

EE6506 - COMPUTATIONAL ELECTROMAGNETICS

ASSIGNMENT - 1

- SRIVENKAT A

EE18B038

I, Srivenkat A, state that the submitted work is my original work.
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1) a) Green's 1st identity:
$$\oint_S \phi \frac{\partial \psi}{\partial n} ds = \int_V \phi \nabla^2 \psi dV + \int_V \nabla \phi \cdot \nabla \psi dV$$

proof:

V : volume of a bound region with surface S .

at any point on S , define outward normal: \hat{n} $(\because \hat{n} \cdot \hat{t} = 0)$.
tangent to surface: \hat{t}

$\therefore \nabla = \frac{\partial}{\partial n} \hat{n} + \frac{\partial}{\partial t} \hat{t}$: del operator

LHS = $\oint_S \phi \frac{\partial \psi}{\partial n} ds = \oint_S \phi \left(\frac{\partial \psi}{\partial n} \hat{n} \cdot d\hat{s} \right)$

$d\hat{s}$: small area element = $ds \hat{n}$. $\therefore \frac{\partial \psi}{\partial n} \hat{n} \cdot d\hat{s} = \left(\frac{\partial \psi}{\partial n} \hat{n} + \frac{\partial \psi}{\partial t} \hat{t} \right) \cdot d\hat{s}$

as the 2nd dot product gives 0.

$$\text{LHS} = \oint_S \phi \frac{\partial \psi}{\partial n} \hat{n} \cdot d\hat{s} = \oint_S (\phi \nabla \psi) \cdot d\hat{s}$$

from Gauss' Divergence theorem, $\oint_S \vec{A} \cdot d\hat{s} = \int_V (\nabla \cdot \vec{A}) dV$

for any vector field \vec{A} . V : vol. enclosed by S .

here, the vector field $\vec{A} \triangleq \phi \nabla \psi$

$$\therefore \oint_S (\phi \nabla \psi) \cdot d\hat{s} = \int_V \nabla \cdot (\phi \nabla \psi) dV$$

from std. theorems of vector calculus,

$$\rightarrow \nabla \cdot (\phi \vec{A}) = \phi (\nabla \cdot \vec{A}) + \vec{A} \cdot \nabla \phi \quad \text{for a vector field } \vec{A}$$

here, $\vec{A} \triangleq \nabla \psi$. $\therefore \nabla \cdot (\phi \nabla \psi) = \phi (\nabla \cdot \nabla \psi) + (\nabla \psi) \cdot (\nabla \phi)$

$$\rightarrow \nabla \cdot (\nabla \psi) = \nabla^2 \psi, \text{ by defn. of scalar Laplacian operator.}$$

$$\therefore \int_V \nabla \cdot (\phi \nabla \psi) dV = \int_V [\phi \nabla^2 \psi + (\nabla \phi) \cdot (\nabla \psi)] dV$$

= RHS

$$\therefore \oint_S \phi \frac{\partial \psi}{\partial n} ds = \int_V (\phi \nabla^2 \psi) dV + \int_V (\nabla \phi) \cdot (\nabla \psi) dV \quad \text{proved}$$

b) Green's 2nd identity: $\oint_S \left(\phi \frac{\partial \psi}{\partial n} - \psi \frac{\partial \phi}{\partial n} \right) ds = \int_V (\phi \nabla^2 \psi - \psi \nabla^2 \phi) dV$

proof: as a corollary of the 1st identity,

$$\oint_S \phi \frac{\partial \psi}{\partial n} ds = \int_V [\phi \nabla^2 \psi + (\nabla \phi \cdot \nabla \psi)] dV.$$

$$\oint_S \psi \frac{\partial \phi}{\partial n} ds = \int_V [\psi \nabla^2 \phi + (\nabla \psi \cdot \nabla \phi)] dV.$$

on subtracting the above two eqns.,

$$\oint_S \left(\phi \frac{\partial \psi}{\partial n} - \psi \frac{\partial \phi}{\partial n} \right) ds = \int_V (\phi \nabla^2 \psi - \psi \nabla^2 \phi) dV \quad \text{proved}$$

2) given conditions about the medium: source-free, homogeneous, isotropic & linear.

$$\therefore \rho_e = 0 \text{ all through the medium.} \quad (\text{source free})$$

$$\epsilon : \text{constant all through the medium} \quad (\text{isotropic})$$

$$\therefore \text{as } \nabla \cdot \bar{D} = \rho_e, \quad \epsilon \nabla \cdot \bar{E} = 0. \quad \therefore \nabla \cdot \bar{E} = 0.$$

$$\bar{E} = [\alpha(x+y) \hat{x} + \beta(x-y) \hat{y}] \sin(\omega t).$$

$$\nabla = \frac{\partial}{\partial x} \hat{x} + \frac{\partial}{\partial y} \hat{y} + \frac{\partial}{\partial z} \hat{z}$$

