# Lecture 5 Gram-Schmidt Orthogonalization

MIT 18.335J / 6.337J

Introduction to Numerical Methods

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# **Gram-Schmidt Projections**

 The orthogonal vectors produced by Gram-Schmidt can be written in terms of projectors

$$q_1 = \frac{P_1 a_1}{\|P_1 a_1\|}, \quad q_2 = \frac{P_2 a_2}{\|P_2 a_2\|}, \quad \dots, \quad q_n = \frac{P_n a_n}{\|P_n a_n\|}$$

where

$$P_j = I - \hat{Q}_{j-1}\hat{Q}_{j-1}^* \text{ with } \hat{Q}_{j-1} = \begin{bmatrix} q_1 & q_2 & \cdots & q_{j-1} \end{bmatrix}$$

•  $P_j$  projects orthogonally onto the space orthogonal to  $\langle q_1,\ldots,q_{j-1}\rangle$ , and  ${\rm rank}(P_j)=m-(j-1)$ 

# The Modified Gram-Schmidt Algorithm

ullet The projection  $P_j$  can equivalently be written as

$$P_j = P_{\perp q_{j-1}} \cdots P_{\perp q_2} P_{\perp q_1}$$

where (last lecture)

$$P_{\perp q} = I - qq^*$$

- $P_{\perp q}$  projects orthogonally onto the space orthogonal to q, and  ${\rm rank}(P_{\perp q})=m-1$
- The Classical Gram-Schmidt algorithm computes an orthogonal vector by

$$v_j = P_j a_j$$

while the Modified Gram-Schmidt algorithm uses

$$v_j = P_{\perp q_{j-1}} \cdots P_{\perp q_2} P_{\perp q_1} a_j$$

## Classical vs. Modified Gram-Schmidt

- Small modification of classical G-S gives modified G-S (but see next slide)
- Modified G-S is numerically stable (less sensitive to rounding errors)

## Classical/Modified Gram-Schmidt

$$\begin{aligned} &\text{for } j = 1 \text{ to } n \\ &v_j = a_j \\ &\text{for } i = 1 \text{ to } j - 1 \\ &\left\{ \begin{array}{l} r_{ij} = q_i^* a_j & \text{(CGS)} \\ r_{ij} = q_i^* v_j & \text{(MGS)} \\ \end{array} \right. \\ &v_j = v_j - r_{ij} q_i \\ &r_{jj} = \|v_j\|_2 \\ &q_j = v_j / r_{jj} \end{aligned}$$

# Implementation of Modified Gram-Schmidt

- In modified G-S,  $P_{\perp q_i}$  can be applied to all  $v_j$  as soon as  $q_i$  is known
- Makes the inner loop iterations independent (like in classical G-S)

## **Classical Gram-Schmidt**

for 
$$j=1$$
 to  $n$  
$$v_j=a_j$$
 for  $i=1$  to  $j-1$  
$$r_{ij}=q_i^*a_j$$
 
$$v_j=v_j-r_{ij}q_i$$
 
$$r_{jj}=\|v_j\|_2$$
 
$$q_j=v_j/r_{jj}$$

## **Modified Gram-Schmidt**

for 
$$i=1$$
 to  $n$  
$$v_i=a_i$$
 for  $i=1$  to  $n$  
$$r_{ii}=\|v_i\|$$
 
$$q_i=v_i/r_{ii}$$
 for  $j=i+1$  to  $n$  
$$r_{ij}=q_i^*v_j$$
 
$$v_j=v_j-r_{ij}q_i$$

# **Example: Classical vs. Modified Gram-Schmidt**

Compare classical and modified G-S for the vectors

$$a_1=(1,\epsilon,0,0)^T,\quad a_2=(1,0,\epsilon,0)^T,\quad a_3=(1,0,0,\epsilon)^T$$
 making the approximation  $1+\epsilon^2\approx 1$ 

#### Classical:

$$v_{1} \leftarrow (1, \epsilon, 0, 0)^{T}, \quad r_{11} = \sqrt{1 + \epsilon^{2}} \approx 1, \quad q_{1} = v_{1}/1 = (1, \epsilon, 0, 0)^{T}$$

$$v_{2} \leftarrow (1, 0, \epsilon, 0)^{T}, \quad r_{12} = q_{1}^{T} a_{2} = 1, \quad v_{2} \leftarrow v_{2} - 1q_{1} = (0, -\epsilon, \epsilon, 0)^{T}$$

$$r_{22} = \sqrt{2}\epsilon, \quad q_{2} = v_{2}/r_{22} = (0, -1, 1, 0)^{T}/\sqrt{2}$$

$$v_{3} \leftarrow (1, 0, 0, \epsilon)^{T}, \quad r_{13} = q_{1}^{T} a_{3} = 1, \quad v_{3} \leftarrow v_{3} - 1q_{1} = (0, -\epsilon, 0, \epsilon)^{T}$$

$$r_{23} = q_{2}^{T} a_{3} = 0, \quad v_{3} \leftarrow v_{3} - 0q_{2} = (0, -\epsilon, 0, \epsilon)^{T}$$

$$r_{33} = \sqrt{2}\epsilon, \quad q_{3} = v_{3}/r_{33} = (0, -1, 0, 1)^{T}/\sqrt{2}$$

