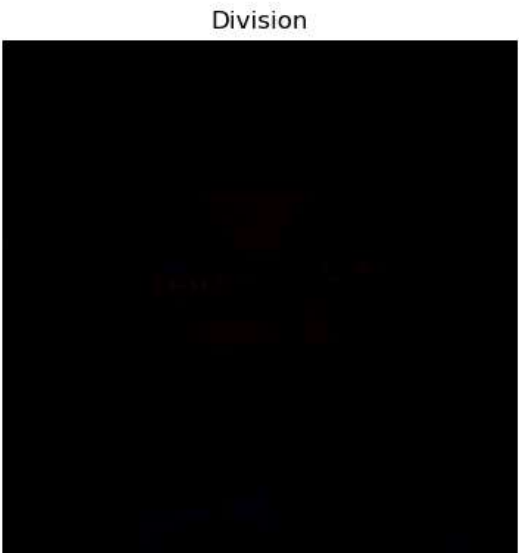
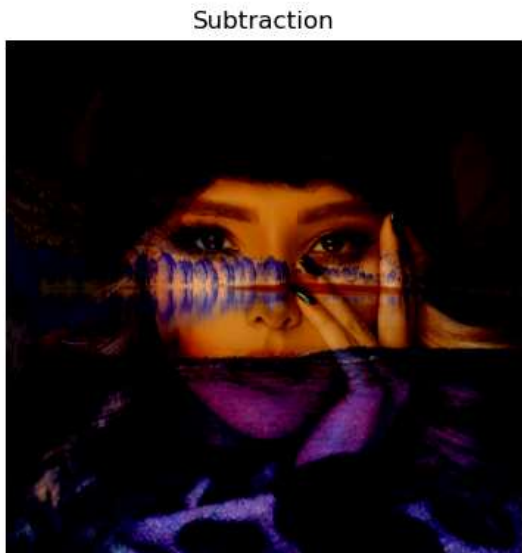
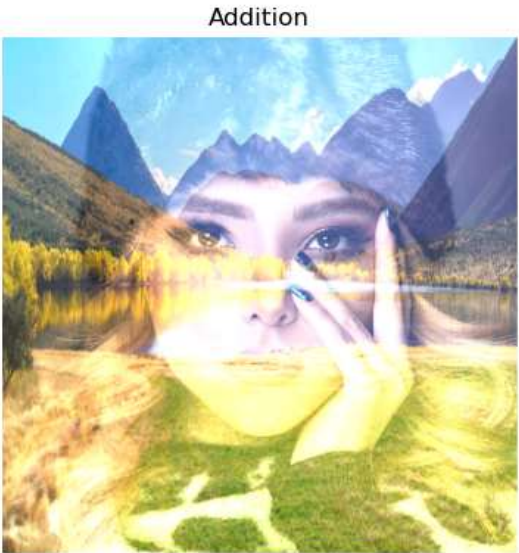
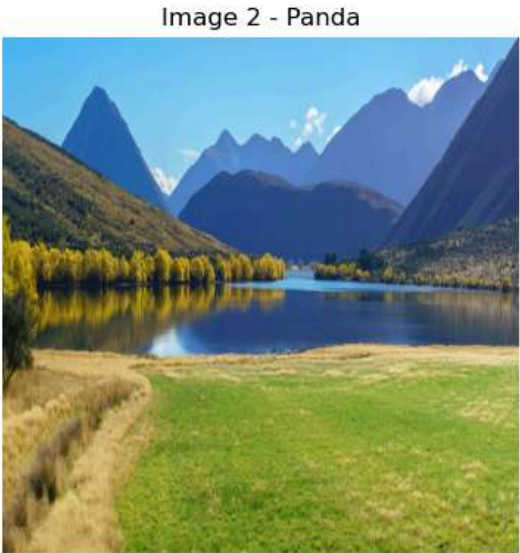
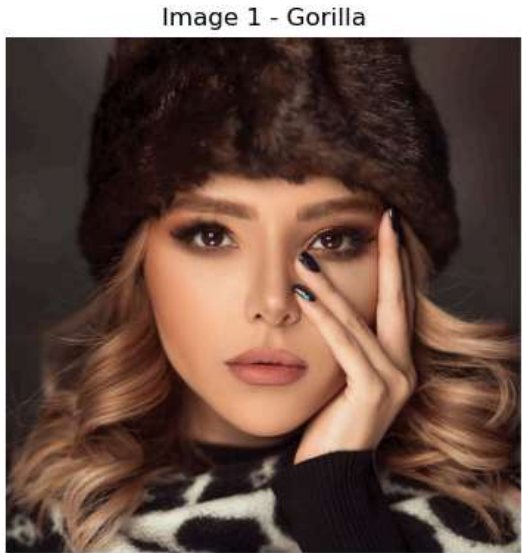


