

EE5121 Convex Optimization

CVX Assignment

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EP16B005

1 Recovering a piecewise constant signal from a noisy measurement

1.1 Formulation

The SoCP formulation of the problem is as follows

$$\begin{aligned} \min \quad & t \\ \text{s.t.} \quad & w_1 \|x - y\|_2 + w_2 \|Ax\|_1 \leq t \end{aligned}$$

w_1 and w_2 are positive weights adjusted such that $w_1 + w_2 = 1$. And A is the matrix as defined in the question.

1.2 Result

```
-----  
number of iterations   = 18  
primal objective value = 1.18238261e+01  
dual  objective value = 1.18238260e+01  
gap := trace(XZ)      = 1.02e-07  
relative gap          = 4.12e-09  
actual relative gap   = 4.11e-09  
rel. primal infeas (scaled problem) = 2.49e-11  
rel. dual    " " " " = 1.00e-12  
rel. primal infeas (unscaled problem) = 0.00e+00  
rel. dual    " " " " = 0.00e+00  
norm(X), norm(y), norm(Z) = 1.6e+01, 9.9e-01, 2.3e+00  
norm(A), norm(b), norm(C) = 4.0e+01, 1.9e+01, 2.8e+00  
Total CPU time (secs) = 0.51  
CPU time per iteration = 0.03  
termination code      = 0  
DIMACS: 1.2e-10 0.0e+00 1.5e-12 0.0e+00 4.1e-09 4.1e-09  
-----  
  
-----  
Status: Solved  
Optimal value (cvx_optval): +11.8238  
  
optimal_error =  
  
11.2061
```

Figure 1: Optimal norm of e

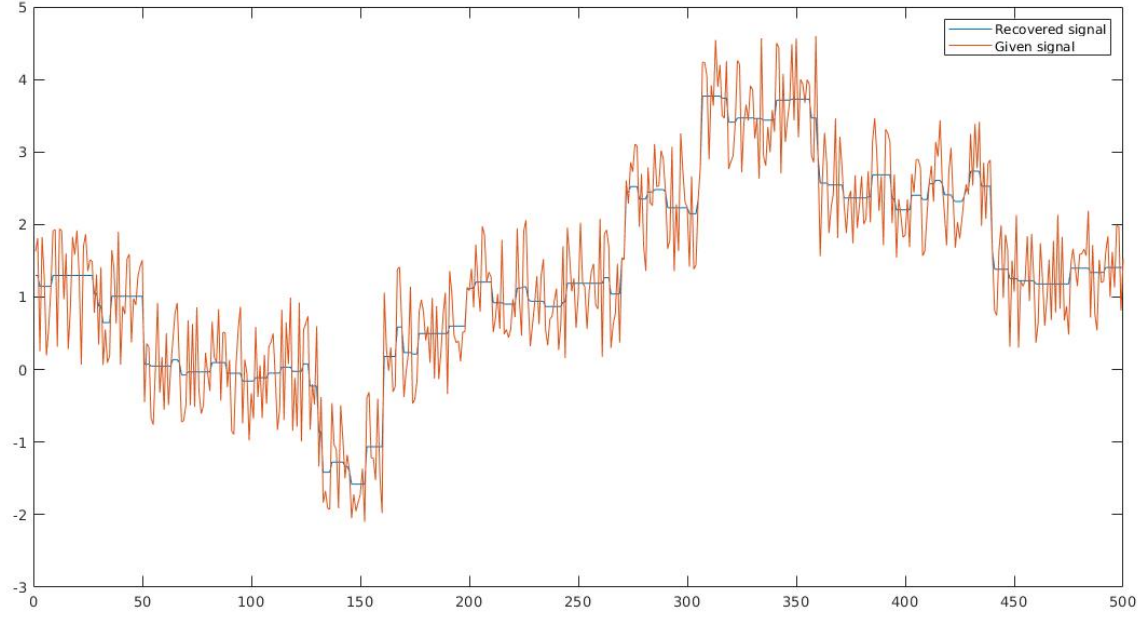


Figure 2: Given noisy signal and the recovered signal with effectively 20 jumps

2 Revenue Maximization

2.1 Formulation

Variables as used with the same name as in the question. Two additional variables, as matrices, are introduced to make the formulation compact: $P = \text{diag}(p)$, $P_{disc} = \text{diag}(p^{disc})$.

