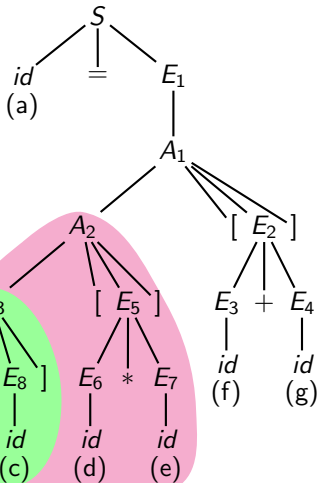
Declaration
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Example of Generating Code for Array Accesses

Declaration `int b[10][20][30];`

Access `a = b[c][d*e][f+g];`



E8.code NULL

E8.place c

A3.name b

A3.ndim 1

A3.code NULL

A3.offset c

E5.code $t_1 = d * e$

E5.place t_1

A2.name b

A2.ndim 2

A2.code $t_1 = d * e$
 $t_2 = c * 20$
 $t_3 = t_2 + t_1$

A2.offset t3

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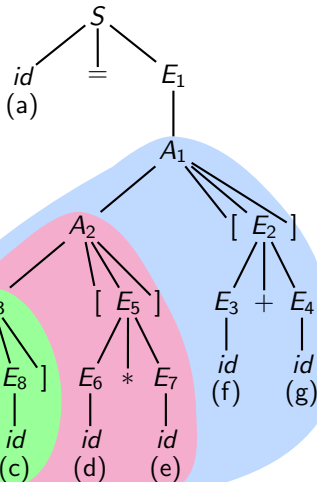
Declaration
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Example of Generating Code for Array Accesses

Declaration `int b[10][20][30];`

Access `a = b[c][d*e][f+g];`



$E_5.code \quad t_1 = d * e$

$E_5.place \quad t_1$

$A_2.name \quad b$

$A_2.ndim \quad 2$

$A_3.code \quad \begin{array}{l} t_1 = d * e \\ t_2 = c * 20 \\ t_3 = t_2 + t_1 \end{array}$

$A_3.offset \quad t_3$

$E_2.code \quad t_4 = f + g$

$E_2.place \quad t_4$

$A_1.name \quad b$

$A_1.ndim \quad 3$

$A_1.code \quad \begin{array}{l} t_1 = d * e \\ t_2 = c * 20 \\ t_3 = t_2 + t_1 \\ t_4 = f + g \\ t_5 = t_3 * 30 \\ t_6 = t_5 + t_4 \end{array}$

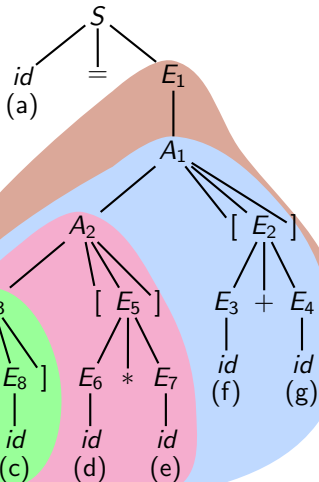
$A_1.offset \quad t_6$



Example of Generating Code for Array Accesses

Declaration `int b[10][20][30];`

Access `a = b[c][d*e][f+g];`



$E_2.code \quad t_4 = f + g$

$E_2.place \quad t_4$

$A_1.name \quad b$

$A_1.ndim \quad 3$

$A_1.code$

$t_1 = d * e$
$t_2 = c * 20$
$t_3 = t_2 + t_1$
$t_4 = f + g$
$t_5 = t_3 * 30$
$t_6 = t_5 + t_4$

$A_1.offset \quad t_6$

$E_1.code$

$t_1 = d * e$
$t_2 = c * 20$
$t_3 = t_2 + t_1$
$t_4 = f + g$
$t_5 = t_3 * 30$
$t_6 = t_5 + t_4$
$t_7 = t_6 * 4$
$t_8 = b[t_7]$

$E_1.place \quad t_8$



Example of Generating Code for Array Accesses

Declaration `int b[10][20][30];`

Access `a = b[c][d*e][f+g];`

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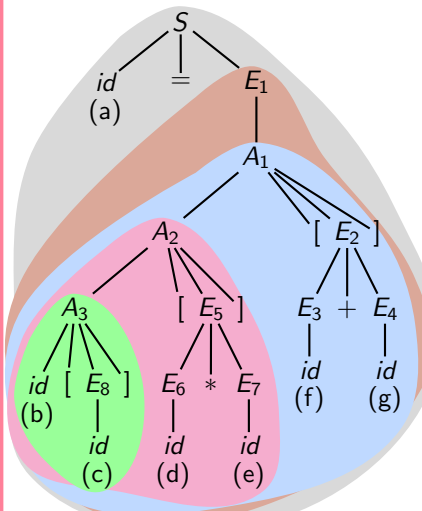
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E₁.code

$$\begin{array}{l} t_1 = d * e \\ t_2 = c * 20 \\ t_3 = t_2 + t_1 \\ t_4 = f + g \\ t_5 = t_3 * 30 \\ t_6 = t_5 + t_4 \\ \hline t_7 = t_6 * 4 \\ t_8 = b[t_7] \end{array}$$

E₁.place t₈

S.code

$$\begin{array}{l} t_1 = d * e \\ t_2 = c * 20 \\ t_3 = t_2 + t_1 \\ t_4 = f + g \\ t_5 = t_3 * 30 \\ t_6 = t_5 + t_4 \\ \hline t_7 = t_6 * 4 \\ t_8 = b[t_7] \\ \hline a = t_8 \end{array}$$



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Generating IR for Field Accesses in a Structure: Approach 1

```
struct A { double a; int b; };  
  
struct B { int c; struct A d; };  
  
struct C { int d; struct B e; };  
  
struct C x;  
  
int b = x.e.d.b;
```



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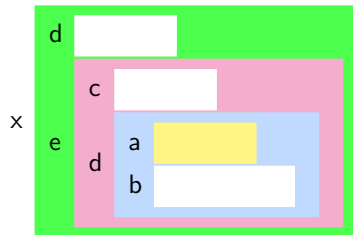
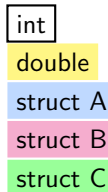
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Generating IR for Field Accesses in a Structure: Approach 1

```
struct A { double a; int b; };  
  
struct B { int c; struct A d; };  
  
struct C { int d; struct B e; };  
  
struct C x;  
  
int b = x.e.d.b;
```





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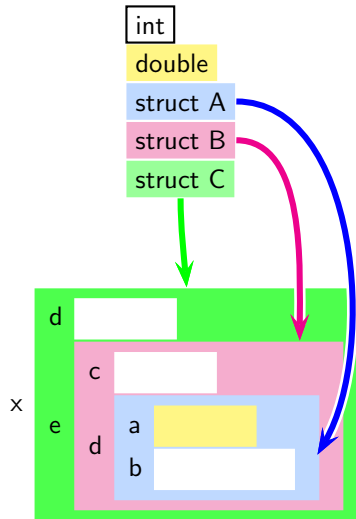
Type Analysis

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Declaration
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Generating IR for Field Accesses in a Structure: Approach 1

```
struct A { double a; int b; };  
struct B { int c; struct A d; };  
struct C { int d; struct B e; };  
  
struct C x;  
  
int b = x.e.d.b;
```





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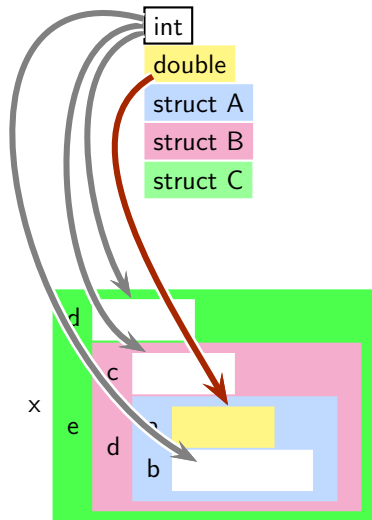
Type Analysis

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Generating IR for Field Accesses in a Structure: Approach 1

```
struct A { double a; int b; };  
struct B { int c; struct A d; };  
struct C { int d; struct B e; };  
  
struct C x;  
  
int b = x.e.d.b;
```





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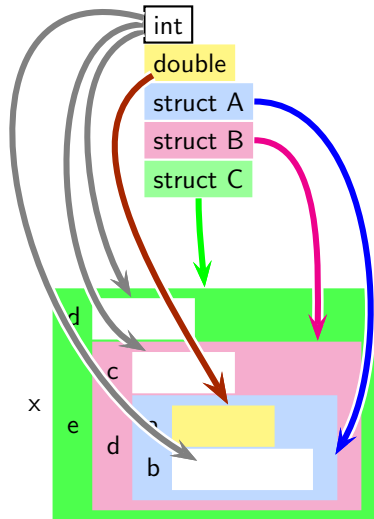
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Generating IR for Field Accesses in a Structure: Approach 1

```
struct A { double a; int b; };  
struct B { int c; struct A d; };  
struct C { int d; struct B e; };  
  
struct C x;  
  
int b = x.e.d.b;
```





Generating IR for Field Accesses in a Structure: Approach 1

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```
struct A { double a; int b; };

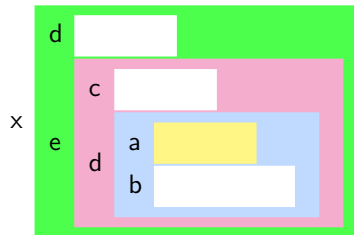
struct B { int c; struct A d; };

struct C { int d; struct B e; };

struct C x;

int b = x.e.d.b;
```

Type	Field	Field Type	Offset
struct C	d	int	0
	e	struct B	4
struct B	c	int	0
	d	struct A	4
struct A	a	double	0
	b	int	8





Generating IR for Field Accesses in a Structure: Approach 1

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```
struct A { double a; int b; };

struct B { int c; struct A d; };

struct C { int d; struct B e; };

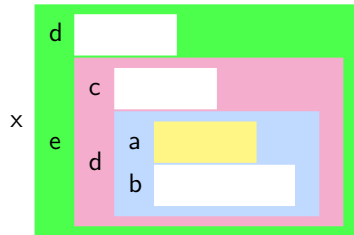
struct C x;

int b = x.e.d.b;
```

Required IR code

$$\begin{aligned} t_1 &= \&x \\ t_2 &= t_1 + 16 \\ t_3 &= *t_2 \\ b &= t_3 \end{aligned}$$

Type	Field	Field Type	Offset
struct C	d	int	0
	e	struct B	4
struct B	c	int	0
	d	struct A	4
struct A	a	double	0
	b	int	8





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Generating IR for Field Accesses in a Structure: Approach 2

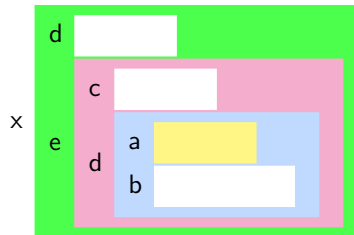
```
struct A { double a; int b; };
struct B { int c; struct A d; };
struct C { int d; struct B e; };

struct C x;

int b = x.e.d.b;
```

Type	Field	Field Type	Offset
struct C	d	int	0
	e	struct B	4
struct B	c	int	0
	d	struct A	4
struct A	a	double	0
	b	int	8

```
t1 = &x
t2 = t1 + 4 //&x.e
t3 = t2 + 4 //&x.e.d
t4 = t3 + 8 //&x.e.d.b
t5 = *t5
b = t5
```





SDD for Generating Code for Field Accesses: Approach 1

We use the following attributes

- $S.code$, $E.place$, $E.code$, $id.name$, and $num.value$
- $F.name$: name of the structure variable
- $F.offset$: offset of the field accessed using F
- $F.type$: type of the field accessed using F

This approach computes the final offsets at compile time and hence uses $F.offset$ attribute but not $F.code$ attribute

We use the following functions apart from $gen(\cdot)$ and $getNewTemp()$

- $offset(\tau, f)$ gives the offset of field f in structure type τ
- $type(\tau, f)$ gives the type of field f in structure type τ

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$S \rightarrow id = E$	
$E \rightarrow id$	
$E \rightarrow \dots$	



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SDD for Generating Code for Field Accesses: Approach 1

$S \rightarrow id = E$	
$E \rightarrow id$	
$E \rightarrow \dots$	
$E \rightarrow F$	



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SDD for Generating Code for Field Accesses: Approach 1

$S \rightarrow id = E$	
$E \rightarrow id$	
$E \rightarrow \dots$	
$E \rightarrow F$	
$F \rightarrow id_1 \cdot id_2$	



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$S \rightarrow id = E$	
$E \rightarrow id$	
$E \rightarrow \dots$	
$E \rightarrow F$	
$F \rightarrow id_1 \cdot id_2$	
$F_1 \rightarrow F_2 \cdot id$	



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Declaration
Processing

$S \rightarrow id = E$	$S.code = E.code \parallel gen(id.place, =, E.place)$
$E \rightarrow id$	$E.code = NULL; E.place = id.name$
$E \rightarrow \dots$	// The usual rules
$E \rightarrow F$	
$F \rightarrow id_1 \cdot id_2$	
$F_1 \rightarrow F_2 \cdot id$	



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Processing

$S \rightarrow id = E$	$S.code = E.code \parallel gen(id.place, =, E.place)$
$E \rightarrow id$	$E.code = NULL; E.place = id.name$
$E \rightarrow \dots$	// The usual rules
$E \rightarrow F$	$t_1 = getNewTemp(); t_2 = getNewTemp(); t_3 = getNewTemp()$ $c_1 = gen(t_1, =, \&F.name)$ $c_2 = gen(t_2, =, t_1 + F.offset)$ $c_3 = gen(t_3, =, *t_2)$ $E.code = c_1 \parallel c_2 \parallel c_3$ $E.place = t_3$
$F \rightarrow id_1 \cdot id_2$	
$F_1 \rightarrow F_2 \cdot id$	



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$S \rightarrow id = E$	$S.code = E.code \parallel gen(id.place, =, E.place)$
$E \rightarrow id$	$E.code = NULL; E.place = id.name$
$E \rightarrow \dots$	// The usual rules
$E \rightarrow F$	$t_1 = getNewTemp(); t_2 = getNewTemp(); t_3 = getNewTemp()$ $c_1 = gen(t_1, =, \&F.name)$ $c_2 = gen(t_2, =, t_1 + F.offset)$ $c_3 = gen(t_3, =, *t_2)$ $E.code = c_1 \parallel c_2 \parallel c_3$ $E.place = t_3$
$F \rightarrow id_1 \cdot id_2$	$F.name = id_1.name$ $F.type = type(id_1.type, id_2.name)$ $F.offset = offset(id_1.type, id_2.name)$
$F_1 \rightarrow F_2 \cdot id$	



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Declaration
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$S \rightarrow id = E$	$S.code = E.code \parallel gen(id.place, =, E.place)$
$E \rightarrow id$	$E.code = NULL; E.place = id.name$
$E \rightarrow \dots$	// The usual rules
$E \rightarrow F$	$t_1 = getNewTemp(); t_2 = getNewTemp(); t_3 = getNewTemp();$ $c_1 = gen(t_1, =, \&F.name)$ $c_2 = gen(t_2, =, t_1 + F.offset)$ $c_3 = gen(t_3, =, *t_2)$ $E.code = c_1 \parallel c_2 \parallel c_3$ $E.place = t_3$
$F \rightarrow id_1 \cdot id_2$	$F.name = id_1.name$ $F.type = type(id_1.type, id_2.name)$ $F.offset = offset(id_1.type, id_2.name)$
$F_1 \rightarrow F_2 \cdot id$	$F_1.name = F_2.name$ $F_1.type = type(F_2.type, id.name)$ $F_1.offset = F_2.offset + offset(F_2.type, id.name)$



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Example of Generating Code for Field Accesses: Approach 1

Field Access

```
b = x.e.d.b;
```

Type	Field	Field Type	Offset
struct C	d	int	0
	e	struct B	4
struct B	c	int	0
	d	struct A	4
struct A	a	double	0
	b	int	8



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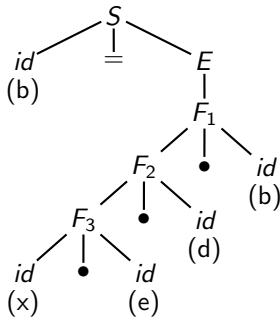
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Example of Generating Code for Field Accesses: Approach 1

Field Access

`b = x.e.d.b;`

Type	Field	Field Type	Offset
struct C	d	int	0
	e	struct B	4
struct B	c	int	0
	d	struct A	4
struct A	a	double	0
	b	int	8





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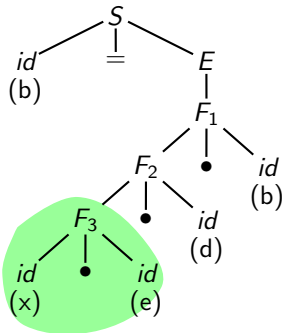
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Field Access

`b = x.e.d.b;`

Type	Field	Field Type	Offset
struct C	d	int	0
	e	struct B	4
struct B	c	int	0
	d	struct A	4
struct A	a	double	0
	b	int	8



$F_3.name$ x
 $F_3.type$ B
 $F_3.offset$ 4



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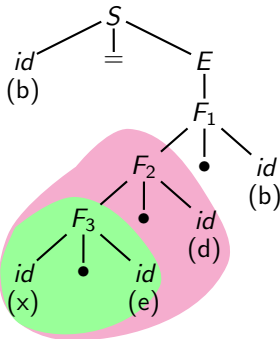
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Example of Generating Code for Field Accesses: Approach 1

Field Access

`b = x.e.d.b;`

Type	Field	Field Type	Offset
struct C	d	int	0
	e	struct B	4
struct B	c	int	0
	d	struct A	4
struct A	a	double	0
	b	int	8