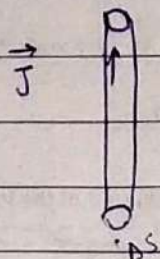
$$\therefore \nabla \cdot \bar{E} = \alpha \frac{\partial}{\partial x} (x+y) + \beta \frac{\partial}{\partial y} (x-y) = 0.$$

$$\therefore \alpha \cdot 1 + \beta(-1) = 0$$

$$\therefore \underline{\underline{\alpha = \beta}} : \text{reln. between } \alpha \text{ \& } \beta$$

for $\alpha = \beta$, even $\nabla \times \bar{E} = 0. \therefore \text{consistent.}$

3)

current is z -invariantimplicit time dependence of $e^{j\omega t}$ is assumed.

in the far field region, medium is free space.

$$\therefore \epsilon = \epsilon_0, \mu = \mu_0$$

 $J = 0$ in free space.
 \therefore from Maxwell's equations, $\nabla \times \vec{H} = \frac{\partial \vec{D}}{\partial t} = j\omega \epsilon_0 \vec{E}$

$$\vec{E} = \frac{-j}{\omega \epsilon_0} (\nabla \times \vec{H})$$

$$\nabla \times \vec{H} = \frac{H_0}{\rho} \begin{vmatrix} \hat{\rho} & \rho \hat{\phi} & \hat{z} \\ \frac{\partial}{\partial \rho} & \frac{\partial}{\partial \phi} & \frac{\partial}{\partial z} \\ 0 & \rho \frac{e^{-j\beta_0 \rho}}{\sqrt{\rho}} & 0 \end{vmatrix}$$

$$\therefore \nabla \times \vec{H} = \frac{H_0}{\rho} \cdot \hat{z} \frac{\partial}{\partial \rho} (\sqrt{\rho} e^{-j\beta_0 \rho}) = \frac{H_0}{\rho} \hat{z} \left[\sqrt{\rho} (-j\beta_0) e^{-j\beta_0 \rho} + \frac{e^{-j\beta_0 \rho}}{2\sqrt{\rho}} \right]$$

$$= \frac{H_0 e^{-j\beta_0 \rho}}{2\rho^{3/2}} (1 - 2j\beta_0 \rho) \hat{z}$$

$$\therefore \vec{E} = \frac{-j H_0 (1 - 2j\beta_0 \rho) e^{-j\beta_0 \rho}}{2\rho^{3/2} \omega \epsilon_0} \hat{z}$$

- 4) the MATLAB code is added in the appendix.
 the plots are also added in the appendix along with the code
 the meshgrid function is used to form the 2D array of x, y coordinates.
 hill is constructed using the gaussian function: $z = \exp(-(x-5)^2 - 4(y-3)^2)$

the outward normal is calculated as $\nabla(g)$ where $g(x, y, z) = z - f(x, y)$.
 $f(x, y) = \exp(-(x-5)^2 - 4(y-3)^2)$

the results are validated against the inbuilt MATLAB function, `surfnorm`

- 5) The medium is assumed to be isotropic. $\therefore \mu$: constant throughout the medium & homogeneous.

\therefore from Maxwell's equations, $\nabla \times \vec{E} = -\frac{\partial \vec{B}}{\partial t}$

as the fields are time harmonic, $\frac{\partial \vec{B}}{\partial t} = \mu \frac{\partial \vec{H}}{\partial t} = j\omega\mu \vec{H}$

$\therefore \nabla \times \vec{E} = -j\omega\mu \vec{H}$. $\therefore \vec{H} = \frac{j}{\omega\mu} (\nabla \times \vec{E})$.

$\nabla \times \vec{E}$ is computed symbolically in terms of x, y, z .

for $\vec{E} = (x \sin z, y^2, z^3 x)$, obtained $\vec{H} = \frac{j}{\omega\mu} (0, x \cos(z) - z^3, 0)$

6) To prove Uniqueness Theorem, consider a region of volume V , bounded by a surface S .

Say, we have 2 possible sets of soln.: E^a, H^a , E^b, H^b .

