# Operation FractureScope: Dataset Preparation and Model Architecture

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# 1 Proposed Dataset Preparation and Model Architecture

### 1.1 Dataset Collection and Organization

To construct a comprehensive multi-modal surface defect dataset, we aggregated samples from three publicly available datasets:

- NEU Surface Defect Dataset (NEU-DET) Provides various steel defect images.
- SDNET2018 Contains concrete crack images from decks, pavements, and walls.
- Severstal Steel Defect Dataset Includes steel surface defect images with annotated classes.

We focused on curating three defect classes:

- 1. Crack: Sourced from SDNET's cracked subfolders (Decks, Pavements, Walls).
- 2. **Corrosion**: Extracted from NEU dataset's *pitted\_surface* and *rolled-in\_scale* categories.
- 3. **Scratch**: Gathered from NEU dataset's *scratches* category and Severstal ClassId=4 (Scratch).

The collected dataset was organized into class-specific folders. The final image counts per class are summarized in Table 1.

Table 1: Summary of collected dataset images.

Class	Number of Images
Crack	8,487
Corrosion	483
Scratch	243

## 1.2 Multi-modal Image Generation

To simulate multi-modal inputs akin to drone-based inspections, three modalities were generated for each image:

- 1. **Original** (RGB image)
- 2. Grayscale (single-channel intensity image)
- 3. **Simulated Thermal** (pseudo-color image using *COLORMAP\_JET*)

An example visualization of generated modalities is shown in Figure 1.

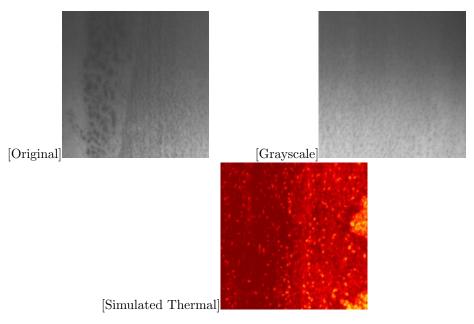


Figure 1: Example of generated modalities: (a) Original, (b) Grayscale, (c) Simulated Thermal.

### 1.3 Train-Validation Split

For robust model evaluation, an 80:20 stratified train-validation split was applied to each class and modality. The resulting dataset sizes are shown in Table 2.

Table 2: Train and Validation sample distribution.

Split	Train Samples	Validation Samples
Overall	27,384	13,566

#### 1.4 Model Architecture: FractureNet

A custom deep learning classifier named **FractureNet** was proposed. The architecture is based on a ResNet18 backbone, with modifications:

- The first convolutional layer was modified to accept 3-channel images (standard RGB or modality composites).
- The final fully connected layer was modified to output logits for 3 classes (crack, corrosion, scratch).

#### 1.5 Dataset Loader and Transformations

To prepare the dataset for training, standard preprocessing and data augmentation steps were applied:

- Images were resized to  $224 \times 224$  resolution.
- Normalization was applied using ImageNet mean and standard deviation.

The dataset loader pipeline was implemented using PyTorch's Dataset and DataLoader classes. The core implementation code is shown in Listing 1.

Listing 1: FractureDataset class implementation

```
class FractureDataset(Dataset):
   def __init__(self, data_dir, classes, modalities, transform=None):
       self.data_dir = data_dir
       self.classes = classes
       self.modalities = modalities
       self.transform = transform
       self.image_paths = []
       self.labels = []
       for idx, cls in enumerate(classes):
          cls_dir = os.path.join(data_dir, cls)
          for modality in modalities:
              modality_dir = os.path.join(cls_dir, modality)
              for fname in os.listdir(modality_dir):
                  self.image_paths.append(os.path.join(modality_dir,
                      fname))
                  self.labels.append(idx)
   def __len__(self):
      return len(self.image_paths)
   def __getitem__(self, idx):
       img_path = self.image_paths[idx]
       img = Image.open(img_path).convert('RGB')
       if self.transform:
```

```
img = self.transform(img)

label = self.labels[idx]
return img, label
```

The data loaders were configured with a batch size of 16 and appropriate shuffling for training:

Listing 2: Train and Validation Data Loader setup

```
train_loader = DataLoader(train_dataset, batch_size=16, shuffle=True)
val_loader = DataLoader(val_dataset, batch_size=16, shuffle=False)
```