$F_3.name \ x$
 $F_3.type \ B$
 $F_3.offset \ 4$

$F_2.name \ x$
 $F_2.type \ A$
 $F_2.offset \ 8$



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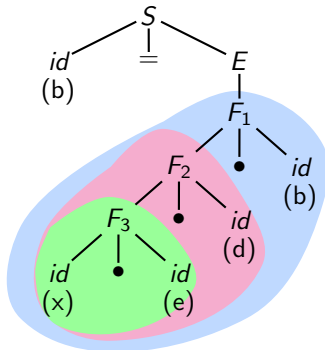
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Example of Generating Code for Field Accesses: Approach 1

Field Access

`b = x.e.d.b;`

Type	Field	Field Type	Offset
struct C	d	int	0
	e	struct B	4
struct B	c	int	0
	d	struct A	4
struct A	a	double	0
	b	int	8



$F_3.name \ x$
 $F_3.type \ B$
 $F_3.offset \ 4$

$F_2.name \ x$
 $F_2.type \ A$
 $F_2.offset \ 8$

$F_1.name \ x$
 $F_1.type \ int$
 $F_1.offset \ 16$

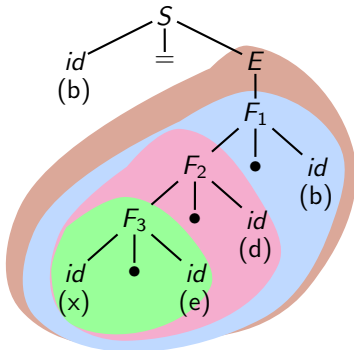


Example of Generating Code for Field Accesses: Approach 1

Field Access

`b = x.e.d.b;`

Type	Field	Field Type	Offset
struct C	d	int	0
	e	struct B	4
struct B	c	int	0
	d	struct A	4
struct A	a	double	0
	b	int	8



$F_3.name \times$
 $F_3.type \ B$
 $F_3.offset \ 4$

$F_2.name \times$
 $F_2.type \ A$
 $F_2.offset \ 8$

$F_1.name \times$
 $F_1.type \ int$
 $F_1.offset \ 16$

$E.code$

$$t_1 = \&x$$

$$t_2 = t_1 + 16$$

$$t_3 = *t_2$$

$E.place \ t_3$



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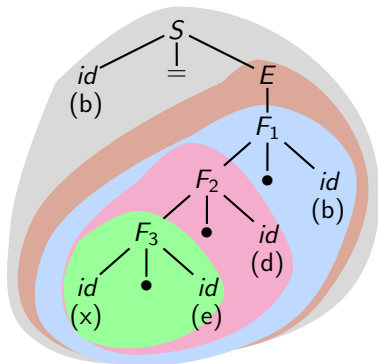
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Example of Generating Code for Field Accesses: Approach 1

Field Access

`b = x.e.d.b;`

Type	Field	Field Type	Offset
struct C	d	int	0
	e	struct B	4
struct B	c	int	0
	d	struct A	4
struct A	a	double	0
	b	int	8



$F_3.name \ x$
 $F_3.type \ B$
 $F_3.offset \ 4$

$F_2.name \ x$
 $F_2.type \ A$
 $F_2.offset \ 8$

$F_1.name \ x$
 $F_1.type \ int$
 $F_1.offset \ 16$

$E.code$

$$\begin{aligned} t_1 &= \&x \\ t_2 &= t_1 + 16 \\ t_3 &= *t_2 \end{aligned}$$

$E.place \ t_3$

$S.code$

$$\begin{aligned} t_1 &= \&x \\ t_2 &= t_1 + 16 \\ t_3 &= *t_2 \\ \hline b &= t_3 \end{aligned}$$



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Generating IR for Field Accesses Through Pointers in a Structure

```
struct A { double a; int b; };  
struct B { int c; struct A *d; };  
struct C { int d; struct B *e; };
```

```
struct C x, *w;  
struct B y;  
struct A z;
```

```
w = &x; x.e = &y; y.d = &z;  
int b = w->e->d->b;
```



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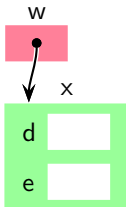
Generating IR for Field Accesses Through Pointers in a Structure

```
struct A { double a; int b; };  
struct B { int c; struct A *d; };  
struct C { int d; struct B *e; };  

```

```
struct C x, *w;  
struct B y;  
struct A z;
```

```
w = &x; x.e = &y; y.d = &z;  
int b = w->e->d->b;
```





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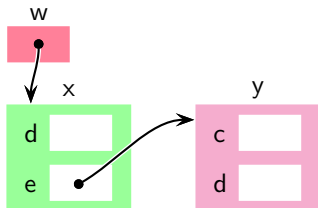
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Generating IR for Field Accesses Through Pointers in a Structure

```
struct A { double a; int b; };  
struct B { int c; struct A *d; };  
struct C { int d; struct B *e; };
```

```
struct C x, *w;  
struct B y;  
struct A z;
```

```
w = &x; x.e = &y; y.d = &z;  
int b = w->e->d->b;
```



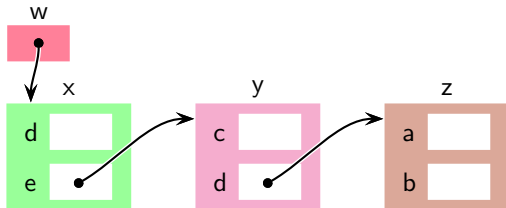


Generating IR for Field Accesses Through Pointers in a Structure

```
struct A { double a; int b; };  
struct B { int c; struct A *d; };  
struct C { int d; struct B *e; };  
  
struct C x, *w;  
struct B y;  
struct A z;
```

```
struct C x, *w;  
struct B y;  
struct A z;
```

```
w = &x; x.e = &y; y.d = &z;  
int b = w->e->d->b;
```





Generating IR for Field Accesses Through Pointers in a Structure

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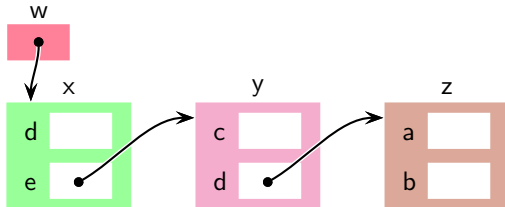
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```
struct A { double a; int b; };
struct B { int c; struct A *d; };
struct C { int d; struct B *e; };
```

```
struct C x, *w;
struct B y;
struct A z;
```

```
w = &x; x.e = &y; y.d = &z;
int b = w->e->d->b;
```

Type	Field	Field Type	Offset
struct C	d	int	0
	e	struct B *	4
struct B	c	int	0
	d	struct A *	4
struct A	a	double	0
	b	int	8





Generating IR for Field Accesses Through Pointers in a Structure

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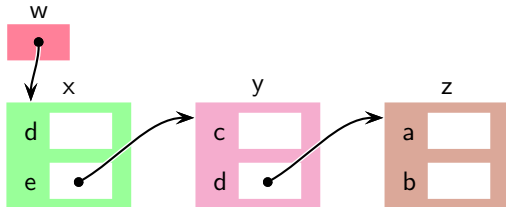
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```
struct A { double a; int b; };
struct B { int c; struct A *d; };
struct C { int d; struct B *e; };
```

```
struct C x, *w;
struct B y;
struct A z;
```

```
w = &x; x.e = &y; y.d = &z;
int b = w->e->d->b;
```



Type	Field	Field Type	Offset
struct C	d	int	0
	e	struct B *	4
struct B	c	int	0
	d	struct A *	4
struct A	a	double	0
	b	int	8

IR code for access

expression $w \rightarrow e \rightarrow d \rightarrow b$

```
t1 = w + 4    //&(x.e)
t2 = *t1     //&y
t3 = t2 + 4   //&(y.d)
t4 = *t3     //&z
t5 = t4 + 8   //&(z.b)
t6 = *t5
```



SDD For Generating Code for Field Accesses

We use the following attributes

- E represents an arithmetic expression and F represents an access expression
- $E.place$, $E.code$, $id.name$, and $id.type$
- $F.type$: type of the field accessed using F
- $F.address$: name of the variable holding the address computed by F
- $F.code$: code representing the access expression F

Unlike the previous approach, we cannot compute the final offsets at compile time because of pointers, and hence we use $F.code$ and not $F.offset$

We use the following functions apart from $gen(\cdot)$ and $getNewTemp()$ functions

- $offset(\tau, f)$ gives the offset of field f in structure type τ
- $type(\tau, f)$ gives the type of field f in structure type τ

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Grammar for Accessing Field Accesses Through Pointers



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Since we need to use \rightarrow as a token in our rules, we use quotes around it (i.e., ' \rightarrow ') to distinguish it from the metacharacter \rightarrow that separates the LHS and RHS in the rule

$$E \rightarrow F$$
$$F \rightarrow id \cdot id$$
$$F \rightarrow F \cdot id$$
$$F \rightarrow id \text{ '}\rightarrow\text{' } id$$
$$F \rightarrow F \text{ '}\rightarrow\text{' } id$$



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$E \rightarrow F$	
$F \rightarrow id_1 \cdot id_2$	
$F_1 \rightarrow F_2 \cdot id$	



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$E \rightarrow F$	$t_1 = \text{getNewTemp}(); E.place = t_1$ $E.code = F.code \parallel \text{gen}(t_1, =, *F.address)$
$F \rightarrow id_1 \cdot id_2$	
$F_1 \rightarrow F_2 \cdot id$	



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Declaration
Processing

$E \rightarrow F$	$t_1 = \text{getNewTemp}(); E.place = t_1$ $E.code = F.code \parallel \text{gen}(t_1, =, *F.address)$
$F \rightarrow id_1 \cdot id_2$	$t_1 = \text{getNewTemp}(); t_2 = \text{getNewTemp}()$ $F.type = \text{type}(id_1.type, id_2.name)$ $c_1 = \text{gen}(t_1, =, \&id_1.name)$ $F.code = c_1 \parallel \text{gen}(t_2, =, t_1 + \text{offset}(id_1.type, id_2.name))$ $F.address = t_2$
$F_1 \rightarrow F_2 \cdot id$	



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Declaration
Processing

$E \rightarrow F$	$t_1 = \text{getNewTemp}()$; $E.place = t_1$ $E.code = F.code \parallel \text{gen}(t_1, =, *F.address)$
$F \rightarrow id_1 \cdot id_2$	$t_1 = \text{getNewTemp}()$; $t_2 = \text{getNewTemp}()$ $F.type = \text{type}(id_1.type, id_2.name)$ $c_1 = \text{gen}(t_1, =, \&id_1.name)$ $F.code = c_1 \parallel \text{gen}(t_2, =, t_1 + \text{offset}(id_1.type, id_2.name))$ $F.address = t_2$
$F_1 \rightarrow F_2 \cdot id$	$t_1 = \text{getNewTemp}()$ $F_1.type = \text{type}(F_2.type, id.name)$ $c_1 = \text{gen}(t_1, =, F_2.address + \text{offset}(F_2.type, id.name))$ $F_1.code = F_2.code \parallel c_1$ $F_1.address = t_1$



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$F \rightarrow id_1 \rightarrow id_2$	
$F_1 \rightarrow F_2 \rightarrow id$	



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$F \rightarrow id_1 \rightarrow' id_2$	<p>Let τ be a type such that $id_1.type = pointer(\tau)$</p> <p>$t_1 = getNewTemp()$</p> <p>$F.type = type(\tau, id_2.name)$</p> <p>$F.code = gen(t_1, id_1.name + offset(\tau, id_2.name))$</p> <p>$F.address = t_1$</p>
$F_1 \rightarrow F_2 \rightarrow' id$	



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Declaration
Processing

$F \rightarrow id_1 ' \rightarrow ' id_2$	<p>Let τ be a type such that $id_1.type = pointer(\tau)$</p> <p>$t_1 = getNewTemp()$</p> <p>$F.type = type(\tau, id_2.name)$</p> <p>$F.code = gen(t_1, =, id_1.name + offset(\tau, id_2.name))$</p> <p>$F.address = t_1$</p>
$F_1 \rightarrow F_2 ' \rightarrow ' id$	<p>Let τ be a type such that $F_2.type = pointer(\tau)$</p> <p>$t_1 = getNewTemp(); t_2 = getNewTemp()$</p> <p>$F_1.type = type(\tau, id.name)$</p> <p>$c_1 = gen(t_1, =, *F_2.address)$</p> <p>$F_1.code = F_2.code c_1 gen(t_2, =, t_1 + offset(\tau, id.name))$</p> <p>$F_1.address = t_2$</p>



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Example of Generating Code for Field Accesses Through Pointers

Field Access

```
w->e->d->b;
```

Type	Field	Field Type	Offset
struct C	d	int	0
	e	struct B *	4
struct B	c	int	0
	d	struct A *	4
struct A	a	double	0
	b	int	8



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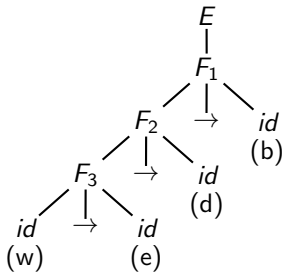
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Example of Generating Code for Field Accesses Through Pointers

Field Access

`w->e->d->b;`

Type	Field	Field Type	Offset
struct C	d	int	0
	e	struct B *	4
struct B	c	int	0
	d	struct A *	4
struct A	a	double	0
	b	int	8





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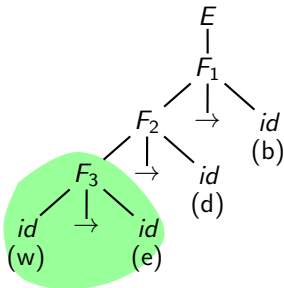
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Example of Generating Code for Field Accesses Through Pointers

Field Access

`w->e->d->b;`

Type	Field	Field Type	Offset
struct C	d	int	0
	e	struct B *	4
struct B	c	int	0
	d	struct A *	4
struct A	a	double	0
	b	int	8



*F*₃.type struct B *
*F*₃.code `t1 = w + 4`
*F*₃.address *t*₁



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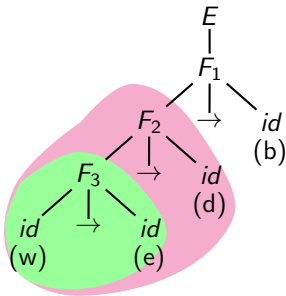
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Example of Generating Code for Field Accesses Through Pointers

Field Access

`w->e->d->b;`

Type	Field	Field Type	Offset
struct C	d	int	0
	e	struct B *	4
struct B	c	int	0
	d	struct A *	4
struct A	a	double	0
	b	int	8



F₃.type struct B *

F₃.code $t_1 = w + 4$

F₃.address t_1

F₂.type struct A *

F₂.code $t_1 = w + 4$
 $t_2 = *t_1$
 $t_3 = t_2 + 4$

F₂.address t_3

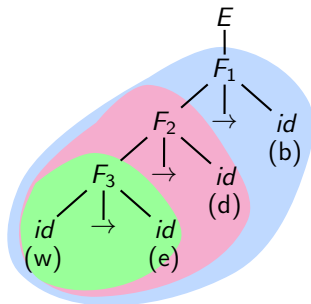


Example of Generating Code for Field Accesses Through Pointers

Field Access

$w \rightarrow e \rightarrow d \rightarrow b;$

Type	Field	Field Type	Offset
struct C	d	int	0
	e	struct B *	4
struct B	c	int	0
	d	struct A *	4
struct A	a	double	0
	b	int	8



$F_2.type$ struct A *

$F_2.code$
$$\frac{t_1 = w + 4}{t_2 = *t_1}$$

 $t_3 = t_2 + 4$

$F_2.address$ t_3

$F_1.type$ int

$F_1.code$
$$\frac{t_1 = w + 4}{t_2 = *t_1}$$

 $t_3 = t_2 + 4$
 $t_4 = *t_3$
 $t_5 = t_4 + 8$

$F_1.address$ t_5



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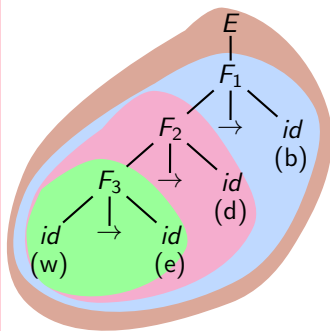
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Example of Generating Code for Field Accesses Through Pointers

Field Access

`w->e->d->b;`

Type	Field	Field Type	Offset
struct C	d	int	0
	e	struct B *	4
struct B	c	int	0
	d	struct A *	4
struct A	a	double	0
	b	int	8



$F_1.type$ *int*

$t_1 = w + 4$

$t_2 = *t_1$

$t_3 = t_2 + 4$

$t_4 = *t_3$

$t_5 = t_4 + 8$

$F_1.address$ t_5

$E.code$

$t_1 = w + 4$

$t_2 = *t_1$

$t_3 = t_2 + 4$

$t_4 = *t_3$

$t_5 = t_4 + 8$

$t_6 = *t_5$

$E.place$ t_6



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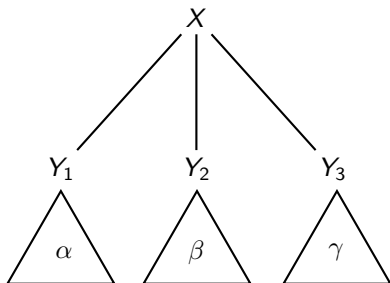
Syntax Directed Translation Schemes



Inherited and Synthesized Attributes

Given a production $X \rightarrow Y_1 Y_2 \dots Y_k$

- If an attribute $X.a$ is computed from those of Y_i , $1 \leq i \leq k$, the $X.a$ is a synthesized attribute
- If an attribute $Y_i.a$, $1 \leq i \leq k$ is computed from those of X or Y_j , $1 \leq j \leq i-1$, then $Y_i.a$ is an inherited attribute

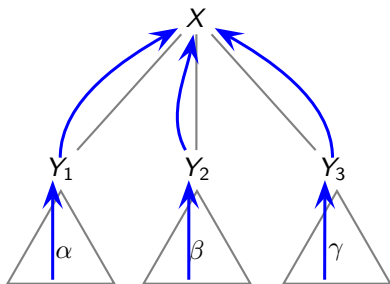




Inherited and Synthesized Attributes

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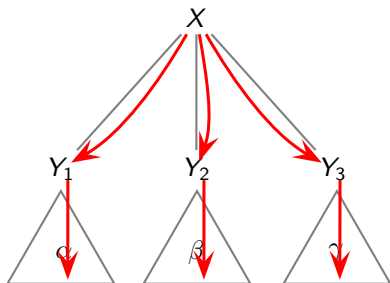
Synthesized attributes (blue arrows) flow upwards in a parse tree (computed from descendants)



Inherited and Synthesized Attributes

Given a production $X \rightarrow Y_1 Y_2 \dots Y_k$

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Synthesized attributes (**blue arrows**) flow upwards in a parse tree (computed from descendants)

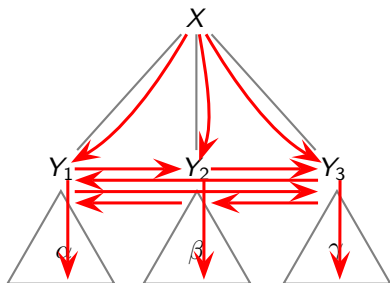
Inherited attributes (**red arrows**) flow downwards or sideways in a parse tree (computed from ancestors or siblings)



Inherited and Synthesized Attributes

Given a production $X \rightarrow Y_1 Y_2 \dots Y_k$

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Synthesized attributes (blue arrows) flow upwards in a parse tree (computed from descendants)

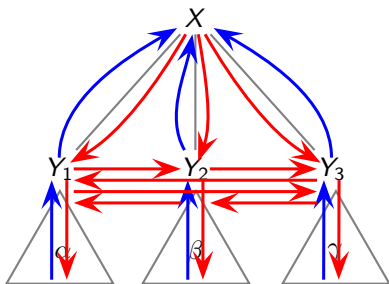
Inherited attributes (red arrows) flow downwards or sideways in a parse tree (computed from ancestors or siblings)



Inherited and Synthesized Attributes

Given a production $X \rightarrow Y_1 Y_2 \dots Y_k$

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Synthesized attributes (blue arrows) flow upwards in a parse tree (computed from descendants)

Inherited attributes (red arrows) flow downwards or sideways in a parse tree (computed from ancestors or siblings)



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Why Inherited Attributes?

