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ModFEM - use cases and the internal flow of calculations



- download and install ModFEM framework
 - a suitable manual (user's guide) chapter should be created (KM?)
 - take into account possible use of ModFEM as part of grid infrastructure (KM?)
- compile (build) a set of particular ModFEM application
 - a suitable manual (user's guide) chapter should be created (JB?)



- prepare mesh files
 - use OpenSource mesh generators
 - the list of generators that can cooperate with ModFEM should be available in ModFEM documentation (Webpage, PDF version) (KM?)
 - the list should indicate whether:
 - » the code of generators is included with ModFEM or
 - » ModFEM documentation contains links to pages with proper versions of code
 - ModFEM documentation should at least sketch the way in which mesh input files should be created by the selected mesh generators (KM?)



- prepare mesh files
 - import files from OpenSource or commercial mesh generators
 - the list of accepted file formats should be included in ModFEM documentation (KM?)
 - available options for importing files to ModFEM should be specified and described in documentation (in a user's guide fashion) (KM?)
 - options may include creation of blocks with internal contact boundaries, creation of "boundary layers", specification of per element data (materials) or per face data (boundary conditions)
 - mesh quality control, improvement



- prepare configuration input files
 - the process of creating input files should be described in the user's guide for each file:
 - problem specification
 - materials specifications (PC?, KM?)
 - boundary conditions specification (PC?, KM?)
 - optional specification of solver input file (KB?)
 - the content of input files (especially problem definition) is related to the options for the flow of calculations that will be described later
 - the different sections in problem specification files should be described in different sections of user's guide (and by different persons)



- start the code for a given problem
 - shell scripts or other means seem to be necessary for proper starting of ModFEM for at least the following situations
 - MPI+...
 - ...+OpenCL
 - MPI+...+OpenCL
 - it is advisable to prepare a guidelines for preparing and several example realizations for such shell scripts (KM?, JB?)



- convection-diffusion
 - diff_in_cube (also diff_in_box)
 - single linear problem
 - example with the known exact solution
 - good for testing new approximation types (quadratic, DG etc.)
 - good for testing adaptivity (error reduction)
 - diff_in_box good for testing parallel adaptivity (large initial mesh), good for testing scalability



- convection-diffusion
 - diff_1d_in_cube
 - example with the known exact solution
 - for testing stabilization and convergence as a function of local Peclet number
 - for testing "boundary layers" of prismatic elements and anisotropic adaptivity

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- convection-diffusion
 - wave_in_box (or wave_in_cube)
 - for testing dynamic adaptivity
 - for testing parallel dynamic adaptivity and load balancing
 - simple case wave_in_box along x-dimension
 - another case wave_in_cube arbitrary direction

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- incompressible Navier-Stokes
 - LDC steady-state problem
 - good for testing pseudo-time integration methods
 - good for testing accuracy for different weak formulations (stability terms)
 - existing reference solutions in the literature
 - good for testing adaptivity for NS equations (but the problem is not singular...)
 - BFS similar to LDC



- incompressible Navier-Stokes
 - VKV transient problem
 - good for testing accuracy of time integration algorithms
 - good for testing accuracy for different weak formulations (stability terms)
 - existing reference solutions in the literature
 - good for testing adaptivity for NS equations
 - good for testing parallel adaptivity with dynamic load balancing



- heat transfer
 - free cooling examples
 - comparison with experimental data
 - good for testing boundary conditions



- incompressible Navier-Stokes + heat transfer
 - HDC
 - comparison with reference solutions
 - good for testing time integration/nonlinear solution/linear solution strategies



- incompressible Navier-Stokes + heat transfer
 - quenching examples
 - comparison with experimental and commercial software results
 - good for testing solution strategies
 - good for testing adaptation strategies



- plasticity with flow formulation...
 - cone
 - cube
 - no friction
 - friction



- each process reads necessary input files and initializes proper data structures
 - parallel reading of input files should be implemented and described in user's guide (KM?)
 - for parallel (distributed memory) execution domain decomposition must be ensured
 - either by reading already prepared files for each process (see above)
 - or by performing DD by suitable tools (Metis, ParMetis interface – described in theory manual and technical specification)(KM?)



- each process starts execution of (depending upon the problem solved):
 - time integration
 - non-linear system solution
 - solver of linear equations
- the choice of particular solution strategy depends on the problem type (ModFEM executable) and particular problem (specified by e.g. problem name)



- starting execution:
 - standard from terminal with working directory as parameter
 - mpirun, mpiexec with suitable parameters
 - scripts:
 - for MPI
 - e.g. for debugging
 - e.g. for clusters
 - for OpenCL
 - copying of suitable kernels
 - for MPI/OpenCL
 - ?



