## E0123049

## **RL Experiment 5**

## Code:

```
import numpy as np
import matplotlib.pyplot as plt
from scipy.stats import beta
TRUE PROBABILITIES = [0.6, 0.4, 0.7]
NUM ARMS = len(TRUE PROBABILITIES)
NUM ROUNDS = 1000
def pull arm(arm index):
    """Simulates pulling an arm and returning a binary reward (0 or
    return 1 if np.random.rand() < TRUE PROBABILITIES[arm index] else 0</pre>
class MABAlgorithm:
    def init (self, num arms, name):
        self.num arms = num arms
        self.name = name
        self.arm counts = np.zeros(num arms)
        self.arm rewards = np.zeros(num arms)
        self.cumulative rewards = []
        self.arm selections history = []
   def select arm(self, round num):
        raise NotImplementedError
    def update(self, chosen arm, reward):
        self.arm counts[chosen arm] += 1
        self.arm rewards[chosen arm] += reward
        self.cumulative rewards.append(self.cumulative rewards[-1] +
reward if self.cumulative rewards else reward)
        self.arm selections history.append(chosen arm)
class UCB (MABAlgorithm):
    def __init__(self, num_arms, c_param=2.0):
        super(). init (num arms, "UCB")
        self.c param = c param
    def select arm(self, round num):
        if round num < self.num arms:</pre>
            return round num
```

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ucb values = np.zeros(self.num arms)
        for arm in range (self.num arms):
            if self.arm counts[arm] == 0:
                ucb values[arm] = float('inf')
                average reward = self.arm rewards[arm] /
self.arm counts[arm]
                confidence interval = self.c param *
np.sqrt(np.log(round num + 1) / self.arm counts[arm])
                ucb values[arm] = average reward + confidence interval
        return np.argmax(ucb values)
class ThompsonSampling(MABAlgorithm):
    def init (self, num arms):
        super(). init (num arms, "Thompson Sampling")
        self.alphas = np.ones(num arms)
        self.betas = np.ones(num arms)
    def select arm(self, round num):
        sampled rewards = [np.random.beta(self.alphas[arm],
self.betas[arm]) for arm in range(self.num arms)]
        return np.argmax(sampled rewards)
    def update(self, chosen arm, reward):
        super().update(chosen arm, reward)
        if reward == 1:
            self.alphas[chosen arm] += 1
        else:
            self.betas[chosen arm] += 1
def run simulation(algorithm, num rounds):
    for round num in range (num rounds):
        chosen arm = algorithm.select arm(round num)
        reward = pull arm(chosen arm)
        algorithm.update(chosen arm, reward)
    return algorithm
ucb agent = UCB(NUM ARMS)
thompson agent = ThompsonSampling(NUM ARMS)
print("Simulating UCB...")
ucb results = run simulation(ucb agent, NUM ROUNDS)
print("Simulating Thompson Sampling...")
thompson_results = run_simulation(thompson_agent, NUM_ROUNDS)
fig, axes = plt.subplots(2, 2, figsize=(16, 12))
fig.suptitle("Multi-Armed Bandit Experiment: UCB vs. Thompson
Sampling", fontsize=16)
```

```
axes[0, 0].plot(ucb results.cumulative rewards, label="UCB")
axes[0, 0].plot(thompson results.cumulative rewards, label="Thompson
Sampling")
axes[0, 0].set title("Cumulative Reward over Time")
axes[0, 0].set xlabel("Round (Student Session)")
axes[0, 0].set ylabel("Cumulative Reward")
axes[0, 0].legend()
axes[0, 0].grid(True)
arm names = ["Video Lectures (0.6)", "Interactive Quizzes (0.4)",
"Gamified Modules (0.7)"]
ucb arm selections = np.bincount(ucb results.arm selections history,
minlength=NUM ARMS)
axes[0, 1].bar(arm names, ucb arm selections, color=['skyblue',
'lightcoral', 'lightgreen'])
axes[0, 1].set title("UCB: Arm Selection Frequency")
axes[0, 1].set xlabel("Teaching Method")
axes[0, 1].set ylabel("Number of Selections")
axes[0, 1].tick params(axis='x', rotation=45)
thompson arm selections =
np.bincount(thompson results.arm selections history,
minlength=NUM ARMS)
axes[1, 0].bar(arm names, thompson arm selections, color=['skyblue',
'lightcoral', 'lightgreen'])
axes[1, 0].set title("Thompson Sampling: Arm Selection Frequency")
axes[1, 0].set xlabel("Teaching Method")
axes[1, 0].set ylabel("Number of Selections")
axes[1, 0].tick_params(axis='x', rotation=45)
x = np.linspace(0, 1, 100)
for i in range(NUM ARMS):
    axes[1, 1].axvline(TRUE PROBABILITIES[i], color=['blue', 'red',
'green'][i], linestyle='--', label=f'True Prob {arm names[i].split("
")[0]}')
    a ts = thompson results.alphas[i]
   b ts = thompson results.betas[i]
    axes[1, 1].plot(x, beta.pdf(x, a ts, b ts), color=['blue', 'red',
'green'][i], label=f'TS Posterior {arm names[i].split(" ")[0]}')
axes[1, 1].set title("Thompson Sampling: Posterior Distributions vs.
True Probabilities")
axes[1, 1].set xlabel("Probability")
axes[1, 1].set_ylabel("Probability Density")
axes[1, 1].legend()
```

```
axes[1, 1].grid(True)
plt.tight layout(rect=[0, 0.03, 1, 0.95])
plt.show()
print("\n--- Comparison ---")
print(f"True Probabilities: {TRUE PROBABILITIES}")
print("\nUCB Results:")
for i in range(NUM ARMS):
    print(f" Arm {i} ({arm names[i]}): Pulled
{ucb results.arm counts[i]} times, Avg Reward =
{ucb results.arm rewards[i] / ucb results.arm counts[i] if
ucb results.arm counts[i] > 0 else 0:.4f}")
print(f" Total Cumulative Reward (UCB):
{ucb results.cumulative rewards[-1]}")
print(f" Best Arm identified by UCB (based on highest final average
reward): Arm {np.argmax(ucb results.arm rewards /
ucb results.arm counts) }")
print("\nThompson Sampling Results:")
for i in range(NUM ARMS):
    print(f" Arm {i} ({arm names[i]}): Pulled
{thompson results.arm counts[i]} times, Avg Reward =
{thompson results.arm rewards[i] / thompson results.arm counts[i] if
thompson results.arm counts[i] > 0 else 0:.4f}")
print(f" Total Cumulative Reward (Thompson Sampling):
{thompson results.cumulative rewards[-1]}")
print(f" Best Arm identified by Thompson Sampling (based on highest
final average reward): Arm {np.argmax(thompson results.arm rewards /
thompson results.arm counts)}")
```

## **Output:**

Simulating UCB... Simulating Thompson Sampling...

Multi-Armed Bandit Experiment: UCB vs. Thompson Sampling