Consider an SDD for processing declarations

$Decl \rightarrow Type \ VarList$	$VarList.type = Type.name$
$Type \rightarrow int$	$Type.name = int$
$Type \rightarrow float$	$Type.name = float$
$VarList_1 \rightarrow VarList_2 \ , \ id$	$VarList_2.type = VarList_1.type$ $id.type = VarList_1.type$
$VarList \rightarrow id$	$id.type = VarList.type$

Here, the attribute *type* is inherited



Why Inherited Attributes?

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Consider IR Generation for a **for** loop with **break** and **continue** statements

$S_1 \rightarrow \mathbf{for} (E_1; E_2; E_3) S_2$	\dots
$S \rightarrow \mathbf{break}$	$S.code = gen(goto, S.exit)$
$S \rightarrow \mathbf{continue}$	$S.code = gen(goto, S.increment)$

We need the labels $S.exit$ and $S.increment$ while parsing the string derivable from S_2



Control Flow Translation of Boolean Expressions

Short-circuit evaluation of boolean expressions	
$E_1 \rightarrow E_2$ or E_3	Evaluate E_3 only if E_2 evaluates to false because if E_2 evaluates to true, E_1 is true regardless of E_2
$E_1 \rightarrow E_2$ and E_3	Evaluate E_3 only if E_2 evaluates to true because if E_2 evaluates to false, E_1 is false regardless of E_2

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Control Flow Translation of Boolean Expressions

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$E_1 \rightarrow E_2 \text{ and } E_3$	Evaluate E_3 only if E_2 evaluates to true because if E_2 evaluates to false, E_1 is false regardless of E_3

Input Expression	Generated Code
$(a < b \text{ or } b > d) \text{ and } c > d$	$t_1 = a < b$ if t_1 goto L3 goto L4 L4: $t_2 = b > c$ if t_2 goto L3 goto L2 L3: $t_3 = c > d$ if t_3 goto L1 // overall true goto L2 // overall false



SDD for Control Flow Translation of Boolean Expressions

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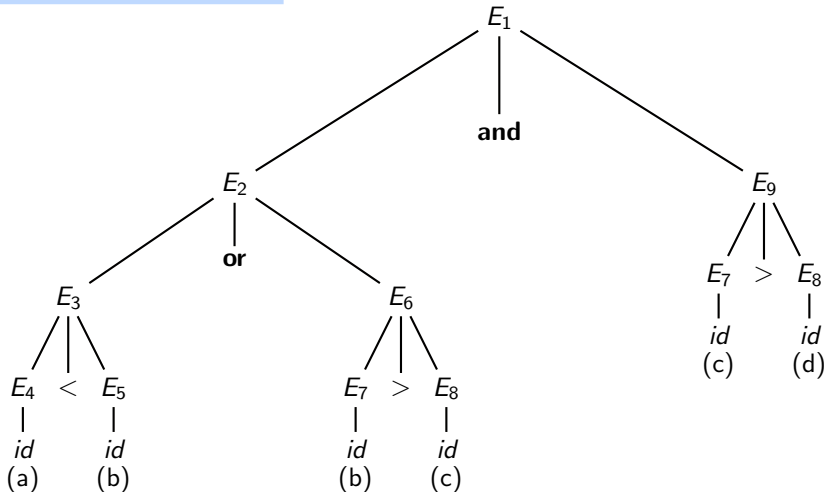
$E_1 \rightarrow E_2 \text{ or } E_3$	$E_2.true = E_1.true$ $E_2.false = \text{getNewLabel}()$ $E_3.true = E_1.true$ $E_3.false = E_1.false$ $E_1.code = E_2.code \parallel \text{gen}(E_2.false, :) \parallel E_3.code$
$E_1 \rightarrow E_2 \text{ and } E_3$	$E_2.true = \text{getNewLabel}()$ $E_2.false = E_1.false$ $E_3.true = E_1.true$ $E_3.false = E_1.false$ $E_1.code = E_2.code \parallel \text{gen}(E_2.true, :) \parallel E_3.code$
$E_1 \rightarrow E_2 \text{ relop } E_3$	$t_1 = \text{getNewTemp}()$ $c_1 = \text{gen}(t_1, =, E_2.place, \text{relop}, E_3.place)$ $c_2 = \text{gen}(\text{if}, t_1, \text{goto}, E_1.true)$ $c_3 = \text{gen}(\text{goto}, E_1.false)$ $E_1.code = E_2.code \parallel E_3.code \parallel c_1 \parallel c_2 \parallel c_3$



Attribute Evaluation for Control Flow Translation of Boolean Expressions

Input Expression:

$(a < b \text{ or } b > d) \text{ and } c > d$

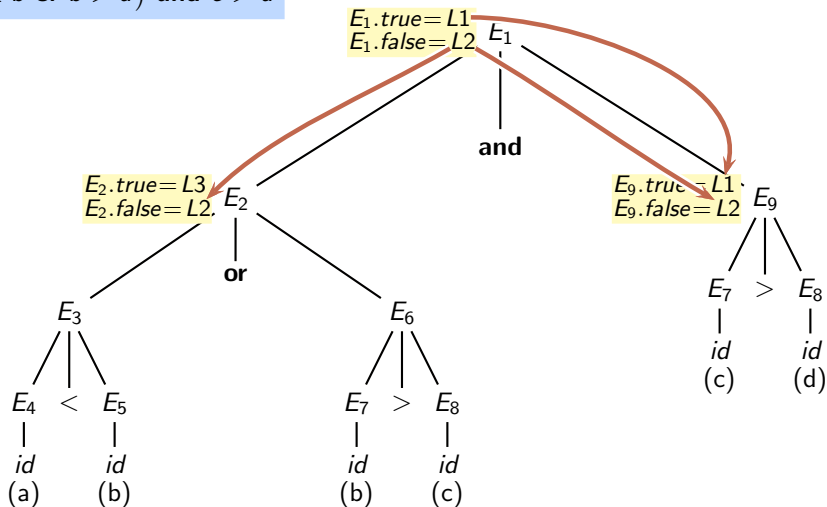




Attribute Evaluation for Control Flow Translation of Boolean Expressions

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$(a < b \text{ or } b > d) \text{ and } c > d$

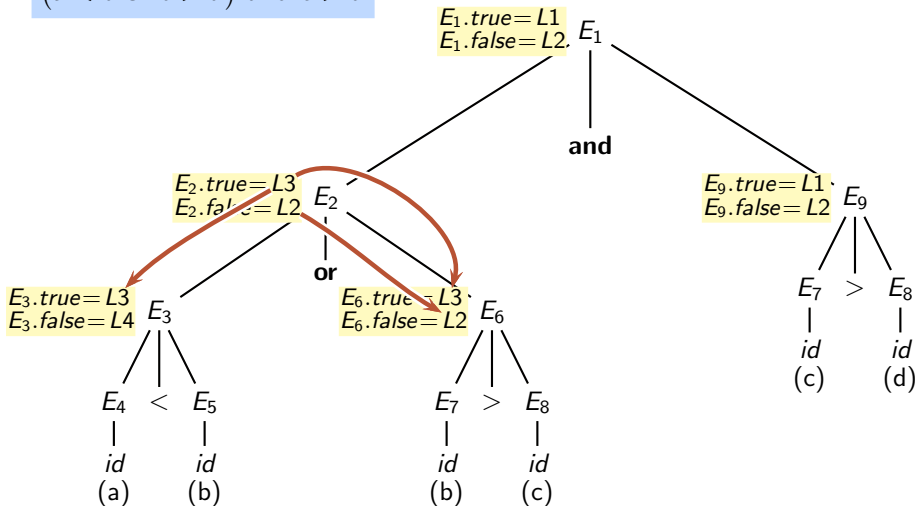




Attribute Evaluation for Control Flow Translation of Boolean Expressions

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$(a < b \text{ or } b > d) \text{ and } c > d$

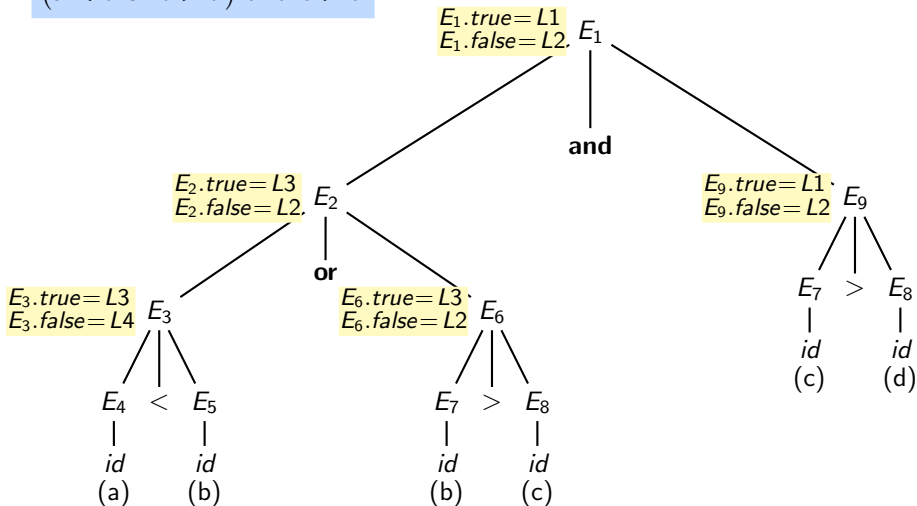




Attribute Evaluation for Control Flow Translation of Boolean Expressions

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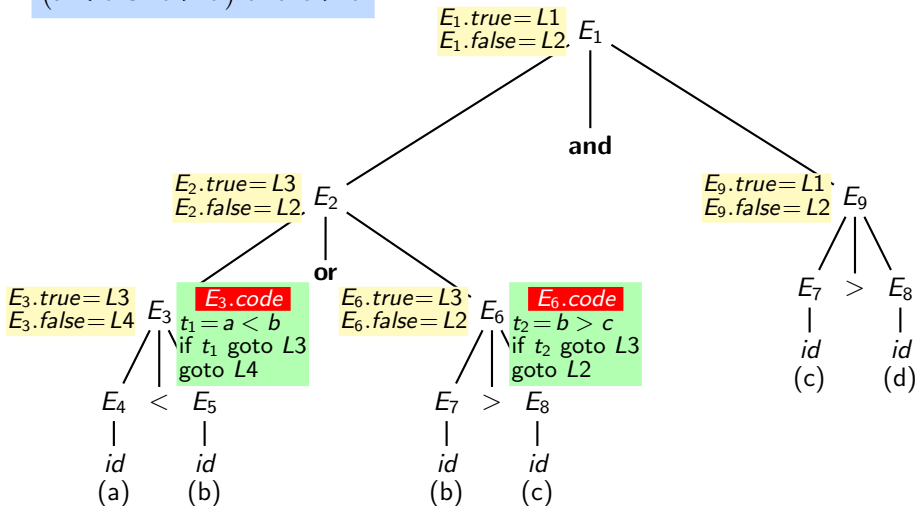




Attribute Evaluation for Control Flow Translation of Boolean Expressions

Input Expression:

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Attribute Evaluation for Control Flow Translation of Boolean Expressions

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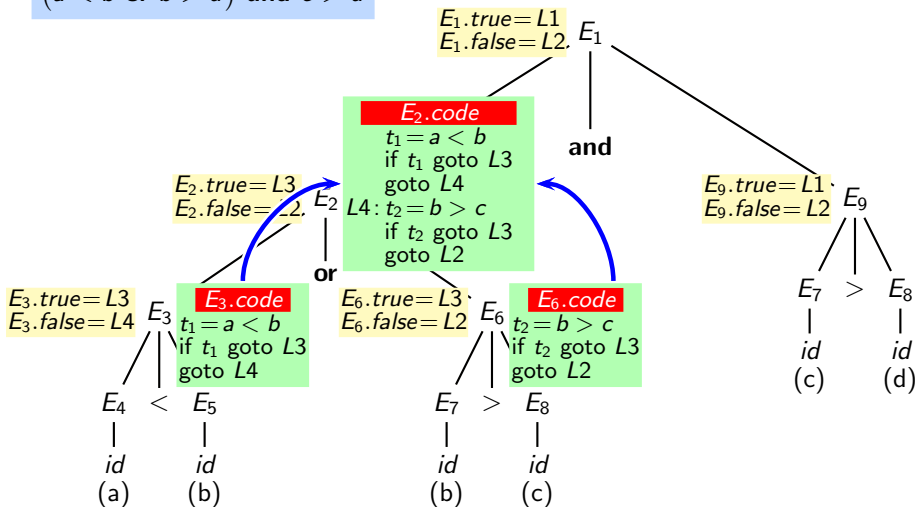
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Attribute Evaluation for Control Flow Translation of Boolean Expressions

Input Expression:

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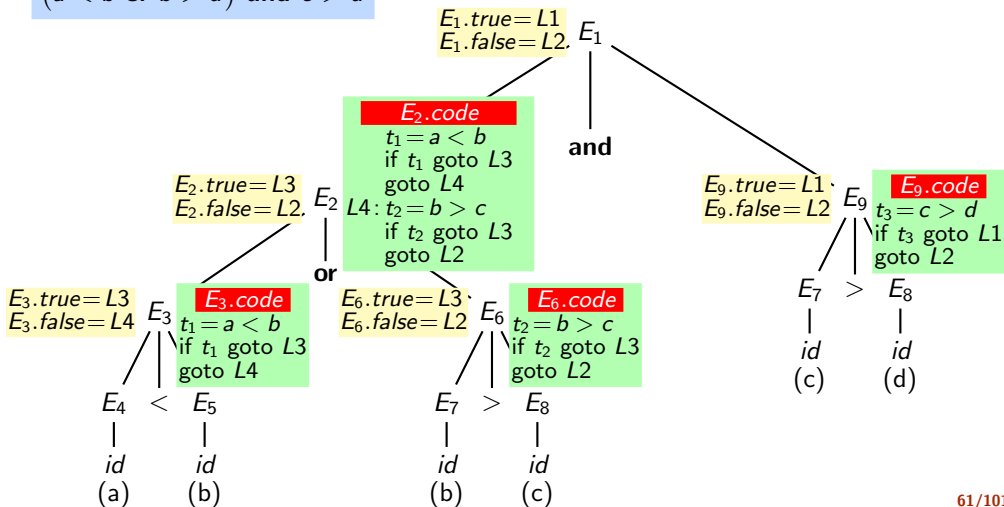
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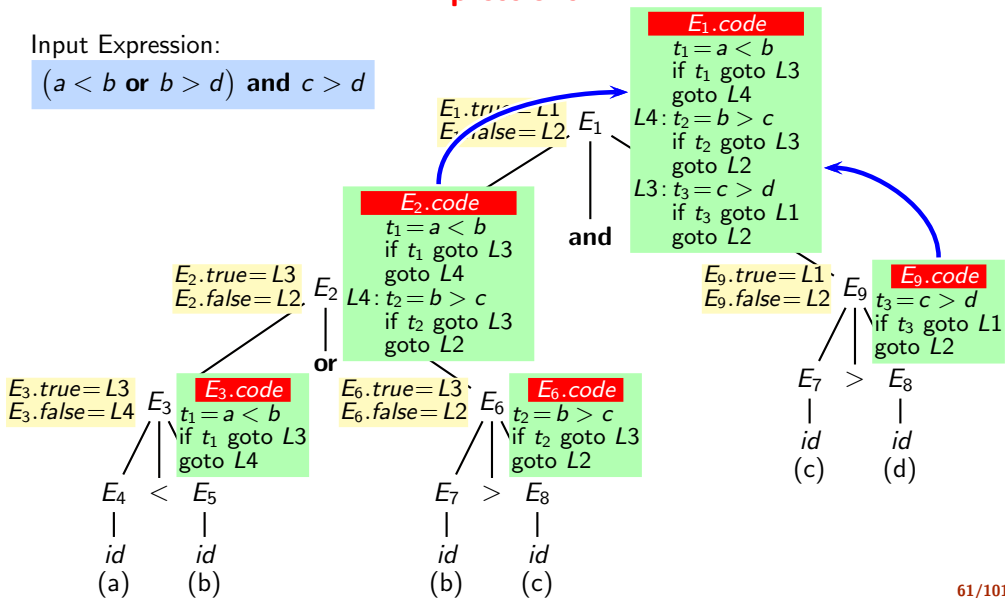