\therefore for uniqueness theorem to be valid, we need to prove $E^a = E^b$, $H^a = H^b$
proof:

both soln. satisfy Maxwell's theorem

$$\therefore \nabla \times E^a = -j\omega\mu H^a - M$$

$$\nabla \times H^a = j\omega\epsilon E^a + J$$

$$\nabla \times E^b = -j\omega\mu H^b - M$$

$$\nabla \times H^b = j\omega\epsilon E^b + J$$

$$\text{let } \delta E \triangleq E^a - E^b, \quad \delta H = H^a - H^b$$

$$\therefore \nabla \times \delta E = -j\omega\mu \delta H \quad \nabla \times \delta H = j\omega\epsilon \delta E \rightarrow (i)$$

here, μ, ϵ are complex and functions of position (need not be isotropic medium)

$$\begin{aligned} \text{energy carried by the diff. fields} &= \int_S (\delta E \times \delta H^*) \cdot d\vec{s} \\ &= \int_V \nabla \cdot (\delta E \times \delta H^*) dV \quad [\text{from divergence theorem}] \end{aligned}$$

$$\nabla \cdot (\vec{A} \times \vec{B}) = \vec{B} \cdot (\nabla \times \vec{A}) - \vec{A} \cdot (\nabla \times \vec{B}) : \text{std. theorem of vector calculus}$$

$$\therefore \nabla \cdot (\delta E \times \delta H^*) = \delta H^* \cdot (\nabla \times \delta E) - \delta E \cdot (\nabla \times \delta H^*)$$

$$\text{from eqn (i), } \delta H^* \cdot (\nabla \times \delta E) = \delta H^* \cdot (-j\omega\mu \delta H) = -j\omega\mu |\delta H|^2$$

$$\nabla \times \delta H^* = (\nabla \times \delta H)^* = -j\omega\epsilon^* \delta E^*$$

$$\therefore \delta E \cdot (\nabla \times \delta H^*) = -j\omega\epsilon^* |\delta E|^2$$

$$\therefore \int_S (\delta E \times \delta H^*) \cdot d\vec{s} = \int_V (-j\omega\mu |\delta H|^2 + j\omega\epsilon^* |\delta E|^2) dV \rightarrow (ii)$$

as γ, ϵ are complex, $\epsilon = \epsilon_r + j\epsilon_i$, $\gamma = \gamma_r + j\gamma_i$

$$\begin{aligned} \therefore \text{RHS of (ii)} &: \int_V -|\delta H|^2 j\omega(\gamma_r + j\gamma_i) + |\delta E|^2 j\omega(\epsilon_r - j\epsilon_i) dV \\ &= \underbrace{\int_V (\omega\gamma_i |\delta H|^2 + \omega\epsilon_i |\delta E|^2) dV}_{\text{real part}} + \underbrace{\int_V (-j\omega\gamma_r |\delta H|^2 + j\omega\epsilon_r |\delta E|^2) dV}_{\text{imaginary part}} \end{aligned}$$

in LHS of (ii), $d\vec{s} = \hat{n} ds$, \hat{n} : outward normal.

$$\therefore (\delta \vec{E} \times \delta \vec{H}^*) \cdot \hat{n} = (\hat{n} \times \delta \vec{E}) \cdot \delta \vec{H}^* = -(\hat{n} \times \delta \vec{H}^*) \cdot \delta \vec{E}$$

- if tangential part of \vec{E} is specified at boundary, $E_t^a = E_t^b = E_t^o$ (specified)

$$\therefore \delta \vec{E} = \delta E_t \hat{t} + \delta E_n \hat{n} \quad \delta E_t = 0 \text{ as } E_t^a = E_t^b$$

$$\therefore \delta \vec{E} = \delta E_n \hat{n} \quad \therefore \hat{n} \times \delta \vec{E} = \delta E_n (\hat{n} \times \hat{n}) = \underline{0}$$

- similarly, if tangential part of \vec{H} is specified at boundary, $\delta H_t = 0$.

$$\therefore \delta \vec{H} = \delta H_n \hat{n} \quad \therefore \hat{n} \times \delta \vec{H}^* = (\hat{n} \times \delta \vec{H})^* = \delta H_n^* (\hat{n} \times \hat{n}) = \underline{0}$$

- if either \vec{H}_{tn} or \vec{E}_{tn} is specified at all pts of the boundary, wherever \vec{E}_{tn} is specified, $\hat{n} \times \delta \vec{E} = 0$. wherever \vec{H}_{tn} is specified, $\hat{n} \times \delta \vec{H} = 0$
 \therefore at all pts on bnd., $\underline{(\delta \vec{E} \times \delta \vec{H}^*) \cdot \hat{n} = 0}$

if any of the condn. are true, $LHS = 0$.

$$\therefore RHS = 0. \quad \text{Re}(RHS) = 0, \quad \text{Im}(RHS) = 0.$$

in the $\text{Im}(RHS)$, $(\epsilon_r |SE|^2 - \mu_r |SH|^2) \omega = 0$.
can be true for positive ϵ_r, μ_r .

but, in the $\text{Re}(RHS)$, $(\epsilon_i |SE|^2 + \mu_i |SH|^2) \omega = 0$.

