Kerr Effect

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In [2]: from math import*
                        import numpy as np
                        import matplotlib.pyplot as plt
                        import scipy.special as sp
                        from matplotlib import pylab
                        from numpy import arange,array,ones
                        from scipy import stats
                        from scipy import optimize
In [3]: U = [14,300,325,350,375,400,425,450,475,500,525,550,575,600,625,650,675,700]
                        I = [.029, .055, .060, .065, .074, .090, .110, .125, .141, .164, .169, .175, .141, .120, .086, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070, .070,
                        I_o = 0.194
                        rel_I = [(x/I_o) \text{ for } x \text{ in } I]
                        delta = [(360/np.pi)*np.arcsin(sqrt(x)) for x in rel_I]
In [4]: delta[12] = 360 - delta[12]
                        delta[13] = 360 - delta[13]
                        delta[14] = 360 - delta[14]
                        delta[15] = 360 - delta[15]
                        delta[16] = 360 + delta[16]
                        delta[17] = 360 + delta[17]
In [5]: Usqr = [u**2 \text{ for } u \text{ in } U]
In [6]: slope, intercept, r_value, p_value, std_err = stats.linregress(delta,Usqr)
In [7]: slope
Out[7]: 1007.8946121033131
In [8]: intercept
Out[8]: 76005.9884206331
In [9]: plt.plot(delta, Usqr, '.k');
                       plt.ylabel(r'$U^2$');
                        plt.xlabel(r'$\Delta$ (Degrees)');
                        fit = [(slope*x + intercept) for x in delta]
                        plt.plot(delta,fit);
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