Attribute Evaluation for Control Flow Translation of Boolean Expressions

Input Expression:

$(a < b \text{ or } b > d) \text{ and } c > d$





Computing Inherited Attributes Concurrently with Parsing

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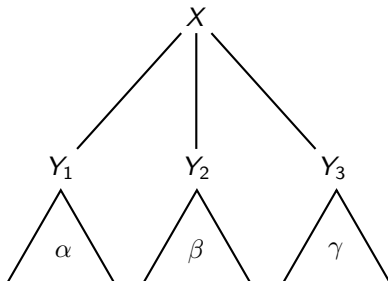
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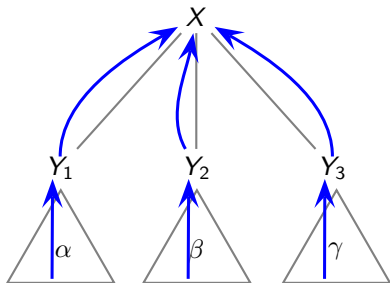
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Computing Inherited Attributes Concurrently with Parsing

- Synthesized attributes can be easily computed during bottom-up parsing



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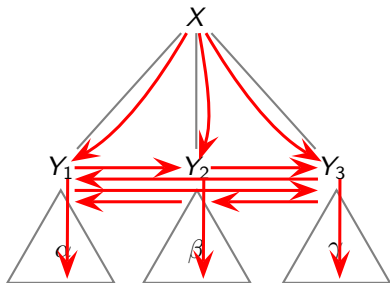
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Computing Inherited Attributes Concurrently with Parsing

- Synthesized attributes can be easily computed during bottom-up parsing
- Inherited attributes cannot be computed if they depend on a symbol not yet seen



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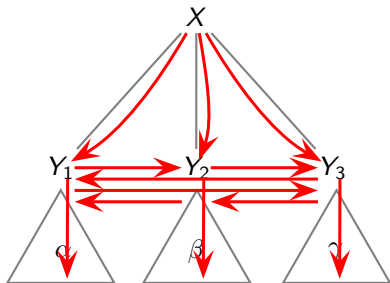
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Computing Inherited Attributes Concurrently with Parsing



- Synthesized attributes can be easily computed during bottom-up parsing
 - Inherited attributes cannot be computed if they depend on a symbol not yet seen
 - We can restrict the inherited attributes to depend only on the attributes of grammar symbols that have been seen
- Given a production $X \rightarrow Y_1 Y_2 \dots Y_k$



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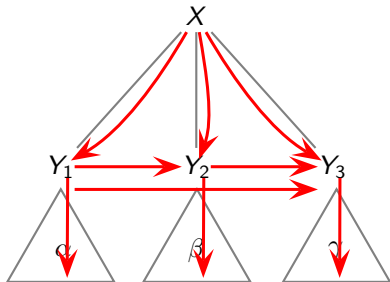
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Given a production $X \rightarrow Y_1 Y_2 \dots Y_k$

- $Y_i.a$, is computed only from the attributes of X or Y_j , $j < i$



Computing Inherited Attributes Concurrently with Parsing

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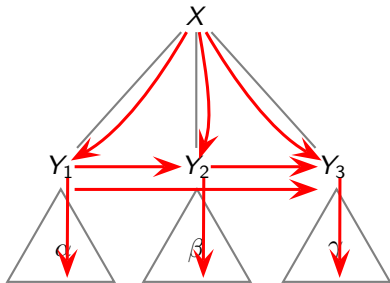
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- Synthesized attributes can be easily computed during bottom-up parsing
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Given a production $X \rightarrow Y_1 Y_2 \dots Y_k$

- $Y_i.a$, is computed only from the attributes of X or Y_j , $j < i$
- $X.a$ would have been computed from the grammar symbols that have already been seen (i.e., in some production $Z \rightarrow \alpha X \beta$)



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S-Attributed and L-Attributed SDDs

- An SDD is *S-attributed* if it uses only synthesized attributes
- An SDD is *L-attributed* if it uses synthesized attributes or inherited attributes that depend on some symbol to the left
 - Given a production $X \rightarrow Y_1 Y_2 \dots Y_k$ attribute $Y_i.a$, of some Y_i is computed only from the attributes of X or $Y_j, j < i$
 - Symbols X and $Y_j, j < i$ appear to the left of Y_i in the production



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S-Attributed and L-Attributed SDDs

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 - Given a production $X \rightarrow Y_1 Y_2 \dots Y_k$ attribute $Y_i.a$, of some Y_i is computed only from the attributes of X or $Y_j, j < i$
 - Symbols X and $Y_j, j < i$ appear to the left of Y_i in the production
- All SDDs in the previous section are S-attributed whereas the declaration processing SDD is L-attributed

$Decl \rightarrow Type \ VarList$	$VarList.type = Type.name$
$Type \rightarrow int$	$Type.name = int$
$Type \rightarrow float$	$Type.name = float$
$VarList_1 \rightarrow VarList_2, id$	$VarList_2.type = VarList_1.type$ $id.type = VarList_1.type$
$VarList \rightarrow id$	$id.type = VarList.type$

Syntax Directed Translation Schemes (SDTS)



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- A Syntax Directed Translation Scheme is an SDD with the following two changes
 - Semantic rules are replaced by actions possibly with side effects
We include the actions in a pair of braces (i.e., within “{” and “}”)
 - The exact time of the action is specified; an action computing an inherited attribute of a non-terminal appears just before the non-terminal
- The SDTS for declaration processing is as follows

$$Decl \rightarrow Type \{ VarList.type = Type.name \} VarList$$
$$Type \rightarrow int \{ Type.name = int \}$$
$$Type \rightarrow float \{ Type.name = float \}$$
$$VarList_1 \rightarrow \{ VarList_2.type = VarList_1.type \} VarList_2 ,$$
$$id \{ id.type = VarList_1.type \}$$
$$VarList \rightarrow id \{ id.type = VarList.type \}$$



S-Attributed and L-Attributed SDTSs

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- An S-Attributed SDTS uses only synthesized attributes and all actions appear at the end of the RHS of a production
- An L-Attributed SDTS uses synthesized attributes or attributes that depend on a symbol towards the left of the grammar symbols of the attributes
The actions may appear in the middle of the rules or at the end of the RHS of a production
- The SDTS for declaration processing is L-attributed



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How and when are the actions in the middle of a rule executed?

- A production with an action in the middle is transformed into two productions

$X \rightarrow Y_1 \{ \text{action} \} Y_2$



$X \rightarrow Y_1 M Y_2$
 $M \rightarrow \epsilon \{ \text{action} \}$

where M is a marker non-terminal for Y_2

- The action is executed after reduction by $M \rightarrow \epsilon$

It is convenient to execute actions consistently after a reduction

- A distinct marker non-terminal is introduced for every such action

We have as many additional ϵ -productions as the number of such actions



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Representing the Actions in the Middle by Marker Non-Terminals

$$Decl \rightarrow Type \{ VarList.type = Type.name \} VarList$$
$$Type \rightarrow int \{ Type.name = int \}$$
$$Type \rightarrow float \{ Type.name = float \}$$
$$VarList_1 \rightarrow \{ VarList_2.type = VarList_1.type \} VarList_2 ,$$
$$id \{ id.type = VarList_1.type \}$$
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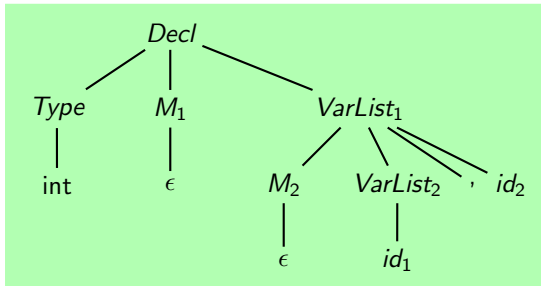
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$$id \{ id.type = VarList_1.type \}$$
$$VarList \rightarrow id \{ id.type = VarList.type \}$$


Attribute Evaluation



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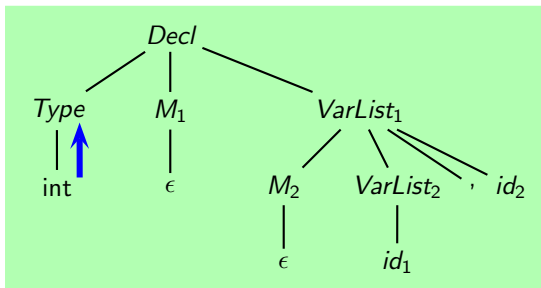
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Representing the Actions in the Middle by Marker Non-Terminals

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$$id \{ id.type = VarList_1.type \}$$
$$VarList \rightarrow id \{ id.type = VarList.type \}$$


Attribute Evaluation

$Type.name = int$



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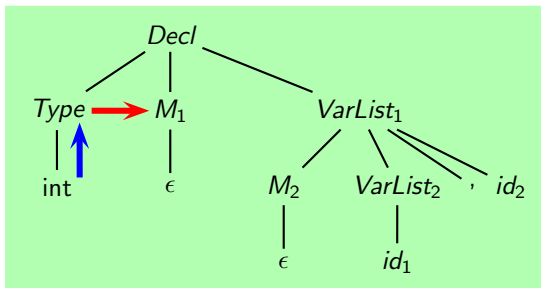
$$Decl \rightarrow Type \{ VarList.type = Type.name \} VarList$$

$$Type \rightarrow int \{ Type.name = int \}$$

$$Type \rightarrow float \{ Type.name = float \}$$

$$VarList_1 \rightarrow \{ VarList_2.type = VarList_1.type \} VarList_2 ,$$

$$id \{ id.type = VarList_1.type \}$$

$$VarList \rightarrow id \{ id.type = VarList.type \}$$


Attribute Evaluation

$Type.name = int$

$VarList_1.type = int$



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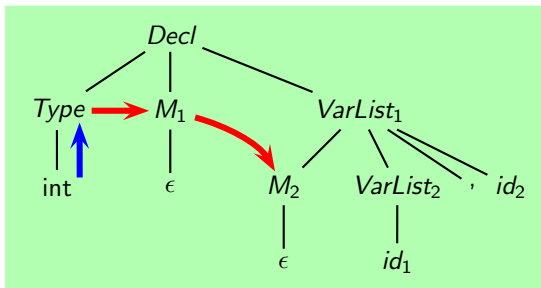
$$Decl \rightarrow Type \{ VarList.type = Type.name \} VarList$$

$$Type \rightarrow int \{ Type.name = int \}$$

$$Type \rightarrow float \{ Type.name = float \}$$

$$VarList_1 \rightarrow \{ VarList_2.type = VarList_1.type \} VarList_2 ,$$

$$id \{ id.type = VarList_1.type \}$$

$$VarList \rightarrow id \{ id.type = VarList.type \}$$


Attribute Evaluation

$$Type.name = int$$

$$VarList_1.type = int$$

$$VarList_2.type = int$$



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Representing the Actions in the Middle by Marker Non-Terminals

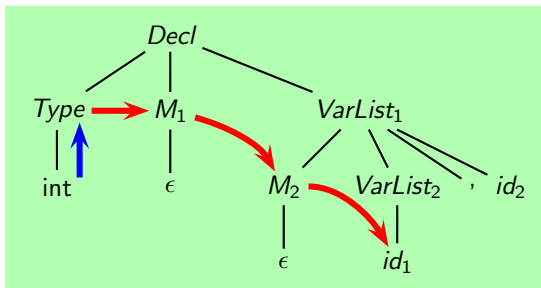
$$Decl \rightarrow Type \{ VarList.type = Type.name \} VarList$$

$$Type \rightarrow int \{ Type.name = int \}$$

$$Type \rightarrow float \{ Type.name = float \}$$

$$VarList_1 \rightarrow \{ VarList_2.type = VarList_1.type \} VarList_2 ,$$

$$id \{ id.type = VarList_1.type \}$$

$$VarList \rightarrow id \{ id.type = VarList.type \}$$


Attribute Evaluation

$$Type.name = int$$

$$VarList_1.type = int$$

$$VarList_2.type = int$$

$$id_1.type = int$$



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Representing the Actions in the Middle by Marker Non-Terminals

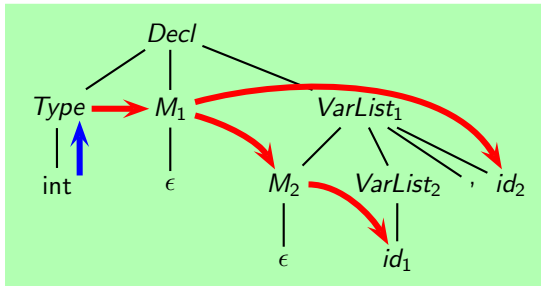
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$$VarList_1 \rightarrow \{ VarList_2.type = VarList_1.type \} VarList_2 ,$$

$$id \{ id.type = VarList_1.type \}$$

$$VarList \rightarrow id \{ id.type = VarList.type \}$$


Attribute Evaluation

$$Type.name = int$$

$$VarList_1.type = int$$

$$VarList_2.type = int$$

$$id_1.type = int$$

$$id_2.type = int$$



The Role of Marker Non-Terminals

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- Marker non-terminals facilitate a corresponding slot on the value stack where the inherited attribute of the next grammar symbol can be stored
- Marker non-terminals may introduce reduce-reduce conflicts because of the ϵ rules



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Marker Non-Terminals Facilitate Recording Inherited Attributes

M is a marker non-terminal for Y_2 in the grammar on the right
 $Y_1.s$ and $Y_2.s$ denote the synthesized attributes of Y_1 and Y_2
whereas $Y_2.i$ denotes the inherited attribute of Y_2

$$\begin{aligned} X &\rightarrow Y_1 M Y_2 \\ M &\rightarrow \epsilon \{ \dots \} \\ Y_2 &\rightarrow \alpha \{ \dots \} \end{aligned}$$



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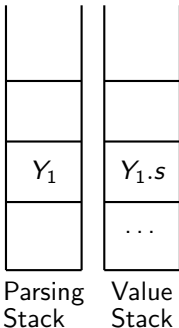
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$$\begin{aligned} X &\rightarrow Y_1 M Y_2 \\ M &\rightarrow \epsilon \{ \dots \} \\ Y_2 &\rightarrow \alpha \{ \dots \} \end{aligned}$$

Before reducing
by $M \rightarrow \epsilon \{ \dots \}$





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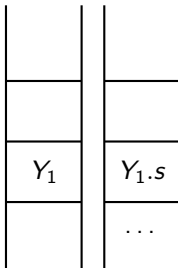
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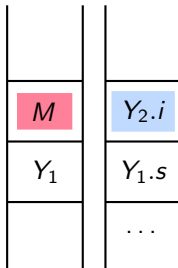
Before reducing
by $M \rightarrow \epsilon \{ \dots \}$



Parsing
Stack

Value
Stack

After reducing
by $M \rightarrow \epsilon \{ \dots \}$



Parsing
Stack

Value
Stack

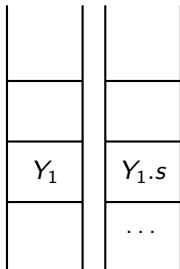


Marker Non-Terminals Facilitate Recording Inherited Attributes

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 $Y_1.s$ and $Y_2.s$ denote the synthesized attributes of Y_1 and Y_2
 whereas $Y_2.i$ denotes the inherited attribute of Y_2

$X \rightarrow Y_1 M Y_2$
 $M \rightarrow \epsilon \{ \dots \}$
 $Y_2 \rightarrow \alpha \{ \dots \}$

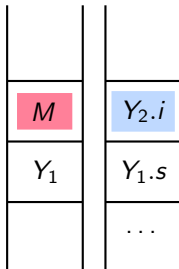
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by $M \rightarrow \epsilon \{ \dots \}$



Parsing
Stack

Value
Stack

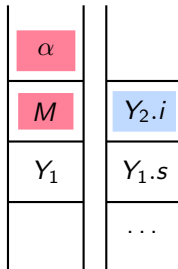
After reducing
by $M \rightarrow \epsilon \{ \dots \}$



Parsing
Stack

Value
Stack

After pushing
handle α



Parsing
Stack

Value
Stack

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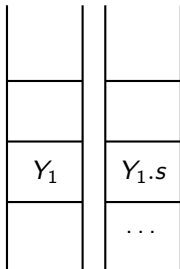


Marker Non-Terminals Facilitate Recording Inherited Attributes

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$X \rightarrow Y_1 M Y_2$
 $M \rightarrow \epsilon \{ \dots \}$
 $Y_2 \rightarrow \alpha \{ \dots \}$

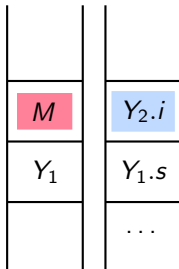
Before reducing
by $M \rightarrow \epsilon \{ \dots \}$



Parsing Stack

Value Stack

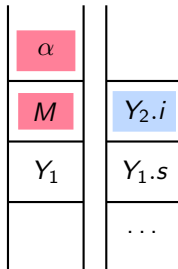
After reducing
by $M \rightarrow \epsilon \{ \dots \}$



Parsing Stack

Value Stack

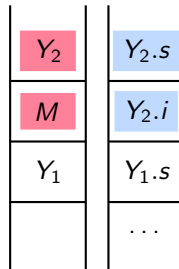
After pushing
handle α



Parsing Stack

Value Stack

After reducing
by $Y_2 \rightarrow \alpha \{ \dots \}$



Parsing Stack

Value Stack



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Marker Non-Terminals May Cause Reduce-Reduce Conflicts