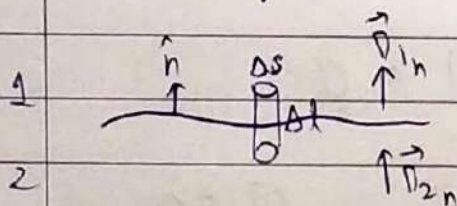
if the medium is lossless, $\epsilon_i = \mu_i = 0 \quad \therefore$ inconclusive about $SE \neq SH$.

but, if the medium is lossy, $\epsilon_i < 0 \neq \mu_i < 0$.

\therefore both terms $\leq 0 \quad \therefore$ for $\epsilon_i |SE|^2 + \mu_i |SH|^2 = 0$
 $\Rightarrow |SE| = |SH| = 0$

\therefore for a lossy medium, the soln. obtained for the fields in a region is unique.

7) at the interface between two regions 1 and 2, analysing continuity of \vec{D}_n



assume a gaussian pillbox at the interface.
 $\Delta S, \Delta l \rightarrow 0$.

from maxwell's eqns, $\nabla \cdot \vec{D} = \rho_e$ at any point.

integrate over vol. of cylinder. $\int_V \nabla \cdot \vec{D} dV = \int_V \rho_e dV$

$\int_V \nabla \cdot \vec{D} dV = \int_S \vec{D} \cdot d\vec{S}$ from divergence theorem

$$\int_V \rho_s dV = Q \text{ enclosed in the cylinder} = \rho_s \cdot \Delta S, \quad \rho_s: \text{surface charge density}$$

$$\int_S \vec{D} \cdot d\vec{S} = D_{1n} \Delta S - D_{2n} \Delta S + D_{\text{polar}} \cdot 2\pi r \Delta l$$

make $\Delta l \rightarrow 0$. $\therefore \rho_s \Delta S = (D_{1n} - D_{2n}) \Delta S$
(property of assumed cylinder)

$$\therefore D_{1n} - D_{2n} = \rho_s \quad D_{1n} - D_{2n} = (\vec{D}_1 - \vec{D}_2) \cdot \hat{n}$$

$$\therefore \hat{n} \cdot (\vec{D}_1 - \vec{D}_2) = \rho_s$$

\downarrow surface charge
 \downarrow difference in normal components of \vec{D}

8) The waveguide is known to have a z -invariant cross section + permittivity $(\epsilon(x,y))$

note: $\epsilon(x,y)$ is the permittivity of the bulk of the waveguide.

\therefore maxwell's equations: $\nabla \cdot \vec{B} = 0 \Rightarrow \nabla \cdot \vec{H} = 0$

$$\nabla \cdot \vec{D} = 0 \text{ (as there are no free charges)} \Rightarrow \nabla \cdot (\epsilon \vec{E}) = 0$$

$$\nabla \times \vec{E} = -\mu \frac{\partial \vec{H}}{\partial t}$$

$$\nabla \times \vec{H} = \frac{\partial \vec{D}}{\partial t} = \epsilon \frac{\partial \vec{E}}{\partial t}$$

Analysing for time-harmonic waves propagating along the z direction,

time dependence: $e^{+j\omega t}$

z dependence: $e^{-\gamma z}$, $\gamma = \alpha + j\beta$

\therefore all the field terms have an implicit $e^{j\omega t - \gamma z}$ term attached.

assuming medium is non magnetic, $\mu = \mu_0$

as the dependence on t, z is uniform for all field components,

$$\frac{\partial(\cdot)}{\partial t} = j\omega(\cdot) \quad \frac{\partial(\cdot)}{\partial z} = -\gamma(\cdot)$$

$$\begin{aligned} \text{as } \nabla \times \vec{E} &= -\mu \frac{\partial \vec{H}}{\partial t} \Rightarrow \left(\frac{\partial E_z}{\partial y} - \frac{\partial E_y}{\partial z}, \frac{\partial E_x}{\partial z} - \frac{\partial E_z}{\partial x}, \frac{\partial E_y}{\partial x} - \frac{\partial E_x}{\partial y} \right) \\ &= -j\omega\mu_0 (H_x, H_y, H_z). \end{aligned}$$

$$\begin{aligned} \text{as } \nabla \times \vec{H} &= \epsilon \frac{\partial \vec{E}}{\partial t} \Rightarrow \left(\frac{\partial H_z}{\partial y} - \frac{\partial H_y}{\partial z}, \frac{\partial H_x}{\partial z} - \frac{\partial H_z}{\partial x}, \frac{\partial H_y}{\partial x} - \frac{\partial H_x}{\partial y} \right) \\ &= j\omega\epsilon (E_x, E_y, E_z) \end{aligned}$$