In [4]:

```
1 import cv2
2 import numpy as np
3 import matplotlib.pyplot as plt
4
5 img1 = cv2.imread("girl1.jpg")
6
7 img2 = cv2.imread("scene.jpg")
8
9 img2 = cv2.resize(img2, (img1.shape[1], img1.shape[0]))
10
11 add = cv2.add(img1, img2)
12 sub = cv2.subtract(img1, img2)
13 mul = cv2.multiply(img1, img2)
14 div = cv2.divide(img1, img2)
15
16 rows, cols = img1.shape[:2]
17 M_trans = np.float32([[1, 0, 100], [0, 1, 50]])
18 translation = cv2.warpAffine(img1, M_trans, (cols, rows))
19
20 M_rot = cv2.getRotationMatrix2D((cols / 2, rows / 2), 90, 1)
21 rotation = cv2.warpAffine(img1, M_rot, (cols, rows))
22
23 transform_images = [translation, rotation]
24 transform_titles = ['Translation', 'Rotation 90°']
25
26 def convert_bgr_to_rgb(img):
27     return cv2.cvtColor(img, cv2.COLOR_BGR2RGB)
28
29 images = [img1, img2, add, sub, mul, div]
30 titles = ['Image 1 - Gorilla', 'Image 2 - Panda', 'Addition', 'Subtraction', 'Multiplication', 'Division']
31
32 # Plot the images
33 plt.figure(figsize=(18, 10))
34 for i, (img, title) in enumerate(zip(images, titles)):
35     plt.subplot(2, 3, i+1)
36     plt.imshow(convert_bgr_to_rgb(img))
37     plt.title(title)
38     plt.axis('off')
39
```



In [7]:

```
1 import cv2
2 import matplotlib.pyplot as plt
3
4 img = cv2.imread("scene.jpg")
5
6 mean = cv2.blur(img, (5, 5))
7 gaussian = cv2.GaussianBlur(img, (5, 5), 0)
8 median = cv2.medianBlur(img, 5)
9 bilateral = cv2.bilateralFilter(img, 9, 75, 75)
10
11 images = [img, mean, gaussian, median, bilateral]
12 titles = ['original', 'mean', 'gaussian', 'median', 'bilateral']
13
14 plt.figure(figsize=(12, 6))
15 for i in range(5):
16     plt.subplot(1, 5, i + 1)
17     plt.imshow(cv2.cvtColor(images[i], cv2.COLOR_BGR2RGB))
18     plt.title(titles[i])
19     plt.axis('off')
20
21 plt.tight_layout()
22 plt.show()
23
```