Consider the grammar of declaration consisting of non-terminals D (Declaration), T (Type), L (List of identifiers), terminals int , $“,”$ and id , and marker non-terminals M_1 , M_2 , and M_3

$$\begin{aligned} D &\rightarrow T M_1 L \\ T &\rightarrow \text{int} \\ L &\rightarrow M_2 L, \text{id} \\ L &\rightarrow M_3 \text{id} \\ M_1 &\rightarrow \epsilon \\ M_2 &\rightarrow \epsilon \\ M_3 &\rightarrow \epsilon \end{aligned}$$



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$$I_0$$

$D' \rightarrow \bullet D$
$D \rightarrow \bullet T M_1 L$
$T \rightarrow \bullet \text{int}$

$$\begin{aligned} D &\rightarrow T M_1 L \\ T &\rightarrow \text{int} \\ L &\rightarrow M_2 L, \text{id} \\ L &\rightarrow M_3 \text{id} \\ M_1 &\rightarrow \epsilon \\ M_2 &\rightarrow \epsilon \\ M_3 &\rightarrow \epsilon \end{aligned}$$



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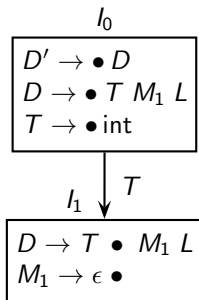
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Marker Non-Terminals May Cause Reduce-Reduce Conflicts

Consider the grammar of declaration consisting of non-terminals D (Declaration), T (Type), L (List of identifiers), terminals `int`, `,` and `id`, and marker non-terminals M_1 , M_2 , and M_3

$$\begin{aligned} D &\rightarrow T M_1 L \\ T &\rightarrow \text{int} \\ L &\rightarrow M_2 L, id \\ L &\rightarrow M_3 id \\ M_1 &\rightarrow \epsilon \\ M_2 &\rightarrow \epsilon \\ M_3 &\rightarrow \epsilon \end{aligned}$$




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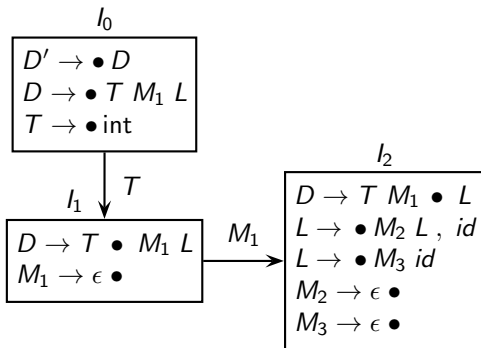
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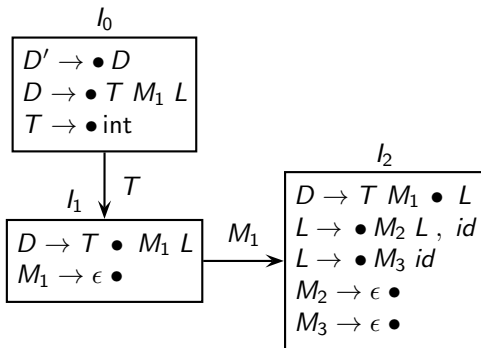
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Marker Non-Terminals May Cause Reduce-Reduce Conflicts

Consider the grammar of declaration consisting of non-terminals D (Declaration), T (Type), L (List of identifiers), terminals `int`, `,` and `id`, and marker non-terminals M_1 , M_2 , and M_3

$$\begin{aligned} D &\rightarrow T M_1 L \\ T &\rightarrow \text{int} \\ L &\rightarrow M_2 L, id \\ L &\rightarrow M_3 id \\ M_1 &\rightarrow \epsilon \\ M_2 &\rightarrow \epsilon \\ M_3 &\rightarrow \epsilon \end{aligned}$$


We have reduce-reduce conflict in I_2 because `id` is in the FOLLOW of M_2 and M_3 . We can avoid it by rewriting the grammar (see the last slide in this pdf)



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SDTS for FOR Loop with BREAK and CONTINUE Statements

$S_1 \rightarrow \text{for } (E_1; E_2; E_3)$

```
{  $S_2.increment = getNewLabel()$  /* needed here because it is inherited */  
   $S_2.loopback = getNewLabel()$  /* can be moved to the end of the rule */  
   $S_2.exit = getNewLabel()$  /* needed here because it is inherited */  
}
```

S_2

```
{  $t_1 = getNewTemp()$   
   $c_1 = gen(S_2.loopback, :)$   
   $c_2 = gen(t_1, \neq, E_2.place) \parallel gen(\text{if}, t_1, \text{goto}, S_2.exit)$   
   $c_3 = gen(\text{goto}, S_2.increment)$   
   $c_4 = gen(S_2.exit, :)$   
   $S_1.code = E_1.code \parallel c_1 \parallel E_2.code \parallel c_2 \parallel S_2.code \parallel c_3 \parallel E_3.code \parallel c_4$   
}
```

$S \rightarrow \text{break } \{S.code = gen(\text{goto}, S.exit)\}$

$S \rightarrow \text{continue } \{S.code = gen(\text{goto}, S.increment)\}$



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Type Analysis

- Type Expressions
- Type Equivalence
- Type Checking and Type Inferencing



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The Role of Types

1. Types provide information about

- the size of data and the interpretation of raw bits, and (the integer value of string of four bytes `1111` is $4096+256+16+1 = 4369$)
- the operations allowed on data

2. The type of a variable may be allowed to change during the lifetime of the data

- Python, AWK allow the same variables to have different types at different program points
- C/C++ do not allow this; instead they allow implicit *type promotion* and explicit type conversion (aka *type casting*)

3. Types may be known at compile time or only at run time

Most literature conflates (2) and (3) above and use the term *dynamically checked languages* for such languages

Property (2) should be called *flow-sensitive* or *flow-insensitive* types and the terms *static* or *dynamic checking* should be reserved for property (3)



Type System

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- A *type system* is a set of rules that assign a unique type to each data item
 - The assigned type may include a *type error*
 - A type system accepts a program if it succeeds in assigning valid non-error types to all data items
- A *sound* type system guarantees that a program accepted by the type system would not have any unchecked type error at run time
 - A sound type system is not required check the types at compile time; the types may well be checked at run time
 - A type system that rejects all programs is vacuously sound



Type Expressions

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A type expression describes types of all entities (variables, functions) in a program

- A basic type such as int, float, void, bool, char is a type expression
- A user defined type name is a type expression
- A type constructor applied to a type expression τ is also a type expression

These type expressions represent derived types



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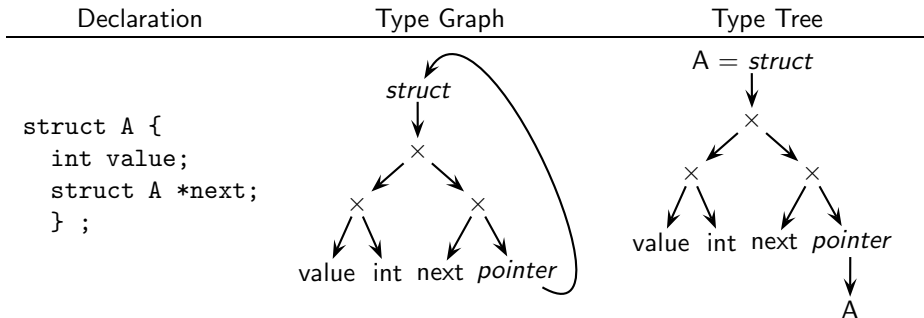
Type Expressions for Derived Types

- $array(k, \tau)$ describes an array of k elements of type τ
 - The size of an array is not a part of the type in C for validation; it is needed for memory allocation
- $pointer(\tau)$ describes a pointer to an element of type τ
- $struct((f_1, \tau_1), (f_2, \tau_2), \dots, (f_k, \tau_k))$ describes a structure containing k fields named f_1 to f_k with types τ_1 to τ_k
 - f_1 to f_k must be distinct but τ_1 to τ_k need not be distinct
- $\tau_1 \rightarrow \tau_2$ describes a function that takes arguments described by τ_1 and returns result described by τ_2 .
- Given τ_1 and τ_2 , $\tau_1 \times \tau_2$ describes the product of the two types
 - Product can be used to represent a list or tuples of type expressions
 - Product is left associative and has a higher precedence than \rightarrow



Representing Type Expression

- A type expression can be represented as a graph
- In general, it may contain cycles but we convert it into a tree by naming the target of the back edge and using the name as a node



- The resulting type expression is written with A as the name of the type expression as $A = struct((value, int), (next, pointer(A)))$



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Type Equivalence

- Consider the following declarations

<pre>struct Person { string name; float weight; };</pre>	<pre>struct Laptop { string name; float weight; };</pre>	<pre>struct Car { string name; float weight; };</pre>
--	--	---

<pre>int A[5][50];</pre>	<pre>int B[10][20];</pre>	<pre>int C[100][200];</pre>
--------------------------	---------------------------	-----------------------------

- Are variables of the type `struct Person`, `struct Laptop`, and `struct Car` compatible with each other?
(i.e., can the value of one be assigned to the other?)
- Are elements of arrays `A`, `B`, and `C` compatible with each other?
(i.e., can the value of one be assigned to the other?)



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Name and Structural Equivalence of Types

- Name Equivalence
 - Same basic types are name equivalent
 - Derived type are name equivalent if they have the same name
 - Every occurrence of a derived type in declarations is given a unique name
- Structural Equivalence
 - Same basic types are structurally equivalent
 - Derived type are structurally equivalent if
 - they are obtained by applying the same type constructors to structurally equivalent types, or
 - one is type name that denotes the other type expressions
- Name equivalence implies structural equivalence but not vice-versa
- C uses structural equivalence for everything except structures
For structures, it uses name equivalence



Examples of Type Equivalence

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- Consider the following declarations

<pre>struct Person { string name; float weight; } p1, p2;</pre>	<pre>struct Laptop { string name; float weight; } l1, l2;</pre>	<pre>struct Car { string name; float weight; } c1, c2;</pre>
---	---	--

- Partition of variables
 - under name equivalence: $\{\{p1, p2\}, \{l1, l2\}, \{c1, c2\}\}$
 - under structural equivalence: $\{\{p1, p2, l1, l2, c1, c2\}\}$



SDD for Type Checking

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$E \rightarrow \text{char_const}$	$\{E.type = \text{char}\}$
$E \rightarrow \text{num}$	$\{E.type = \text{int}\}$
$E \rightarrow \text{id}$	$\{E.type = \text{id.type}\}$
$E_1 \rightarrow E_2 \text{ mod } E_3$	$\{ \text{ if } ((E_2.type \equiv \text{int}) \ \&\& \ (E_3.type \equiv \text{int})) \ E_1.type = \text{int}$ $\text{ else } E_1.type = \text{type_error} \}$
$E_1 \rightarrow E_2 \text{ op } E_3$	$\{ \ E_1.type = \text{type_error}$ $\text{ if } (E_2.type \equiv E_3.type)$ $\{ \ \text{vall} = (E_2.type \equiv \text{int}); \ \text{valF} = (E_2.type \equiv \text{float})$ $\text{ valB} = (E_2.type \equiv \text{bool}); \ \text{opA} = (\text{op.type} \equiv \text{arith})$ $\text{ opB} = (\text{op.type} \equiv \text{bool}); \ \text{opR} = (\text{op.type} \equiv \text{rel})$ $\text{ if } (\text{opR} \ \&\& \ (\text{vall} \ \ \text{valF})) \ E_1.type = \text{bool}$ $\text{ if } ((\text{opA} \ \&\& \ (\text{vall} \ \ \text{valF})) \ \ (\text{opB} \ \&\& \ \text{valB}))$ $\quad E_1.type = E_2.type \}$
$E_1 \rightarrow E_2[E_3]$	$\{ \text{ if } ((E_2.type \equiv \text{array}(n, t)) \ \&\& \ (E_3.type \equiv \text{int})) \ E_1.type = t$ $\text{ else } E_1.type = \text{type_error} \}$
$E_1 \rightarrow *E_2$	$\{ \text{ if } (E_2.type \equiv \text{pointer}(t)) \ E_1.type = t$ $\text{ else } E_1.type = \text{type_error} \}$



Type Inferencing

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- Functional languages do not require separate declarations for variables and types
- Usually, functions are annotated with type information and most other types are inferred from these annotations, the constants, and the operators
- The type expressions in such languages also contain type variables whose values are type expressions
- The values of type variables is inferred by unifying type expressions that are expected to represent the same type



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Scope Analysis: Key Ideas

- Maintain a stack of symbol tables
- At the start of a new scope, push a new symbol table on the stack
 - Beginning of the program ("global" scope)
 - Beginning of every procedure
 - The procedure name belongs to the outer scope
 - Beginning of every compound statement
- At the end of every scope, pop the top symbol table from the stack
(Store it in a persistent data structure)
- For use of a name, look it up in the symbol table starting from the stack top
 - If the name is not found in a symbol table, search in the symbol table below
 - If the same name appears in two symbol tables, the one closer to the top hides the one below
 - The symbol table below closer to the top represents the more closely nested procedure and shadows the names in the outer procedures



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Access to Non-local Variables

```
int main()  
{
```

```
    // body of main  
}
```

Nested function in C supported by GCC extension

(Originally supported in Pascal but not supported by
C standards)



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Access to Non-local Variables

```
int main()
{ void S()
  { int a, x;
    void R()
    { int i;

      // body of R }

    // body of S
  }
  // body of main
}
```

Nested function in C supported by GCC extension

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Access to Non-local Variables

```
int main()
{ void S()
  { int a, x;
    void R()
    { int i;
      int T()
      { int m,n;
        // body of T
      }
      // body of R }
    // body of S
  }
  // body of main
}
```

Nested function in C supported by GCC extension

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Access to Non-local Variables

```
int main()
{
    void S()
    {
        int a, x;

        void R()
        {
            int i;

            int T()
            {
                int m,n;
                // body of T
            }

            // body of R }

        void E()
        { // body of E }

        // body of S
    }

    // body of main
}
```

Nested function in C supported by GCC extension

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Access to Non-local Variables

```
int main()
{ void S()
  { int a, x;
    void R()
    { int i;
      int T()
      { int m,n;
        // body of T
      }
      // body of R }
    void E()
    { // body of E }
    void Q()
    { int a, x;

      // body of Q }
    // body of S
  }
  // body of main
}
```

Nested function in C supported by GCC extension

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```
int main()
{ void S()
  { int a, x;
    void R()
    { int i;
      int T()
      { int m,n;
        // body of T
      }
      // body of R }
    void E()
    { // body of E }
    void Q()
    { int a, x;
      int P(int y, int z)
      { int i,j;
        // body of P
      }
      // body of Q }
    // body of S
  }
  // body of main
}
```

Nested function in C supported by GCC extension

(Originally supported in Pascal but not supported by C standards)



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Access to Non-local Variables: Static Scope

```
int main()
{ void S()
  { int a, x;
    void R()
    { int i;
      int T()
      { int m,n;
        // body of T
      }
      // body of R }
    void E()
    { // body of E }
    void Q()
    { int a, x;
      int P(int y, int z)
      { int i,j;
        // body of P
      }
      // body of Q }
    // body of S
  }
  // body of main
}
```

- Under *static scoping*, the names visible at line i in procedure X are:
 - names declared locally within X before line i
 - names declared in procedures enclosing X
upto the declaration of X in the program
- A name declared in more closely nested procedure overrides the same name declared in an outer procedure.



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Access to Non-local Variables: Static Scope

```
int main()
{ void S()
  { int a, x;
    void R()
    { int i;
      int T()
      { int m,n;
        // body of T
      }
      // body of R }
    void E()
    { // body of E }
    void Q()
    { int a, x;
      int P(int y, int z)
      { int i,j;
        // body of P
      }
      // body of Q }
    // body of S
  }
  // body of main
}
```

- Under *static scoping*, the names visible at line i in procedure X are:
 - names declared locally within X before line i
 - names declared in procedures enclosing X
upto the declaration of X in the program
- A name declared in more closely nested procedure overrides the same name declared in an outer procedure.
- The names visible in the body of T are:
 - T, R, S, main (enclosing procedure names)
 - $T:m, T:n, R:i, S:a$, and $S:x$ (names declared immediately within T, R and S)
 - E and Q are declared within S but are *not* visible in T (but they are visible in P)
 - For call chain $\text{main} \rightarrow S \rightarrow Q \rightarrow E \rightarrow R \rightarrow T$, variables $S:a$ and $S:x$ are accessed in T and not $Q:a$ and $Q:x$



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Access to Non-local Variables: Dynamic Scope

```
int main()
{
  void S()
  {
    int a, x;

    void R()
    {
      int i;

      int T()
      {
        int m,n;
        // body of T
      }

      // body of R }

    void E()
    { // body of E }

    void Q()
    {
      int a, x;

      int P(int y, int z)
      {
        int i,j;
        // body of P
      }

      // body of Q }

    // body of S
  }

  // body of main
}
```

- Under *dynamic scoping*, the names visible at line *i* in procedure *X* are:
 - names declared locally within *X* before line *i*
 - names declared in procedures enclosing *X* in a call chain reaching *X*
- A name declared in more closely nested procedure in the call chain overrides the same name declared in an outer procedure.



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Access to Non-local Variables: Dynamic Scope

