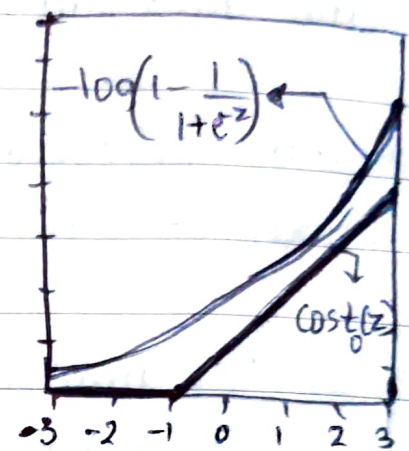
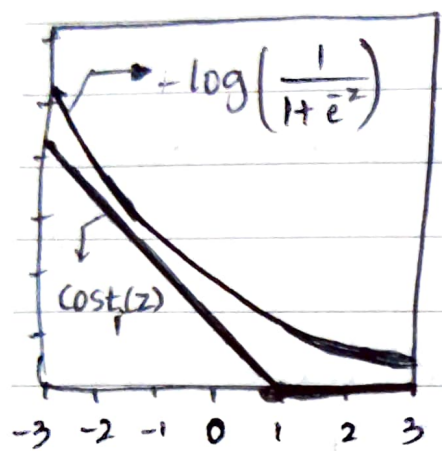


SUPPORT VECTOR MACHINE

- The objective of the support vector machine is to find a hyper plane in an N dimensional space (N - number of features) that distinctly classifies the data points.
- Our objective is to find a plane that has the maximum margin.
- If the number of features is 2, then hyperplane is just a line. If the number of features is 3, then the hyperplane is just a 2-D plane.
- Support vectors are datapoints which influence the position and orientation of hyperplane i.e. which are closer to hyperplane.

→ Cost function, which has to be minimized in LOGISTIC:

$$\min_{\theta} \frac{1}{m} \left[\sum_{i=1}^m y^{(i)} (-\log h_{\theta}(x^{(i)})) + (1-y^{(i)}) (-\log (1-h_{\theta}(x^{(i)}))) \right] + \frac{\lambda}{2m} \sum_{j=1}^n \theta_j^2$$



SUPPORT VECTOR:

$$\min_{\theta} \frac{1}{m} \left[\sum_{i=1}^m y^{(i)} \text{cost}_1(\theta^T x^{(i)}) + (1-y^{(i)}) \text{cost}_0(\theta^T x^{(i)}) \right] + \frac{\lambda}{2m} \sum_{j=1}^n \theta_j^2$$

$$\Leftrightarrow \min_{\theta} \left(\sum_{i=1}^m \left[y^{(i)} \text{cost}_1(\theta^T x^{(i)}) + (1-y^{(i)}) \text{cost}_0(\theta^T x^{(i)}) \right] + \frac{1}{2} \sum_{j=1}^n \theta_j^2 \right)$$

→ The hypothesis of SVM is straight forward,

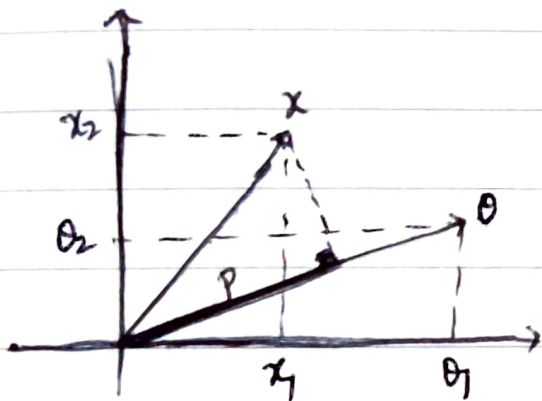
- if $\theta^T x \geq 0$; predict 1
- if $\theta^T x < 0$; predict 0

as:

$$\min_{\theta} \frac{1}{2} \sum_{j=1}^n \theta_j^2 \quad \text{where; } \theta^T x^{(i)} \geq 1 \quad \text{if } y^{(i)} = 1$$

$$\theta^T x^{(i)} \leq -1 \quad \text{if } y^{(i)} = 0.$$

UNDERSTANDING $\theta_x^{(i)}$



$$\theta^T x^{(i)} = \underbrace{p^{(i)}}_{\text{Projected length}} \underbrace{\| \theta \|}_{\text{Length of vector } \theta} = \theta(x^{(i)})^T$$