original



mean



gaussian



median



bilateral



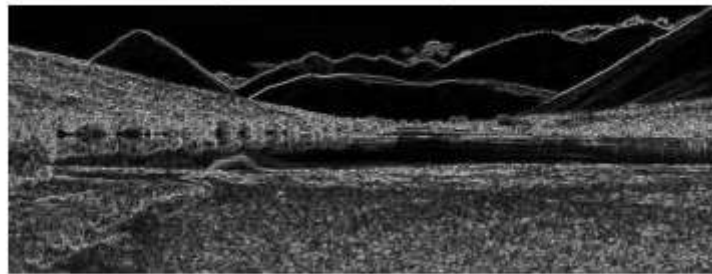
In [8]:

```
1 import cv2
2 import numpy as np
3 import matplotlib.pyplot as plt
4
5 # Load the image in grayscale
6 image = cv2.imread("scene.jpg", cv2.IMREAD_GRAYSCALE)
7
8 # Apply Sobel operator in x and y directions
9 sobel_x = cv2.Sobel(image, cv2.CV_64F, 1, 0, ksize=3)
10 sobel_y = cv2.Sobel(image, cv2.CV_64F, 0, 1, ksize=3)
11
12 # Calculate gradient magnitude
13 sobel_magnitude = np.uint8(np.absolute(cv2.magnitude(sobel_x, sobel_y)))
14
15 # Sharpen image by adding edge magnitude to original
16 sharp_image = cv2.add(image, sobel_magnitude)
17
18 # Plotting the results
19 plt.figure(figsize=(10, 10))
20
21 plt.subplot(1, 2, 1)
22 plt.imshow(image, cmap='gray')
23 plt.title("Original Image")
24 plt.axis('off')
25
26 plt.subplot(1, 2, 2)
27 plt.imshow(sobel_magnitude, cmap='gray')
28 plt.title("Edge Detection (Sobel)")
29 plt.axis('off')
30
31 plt.figure(figsize=(6, 6))
32 plt.imshow(sharp_image, cmap='gray')
33 plt.title("Sharpened Image")
34 plt.axis('off')
35
36 plt.show()
37
```

Original Image



Edge Detection (Sobel)



Sharpened Image



In [9]:

```
1 import cv2
2 import numpy as np
3 import matplotlib.pyplot as plt
4
5 # Load the image in grayscale
6 image = cv2.imread("girl1.jpg", cv2.IMREAD_GRAYSCALE)
7
8 # Apply Gaussian blur before Canny to reduce noise
9 edges = cv2.Canny(cv2.GaussianBlur(image, (5, 5), 1.5), 50, 150)
10
11 # Plot original and edge-detected images
12 plt.subplot(1, 2, 1)
13 plt.imshow(image, cmap='gray')
14 plt.title('Original')
15 plt.axis('off')
16
17 plt.subplot(1, 2, 2)
18 plt.imshow(edges, cmap='gray')
19 plt.title('Canny Edges')
20 plt.axis('off')
21
22 plt.show()
23
```



In [13]:

```
1 import cv2
2 import numpy as np
3 import matplotlib.pyplot as plt
4 image = cv2.imread("girl1.jpg", cv2.IMREAD_GRAYSCALE)
5 equalized = cv2.equalizeHist(image)
6 stretched = np.uint8(((image - np.min(image)) * 255) / (np.max(image) - np.min(image)))
7 for i, (img, title) in enumerate([...]):
8     plt.subplot(2, 3, 2*i + 1)
9     plt.imshow(img, cmap='gray')
10     ...
11     plt.subplot(2, 3, 2*i + 2)
12     plt.hist(img.ravel(), bins=256, range=(0, 256))
13
```

TypeError Traceback (most recent call last)
Cell In[13], line 7
 5 equalized = cv2.equalizeHist(image)
 6 stretched = np.uint8(((image - np.min(image)) * 255) / (np.max(image) - np.min(image)))
----> 7 for i, (img, title) in enumerate([...]):
 8 plt.subplot(2, 3, 2*i + 1)
 9 plt.imshow(img, cmap='gray')