# **Example: Classical vs. Modified Gram-Schmidt**

#### Modified:

$$v_{1} \leftarrow (1, \epsilon, 0, 0)^{T}, \quad r_{11} = \sqrt{1 + \epsilon^{2}} \approx 1, \quad q_{1} = v_{1}/1 = (1, \epsilon, 0, 0)^{T}$$

$$v_{2} \leftarrow (1, 0, \epsilon, 0)^{T}, \quad r_{12} = q_{1}^{T} v_{2} = 1, \quad v_{2} \leftarrow v_{2} - 1q_{1} = (0, -\epsilon, \epsilon, 0)^{T}$$

$$r_{22} = \sqrt{2}\epsilon, \quad q_{2} = v_{2}/r_{22} = (0, -1, 1, 0)^{T}/\sqrt{2}$$

$$v_{3} \leftarrow (1, 0, 0, \epsilon)^{T}, \quad r_{13} = q_{1}^{T} v_{3} = 1, \quad v_{3} \leftarrow v_{3} - 1q_{1} = (0, -\epsilon, 0, \epsilon)^{T}$$

$$r_{23} = q_{2}^{T} v_{3} = \epsilon/\sqrt{2}, \quad v_{3} \leftarrow v_{3} - r_{23}q_{2} = (0, -\epsilon/2, -\epsilon/2, \epsilon)^{T}$$

$$r_{33} = \sqrt{6}\epsilon/2, \quad q_{3} = v_{3}/r_{33} = (0, -1, -1, 2)^{T}/\sqrt{6}$$

## Check Orthogonality:

- Classical:  $q_2^T q_3 = (0, -1, 1, 0)(0, -1, 0, 1)^T/2 = 1/2$
- Modified:  $q_2^T q_3 = (0, -1, 1, 0)(0, -1, -1, 2)^T / \sqrt{12} = 0$

## **Operation Count**

- Count number of floating points operations "flops" in an algorithm
- Each +, -, \*, /, or  $\sqrt{\phantom{a}}$  counts as one flop
- No distinction between real and complex
- No consideration of memory accesses or other performance aspects

# **Operation Count - Modified G-S**

• Example: Count all +, -, \*, / in the Modified Gram-Schmidt algorithm (not just the leading term)

(1) for 
$$i=1$$
 to  $n$ 

$$(2) v_i = a_i$$

(3) for 
$$i=1$$
 to  $n$ 

$$(4) r_{ii} = ||v_i||$$

$$(5) q_i = v_i/r_{ii}$$

(6) for 
$$j = i + 1$$
 to  $n$ 

$$(7) r_{ij} = q_i^* v_j$$

$$(8) v_j = v_j - r_{ij}q_i$$

m multiplications, m-1 additions m divisions

m multiplications, m-1 additions m multiplications, m subtractions

## **Operation Count - Modified G-S**

The total for each operation is

$$\#A = \sum_{i=1}^{n} \left( m - 1 + \sum_{j=i+1}^{n} m - 1 \right) = n(m-1) + \sum_{i=1}^{n} (m-1)(n-i) =$$

$$= n(m-1) + \frac{n(n-1)(m-1)}{2} = \frac{1}{2}n(n+1)(m-1)$$

$$\#S = \sum_{i=1}^{n} \sum_{j=i+1}^{n} m = \sum_{i=1}^{n} m(n-i) = \frac{1}{2}mn(n-1)$$

$$\#M = \sum_{i=1}^{n} \left( m + \sum_{j=i+1}^{n} 2m \right) = mn + \sum_{i=1}^{n} 2m(n-i) =$$

$$= mn + \frac{2mn(n-1)}{2} = mn^{2}$$

$$\#D = \sum_{i=1}^{n} m = mn$$

# **Operation Count - Modified G-S**

and the total flop count is

$$\frac{1}{2}n(n+1)(m-1) + \frac{1}{2}mn(n-1) + mn^2 + mn =$$

$$2mn^2 + mn - \frac{1}{2}n^2 - \frac{1}{2}n \sim 2mn^2$$

- The symbol  $\sim$  indicates asymptotic value as  $m,n\to\infty$  (leading term)
- Easier to find just the leading term:
  - Most work done in lines (7) and (8), with 4m flops per iteration
  - Including the loops, the total becomes

$$\sum_{i=1}^{n} \sum_{j=i+1}^{n} 4m = 4m \sum_{i=1}^{n} (n-i) \sim 4m \sum_{i=1}^{n} i = 2mn^{2}$$

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