BackPropagation There will be some functions that start with the word "grader" ex: grader_sigmoid(), grader_forwardprop(), grader_backprop() etc, you should not change those function definition. **Every Grader function has to return True.** Loading data import pickle import numpy as np from tqdm import tqdm import matplotlib.pyplot as plt path = '/content/drive/MyDrive/AAIC/Assignments/19.Backpropagation and Gradient Checking/practice/Copy of data.pkl' with open(path, 'rb') as f: data = pickle.load(f) print(data.shape) X = data[:, :5]y = data[:, -1]print(X.shape, y.shape) (506, 6)(506, 5) (506,) In [] Computational graph • If you observe the graph, we are having input features [f1, f2, f3, f4, f5] and 9 weights [w1, w2, w3, w4, w5, w6, w7, w8, w9]. • The final output of this graph is a value L which is computed as (Y-Y')^2 Task 1: Implementing backpropagation and Gradient checking Check this video for better understanding of the computational graphs and back propagation from IPython.display import YouTubeVideo YouTubeVideo('i940vYb6noo', width="1000", height="500") Out[]: · Write two functions Forward propagation(Write your code in def forward_propagation()) For easy debugging, we will break the computational graph into 3 parts. Part 1 Part 2 Part 3 def forward_propagation(X, y, W): # X: input data point, note that in this assignment you are having 5-d data points # y: output varible # W: weight array, its of length 9, W[0] corresponds to w1 in graph, W[1] corresponds to w2 in graph, ..., W[8] corresponds to w9 in graph. # you have to return the following variables # exp= part1 (compute the forward propagation until exp and then store the values in exp) # tanh =part2(compute the forward propagation until tanh and then store the values in tanh) # sig = part3(compute the forward propagation until sigmoid and then store the values in sig) # now compute remaining values from computional graph and get y' # write code to compute the value of $L=(y-y')^2$ # compute derivative of L w.r.to Y' and store it in dl # Create a dictionary to store all the intermediate values # store L, exp,tanh,sig,dl variables return (dictionary, which you might need to use for back propagation) Backward propagation(Write your code in def backward_propagation()) def backward_propagation(L, W, dictionary): # L: the loss we calculated for the current point # dictionary: the outputs of the forward_propagation() function # write code to compute the gradients of each weight [w1,w2,w3,...,w9] # Hint: you can use dict type to store the required variables # return dW, dW is a dictionary with gradients of all the weights return dW **Gradient clipping** Check this blog link for more details on Gradient clipping we know that the derivative of any function is $\lim_{\epsilon \to 0} \frac{f(x+\epsilon) - f(x-\epsilon)}{2\epsilon}$ • The definition above can be used as a numerical approximation of the derivative. Taking an epsilon small enough, the calculated approximation will have an error in the range of epsilon squared. • In other words, if epsilon is 0.001, the approximation will be off by 0.00001. Therefore, we can use this to approximate the gradient, and in turn make sure that backpropagation is implemented properly. This forms the basis of gradient checking! Gradient checking example lets understand the concept with a simple example: $f(w1,w2,x1,x2)=w_1^2.\,x_1+w_2.\,x_2$ from the above function , lets assume $w_1=1,\,w_2=2,\,x_1=3,\,x_2=4$ the gradient of f w.r.t w_1 is $rac{df}{dw_1}=dw_1 \quad = \quad 2.w_1.