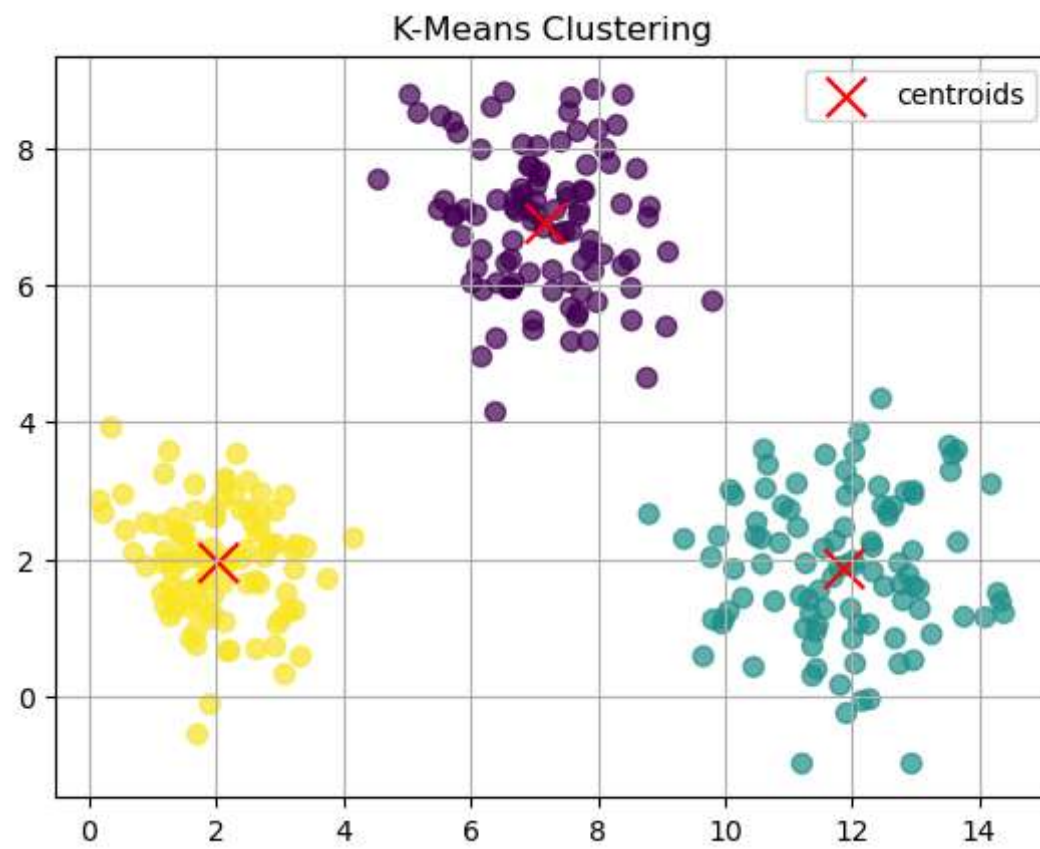
TypeError: cannot unpack non-iterable ellipsis object

In [20]:

```
1 import cv2
2 import numpy as np
3 import matplotlib.pyplot as plt
4 from sklearn.cluster import KMeans
5 X = np.vstack([
6     np.random.normal(loc=[2, 2], scale=0.8, size=(100, 2)),
7     np.random.normal(loc=[7, 7], scale=1.0, size=(100, 2)),
8     np.random.normal(loc=[12, 2], scale=1.2, size=(100, 2))
9 ])
10 kmeans = KMeans(n_clusters=3, random_state=0).fit(X)
11 plt.scatter(X[:, 0], X[:, 1], c=kmeans.labels_, cmap='viridis', s=50, alpha=0.7)
12 plt.scatter(kmeans.cluster_centers_[0, 0], kmeans.cluster_centers_[0, 1], c='red', marker='x', s=200, label="centroids")
13
14 plt.title('K-Means Clustering')
15 plt.legend()
16 plt.grid(True)
17 plt.show()
```

E:\Anaconda3\envs\tensorflow\Lib\site-packages\sklearn\cluster_kmeans.py:1412: FutureWarning: The default value of `n_init` will change from 10 to 'auto' in 1.4. Set the value of `n_init` explicitly to suppress the warning
super()._check_params_vs_input(X, default_n_init=10)

