

Srijal Poojari

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EDUCATION

SARDAR PATEL INSTITUTE OF TECHNOLOGY

BE IN ELECTRONICS

University of Mumbai
 May 2019 | Mumbai, India
 CGPA: 8.49 / 10

MVM JUNIOR COLLEGE

HIGHER SECONDARY CERTIFICATE

Maharashtra State Board
 Feb 2015 | Mumbai, India
 540/650 (83.08%)

ST. XAVIER'S HIGH SCHOOL

SECONDARY SCHOOL CERTIFICATE

Maharashtra State Board
 Mar 2013 | Mumbai, India
 501/550 (91.09%)

SKILLS

PROGRAMMING

Proficient:

Python • C • C++

Intermediate:

MATLAB • \LaTeX

Familiar:

C# • Lua • JavaScript

HARDWARE

Development Boards and SoCs:

Arduino AVR, ARM • ATmega

ESP32 • ESP8266 • Microchip dsPIC

C2000 DSP • Raspberry Pi • MSP430

Nvidia Jetson TX2, Nano

Particle Photon • Spartan V FPGA

Design and Development:

PCB Design • Power PCB Layouts

SMD Soldering (QFP, QFN) • 3D Printing

SOFTWARE

OpenCV • ROS • VRep

EAGLE • Fusion 360 • Unity

OTHER INTERESTS

RC Planes • Aviation • Electronics Salvage
 Swimming • Reading • Video Games

ACHIEVEMENTS

- **2nd Prize in Technical Paper Competition** at SPIT, Mumbai (2019)
- **3rd Prize in Innovatron'18**, an inter-college project competition held at SPIT, Mumbai, for the project "Room Occupancy Indicating System" (2018)
- **1st out of 162 teams nationwide** in e-Yantra Robotics Competition. (2016-17)
- **1st Prize in InterThrone 2017** an IoT focused contest. Award of INR 300,000 given for the automated cycle locking prototypes developed for CYKLO (2017)
- **1st Prize in Circuit Troubleshooting Competition** at SPIT, Mumbai (2016)
- **2nd out of 459 entries worldwide** in the Arduino All-The-Things Contest on Instructables, for the project of "The Companion IC" 📄 (2016)
- **1st Prize in CodeChamps**, a programming competition across all departments of SPIT, Mumbai. Language of choice used was C++ (2015)

TEACHING

2019	Teaching Assistantship: Digital Circuits	SPIT, Mumbai
2019	Teaching Assistantship: Product Design	SPIT, Mumbai
2019	IEEE Workshop on adding WiFi to your projects using ESP8266 and MQTT	SPIT, Mumbai
2019	Teaching Assistantship: Robotic Vision	SPIT, Mumbai
2018	IEEE Workshop on Introduction to Microcontrollers, Sensors and Arduino	SPIT, Mumbai
2018	Workshop on Introduction to Embedded Systems Design	SPIT, Mumbai
2016	Robocon Workshop on PCB making and basics of a robotic system	SPIT, Mumbai

WORK EXPERIENCE

SP PRODUCT DEVELOPMENT CELL | RESEARCH ASSOCIATE

July '19 onwards | SPIT, Mumbai

Work on industry consultancy projects under Dr. R. R. Sawant and Dr. Y. S. Rao. Involves development of embedded systems of different microcontroller families like dsPIC, C2000 and ATmega that usually deal with high power electronics.

DRISHTI WORKS | INTERN - ROBOTICS ENGINEER

4 Jun – 15 Jul '18 | Mumbai

Developed the sensing, power distribution and IMU system for AURUS, a beach cleaning robot. Vastly improved system reliability by creating a custom ROS nodes communication between the station (desktop) and the robot (Nvidia Jetson).

FRACTAL ANALYTICS | PROJECT INTERN

27 Nov - 26 Dec '17 | Mumbai

Developed applications using Unity (C#) on the Microsoft HoloLens Mixed Reality(MR) headsets for displaying conventional statistical results in the form of holograms.

IIT BOMBAY | SUMMER INTERN - MODULAR ROBOTS

27 Nov - 26 Dec '17 | Mumbai

Created self-reconfigurable robot modules inspired by the Dttto Robot. Developed virtual simulations of the same modules on VRep with bluetooth control.

RELEVANT PROJECTS

PROJECT ATLAS | BE FINAL YEAR PROJECT

Jul '18 - Apr '19 | Drishti Works, Mumbai

- Build of a tethered multirotor with an AUW of 10Kgs.
- Designed 140V to 32V@20A step-down converters in a small form-factor for increasing the altitude capabilities of the system. [Final Report [📄](#)]

TINYBOT | PERSONAL PROJECT

Mar - Nov '19

- Created a very small wireless remote-controlled car of the order of 10*10*10mm as a challenge to a reddit post.
- Custom designed a PCB for the power regulators and motor drivers, to be used along with the ESP8285. I believe it to be the smallest hobby-level RC car.

ROOM OCCUPANCY INDICATING SYSTEM | BE SEM VI PROJECT

Feb - Apr '18 | SPIT, Mumbai

- A network of small wireless sensors to detect human presence in a room, across multiple such rooms.
- Involved a strong focus on wireless networking, low power design, PCB design, 3D modelling and printing.

3D INDOOR MAPPING | BE SEM V PROJECT

Aug - Oct '17 | SPIT, Mumbai

- Used the Microsoft Kinect depth sensor and a Raspberry Pi running the Robot Operating System (ROS) to create a wireless 3D mapping setup.

EYANTRA ROBOTICS COMPETITION

Nov '16 - Apr '17 | IIT Bombay

- Planned and implemented the algorithms for motion planning and used OpenCV with Python for Image Processing.
- Played the role of team leader in a team of 4. [Demo Video [📺](#)]

CYKLO | STARTUP

Nov '15 - May '17 | SPIT, Mumbai

- CYKLO is a point-to-point, peer-to-peer cycle sharing service, started in 2015 at Sardar Patel Institute of Technology (SPIT), Mumbai, with me as a core part of the team.
- Designed, built and programmed several hardware prototypes for the automated cycle locking system, including the locking mechanism, electronic controller and network interface.

TRAINING

ROBOTICS: FUNDAMENTALS | UPENN X, EDX - CERTIFICATE [📄](#)

Oct 2018

Kinematics and Mathematical Foundations for describing robotic arms and mobile robots using MATLAB.

COMPUTATION STRUCTURES | MIT X, EDX - UNCERTIFIED

Sep '16 - May '17

Designed a 32-bit 'Beta' processor, ground up, from basic logic gates on the Jade simulator.

MSP-FPGA HARDWARE AND SOFTWARE CO-DESIGN | SPIT, MUMBAI

Sep 2016

Workshop on interfacing of MSP430 with an FPGA to enable parallel processing of general purpose calculations on MSP and hardware optimized tasks on FPGA for faster throughput.

EMBEDDED SYSTEMS DESIGN | SPIT, MUMBAI

Jun 2016

Workshop on introduction to various technologies in Embedded Systems with hands-on practice on development boards including Atmel AVR, ARM, Texas Instruments MSP and DSP.

ROBOCAMP(SR.) BY THINKLABS | IIT BOMBAY

Dec 2010

Basic STEM learning for school kids for an early start on autonomous robots and their control using graphical block-programming. Interfaced sensors like touch, IR and control of DC motor for robot actuation was learnt on the iPitara Robot by ThinkLABS. Participated in TRICKS 2010, IIT Bombay.