\,x_1$ = 2.1.3let calculate the aproximate gradient of w_1 as mentinoned in the above formula and considering $\epsilon=0.0001$ $egin{array}{lcl} dw_1^{approx} & = & rac{f(w1+\epsilon,w2,x1,x2)-f(w1-\epsilon,w2,x1,x2)}{2\epsilon} \ & = & rac{((1+0.0001)^2.3+2.4)-((1-0.0001)^2.3+2.4)}{2\epsilon} \end{array}$ (1.00020001.3+2.4)-(0.99980001.3+2.4)(11.00060003) - (10.99940003)Then, we apply the following formula for gradient check: $gradient_check = \frac{\|(dW - dW^{approx})\|_2}{\|(dW)\|_2 + \|(dW^{approx})\|_2}$ The equation above is basically the Euclidean distance normalized by the sum of the norm of the vectors. We use normalization in case that one of the vectors is very small. As a value for epsilon, we usually opt for 1e-7. Therefore, if gradient check return a value less than 1e-7, then it means that backpropagation was implemented correctly. Otherwise, there is potentially a mistake in your implementation. If the value exceeds 1e-3, then you are sure that the code is not correct. in our example: $\textit{gradient_check} = \frac{(6-5.99999999994898)}{(6+5.99999999994898)} = 4.2514140356330737e^{-13}$ you can mathamatically derive the same thing like this $egin{array}{lll} dw_1^{approx} & = & rac{f(w1+\epsilon,w2,x1,x2)-f(w1-\epsilon,w2,x1,x2)}{2\epsilon} \ & = & rac{((w_1+\epsilon)^2.x_1+w_2.x_2)-((w_1-\epsilon)^2.x_1+w_2.x_2)}{2\epsilon} \ & = & rac{4.\epsilon.w_1.x_1}{2\epsilon} \end{array}$ Implement Gradient checking (Write your code in def gradient_checking()) **Algorithm** W = initilize_randomly def gradient_checking(data_point, W): # compute the L value using forward_propagation() # compute the gradients of W using backword_propagation() approx_gradients = [] for each wi weight value in W: # add a small value to weight wi, and then find the values of L with the updated weights # subtract a small value to weight wi, and then find the values of L with the updated weights # compute the approximation gradients of weight wi approx_gradients.append(approximation gradients of weight wi) # compare the gradient of weights W from backword_propagation() with the aproximation gradients of weights with

| gradient_check formula return gradient_check NOTE: you can do sanity check by checking all the return values of gradient_checking(), they have to be zero. if not you have bug in your code Task 2 : Optimizers • As a part of this task, you will be implementing 3 type of optimizers(methods to update weight) · Use the same computational graph that was mentioned above to do this task Initilze the 9 weights from normal distribution with mean=0 and std=0.01 Check below video and this blog In []: from IPython.display import YouTubeVideo YouTubeVideo('gYpoJMlgyXA', width="1000", height="500") Out[]: **Algorithm** for each epoch(1-100): for each data point in your data: using the functions forward_propagation() and backword_propagation() compute the gradients of weights update the weigts with help of gradients ex: w1 = w1-learning_rate*dw1 Implement below tasks Task 2.1: you will be implementing the above algorithm with Vanilla update of weights Task 2.2: you will be implementing the above algorithm with Momentum update of weights · Task 2.3: you will be implementing the above algorithm with Adam update of weights Note: If you get any assertion error while running grader functions, please print the variables in grader functions and check which variable is returning False. Recheck your logic for that variable. Task 1 from google.colab import drive drive.mount('/content/drive') Mounted at /content/drive Forward propagation In []: def sigmoid(z): '''In