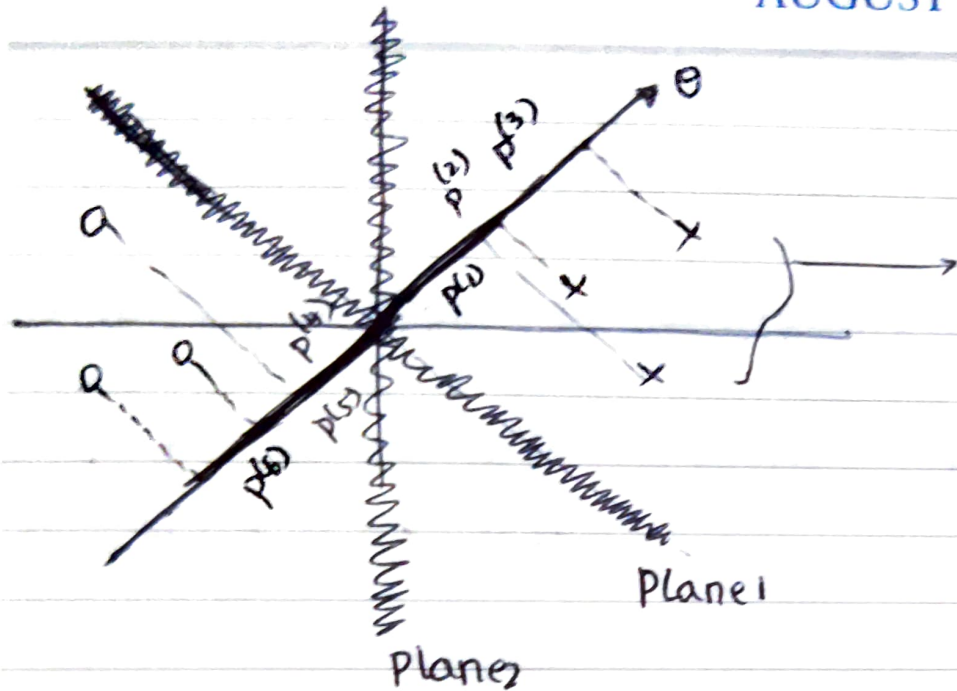
50;

For very large c .

$$\left\{ \begin{array}{l} \min_{\theta} \frac{1}{2} \sum_{j=1}^n \theta_j^2 \quad \text{where;} \\ = \frac{1}{2} ||\theta||^2 \end{array} \right.$$

UNDERSTANDING LARGE-MARGIN CLASSIFIER:

For simplicity let us take $\theta_0 = 0$.



$$p^{(i)} ||\theta|| \geq 1$$

But we will minimize $||\theta||$ so, $p^{(i)}$ should be greater so; plane 2 will be found using SVM i.e. with more margin

NAIVE BAYES

- Naive Bayes classifiers are a collection of classifiers based on Bayes's Theorem.
- The fundamental assumption is that each feature makes an:
 - Independent
 - Equalcontribution to outcome.

→ Bayes Theorem:

$$P(A|B) = \frac{P(B|A) \cdot P(A)}{P(B)}$$

→ So, wrt the dataset, we can apply Bayes's Theorem as:

$$P(y|x) = \frac{P(x|y) \cdot P(y)}{P(x)}$$

Where, y is class variable & x is dependent feature vector (of size n) where:

$$x = [x_1, x_2, x_3, \dots, x_n]$$

$$\rightarrow P(y|x_1, x_2, \dots, x_n) = \frac{P(x_1|y) \cdot P(x_2|y) \dots P(x_n|y) \cdot P(y)}{P(x_1) \cdot P(x_2) \dots P(x_n)}$$

$$= \frac{P(y) \prod_{i=1}^n P(x_i|y)}{P(x_1) \cdot P(x_2) \dots P(x_n)}$$

$$\propto P(y) \prod_{i=1}^n P(x_i|y)$$

→ In gaussian Naive Bayes, each feature is assumed to be distributed according to gaussian.

i.e.,

$$P(x_i|y) = \frac{1}{\sqrt{2\pi\sigma_y^2}} e^{-\left(\frac{(x_i - \mu_y)^2}{2\sigma_y^2}\right)}$$

→ Other Naive Bayes Classifiers are:

- 1) Multinomial Naive Bayes
- 2) Bernoulli Naive Bayes