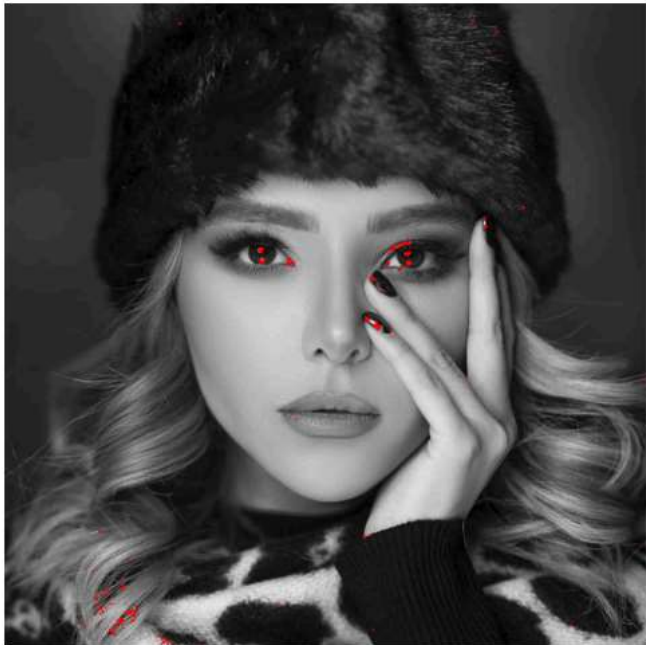
E:\Anaconda3\envs\tensorflow\Lib\site-packages\sklearn\cluster_kmeans.py:1436: UserWarning: KMeans is known to have a memory leak on Windows with MKL, when there are less chunks than available threads. You can avoid it by setting the environment variable OMP_NUM_THREADS=2.
warnings.warn(



In [21]:

```
1 import cv2
2 import numpy as np
3 import matplotlib.pyplot as plt
4
5 # Load image in grayscale
6 image = cv2.imread("girl1.jpg", cv2.IMREAD_GRAYSCALE)
7
8 # Harris Corner Detection
9 harris = cv2.cornerHarris(image, 2, 3, 0.04)
10 harris = cv2.dilate(harris, None)
11 image_harris = cv2.cvtColor(image, cv2.COLOR_GRAY2BGR)
12 image_harris[harris > 0.01 * harris.max()] = [0, 0, 255]
13
14 # SIFT Feature Detection
15 sift = cv2.SIFT_create()
16 kp_sift, des_sift = sift.detectAndCompute(image, None)
17 image_sift = cv2.drawKeypoints(image, kp_sift, None)
18
19 # ORB Feature Detection
20 orb = cv2.ORB_create()
21 kp_orb, des_orb = orb.detectAndCompute(image, None)
22 image_orb = cv2.drawKeypoints(image, kp_orb, None)
23
24 # Combine images and titles
25 images = [image_harris, image_sift, image_orb]
26 titles = ['Harris Corner', 'SIFT Features', 'ORB Features']
27
28 # Plot results
29 plt.figure(figsize=(15, 8))
30 for i, (img, title) in enumerate(zip(images, titles), 1):
31     plt.subplot(1, 3, i)
32     plt.imshow(cv2.cvtColor(img, cv2.COLOR_BGR2RGB))
33     plt.title(title)
34     plt.axis('off')
35
36 plt.tight_layout()
37 plt.show()
38
39 # Print number of keypoints
40 print(f"SIFT Keypoints: {len(kp_sift)} | ORB Keypoints: {len(kp_orb)}")
41
```