this function, we will compute the sigmoid(z)''' # we can use this function in forward and backward propagation return 1/(1+np.exp(-z))def forward_propagation(x, y, w): '''In this function, we will compute the forward propagation ''' # X: input data point, note that in this assignment you are having 5-d data points # y: output varible # W: weight array, its of length 9, W[0] corresponds to w1 in graph, W[1] corresponds to w2 in graph,..., W[8] corresponds to w9 in graph. # you have to return the following variables # exp= part1 (compute the forward propagation until exp and then store the values in exp) # tanh =part2(compute the forward propagation until tanh and then store the values in tanh) # sig = part3(compute the forward propagation until sigmoid and then store the values in sig) # now compute remaining values from computional graph and get y' # write code to compute the value of $L=(y-y')^2$ # compute derivative of L w.r.to Y' and store it in dl # Create a dictionary to store all the intermediate values # store L, exp, tanh, sig variables return (dictionary, which you might need to use for back propagation) In [145... import pandas as pd import math import pickle import numpy as np from tqdm import tqdm import matplotlib.pyplot as plt path = '/content/drive/MyDrive/AAIC/Assignments/19.Backpropagation and Gradient Checking/practice/Copy of data.pkl' with open(path, 'rb') as f: data = pickle.load(f) #print(data.shape) X = data[:, :5]y = data[:, -1] #print(X.shape, y.shape) #w = np.empty(shape=(dim))#X = pd.DataFrame(X,columns=['f1','f2','f3','f4','f5']) In [146... def sigmoid(z): return 1/(1+np.exp(-z))def forward_propagation(x, y, w): d = dict()p1 = np.exp((((w[0]*x[0]) + (w[1]*x[1]))**2)+w[5])p2 = np.tanh(p1+w[6])p3 = sigmoid(((np.sin(w[2]*x[2])) * ((w[3]*x[3]) + (w[4]*x[4]))) + w[7]) $y_hat = p2 + (p3*w[8])$ $loss = (y-y_hat)**2$ $dl = -2*(y-y_hat)$ $d['dy_pr'] = d1$ d['loss'] = loss d['exp'] = p1d['tanh'] = p2d['sigmoid'] = p3 return d **Grader function - 1** In []: In [147... def grader_sigmoid(z): val=sigmoid(z) assert(val==0.8807970779778823) return True grader_sigmoid(2) True Out[147... **Grader function - 2** In [148... def grader_forwardprop(data): dl = (data['dy_pr']==-1.9285278284819143) loss=(data['loss']==0.9298048963072919) part1=(data['exp']==1.1272967040973583) part2=(data['tanh']==0.8417934192562146) part3=(data['sigmoid']==0.5279179387419721) assert(dl and loss and part1 and part2 and part3) return True w=np.ones(9)*0.1d1=forward_propagation(X[0], y[0], w) grader_forwardprop(d1) True Out[148... In []: **Backward propagation** In []: def backward_propagation(L,W,dict): '''In this function, we will compute the backward propagation ''' # L: the loss we calculated for the current point # dictionary: the outputs of the forward_propagation() function # write code to compute the gradients of each weight [w1, w2, w3, ..., w9] # Hint: you can use dict type to store the required variables # dw1 = # in dw1 compute derivative of L w.r.to w1 # dw2 = # in dw2 compute derivative of L w.r.to w2 # dw3 = # in dw3 compute derivative of L w.r.to w3 # dw4 = # in dw4 compute derivative of L w.r.to w4 # dw5 = # in dw5 compute derivative of L w.r.to w5 # dw6 = # in dw6 compute derivative of L w.r.to w6 # dw7 = # in dw7 compute derivative of L w.r.to w7 # dw8 = # in dw8 compute derivative of L w.r.to w8 # dw9 = # in dw9 compute derivative of L w.r.to w9 # return dW, dW is a dictionary with gradients of all the weights In [149... def backward_propagation(x,w,d1): dW = dict() $dW['dw1'] = float(d1['dy_pr']) * float(np.subtract(1,np.square(float(d1['tanh']))))*float((d1['exp']))* 2 * float(float((float(w[0]*x[0])+float(w[1]*x[1]))*x[0]))$ $dW['dw2'] = float(d1['dy_pr']) * float(np.subtract(1,float(np.square(float(d1['tanh']))))) * float((d1['exp'])) * 2 * float((float(w[0]*x[0])+float(w[1]*x[1])) * x[1]) * float(float(w[0]*x[0]) *$ $dW['dw3'] = float(d1['dy_pr']) * float(w[8]) * float(d1['sigmoid']) * float(np.subtract(1,float(d1['sigmoid']))) * float(np.cos(w[2]*x[2])*x[2]) * float(w[3]*x[3] + v[2]) * float(w[3]*x[3] + v[2]) * float(w[3]*x[3]) * fl$ dW['dw4'] = float(d1['dy_pr'])*float(w[8])*float(d1['sigmoid'])* float(np.subtract(1,float(d1['sigmoid']))) * float(x[3])* float(np.sin(float(x[2]*w[2]))) $dW['dw5'] = float(d1['dy_pr']) * float((w[8])) * float(d1['sigmoid']) * float(np.subtract(1,float(d1['sigmoid']))) * float(x[4]) * float(np.sin(float(x[2]*w[2])))$ dW['dw6'] = float(d1['dy_pr']) * float(np.subtract(1,np.square(float(d1['tanh'])))) * float(d1['exp']) dW['dw7'] = float(d1['dy_pr']) * float(np.subtract(1,np.square(float(d1['tanh'])))) $dW['dw8'] = float(d1['dy_pr']) * float(w[8]) * float(d1['sigmoid']) * float(np.subtract(1,float(d1['sigmoid'])))$ dW['dw9'] = float(d1['dy_pr']) * float((d1['sigmoid'])) return dW **Grader function - 3** In [150... def grader_backprop(data): dw1=(data['dw1']==-0.22973323498702003) dw2=(data['dw2']==-0.021407614717752925) dw3=(data['dw3']==-0.005625405580266319) dw4=(data['dw4']==-0.004657941222712423) dw5=(data['dw5']==-0.0010077228498574246) dw6=(data['dw6']==-0.6334751873437471) dw7=(data['dw7']==-0.561941842854033) dw8=(data['dw8']==-0.04806288407316516) dw9=(data['dw9']==-1.0181044360187037) assert(dw1 and dw2 and dw3 and dw4 and dw5 and dw6 and dw7 and dw8 and dw9) return True w=np.ones(9)*0.1d1=forward_propagation(X[0], y[0], w) d1=backward_propagation(X[0], w, d1) grader_backprop(d1) True Out[150... Implement gradient checking In []: In []: W = initilize_randomly def gradient_checking(data_point, W): # compute the L value using forward_propagation() # compute the gradients of W using backword_propagation() #approx_gradients = [] #for each wi weight value in W: # add a small value to weight wi, and then find the values of L with the updated weights # subtract a small value to weight wi, and then find the values of L with the updated weights # compute the approximation gradients of weight wi #approx_gradients.append(approximation gradients of weight wi) # compare the gradient of weights W from backword_propagation() with the aproximation gradients of weights with gradient_check formula #return gradient_check In [151... epslon = float(0.0001)from numpy.linalg import norm def gradient_check(a,b): return (norm(a-b))/(norm(a)+norm(b)) W = (np.random.random(9)) # np.ones(9) * 0.1# $d1 = forward_propagation(X[0], y[0], W)$ dW = backward_propagation(X[0], W, d1) approx_gradients = [] for ind, val in enumerate(W): W[ind] = float(val) + epslon $f1 = forward_propagation(X[0], y[0], W)$ W[ind] = float(val) - epslon $f2 = forward_propagation(X[0], y[0], W)$ W[ind] = float(val) dw_approx = float((np.subtract(float(f1['loss']),float(f2['loss'])))/(2*epslon)) approx_gradients.append(dw_approx) for ind, val in enumerate(dW.keys()): #print(ind, val) a = dW[val]b = approx_gradients[ind] res = gradient_check(a,b) print(val, res) dw1 8.533173538905722e-07 dw2 9.917020864221196e-07 dw3 2.3042874299018845e-11 dw4 3.300546022331628e-11 dw5 6.495243010971898e-11 dw6 2.497466895588638e-07 dw7 3.3170006663696535e-06 dw8 6.955443749306078e-10 dw9 1.3123786592084996e-13 Task 2: Optimizers for