- reading input files:
 - problem
 - mesh
 - field
 - BC
 - materials
- MPI
 - one node reads all
 - Metis domain decomposition
 - all nodes read all
 - initial load balance ParMetis?



- how the hell parallel (MPI) solution works?
 - domain decomposition with overlap
 - each process holds data for:
 - owned mesh and DOF entities
 - overlap mesh and DOF entities
 - three distinct problems:
 - parallel mesh adaptation (and load balance)
 - parallel solution
 - linear solution only time integration and nonlinear solution are just replicated on each node
 - parallel input/output



- how the hell parallel (MPI) solution works?
 - standard mesh and approximation modules are agnostic to parallel (MPI) execution
 - all necessary mesh and approximation procedures are in separate overlay modules for handling domain decomposition
 - mmpd_prism and mmpd_adapter
 - appd_std_lin and appd_dg_prism
 - as usual, only problem dependent procedures and general utilities call overlay procedures
 - solver interface call problem dependent procedures for necessary operations



- starting simulation:
 - MPI: synchronisation (broadcast)
- time integration or single problem solution
- each solution strategy (related to particular problems) leads finally to a sequence of solutions of linear problems
- between solutions mesh adaptations (and dynamic load balancing for parallel examples) can be performed
- solution strategies are contained in time integration sub-directories of problem modules



- mesh adaptations are performed by mesh management modules
 - technical details can be described in manuals and user's guides related to particular mesh management modules
 - interesting variations include:
 - isotropic refinements
 - anisotropic refinements
 - strategies for near boundary regions ("boundary layers")
 - parallel (MPI) mesh adaptations are accompanied by load balancing
 - details left to particular parallel mesh management modules (currently mmd_prism and mmd_adapter)



- mesh adaptivity can be based on:
 - error estimation
 - any other user defined indicators (possibly problem dependent)
- error estimation
 - the only method in ModFEM is ZZ (Zienkiewicz-Zhu) error estimate based on derivative recovery
- for selected examples exact solutions exist and errors can be computed not estimated



- time integration procedures
 - single stage procedures only
 - non-linear implicit first order Euler scheme
 - inner non-linear iterations
 - » different strategies for transient and steady-state problems
 - » breaking criteria based on the number of iterations or the norm of update of unknowns
 - » how about ns_supg?
 - linear implicit second order Crank-Nicolson (trapezoidal rule)
 - does it work at all??? (PC!!!)
 - adaptive time stepping strategies
 - CFL based
 - non-linear convergence based



- time integration procedures
 - adaptive time stepping strategies
 - CFL based
 - non-linear convergence based
 - after each time step
 - time step length adaptation
 - solution rewriting
 - dumping
 - graphics data
 - checkpoint-restart data
 - breaking condition calculations
 - after mesh adaptation (and initially)
 - solver data structure recreation
 - DOFs exchange tables recreation



- time integration procedures
 - non-linear solver strategies
 - Picard iterations only...
 - two kinds of stopping criteria:
 - based on absolute value of update norm
 - based on relative to initial value of update norm
 - opportunities for OpenMP parallelization
 - reading, writing and rewriting DOFs
 - calculating (error) norms
 - MPI (PARALLEL) modifications
 - exchange tables creation
 - control data broadcasts



- how the hell parallel (MPI) solution works?
 - the key procedure: utr_get_list_ent
 - all (active) integration entities in process data structures can be included
 - if their SMs contain rows corresponding to not owned DOF entities their will simply not be assembled
 - there must be strict division of DOF entities
 - owned entities will have rows of global SM assembled (and used in solution)
 - ghost (overlap) entities will have no rows, but will have DOF structures and blocks, and will be used in matrix-vector products
 - owned entities must be first on the list
 - » they should not be considered in renumbering...



- how the hell parallel (MPI) solution works?
 - iterative solver needs only:
 - global vector norm
 - global scalar product
 - exchange of DOFs for matrix-vector product
 - all procedures are called back to problem module
 - finally that is parallel approximation module that handles all these procedures



- how the hell parallel (MPI) solution works?
 - exchange tables
 - creating
 - all-to-all communication
 - establishing local-to-global mapping, i.e.:
 - » for a given sending/receiving processor and a DOF entity with local position on sending/receiving list
 - » set the position in subdomain vector of DOFs (including ghost (overlap) DOFs (entities))
 - using
 - for each sending/receiving processor (communication only with neighbours)
 - just rewrite from one vector (sending/receiving list) to another vector (subdomain vector of DOFs)



ModFEM - performance

- Phases important for performance:
 - read data from CPU data structures
 - geometry
 - problem dependent coefficients
 - (shape functions and integration points data for reference elements must be present in fast memory during calculations)
 - send possibly to accelerator memory