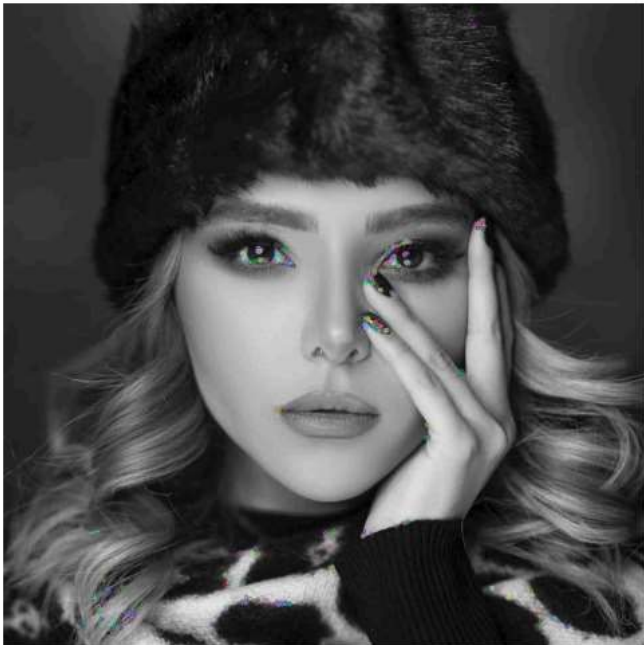
Harris Corner



SIFT Features



ORB Features



SIFT Keypoints: 2016 | ORB Keypoints: 500

In [22]:

```
1 import cv2
2 import matplotlib.pyplot as plt
3
4 # Load image in grayscale
5 image = cv2.imread("scene.jpg", cv2.IMREAD_GRAYSCALE)
6
7 # Apply various thresholding techniques
8 global_thresh = cv2.threshold(image, 127, 255, cv2.THRESH_BINARY)[1]
9 adaptive_thresh = cv2.adaptiveThreshold(image, 255, cv2.ADAPTIVE_THRESH_MEAN_C,
10                                       cv2.THRESH_BINARY, 11, 2)
11 otsu_thresh = cv2.threshold(image, 0, 255, cv2.THRESH_BINARY + cv2.THRESH_OTSU)[1]
12 inverse_thresh = cv2.threshold(image, 127, 255, cv2.THRESH_BINARY_INV)[1]
13
14 # Titles and images for display
15 titles = ['Global Thresholding', 'Adaptive Thresholding', "Otsu's Thresholding", 'Inverse Thresholding']
16 images = [global_thresh, adaptive_thresh, otsu_thresh, inverse_thresh]
17
18 # Display the images
19 plt.figure(figsize=(12, 8))
20 for i, (title, img) in enumerate(zip(titles, images)):
21     plt.subplot(2, 3, i + 1)
22     plt.imshow(img, cmap='gray')
23     plt.title(title)
24     plt.axis('off')
25
26 plt.tight_layout()
27 plt.show()
28
```

Global Thresholding



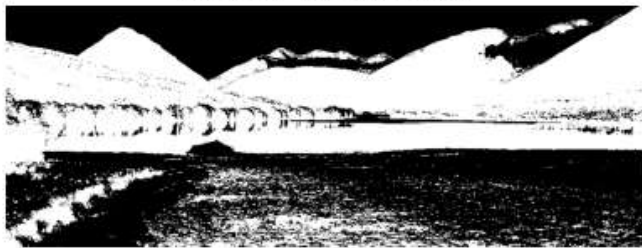
Adaptive Thresholding



Otsu's Thresholding



Inverse Thresholding



In [23]:

```
1 import cv2
2 import numpy as np
3 from sklearn.neighbors import KNeighborsClassifier
4 import matplotlib.pyplot as plt
5
6 # Load grayscale image
7 image = cv2.imread("girl1.jpg", cv2.IMREAD_GRAYSCALE)
8
9 # Create a second image filled with zeros, same shape as the original
10 image2 = np.zeros_like(image)
11
12 # Flatten both images and use them as features
13 X = np.array([image.flatten(), image2.flatten()])
14 y = [0, 1] # Labels for classification
15
16 # Initialize and train the K-Nearest Neighbors classifier
17 knn = KNeighborsClassifier(n_neighbors=1)
18 knn.fit(X, y)
19
20 # Predict the class of the input image
21 y_pred = knn.predict([image.flatten()])
22
23 # Display the image with predicted class
24 plt.imshow(image, cmap='gray')
25 plt.title(f'Predicted Class: {y_pred[0]}')
26 plt.axis('off')
27 plt.show()
28
```

Predicted Class: 0



In [25]:

```
1 import cv2
2 import numpy as np
3 import matplotlib.pyplot as plt
4
5 img_local = cv2.imread("scene.jpg")
6
7 gray_local = cv2.cvtColor(img_local, cv2.COLOR_BGR2GRAY)
8 kernel = np.ones((5, 5), np.float32) / 25
9 local_corr = cv2.filter2D(gray_local, -1, kernel)
10
11 images = [gray_local, local_corr]
12 titles = ['Original Grayscale Image', 'Local Correlation Image']
13 cmaps = ['gray', 'inferno']
14
15 plt.figure(figsize=(12, 6))
16 for i, (img, title, cmap) in enumerate(zip(images, titles, cmaps), 1):
17     plt.subplot(1, 2, i)
18     plt.imshow(img, cmap=cmap)
19     plt.title(title)
20     plt.axis('off')
21
22 plt.suptitle('Original vs Local Correlation', fontsize=16)
23 plt.tight_layout()
24 plt.show()
25
```

Original vs Local Correlation



In []:

1	
---	--