$$\therefore \frac{\partial E_z}{\partial y} + \gamma E_y = -j\omega\mu_0 H_x \quad \text{-(i)} \quad \frac{\partial H_z}{\partial y} + \gamma H_y = j\omega\epsilon E_x \quad \text{-(iv)}$$

$$-\gamma E_x - \frac{\partial E_z}{\partial x} = -j\omega\mu_0 H_y \quad \text{-(ii)} \quad -\gamma H_x - \frac{\partial H_z}{\partial x} = j\omega\epsilon E_y \quad \text{-(v)}$$

$$\frac{\partial E_y}{\partial x} - \frac{\partial E_x}{\partial y} = -j\omega\mu_0 H_z \quad \text{-(iii)} \quad \frac{\partial H_y}{\partial x} - \frac{\partial H_x}{\partial y} = j\omega\epsilon E_z \quad \text{-(vi)}$$

these 6 equations are valid even for any arbitrary $E(x, y)$.

solve this system of eqns. to represent E_x, E_y, H_x, H_y in terms of E_z, H_z

solving (i) & (v), $H_x = \frac{1}{(\gamma^2 + \omega^2 \epsilon_0 \epsilon)} \left[j\omega \epsilon \frac{\partial E_z}{\partial y} - \gamma \frac{\partial H_z}{\partial x} \right]$

$$E_y = \frac{1}{(\gamma^2 + \omega^2 \epsilon_0 \epsilon)} \left[j\omega \epsilon_0 \frac{\partial H_z}{\partial x} - \gamma \frac{\partial E_z}{\partial y} \right]$$

solving (ii) & (iv), $H_y = \frac{-1}{(\gamma^2 + \omega^2 \epsilon_0 \epsilon)} \left[j\omega \epsilon \frac{\partial E_z}{\partial x} + \gamma \frac{\partial H_z}{\partial y} \right]$

$$E_x = \frac{-1}{(\gamma^2 + \omega^2 \epsilon_0 \epsilon)} \left[j\omega \epsilon_0 \frac{\partial H_z}{\partial y} + \gamma \frac{\partial E_z}{\partial x} \right]$$

to bring all info into one eqn.,

$$\begin{aligned} \nabla \times (\nabla \times \vec{H}) &= \nabla \times (j\omega \epsilon \vec{E}) \\ \nabla(\nabla \cdot \vec{H}) - \nabla^2 \vec{H} &= j\omega \nabla \times (\epsilon \vec{E}) \end{aligned}$$

from std. theorems of vector calculus,

$$\begin{aligned} \nabla \times (\epsilon \vec{E}) &= \epsilon (\nabla \times \vec{E}) + (\nabla \epsilon \times \vec{E}) \\ &= -j\omega \epsilon_0 \epsilon \vec{H} + (\nabla \epsilon \times \vec{E}) \end{aligned}$$

$$\therefore -\nabla^2 \vec{H} = \omega^2 \epsilon_0 \epsilon \vec{H} + (\nabla \epsilon \times \vec{E})$$

$$\therefore \nabla^2 \vec{H} + \omega^2 \epsilon_0 \epsilon \vec{H} = -(\nabla \epsilon \times \vec{E})$$

as $\frac{\partial}{\partial z} = -\gamma \cdot (\cdot)$, $\nabla^2(\cdot) \triangleq \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + \gamma^2 \right) (\cdot)$

define $h^2 = \gamma^2 + \omega^2 \mu_0 \epsilon$

note: h^2 : not a constant

depends on (x, y) due to ϵ .

→ analysing for TE polarisation ($E_z = 0$):

$$\therefore \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + h^2 \right) (\vec{H}) = -\nabla \epsilon \times \vec{E} = \vec{E} \times \nabla \epsilon$$

$$= \frac{-1}{h^2} \left[\left(j\omega\mu_0 \frac{\partial H_z}{\partial y} + \gamma \frac{\partial E_z}{\partial x} \right) \hat{x} + \left(\gamma \frac{\partial E_z}{\partial y} - j\omega\mu_0 \frac{\partial H_z}{\partial x} \right) \hat{y} \right] \times (\nabla \epsilon)$$

since $\epsilon \triangleq \epsilon(x, y)$, $\nabla \epsilon = \frac{\partial \epsilon}{\partial x} \hat{x} + \frac{\partial \epsilon}{\partial y} \hat{y}$

∴ RHS has only \hat{z} terms. ∴ \hat{x}, \hat{y} terms on LHS: 0

$$\text{LHS: } \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + h^2 \right) (H_x \hat{x} + H_y \hat{y} + H_z \hat{z})$$

$$\therefore \left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + h^2 \right) H_x = 0$$

$$\left(\frac{\partial^2}{\partial x^2} + \frac{\partial^2}{\partial y^2} + h^2 \right) H_y = 0$$