```
int main()
{ void S()
  { int a, x;
    void R()
    { int i;
      int T()
      { int m,n;
        // body of T
      }
      // body of R }
    void E()
    { // body of E }
    void Q()
    { int a, x;
      int P(int y, int z)
      { int i,j;
        // body of P
      }
      // body of Q }
    // body of S
  }
  // body of main
}
```

- Under *dynamic scoping*, the names visible at line *i* in procedure *X* are:
 - names declared locally within *X* before line *i*
 - names declared in procedures enclosing *X* in a call chain reaching *X*
- A name declared in more closely nested procedure in **the call chain** overrides the same name declared in an outer procedure.
- For a call chain $\text{main} \rightarrow \text{S} \rightarrow \text{Q} \rightarrow \text{E} \rightarrow \text{R} \rightarrow \text{T}$ the names visible in the body of *T* are:
 - The names in *T*, *R*, *E*, *Q*, *S* and *main*
 - Variables *S*:*a* and *S*:*x* are shadowed by *Q*:*a* and *Q*:*x* in *T*

Scope Analysis Demo for Static Scope



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Scope Analysis: Grammar

Program \rightarrow DL SL

DL \rightarrow DL D $\mid \epsilon$

D \rightarrow T *id*

D \rightarrow T *id* (PL) { DL SL }

T \rightarrow int \mid void

PL \rightarrow PL , P \mid P

P \rightarrow T *id*

SL \rightarrow SL Call $\mid \epsilon$

Call \rightarrow *id* (AL) ;

AL \rightarrow AL , *id* \mid *id*

We consider a simplified grammar in which

- DL denotes a list of declarations

- D denotes a declaration

For simplicity, we assume that a single name can be declared in a declaration

- T denotes a type declaration

- PL denotes a list of formal parameters

- P denotes a formal parameter

- SL denotes a list of statement

For simplicity, we consider only a call statement

- AL denotes a list of actual parameters



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Scope Analysis: SDTS

Program \rightarrow

DL SL

$DL \rightarrow DL D \mid \epsilon$

$D \rightarrow T id$

$D \rightarrow T id$

$(PL) \{ DL SL \}$

$T \rightarrow int$

$\mid void$

$PL \rightarrow PL , P \mid P$

$P \rightarrow T id$

$SL \rightarrow SL Call \mid \epsilon$

$Call \rightarrow id$

$(AL) ;$

$AL \rightarrow AL , id$

$\mid id$



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Scope Analysis: SDTS

Program $\rightarrow \{ \text{push_new_symtab}(); \}$ DL SL

$DL \rightarrow DL D \mid \epsilon$

$D \rightarrow T \text{ id}$

$D \rightarrow T \text{ id}$

$(PL) \{ DL SL \}$

$T \rightarrow \text{int} \mid \text{void}$

$PL \rightarrow PL , P \mid P$

$P \rightarrow T \text{ id}$

$SL \rightarrow SL \text{ Call} \mid \epsilon$

$\text{Call} \rightarrow \text{id} \mid (AL) ;$

$AL \rightarrow AL , \text{id} \mid \text{id}$



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Scope Analysis: SDTS

Program $\rightarrow \{ \text{push_new_symtab}(); \} \text{ DL SL}$

$\text{DL} \rightarrow \text{DL D} \mid \epsilon$

$\text{D} \rightarrow \text{T id} \{ \text{add_var_to_symtab}(\text{id.name}, \text{T.name}) \}$

$\text{D} \rightarrow \text{T id}$

$(\text{PL}) \{ \text{DL SL} \}$

$\text{T} \rightarrow \text{int} \{ \text{T.name} = \text{int}; \} \mid \text{void} \{ \text{T.name} = \text{void}; \}$

$\text{PL} \rightarrow \text{PL} , \text{P} \mid \text{P}$

$\text{P} \rightarrow \text{T id}$

$\text{SL} \rightarrow \text{SL Call} \mid \epsilon$

$\text{Call} \rightarrow \text{id} \quad (\text{AL}) ;$

$\text{AL} \rightarrow \text{AL} , \text{id} \quad \mid \text{id}$



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Scope Analysis: SDTS

Program $\rightarrow \{ \text{push_new_syntab}(); \} \text{ DL SL}$

$\text{DL} \rightarrow \text{DL D} \mid \epsilon$

$\text{D} \rightarrow \text{T id} \{ \text{add_var_to_syntab}(\text{id.name}, \text{T.name}) \}$

$\text{D} \rightarrow \text{T id} \{ \text{add_proc_to_syntab}(\text{id.name}, \text{T.name}); \}$

$(\text{PL}) \{ \text{DL SL} \}$

$\text{T} \rightarrow \text{int} \{ \text{T.name} = \text{int}; \} \mid \text{void} \{ \text{T.name} = \text{void}; \}$

$\text{PL} \rightarrow \text{PL} , \text{P} \mid \text{P}$

$\text{P} \rightarrow \text{T id}$

$\text{SL} \rightarrow \text{SL Call} \mid \epsilon$

$\text{Call} \rightarrow \text{id} \quad (\text{AL}) ;$

$\text{AL} \rightarrow \text{AL} , \text{id} \quad \mid \text{id}$



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Scope Analysis: SDTS

Program $\rightarrow \{ \text{push_new_syntab}(); \}$ DL SL

DL $\rightarrow \text{DL D} \mid \epsilon$

D $\rightarrow \text{T id} \{ \text{add_var_to_syntab}(\text{id.name}, \text{T.name}) \}$

D $\rightarrow \text{T id} \{ \text{add_proc_to_syntab}(\text{id.name}, \text{T.name}); \}$

$\{ \text{push_new_syntab}(); \}$ (PL) { DL SL }

T $\rightarrow \text{int} \{ \text{T.name} = \text{int}; \} \mid \text{void} \{ \text{T.name} = \text{void}; \}$

PL $\rightarrow \text{PL} , \text{P} \mid \text{P}$

P $\rightarrow \text{T id}$

SL $\rightarrow \text{SL Call} \mid \epsilon$

Call $\rightarrow \text{id} \quad (\text{AL}) ;$

AL $\rightarrow \text{AL} , \text{id} \quad \mid \text{id}$



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Scope Analysis: SDTS

Program \rightarrow { push_new_symtab(); } DL SL

DL \rightarrow DL D | ϵ

D \rightarrow T id { add_var_to_symtab(id.name, T.name) }

D \rightarrow T id { add_proc_to_symtab(id.name, T.name); }

{ push_new_symtab(); } (PL) { DL SL }

{ pop_symtab(); }

T \rightarrow int { T.name = int; } | void { T.name = void; }

PL \rightarrow PL , P | P

P \rightarrow T id

SL \rightarrow SL Call | ϵ

Call \rightarrow id (AL) ;

AL \rightarrow AL , id | id

Pop and move it to
a persistent storage
for later phases



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Scope Analysis: SDTS

Program $\rightarrow \{ \text{push_new_symtab}(); \} \text{ DL SL}$

$\text{DL} \rightarrow \text{DL D} \mid \epsilon$

$\text{D} \rightarrow \text{T id} \{ \text{add_var_to_symtab}(\text{id.name}, \text{T.name}) \}$

$\text{D} \rightarrow \text{T id} \{ \text{add_proc_to_symtab}(\text{id.name}, \text{T.name}); \}$

$\{ \text{push_new_symtab}(); \} \text{ (PL) } \{ \text{DL SL} \}$

$\{ \text{pop_symtab}(); \}$

$\text{T} \rightarrow \text{int} \{ \text{T.name} = \text{int}; \} \mid \text{void} \{ \text{T.name} = \text{void}; \}$

$\text{PL} \rightarrow \text{PL} , \text{ P} \mid \text{P}$

$\text{P} \rightarrow \text{T id} \{ \text{add_param_to_symtab}(\text{id.name}, \text{T.name}); \}$

$\text{SL} \rightarrow \text{SL Call} \mid \epsilon$

$\text{Call} \rightarrow \text{id} \quad \quad \quad \text{(AL) ;}$

$\text{AL} \rightarrow \text{AL} , \text{id} \quad \quad \quad \mid \text{id}$



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Program $\rightarrow \{ \text{push_new_symtab}(); \} \text{ DL SL}$

$\text{DL} \rightarrow \text{DL D} \mid \epsilon$

$\text{D} \rightarrow \text{T id} \{ \text{add_var_to_symtab}(id.name, T.name) \}$

$\text{D} \rightarrow \text{T id} \{ \text{add_proc_to_symtab}(id.name, T.name); \}$

$\{ \text{push_new_symtab}(); \} \text{ (PL) } \{ \text{DL SL} \}$

$\{ \text{pop_symtab}(); \}$

$\text{T} \rightarrow \text{int} \{ \text{T.name} = \text{int}; \} \mid \text{void} \{ \text{T.name} = \text{void}; \}$

$\text{PL} \rightarrow \text{PL} , \text{ P} \mid \text{P}$

$\text{P} \rightarrow \text{T id} \{ \text{add_param_to_symtab}(id.name, T.name); \}$

$\text{SL} \rightarrow \text{SL Call} \mid \epsilon$

$\text{Call} \rightarrow \text{id} \{ \text{lookup}(id.name); \} \text{ (AL) ;}$

$\text{AL} \rightarrow \text{AL} , \text{id} \mid \text{id}$



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Program $\rightarrow \{ \text{push_new_symtab}(); \} \text{ DL SL}$

$\text{DL} \rightarrow \text{DL D} \mid \epsilon$

$\text{D} \rightarrow \text{T id} \{ \text{add_var_to_symtab}(\text{id.name}, \text{T.name}) \}$

$\text{D} \rightarrow \text{T id} \{ \text{add_proc_to_symtab}(\text{id.name}, \text{T.name}); \}$

$\{ \text{push_new_symtab}(); \} \text{ (PL) } \{ \text{DL SL} \}$

$\{ \text{pop_symtab}(); \}$

$\text{T} \rightarrow \text{int} \{ \text{T.name} = \text{int}; \} \mid \text{void} \{ \text{T.name} = \text{void}; \}$

$\text{PL} \rightarrow \text{PL} , \text{ P} \mid \text{P}$

$\text{P} \rightarrow \text{T id} \{ \text{add_param_to_symtab}(\text{id.name}, \text{T.name}); \}$

$\text{SL} \rightarrow \text{SL Call} \mid \epsilon$

$\text{Call} \rightarrow \text{id} \{ \text{lookup}(\text{id.name}); \} \text{ (AL) ;}$

$\text{AL} \rightarrow \text{AL} , \text{id} \{ \text{lookup}(\text{id.name}); \} \mid \text{id} \{ \text{lookup}(\text{id.name}); \}$



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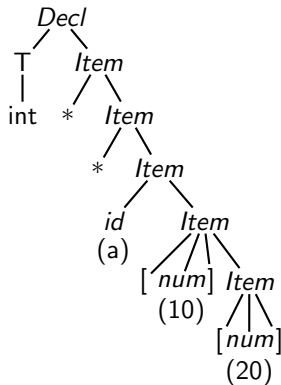
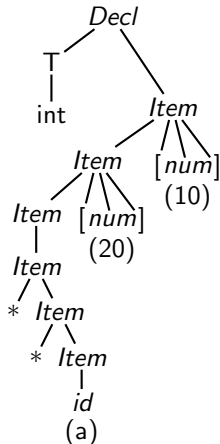
Declaration Processing



Processing C Declarations

Example Declaration: `int **a[20][10];`

Two of the many possible parse trees



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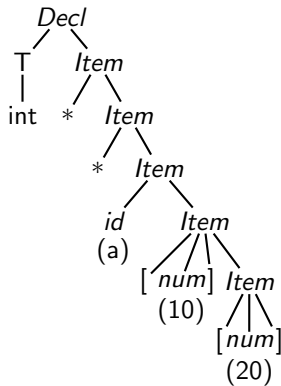
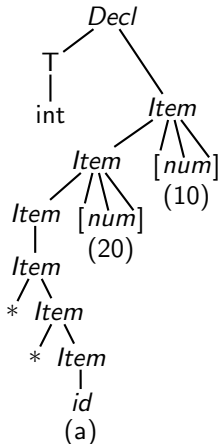
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Processing C Declarations

Example Declaration: `int **a[20][10];`

Two of the many possible parse trees



Difficulties in implementing a syntax directed translation scheme

- Type constructor '`*`' appears before `id` whereas `array` appears after `id`
- Both constructors may appear together for the same `id`
- Final type can be entered in the symbol table only on seeing `id` but the type expression is not complete when `id` is seen
- A combination of synthesized and inherited attributes is needed

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Processing C Declarations

- Basic types
- Derived types using type constructors
(such as arrays, structs, pointer dereferences, address expressions)
- Representing types using type expressions (drawn as trees)



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Processing C Declarations

- Basic types
- Derived types using type constructors
(such as arrays, structs, pointer dereferences, address expressions)
- Representing types using type expressions (drawn as trees)

```
int **a[20][10];
```

Row major representation of arrays in C

- 20 rows of (i.e. 20 arrays) where
- each row is an array of 10 double pointers to int
- the tree is right-recursive for type constructor *array*



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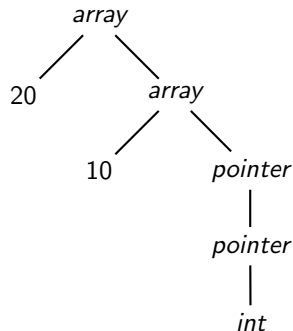
Processing C Declarations

- Basic types
- Derived types using type constructors
(such as arrays, structs, pointer dereferences, address expressions)
- Representing types using type expressions (drawn as trees)

`int **a[20][10];`

Row major representation of arrays in C

- 20 rows of (i.e. 20 arrays) where
- each row is an array of 10 double pointers to int
- the tree is right-recursive for type constructor *array*





Processing C Array Declarations

```
int a[20][10];
```

$Decl \rightarrow T \ Item \ ;$

$T \rightarrow \text{int} \mid \text{double}$

$Item \rightarrow id \mid Item \ [\ num \]$

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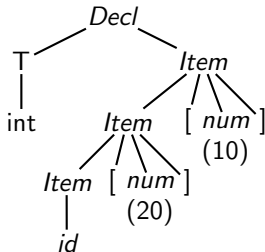
Processing C Array Declarations

`int a[20][10];`

$Decl \rightarrow T \text{ Item} ;$

$T \rightarrow \text{int} \mid \text{double}$

$\text{Item} \rightarrow \text{id} \mid \text{Item} [\text{num}]$



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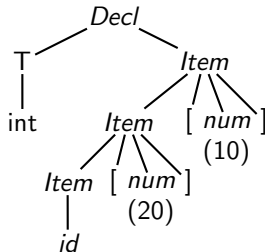
Processing C Array Declarations

