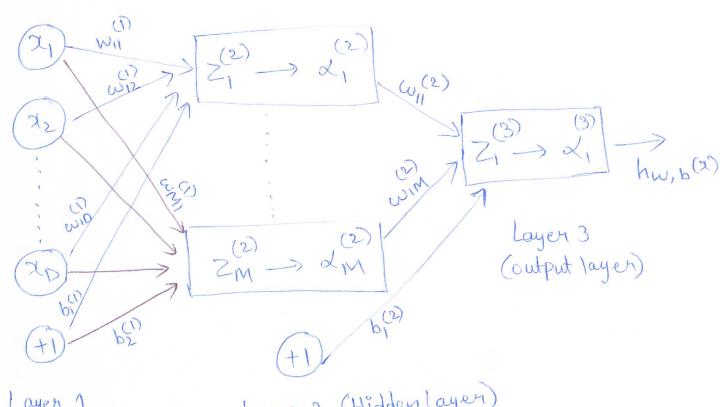
## Schematic Representation:



Layer 1 (Input layer) Layer 2 (Hidden Layer)

$$Z_{1}^{(2)} = \omega_{11}^{(1)} \times_{1} + \omega_{12}^{(1)} \times_{2} + \omega_{13}^{(1)} \times_{3} + \dots + \omega_{1D}^{(1)} \times_{D} + b_{1}^{(1)}$$

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output = 
$$h_{w,b}(x) = \chi_1^{(3)} = f_{\sigma}(z_1^{(3)})$$

$$W = \begin{bmatrix} w_{11} & w_{12} & \dots & w_{1D} \\ \vdots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots & \ddots & \ddots \\ \vdots & \ddots & \ddots &$$

$$b^{(1)} = \begin{bmatrix} b_1^{(1)} & b_2^{(1)} & \cdots & b_M \end{bmatrix}$$
1xM

$$x^{(2)} = f(\omega^{(1)} \times + b^{(1)})$$

$$h_{w,b}(x) = x^{(3)} = f(w^{(2)}, x^{(2)} + b^{(2)})$$

output = 
$$hw_1b(x) = d_1 = f(w_1)d_1 + \dots + w_1m d_1 + b_1$$

where 
$$d_M = f(w_{M1} x_1 + w_{M2} x_2 + \cdots + w_{MD} x_D + b_n)$$

In general,

where 
$$z^{(2)} = f_{o}(w^{(2)}) + f^{(1)}$$

Sigmoid(
$$\lambda$$
) =  $f(x) = \frac{1}{1+e^{-\lambda}}$ ;  $f(x) = f(x) = \frac{e^{\lambda} - e^{\lambda}}{e^{\lambda} + e^{-\lambda}}$ 

$$\Rightarrow f_{ton}(x) = \frac{e^{x}-1}{e^{x}+1}$$

$$\Rightarrow f_{tan}(x) = \frac{e^{2x}}{e^{2x}+1}$$

$$\Rightarrow f_{tan}(x) = 2\left[\frac{e^{2x}}{e^{2x}+1}\right] - 1$$

$$= 2f_{0}(2x) - 1$$

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$$= 2f_{0}(2x) - 1$$

Newal Network - 1 with sigmoid Activation:

output = 
$$hw_1b(x) = d_1 = f(w_1)d_1 + ... + cw_1m d_m + b_1$$

(1) -> where 
$$dm = f_{\sigma}(w_{m1} x_{1} + w_{m2} x_{2} + ... + w_{m0} x_{D} + b_{m})$$

newral Network-2 with tanh Activation: (w,b) (V, c)

(2) -> where 
$$d_{M} = f_{tan} \left( V_{m1} \times_{1} + V_{m2} \times_{2} + \cdots + V_{mp} \times_{p} + c_{m} \right)$$

we know that, 
$$f_{tan}(x) = 2f_{\sigma}(2x) - 1$$

Consider, (2)

From (1), 
$$dm = f_{\sigma}(\omega_{m1} x_{1} + ... + \omega_{mp} x_{p} + b_{m})$$

From (2)

(2)

$$dm = \frac{1}{2} f_{ton}(\omega_{m1} x_{1} + \omega_{m2} x_{2} + ... + b_{m}) + \frac{1}{2}$$

$$\frac{i}{V_{MD}} = K_1 \frac{i}{V_{MD}} + K_2$$
and  $\frac{i}{C_{M}} = K_1 \frac{i}{V_{M}} + K_2 = 0$  on.

where VMI,... Vmb are weights in the network-2 and wmi,... wmp are weights in the network-1 After substituting these in output equation, we can see that there exists an equivalent network with hidden unit activation functions given by hyperbolic tangent, which computes exactly the same function as their of with Sigmoid activation function. END OF Question 1