∴ H_x & H_y satisfy scalar Helmholtz equation

analysing for H_z :

$$\text{RHS: } \frac{-1}{h^2} \left[j\omega\mu_0 \frac{\partial H_z}{\partial y} \cdot \frac{\partial \epsilon}{\partial y} + j\omega\mu_0 \frac{\partial H_z}{\partial x} \cdot \frac{\partial \epsilon}{\partial x} \right] \hat{z}$$

$$\therefore \frac{\partial^2 H_z}{\partial x^2} + \frac{\partial^2 H_z}{\partial y^2} + h^2 H_z = \frac{-j\omega\mu_0}{h^2} \left(\frac{\partial H_z}{\partial y} \frac{\partial \epsilon}{\partial y} + \frac{\partial H_z}{\partial x} \frac{\partial \epsilon}{\partial x} \right)$$

can be written as $\nabla^2 H_z + K^2 H_z = \frac{-j\omega\mu_0}{h^2} (\nabla H_z \cdot \nabla \epsilon)$

$$\nabla^2 H_z + \omega^2 \mu_0 \epsilon H_z = \frac{-j\omega\mu_0}{\gamma^2 + \omega^2 \mu_0 \epsilon} (\nabla H_z \cdot \nabla \epsilon)$$

once H_z is known,

$$E_x = \frac{-j\omega\mu_0}{\gamma^2 + \omega^2 \mu_0 \epsilon} \frac{\partial H_z}{\partial y}$$

$$E_y = \frac{j\omega\mu_0}{\gamma^2 + \omega^2 \mu_0 \epsilon} \frac{\partial H_z}{\partial x}$$

Appendix

1 Question 4

The plots are attached below:

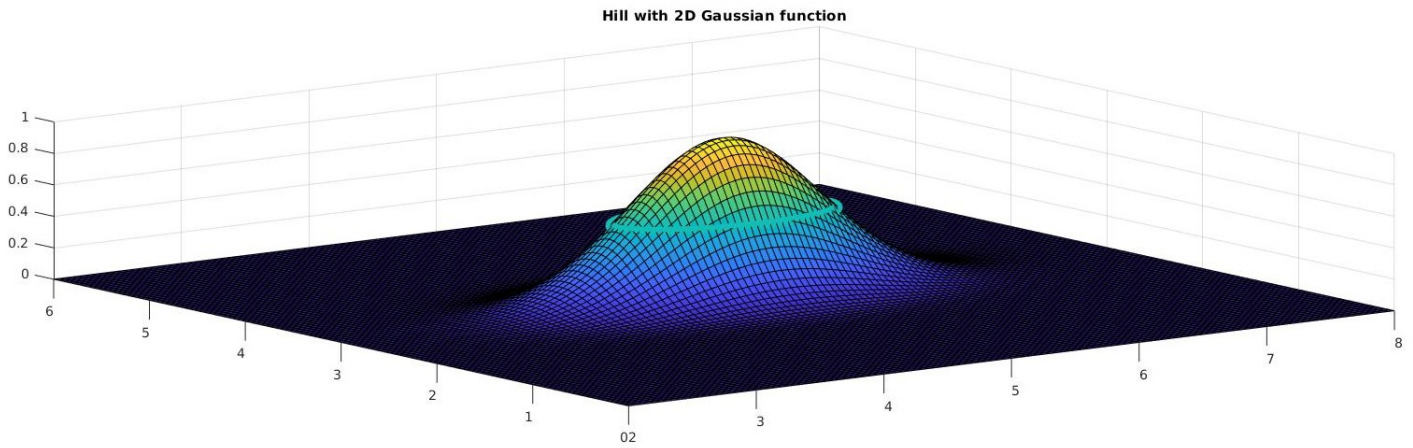


Figure 1: Hill constructed using 2D gaussian function

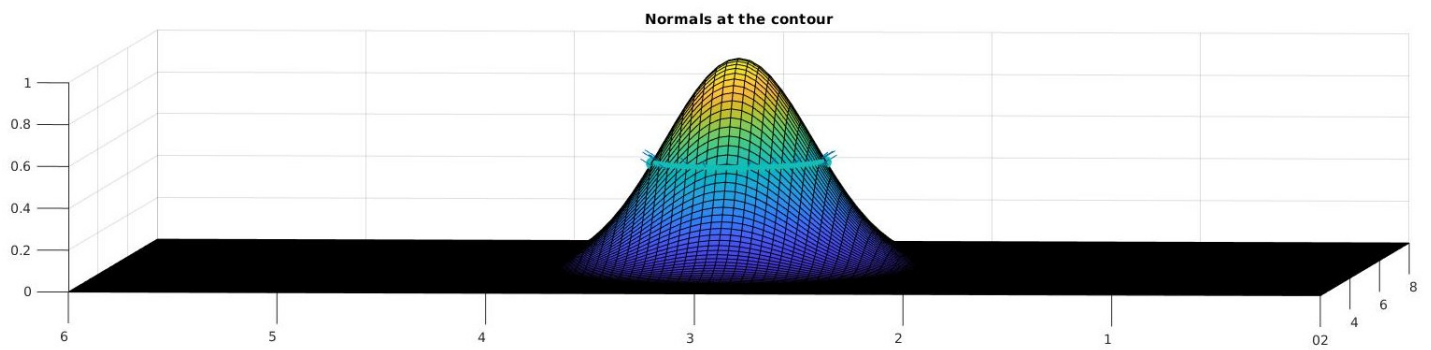


Figure 2: Normals plotted at the contour

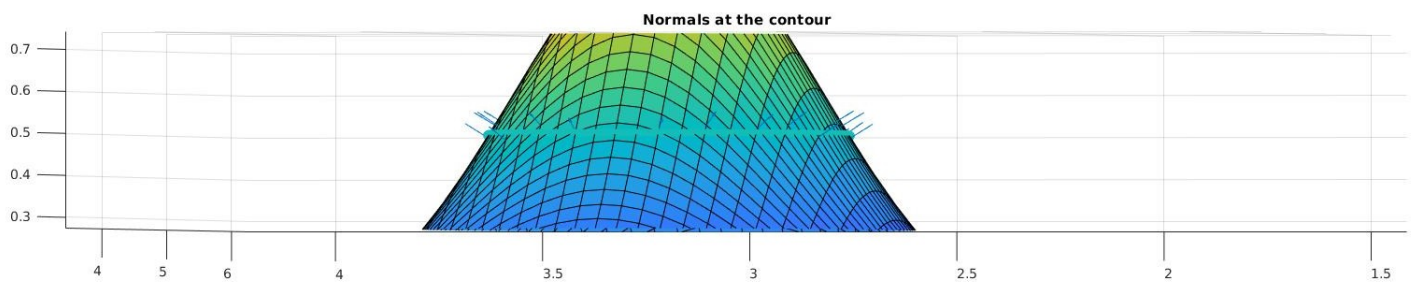


Figure 3: Zoomed in view to see the normals

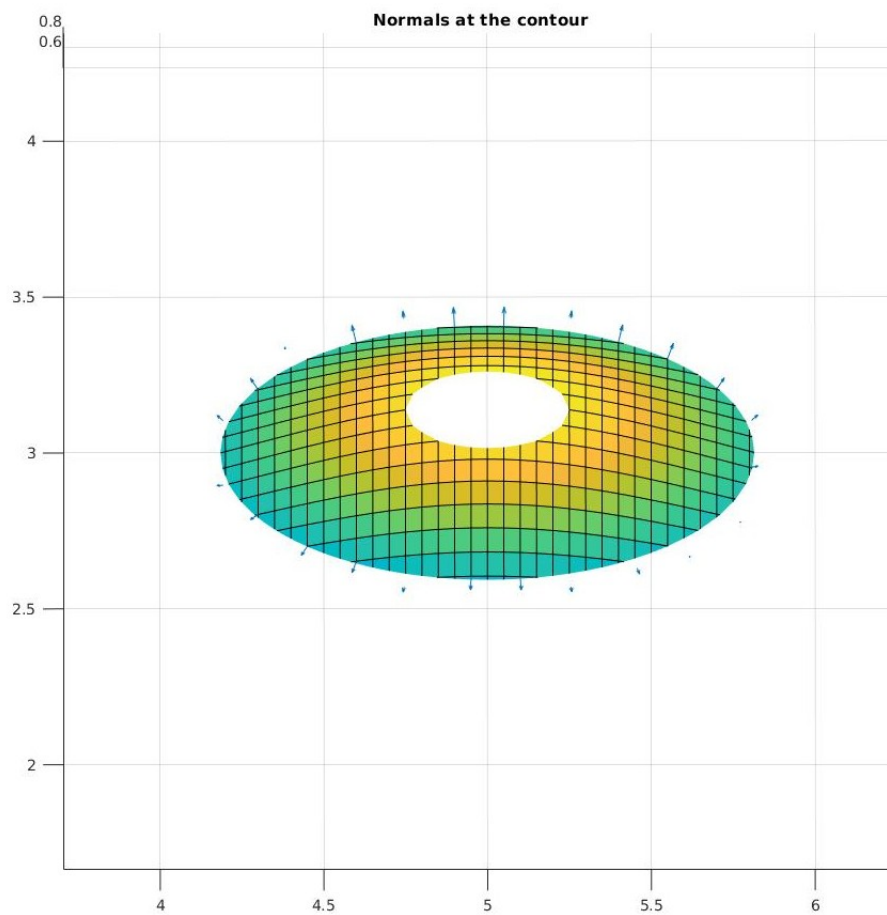


Figure 4: Top View to see the equispaced contours

Note: I have used the external function, **curvspace** in MATLAB to analytically compute equispaced points on the chosen contour and then plot normals at those points. ref: [Curvspace in MATLAB file exchange](#)