```
int a[20][10];
```

$Decl \rightarrow T \text{ Item} ;$

$T \rightarrow \text{int} \mid \text{double}$

$\text{Item} \rightarrow \text{id} \mid \text{Item} [\text{num}]$



Inconvenient
layout for

20 arrays of
arrays of 10 ints

Dimensions are collected
by a left-recursive rule



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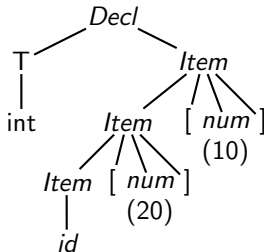
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`int a[20][10];`

$Decl \rightarrow T \text{ Item} ;$

$T \rightarrow \text{int} \mid \text{double}$

$\text{Item} \rightarrow \text{id} \mid \text{Item} [\text{num}]$



Inconvenient
layout for

20 arrays of
arrays of 10 ints

Dimensions are collected
by a left-recursive rule

`int a[20][10];`

$Decl \rightarrow T \text{ Item} ;$

$T \rightarrow \text{int} \mid \text{double}$

$\text{Item} \rightarrow \text{id} \mid \text{id ListDim}$

$\text{ListDim} \rightarrow [\text{num}] \mid [\text{num}] \text{ ListDim}$



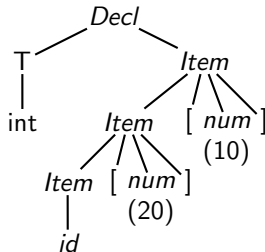
Processing C Array Declarations

`int a[20][10];`

$Decl \rightarrow T \text{ Item} ;$

$T \rightarrow \text{int} \mid \text{double}$

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Inconvenient
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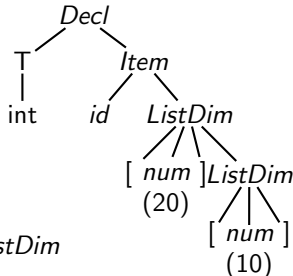
`int a[20][10];`

$Decl \rightarrow T \text{ Item} ;$

$T \rightarrow \text{int} \mid \text{double}$

$\text{Item} \rightarrow \text{id} \mid \text{id ListDim}$

$\text{ListDim} \rightarrow [\text{num}] \mid [\text{num}] \text{ListDim}$





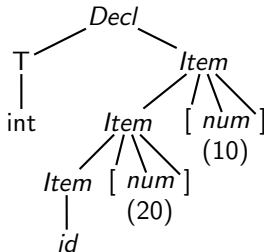
Processing C Array Declarations

`int a[20][10];`

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$T \rightarrow \text{int} \mid \text{double}$

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Inconvenient
layout for

20 arrays of
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Dimensions are collected
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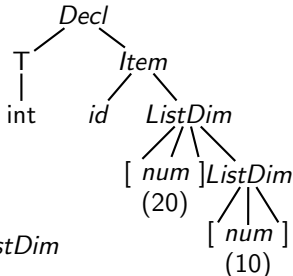
`int a[20][10];`

$Decl \rightarrow T \text{ Item} ;$

$T \rightarrow \text{int} \mid \text{double}$

$\text{Item} \rightarrow \text{id} \mid \text{id ListDim}$

$\text{ListDim} \rightarrow [\text{num}] \mid [\text{num}] \text{ListDim}$



Convenient
layout for

20 arrays of
arrays of 10 ints

Dimensions are collected
by a right-recursive rule

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SDTS for Processing C Array Declarations: Identifying Type

Attribute	Description	Type
$X.bt$	Base type	inherited for $X = I$ and $X = L$, synthesized for $X = T$
$X.dt$	Derived type	synthesized
$X.v$	Value	synthesized
$X.nm$	Name	synthesized

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$$D \rightarrow T \quad I;$$

$$T \rightarrow \text{int}$$

$$T \rightarrow \text{double}$$

$$I \rightarrow id$$

$$I \rightarrow id \quad L$$

$$L \rightarrow [\text{num}]$$

$$L_1 \rightarrow [\text{num}] \quad L_2$$



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$X.nm$	Name	synthesized

$$D \rightarrow T \{I.bt = T.bt\} I;$$

$$T \rightarrow \text{int} \{T.bt = \text{int}\}$$

$$T \rightarrow \text{double} \{T.bt = \text{double}\}$$

$$I \rightarrow id$$

$$I \rightarrow id \quad L$$

$$L \rightarrow [num]$$

$$L_1 \rightarrow [num] \quad L_2$$



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$X.dt$	Derived type	synthesized
$X.v$	Value	synthesized
$X.nm$	Name	synthesized

$$D \rightarrow T \{I.bt = T.bt\} \ I; \ \{Enter_In_Symtab(I.nm, I.dt)\}$$

$$T \rightarrow \text{int} \ \{T.bt = \text{int}\}$$

$$T \rightarrow \text{double} \ \{T.bt = \text{double}\}$$

$$I \rightarrow id$$

$$I \rightarrow id \qquad L$$

$$L \rightarrow [\text{num}]$$

$$L_1 \rightarrow [\text{num}] \qquad L_2$$



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$X.v$	Value	synthesized
$X.nm$	Name	synthesized

$$D \rightarrow T \{I.bt = T.bt\} \quad I; \quad \{Enter_In_Symtab(I.nm, I.dt)\}$$

$$T \rightarrow \text{int} \quad \{T.bt = \text{int}\}$$

$$T \rightarrow \text{double} \quad \{T.bt = \text{double}\}$$

$$I \rightarrow id \quad \{I.dt = I.bt; I.nm = id.nm\}$$

$$I \rightarrow id \quad L$$

$$L \rightarrow [\text{num}]$$

$$L_1 \rightarrow [\text{num}] \quad L_2$$



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$X.v$	Value	synthesized
$X.nm$	Name	synthesized

$$D \rightarrow T \{I.bt = T.bt\} \ I; \ \{Enter_In_Symtab(I.nm, I.dt)\}$$

$$T \rightarrow \text{int} \ \{T.bt = \text{int}\}$$

$$T \rightarrow \text{double} \ \{T.bt = \text{double}\}$$

$$I \rightarrow id \ \{I.dt = I.bt; \ I.nm = id.nm\}$$

$$I \rightarrow id \ \{L.bt = I.bt\} \ L$$

$$L \rightarrow [\text{num}]$$

$$L_1 \rightarrow [\text{num}]$$

$$L_2$$



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$X.nm$	Name	synthesized

$$D \rightarrow T \{I.bt = T.bt\} \ I; \ \{Enter_In_Symtab(I.nm, I.dt)\}$$

$$T \rightarrow \text{int} \ \{T.bt = \text{int}\}$$

$$T \rightarrow \text{double} \ \{T.bt = \text{double}\}$$

$$I \rightarrow id \ \{I.dt = I.bt; \ I.nm = id.nm\}$$

$$I \rightarrow id \ \{L.bt = I.bt\} \ L \ \{I.dt = L.dt; \ I.nm = id.nm\}$$

$$L \rightarrow [\text{num}]$$

$$L_1 \rightarrow [\text{num}]$$

$$L_2$$



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$X.nm$	Name	synthesized

$$D \rightarrow T \{I.bt = T.bt\} \ I; \ \{Enter_In_Symtab(I.nm, I.dt)\}$$

$$T \rightarrow \text{int} \ \{T.bt = \text{int}\}$$

$$T \rightarrow \text{double} \ \{T.bt = \text{double}\}$$

$$I \rightarrow id \ \{I.dt = I.bt; \ I.nm = id.nm\}$$

$$I \rightarrow id \ \{L.bt = I.bt\} \ L \ \{I.dt = L.dt; \ I.nm = id.nm\}$$

$$L \rightarrow [\text{num}] \ \{L.dt = \text{array}(\text{num}.v, L.bt)\}$$

$$L_1 \rightarrow [\text{num}] \qquad L_2$$



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$X.dt$	Derived type	synthesized
$X.v$	Value	synthesized
$X.nm$	Name	synthesized

$$D \rightarrow T \{I.bt = T.bt\} \ I; \ \{Enter_In_Symtab(I.nm, I.dt)\}$$

$$T \rightarrow \text{int} \ \{T.bt = \text{int}\}$$

$$T \rightarrow \text{double} \ \{T.bt = \text{double}\}$$

$$I \rightarrow id \ \{I.dt = I.bt; \ I.nm = id.nm\}$$

$$I \rightarrow id \ \{L.bt = I.bt\} \ L \ \{I.dt = L.dt; \ I.nm = id.nm\}$$

$$L \rightarrow [\text{num}] \ \{L.dt = \text{array}(\text{num}.v, L.bt)\}$$

$$L_1 \rightarrow [\text{num}] \ \{L_2.bt = L_1.bt\} \ L_2$$



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$X.v$	Value	synthesized
$X.nm$	Name	synthesized

$$D \rightarrow T \{I.bt = T.bt\} \ I; \ \{Enter_In_Symtab(I.nm, I.dt)\}$$

$$T \rightarrow \text{int} \ \{T.bt = \text{int}\}$$

$$T \rightarrow \text{double} \ \{T.bt = \text{double}\}$$

$$I \rightarrow id \ \{I.dt = I.bt; \ I.nm = id.nm\}$$

$$I \rightarrow id \ \{L.bt = I.bt\} \ L \ \{I.dt = L.dt; \ I.nm = id.nm\}$$

$$L \rightarrow [\text{num}] \ \{L.dt = \text{array}(\text{num}.v, L.bt)\}$$

$$L_1 \rightarrow [\text{num}] \ \{L_2.bt = L_1.bt\} \ L_2 \ \{L_1.dt = \text{array}(\text{num}.v, L_2.dt)\}$$



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SDTS for Processing C Array Declarations: Identifying Type

