## GATE 2023 EC 49

## EE23BTECH11045 - Palavelli Srija\*

**Question 12.7.7:** Let  $x(t) = 10\cos(10.5\omega t)$  be passed through an LTI system with impulse response  $h(t) = \pi \left(\frac{\sin(\omega t)}{\pi t}\right)^2 \cos(10\omega t)$ . The output of the system is:

## **Solution:**

Symbol	Description	Value
x(t)	input	$10\cos(10.5\omega t)$
h(t)	impulse	$\pi \left(\frac{\sin(\omega t)}{\pi t}\right)^2 \cos(10\omega t)$
y(t)	output	??

TABLE 0: Input Parameters

Given h(t) is real and even. When a sinusoidal input is applied to an LTI system with an even impulse response, the output will also be sinusoidal. Hence,  $y(t) = A \cdot 10 \cos(10.5\omega t + \theta)$ .

$$x(t) \to \boxed{\mathbf{h}(\mathbf{t})} \to y(t)$$

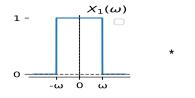
Let 
$$f(t) = \pi \left(\frac{\sin(\omega t)}{\pi t}\right)^2$$
 (1)

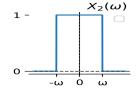
$$h(t) = f(t)\cos(10\omega t) \tag{2}$$

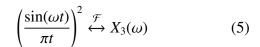
Using

$$x_1(t) \cdot x_2(t) \stackrel{\mathcal{F}}{\longleftrightarrow} X_1(\omega) * X_2(\omega)$$
 (3)

$$\left(\frac{\sin(\omega t)}{\pi t}\right) \cdot \left(\frac{\sin(\omega t)}{\pi t}\right) \stackrel{\mathcal{F}}{\longleftrightarrow} X_1(\omega) * X_2(\omega) \tag{4}$$







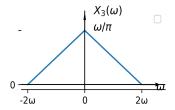


Fig. 0

$$\pi \left(\frac{\sin(\omega t)}{\pi t}\right)^2 \stackrel{\mathcal{F}}{\longleftrightarrow} X_4(\omega) \tag{6}$$

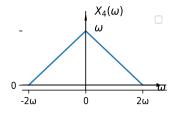


Fig. 0

From modulating property:

$$f(t)\cos(\omega_0 t) \stackrel{\mathcal{F}}{\longleftrightarrow} \frac{1}{2} \left[ F(\omega + \omega_0) + F(\omega - \omega_0) \right]$$
 (7)

$$H(\omega) = \frac{1}{2} \left[ F(\omega + 10\omega) + F(\omega - 10\omega) \right]$$
 (8)

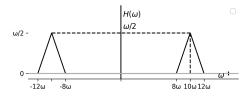


Fig. 0

$$\frac{\frac{\omega}{2} - 0}{10\omega - 12\omega} = \frac{|H(10.5\omega)| - 0}{10.5\omega - 12\omega} \tag{9}$$

$$A = |H(10.5\omega)| = \frac{3}{8}\omega$$
 and  $\theta = \angle H(10.5\omega) = 0^{\circ}$  (10)

The output y(t):

$$y(t) = \frac{3}{8}\omega \cdot 10\cos(10.5\omega t)$$
 (11)

$$=\frac{15}{4}\omega\cos(10.5\omega t)\tag{12}$$