1.1 Code used

```

1 w = 0.05; %discretisation parameter
2 x = 2:w:8; %range for x and y
3 y = 0:w:6;
4
5 [X,Y] = meshgrid(x,y);
6
7 Z = exp( -(X-5).^2 - 4.*(Y-3).^2 ); %construct 2d gaussian hill
8 z_max = max(max(Z));
9 z_contour = z_max/2; %find contour at half the height
10
11 figure(1);
12 surf(X,Y,Z); %plotting the 2d gaussian hill
13 title("Hill with 2D Gaussian function");
14 hold on;
15 [~,H] = contour3(X,Y,Z,[z_contour,z_contour]); %marking contour
16 % at half the height
17 H.LineWidth = 8;
18 axis equal;
19 hold off;
20
21 figure(2);
22 surf(X,Y,Z); %plotting the 2d gaussian hill
23 title("Normals at the contour");
24 hold on;

```



```

24 [C,H] = contour3(X,Y,Z,[z_contour,z_contour]); %plot contour
25 H.LineWidth = 8;
26
27 P = C(:,2:101)';
28 Eq_P = curvspace(P,25)'; %find equispaced points on the contour
29
30 [nx,ny,nz] = find_normal(Z,w); %defined function to calculate
    normal
31 filter = filterxy(X,Y,Eq_P);
32 quiver3(X, Y, Z, nx .* filter, ny .* filter, nz .* filter); %
    plotting normals at equispaced points
33 axis equal;
34 hold off;
35
36 %{
37 % Validation for finding the normal done using the inbuilt
    surfnorm function
38 figure(3);
39 surf(X,Y,Z);
40 title("Validation: Normals found from surfnorm");
41 hold on;
42 [~,C] = contour3(X,Y,Z,[z_contour,z_contour]);
43 C.LineWidth = 8;
44 [U,V,W] = surfnorm(X,Y,Z);
45 quiver3(X,Y,Z,U,V,W);
46 axis equal;
47 hold off;
48 %}
49
50 function filter = filterxy(X,Y,q) %to overlay equispaced points
    on the predefined mesh
51     tol = 0.026;
52     filter = zeros(size(X));
53     %calculate nearest points on the mesh for each one of the
    equispaced
54     %points. then do elementwise OR for individual filters to get
    net filter
55     for i=1:size(q')
56         temp_filter = X < (q(1,i) + tol) & X > (q(1,i) - tol) & Y
        < (q(2,i) + tol) & Y > (q(2,i) - tol);
57         filter = filter | temp_filter;
58     end
59 end
60
61 function [nx,ny,nz] = find_normal(g,w) %to find normal for a
    surface g
62     %g = z - f(x,y), normal(g) = 1 - grad(f)
63     [nx,ny] = gradient(g .* (-1/w));
64     nz = ones([1 + (6/w), 1 + (6/w)]);
65 end

```

2 Question 5

Explanation mentioned in handwritten solution. Obtained expression for H is

$$\vec{H} = \frac{j}{\omega\mu}(x(\cos(z) - z^3)\hat{y} \quad (1)$$

2.1 Code used

```
1 syms x y z w mu;      %define symbols for x,y,z, permiability
2
3 E = [x * sin(z), y^2, z^3 * x];    %give input electric field
    expression here
4 %mu = 4*pi*(10^(-7));    %give permeability value here
5
6 H = symbolic_H_finder(E, mu)
7
8 function H = symbolic_H_finder(E, mu)
9     syms x y z w;
10     Ex = E(1); Ey = E(2); Ez = E(3);    %define x,y,z components
    of E
11
12     %curl(E) = -jwu*H,    H = (j/wu) * curl(E)
13     Hx = ( diff(Ez,y) - diff(Ey,z) ) * 1i / (w * mu) ;    %assign
    corresponding curl elements to components of H
14     Hy = ( diff(Ex,z) - diff(Ez,x) ) * 1i / (w * mu) ;
15     Hz = ( diff(Ey,x) - diff(Ex,y) ) * 1i / (w * mu) ;
16
17     H = [Hx, Hy, Hz];
18 end
```