```
int a[20][10];
```

$$D \rightarrow T \{l.bt = T.bt\} \quad l;$$
$$\{Enter_In_Symtab(l.nm, l.dt)\}$$
$$T \rightarrow \text{int} \{T.bt = \text{int}\}$$
$$T \rightarrow \text{double} \{T.bt = \text{double}\}$$
$$l \rightarrow id \{l.dt = l.bt; l.nm = id.nm\}$$
$$l \rightarrow id \{L.bt = l.bt\} \quad L$$
$$\{l.dt = L.dt; l.nm = id.nm\}$$
$$L \rightarrow [num] \{L.dt = \text{array}(num.v, L.bt)\}$$
$$L_1 \rightarrow [num] \{L_2.bt = L_1.bt\}$$
$$L_2 \{L_1.dt = \text{array}(num.v, L_2.dt)\}$$



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SDTS for Processing C Array Declarations: Identifying Type

`int a[20][10];`

$D \rightarrow T \{l.bt = T.bt\} \ I;$

$\{Enter_In_Symtab(l.nm, l.dt)\}$

$T \rightarrow int \{T.bt = int\}$

$T \rightarrow double \{T.bt = double\}$

$I \rightarrow id \{l.dt = l.bt; l.nm = id.nm\}$

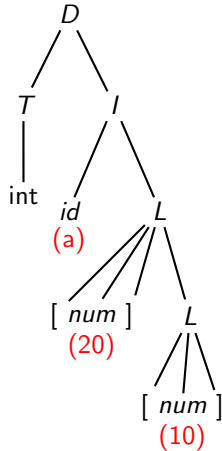
$I \rightarrow id \{L.bt = l.bt\} \ L$

$\{l.dt = L.dt; l.nm = id.nm\}$

$L \rightarrow [num] \{L.dt = array(num.v, L.bt)\}$

$L_1 \rightarrow [num] \{L_2.bt = L_1.bt\}$

$L_2 \{L_1.dt = array(num.v, L_2.dt)\}$





SDTS for Processing C Array Declarations: Identifying Type

`int a[20][10];`

$D \rightarrow T \{l.bt = T.bt\} I;$

$\{Enter_In_Symtab(l.nm, l.dt)\}$

$T \rightarrow int \{T.bt = int\}$

$T \rightarrow double \{T.bt = double\}$

$I \rightarrow id \{l.dt = l.bt; l.nm = id.nm\}$

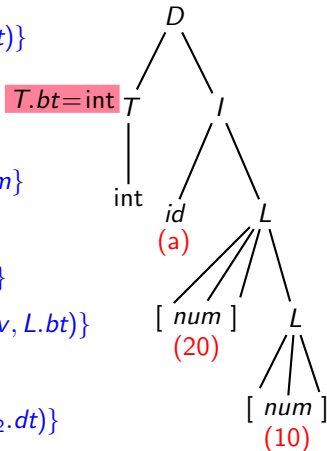
$I \rightarrow id \{L.bt = l.bt\} L$

$\{l.dt = L.dt; l.nm = id.nm\}$

$L \rightarrow [num] \{L.dt = array(num.v, L.bt)\}$

$L_1 \rightarrow [num] \{L_2.bt = L_1.bt\}$

$L_2 \{L_1.dt = array(num.v, L_2.dt)\}$



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SDTS for Processing C Array Declarations: Identifying Type

`int a[20][10];`

$D \rightarrow T \{l.bt = T.bt\} I;$

$\{Enter_In_Symtab(l.nm, l.dt)\}$

$T \rightarrow int \{T.bt = int\}$

$T \rightarrow double \{T.bt = double\}$

$I \rightarrow id \{l.dt = l.bt; l.nm = id.nm\}$

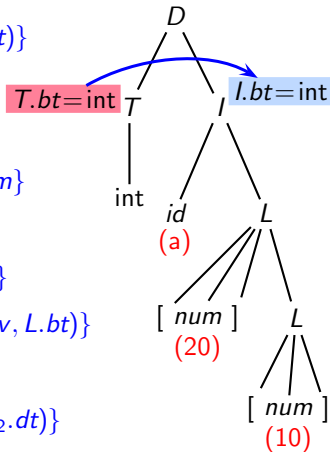
$I \rightarrow id \{L.bt = l.bt\} L$

$\{l.dt = L.dt; l.nm = id.nm\}$

$L \rightarrow [num] \{L.dt = array(num.v, L.bt)\}$

$L_1 \rightarrow [num] \{L_2.bt = L_1.bt\}$

$L_2 \{L_1.dt = array(num.v, L_2.dt)\}$



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SDTS for Processing C Array Declarations: Identifying Type

`int a[20][10];`

$D \rightarrow T \{l.bt = T.bt\} I;$

$\{Enter_In_Symtab(l.nm, l.dt)\}$

$T \rightarrow int \{T.bt = int\}$

$T \rightarrow double \{T.bt = double\}$

$I \rightarrow id \{l.dt = l.bt; l.nm = id.nm\}$

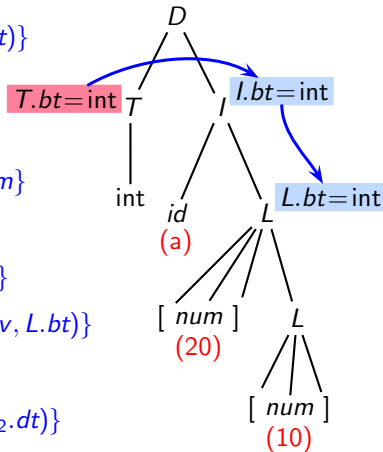
$I \rightarrow id \{L.bt = l.bt\} L$

$\{l.dt = L.dt; l.nm = id.nm\}$

$L \rightarrow [num] \{L.dt = array(num.v, L.bt)\}$

$L_1 \rightarrow [num] \{L_2.bt = L_1.bt\}$

$L_2 \{L_1.dt = array(num.v, L_2.dt)\}$



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SDTS for Processing C Array Declarations: Identifying Type

`int a[20][10];`

$D \rightarrow T \{l.bt = T.bt\} I;$

$\{Enter_In_Symtab(l.nm, l.dt)\}$

$T \rightarrow int \{T.bt = int\}$

$T \rightarrow double \{T.bt = double\}$

$I \rightarrow id \{l.dt = l.bt; l.nm = id.nm\}$

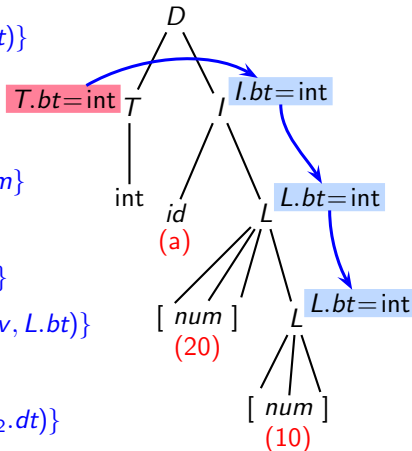
$I \rightarrow id \{L.bt = l.bt\} L$

$\{l.dt = L.dt; l.nm = id.nm\}$

$L \rightarrow [num] \{L.dt = array(num.v, L.bt)\}$

$L_1 \rightarrow [num] \{L_2.bt = L_1.bt\}$

$L_2 \{L_1.dt = array(num.v, L_2.dt)\}$



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SDTS for Processing C Array Declarations: Identifying Type

`int a[20][10];`

$D \rightarrow T \{l.bt = T.bt\} I;$

$\{Enter_In_Symtab(l.nm, l.dt)\}$

$T \rightarrow int \{T.bt = int\}$

$T \rightarrow double \{T.bt = double\}$

$I \rightarrow id \{l.dt = l.bt; l.nm = id.nm\}$

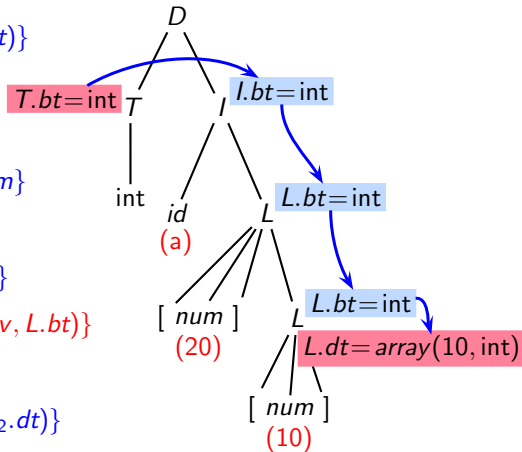
$I \rightarrow id \{L.bt = l.bt\} L$

$\{l.dt = L.dt; l.nm = id.nm\}$

$L \rightarrow [num] \{L.dt = array(num.v, L.bt)\}$

$L_1 \rightarrow [num] \{L_2.bt = L_1.bt\}$

$L_2 \{L_1.dt = array(num.v, L_2.dt)\}$



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SDTS for Processing C Array Declarations: Identifying Type

`int a[20][10];`

$D \rightarrow T \{l.bt = T.bt\} I;$

$\{Enter_In_Symtab(l.nm, l.dt)\}$

$T \rightarrow int \{T.bt = int\}$

$T \rightarrow double \{T.bt = double\}$

$I \rightarrow id \{l.dt = l.bt; l.nm = id.nm\}$

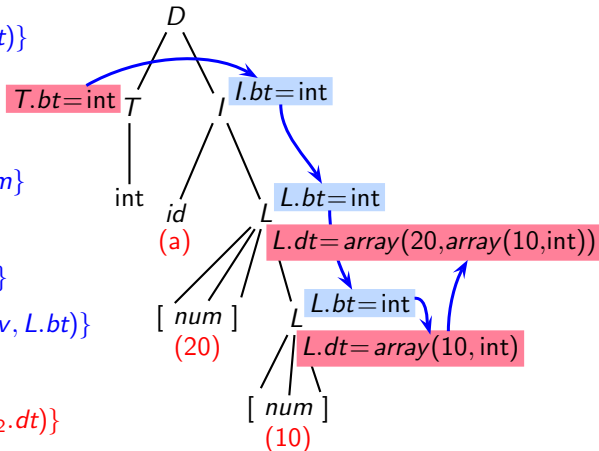
$I \rightarrow id \{L.bt = l.bt\} L$

$\{l.dt = L.dt; l.nm = id.nm\}$

$L \rightarrow [num] \{L.dt = array(num.v, L.bt)\}$

$L_1 \rightarrow [num] \{L_2.bt = L_1.bt\}$

$L_2 \{L_1.dt = array(num.v, L_2.dt)\}$



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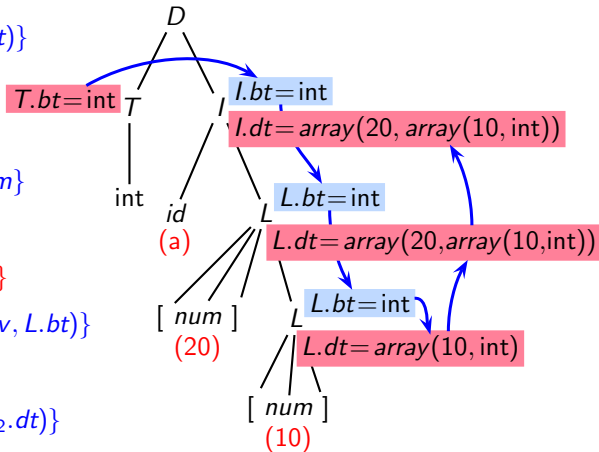
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$$D \rightarrow T \{l.bt = T.bt\} \quad l;$$
$$T \rightarrow \text{int} \quad \{ T.bt = \text{int} \}$$
$$I \rightarrow id \quad \{I.dt = I.bt; \quad I.nm = id.nm\}$$
$$l \rightarrow id \quad \{L.bt = l.bt\} \quad L$$
$$\{l.dt = L.dt; l.nm = id.nm)\}$$
$$L \rightarrow [num] \{L.dt = array(num.v, L.bt)\}$$
$$L_1 \rightarrow [num] \{L_2.bt = L_1.bt\}$$
$$L_2 \quad \{L_1.dt = array(num.v, L_2.dt)\}$$




SDTS for Processing C Array Declarations: Identifying Type

`int a[20][10];`

$D \rightarrow T \{l.bt = T.bt\} \ I;$

$\{Enter_In_Symtab(l.nm, l.dt)\}$

$T \rightarrow int \{T.bt = int\}$

$T \rightarrow double \{T.bt = double\}$

$I \rightarrow id \{l.dt = l.bt; \ l.nm = id.nm\}$

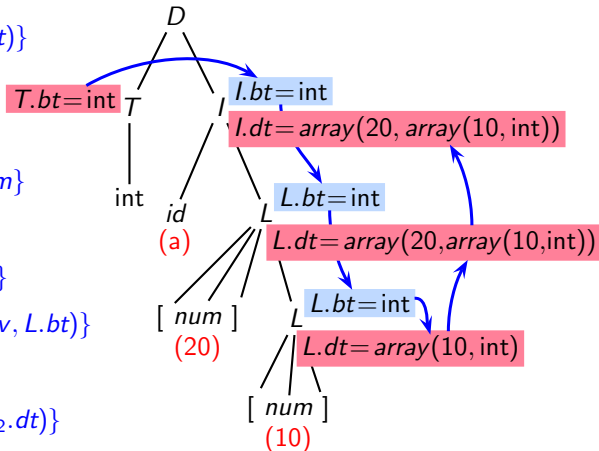
$I \rightarrow id \{L.bt = l.bt\} \ L$

$\{l.dt = L.dt; \ l.nm = id.nm\}$

$L \rightarrow [\ num \] \{L.dt = array(num.v, L.bt)\}$

$L_1 \rightarrow [\ num \] \{L_2.bt = L_1.bt\}$

$L_2 \{L_1.dt = array(num.v, L_2.dt)\}$



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C Array Size Calculations

Attribute	Description	Type
$X.bt$	Base type	inherited for $X = I$ and $X = L$, synthesized for $X = T$
$X.dt$	Derived type	synthesized
$X.v$	Value	synthesized
$X.s$	Size	synthesized
$X.nm$	Name	synthesized
$X.w$	Width	inherited for $X = I$, synthesized for $X = T$

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$$D \rightarrow T \{I.bt = T.bt; I.w = T.w\} \quad I; \{Enter_In_Syntab(I.nm, I.dt, I.s)\}$$

$$T \rightarrow \text{int} \{T.bt = \text{int}; T.w = 4\}$$

$$T \rightarrow \text{double} \{T.bt = \text{double}; T.w = 8\}$$

$$I \rightarrow id \{I.dt = I.bt; I.nm = id.nm; I.s = I.w\}$$

$$I \rightarrow id \{L.bt = I.bt\} \quad L \{I.dt = L.dt; I.nm = id.nm; I.s = L.s \times I.w\}$$

$$L \rightarrow [num] \{L.dt = \text{array}(num.v, L.bt); L.s = num.v\}$$

$$L_1 \rightarrow [num] \{L_2.bt = L_1.bt\} \quad L_2 \{L_1.dt = \text{array}(num.v, L_2.dt); L_1.s = L_2.s \times num.v\}$$



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- yacc script: c-decl-arrays-sdts.y
- lex script: c-decl-scanner.l



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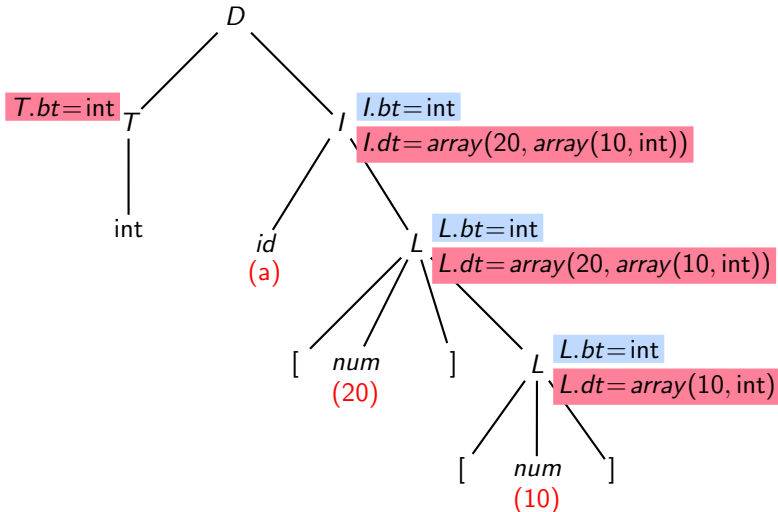
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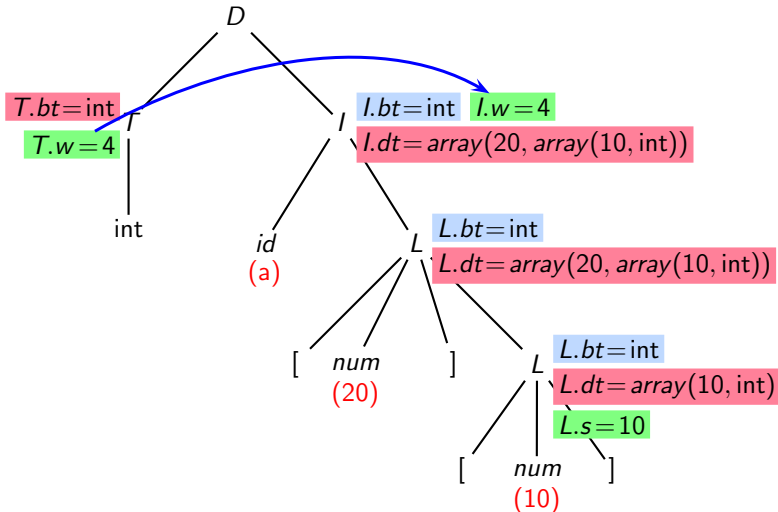
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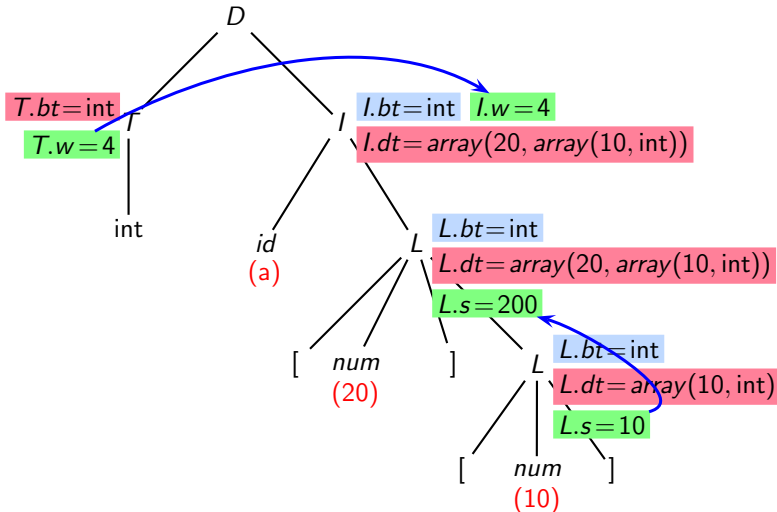
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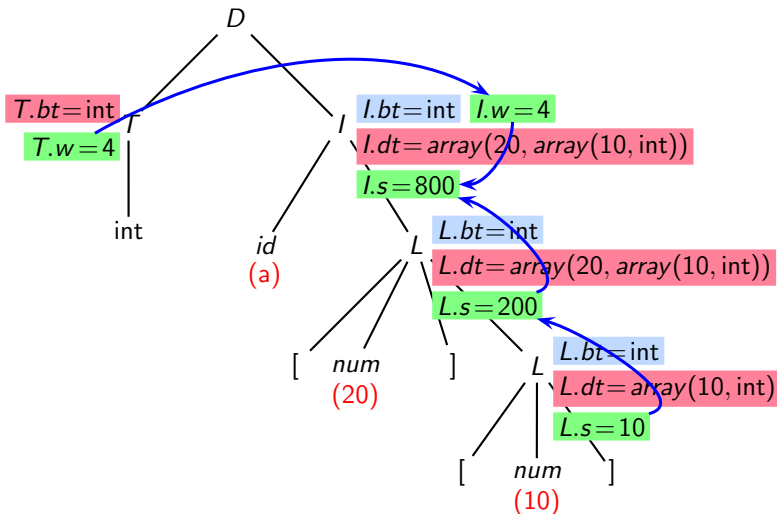
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$Item \rightarrow id$

| $id\ ListDim$

| $ListStar\ id$

| $ListStar\ id\ ListDim$

| $(\ ListStar\ id)\ ListDim$

| $ListStar\ (\ ListStar\ id)\ ListDim$

$ListStar \rightarrow *$

| $*\ ListStar$

$ListDim \rightarrow [\ num]$

| $[\ num]\ ListDim$



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$$\begin{aligned} \textit{Item} \rightarrow & id \\ & | id \textit{ListDim} \\ & | \textit{ListStar} id \\ & | \textit{ListStar} id \textit{ListDim} \\ & | (\textit{ListStar} id) \textit{ListDim} \\ & | \textit{ListStar} (\textit{ListStar} id) \textit{ListDim} \end{aligned}$$
$$\begin{aligned} \textit{ListStar} \rightarrow & * \\ & | * \textit{ListStar} \end{aligned}$$
$$\begin{aligned} \textit{ListDim} \rightarrow & [num] \\ & | [num] \textit{ListDim} \end{aligned}$$



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$$\begin{array}{l} \textit{Item} \rightarrow \textit{id} \\ \quad | \textit{id ListDim} \\ \quad | \textit{ListStar id} \\ \quad | \textit{ListStar id ListDim} \\ \quad | (\textit{ListStar id}) \textit{ListDim} \\ \quad | \textit{ListStar} (\textit{ListStar id}) \textit{ListDim} \end{array}$$
$$\begin{array}{l} \textit{ListStar} \rightarrow * \\ \quad | * \textit{ListStar} \end{array}$$
$$\begin{array}{l} \textit{ListDim} \rightarrow [\textit{num}] \\ \quad | [\textit{num}] \textit{ListDim} \end{array}$$



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Including Pointers in C Array Declarations

Item \rightarrow *id*

| *id ListDim*

| *ListStar id*

| *ListStar id ListDim*

| (*ListStar id*) *ListDim*

| *ListStar* (*ListStar id*) *ListDim*

ListStar \rightarrow *

| * *ListStar*

ListDim \rightarrow [*num*]

| [*num*] *ListDim*



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$Item \rightarrow id$

| $id\ ListDim$

| $ListStar\ id$

| $ListStar\ id\ ListDim$

| $(\ ListStar\ id)\ ListDim$

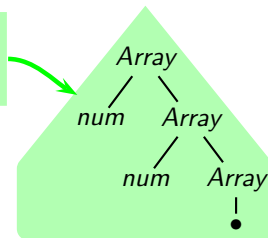
| $ListStar\ (\ ListStar\ id)\ ListDim$

$ListStar \rightarrow *$

| $*\ ListStar$

$ListDim \rightarrow [\ num]$

| $[\ num]\ ListDim$





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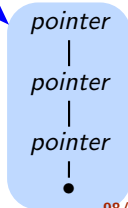
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$Item \rightarrow id$
| $id\ ListDim$
| $ListStar\ id$
| $ListStar\ id\ ListDim$
| $(\ ListStar\ id)\ ListDim$
| $ListStar\ (\ ListStar\ id)\ ListDim$

$ListStar \rightarrow *$
| $*\ ListStar$

$ListDim \rightarrow [\ num]$
| $[\ num]\ ListDim$





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$Item \rightarrow id$

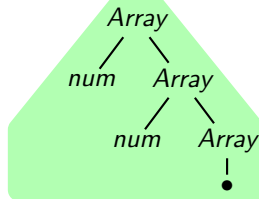
| *id ListDim*
| *ListStar id*
| *ListStar id ListDim*
| *(ListStar id) ListDim*
| *ListStar (ListStar id) ListDim*

$ListStar \rightarrow *$

| $* ListStar$

$ListDim \rightarrow [num]$

| $[num] ListDim$





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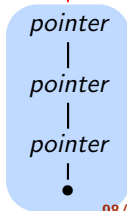
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$Item \rightarrow id$
| $id\ ListDim$
| **$ListStar\ id$**
| $ListStar\ id\ ListDim$
| $(\ ListStar\ id)\ ListDim$
| $ListStar\ (\ ListStar\ id)\ ListDim$

$ListStar \rightarrow *$
| $*\ ListStar$

$ListDim \rightarrow [\ num]$
| $[\ num]\ ListDim$





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$Item \rightarrow id$

| $id\ ListDim$

| $ListStar\ id$

| $ListStar\ id\ ListDim$

| $(\ ListStar\ id)\ ListDim$

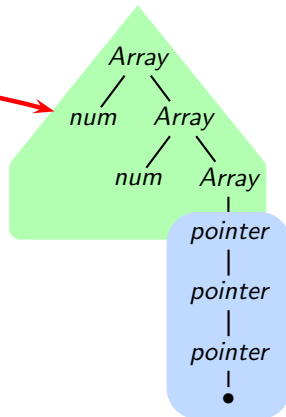
| $ListStar\ (\ ListStar\ id)\ ListDim$

$ListStar \rightarrow *$

| $*\ ListStar$

$ListDim \rightarrow [\ num]$

| $[\ num]\ ListDim$





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$Item \rightarrow id$

| $id\ ListDim$

| $ListStar\ id$

| $ListStar\ id\ ListDim$

| $(\textcolor{red}{ListStar\ id})\ ListDim$

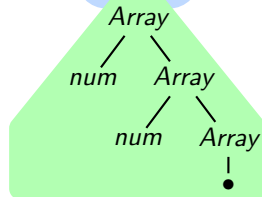
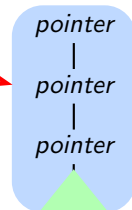
| $ListStar\ (ListStar\ id)\ ListDim$

$ListStar \rightarrow *$

| $*\ ListStar$

$ListDim \rightarrow [num]$

| $[num]\ ListDim$





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$Item \rightarrow id$

| $id\ ListDim$

| $ListStar\ id$

| $ListStar\ id\ ListDim$

| $(\ ListStar\ id)\ ListDim$

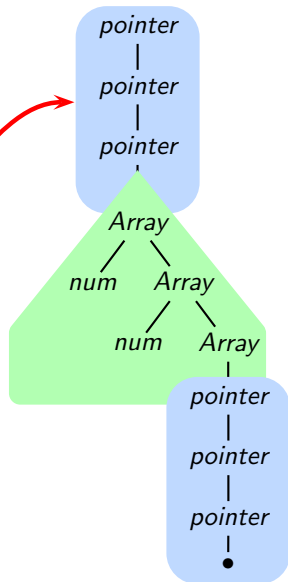
| $ListStar\ (\ ListStar\ id)\ ListDim$

$ListStar \rightarrow *$

| $*\ ListStar$

$ListDim \rightarrow [\ num]$

| $[\ num]\ ListDim$





Adding a List

```
int *a[10][20], **b, c;
```

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$$Decl \rightarrow T \text{ List} ;$$
$$List_1 \rightarrow \{List_2.bt = List_1.bt\} List_2 ,$$
$$\{Item.bt = List_1.bt\} Item$$
$$List \rightarrow \{Item.bt = List.bt\} Item$$



Adding a List

```
int *a[10][20], **b, c;
```

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$Decl \rightarrow T \text{ List} ;$

$List_1 \rightarrow \{List_2.bt = List_1.bt\} List_2 ,$
 $\{Item.bt = List_1.bt\} Item$

$List \rightarrow \{Item.bt = List.bt\} Item$

$List_1 \rightarrow \$ACT1 \text{ List}_2 , \$ACT2 \text{ Item}$

$List \rightarrow \$ACT3 \text{ Item}$

$\$ACT1 \rightarrow \%empty \{List_2.bt = List_1.bt\}$

$\$ACT2 \rightarrow \%empty \{Item.bt = List_1.bt\}$

$\$ACT3 \rightarrow \%empty \{Item.bt = List.bt\}$



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Adding a List

```
int *a[10][20], **b, c;
```

$$Decl \rightarrow T \text{ List} ;$$
$$List_1 \rightarrow \{ List_2.bt = List_1.bt \} List_2 ,$$
$$\{ Item.bt = List_1.bt \} Item$$
$$List \rightarrow \{ Item.bt = List.bt \} Item$$
$$List_1 \rightarrow \$ACT1 \text{ List}_2 , \$ACT2 \text{ Item}$$
$$List \rightarrow \$ACT3 \text{ Item}$$
$$\$ACT1 \rightarrow \%empty \{ List_2.bt = List_1.bt \}$$
$$\$ACT2 \rightarrow \%empty \{ Item.bt = List_1.bt \}$$
$$\$ACT3 \rightarrow \%empty \{ Item.bt = List.bt \}$$

The actions in the beginning of the RHSs give rise
to reduce-reduce conflict in a yacc/bison parser



Adding A List

```
int *a[10][20], **b, c;
```

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$Decl \rightarrow T \text{ List} ;$

$List_1 \rightarrow \{List_2.bt = List_1.bt\} List_2 ,$
 $\{Item.bt = List_1.bt\} Item$

$List \rightarrow \{Item.bt = List.bt\} Item$



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Adding A List

```
int *a[10][20], **b, c;
```

$$Decl \rightarrow T \text{ List} ;$$
$$List_1 \rightarrow \{List_2.bt = List_1.bt\} \text{ List}_2 , \\ \{Item.bt = List_1.bt\} \text{ Item}$$
$$List \rightarrow \{Item.bt = List.bt\} \text{ Item}$$
$$Decl \rightarrow T \text{ List} ;$$
$$List \rightarrow \{Item.bt = List.bt\} \text{ Item} \\ \{List_Tail.bt = List.bt\} \text{ List_Tail}$$
$$List_Tail \rightarrow , \{List.bt = List_Tail.bt\} \text{ List}$$
$$List_Tail \rightarrow \%empty$$

No reduce-reduce conflicts because recursion on *List* is an indirect recursion rather than a direct recursion, separating the two marker non-terminals representing the action before *Item*, apart



Demo of Processing C Array Declarations with Pointers

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- Parser (without attribute evaluation)
 - yacc script: c-decl-processing-grammar.y
 - lex script: c-decl-scanner-without-actions.l
- SDTS
 - yacc script: c-decl-arrays-pointers-sdts.y
 - lex script: c-decl-scanner.l