$$\begin{aligned}
 & \max \quad 1^T u \\
 & \text{s.t.} \quad Ax \leq c_{max} \\
 & \quad \quad x \geq 0 \\
 & \quad \quad Px \geq u \\
 & \quad \quad P_{disc}x + (P - P_{disc})q \geq u
 \end{aligned}$$

2.2 Result

```
-----  
Status: Solved  
Optimal value (cvx_optval): +192.5  
  
Activity_Levels =  
  
    4.0000  
   22.5000  
   31.0000  
    1.5000  
  
Revenue_of_each_activity =  
  
   12.0000  
   32.5000  
  139.0000  
    9.0000  
  
Average_price_of_each_activity =  
  
    3.0000  
    1.4444  
    4.4839  
    6.0000  
  
fx >>
```

Figure 3: Command Window

3 Matrix Completion

3.1 Formulation

The SDP formulation is as follows

$$\begin{aligned} & \min \quad r \\ \text{s.t.} \quad & \text{Trace}(Y) + \text{Trace}(Z) \leq 2r \\ & \hat{x}_{ij} = X_{ij} \text{ wherever } X_{ij} \neq 0 \\ & \begin{bmatrix} Y & X \\ X^T & Z \end{bmatrix} \geq 0 \end{aligned}$$

3.2 Result

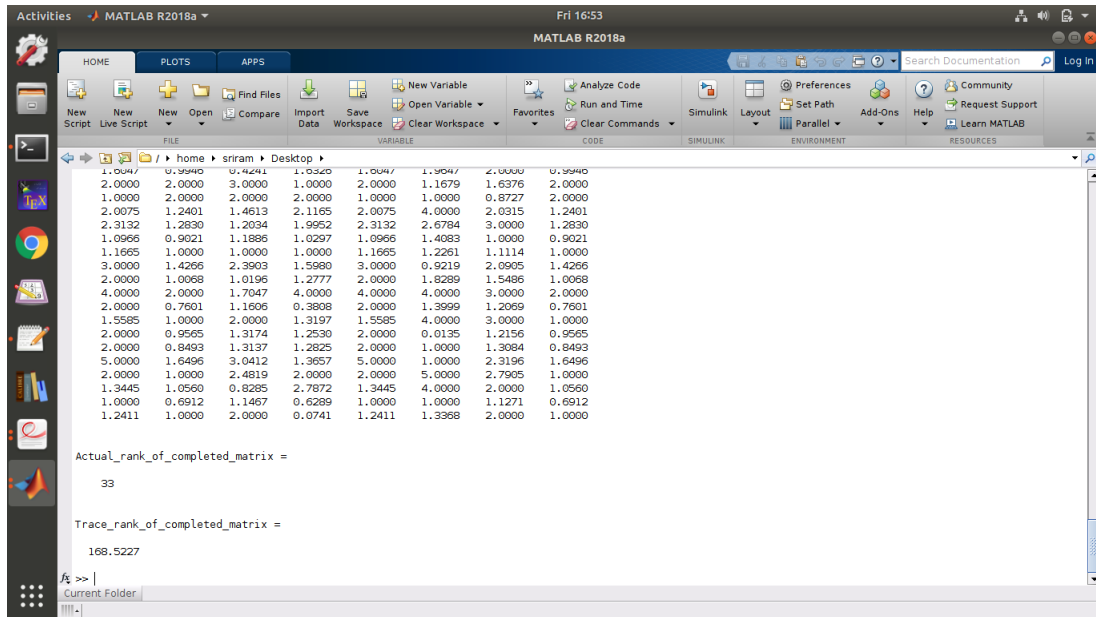


Figure 4: The trace rank of the completed matrix is 168.523