each epoch(1-100): for each data point in your data: using the functions forward_propagation() and backword_propagation() compute the gradients of weights update the weigts with help of gradients ex: w1 = w1-learning_rate*dw1 Algorithm with Vanilla update of weights • Task 2.1: you will be implementing the above algorithm with Vanilla update of weights In [143... path = '/content/drive/MyDrive/AAIC/Assignments/19.Backpropagation and Gradient Checking/practice/Copy of data.pkl' with open(path, 'rb') as f: data = pickle.load(f) #print(data.shape) X = data[:, :5]y = data[:, -1] weights = np.random.normal(0,0.01,9)lr = 0.001plot1 = dict() for epoch in range(1,101,1): for i in range(X.shape[0]): x = data[i,:5]y = data[i, -1]d1 = forward_propagation(x,y,weights) dw = np.array(list(backward_propagation(x,weights,d1).values())) weights = weights - lr*dw plot1[epoch] = d1['loss'] #https://stackoverflow.com/questions/37266341/plotting-a-python-dict-in-order-of-key-values import matplotlib.pylab as plt lists = sorted(plot1.items()) x, y = zip(*lists)plt.plot(x, y, label='Vanilla Update') plt.xlabel('Epochs') plt.ylabel('Loss') plt.legend(loc="upper right") plt.show() Vanilla Update 0.20 0.15 0.10 0.05 0.00 20 40 60 80 100 Epochs Algorithm with Momentum update of weights • Task 2.2: you will be implementing the above algorithm with Momentum update of weights In [142... path = '/content/drive/MyDrive/AAIC/Assignments/19.Backpropagation and Gradient Checking/practice/Copy of data.pkl' with open(path, 'rb') as f: data = pickle.load(f) #print(data.shape) X = data[:, :5]y = data[:, -1]gamma = 0.9v_previous = 0 weights = np.random.normal(0,0.01,9)1r = 0.001plot2 = dict() for epoch in range(1,101,1): for i in range(X.shape[0]): x = data[i,:5]y = data[i, -1]d1 = forward_propagation(x,y,weights) dw = np.array(list(backward_propagation(x, weights, d1).values())) momentum_term = (gamma * v_previous) gradient_term = (lr * dw) v_new = (momentum_term + gradient_term) weights = weights - v_new v_previous = v_new plot2[epoch] = d1['loss'] import matplotlib.pylab as plt lists = sorted(plot2.items()) x, y = zip(*lists)plt.plot(x, y, label = 'Momentum Update') plt.xlabel('Epochs') plt.ylabel('Loss') plt.legend(loc="upper right") plt.show() 0.08 Momentum Update 0.07 0.06 0.05 S 0.04 0.03 0.02 0.01 0.00 20 60 100 Epochs Algorithm with Adam update of weights • Task 2.3: you will be implementing the above algorithm with Adam update of weights path = '/content/drive/MyDrive/AAIC/Assignments/19.Backpropagation and Gradient Checking/practice/Copy of data.pkl' with open(path, 'rb') as f: data = pickle.load(f) #print(data.shape) X = data[:, :5]y = data[:, -1]beta1 = 0.9beta2 = 0.99eps = 1e-8weights = np.random.normal(0,0.01,9) lr = 0.001plot3 = dict() for epoch in range(1, 101, 1): m, v=0, 0for i in range(X.shape[0]): x = data[i,:5]y = data[i, -1]d1 = forward_propagation(x,y,weights) dw = np.array(list(backward_propagation(x,weights,d1).values())) m = (beta1 * m) + (np.subtract(1.0, beta1)) * (dw)v = (beta2 * v) + (np.subtract(1.0, beta2))* (np.square(dw))mhat = m / np.subtract(1.0, np.power(beta1,epoch)) vhat = v / np.subtract(1.0, np.power(beta2,epoch)) z = 1r * ((mhat) / (np.sqrt(vhat) + eps))weights = weights - z plot3[epoch] = d1['loss'] import matplotlib.pylab as plt lists = sorted(plot3.items()) x, y = zip(*lists)plt.plot(x, y, label = 'Adam Update') plt.xlabel('Epochs') plt.ylabel('Loss') plt.legend(loc="upper right") plt.show() Adam Update 0.08 0.06 0.04 0.02 0.00 20 40 60 80 100 Epochs Comparision plot between epochs and loss with different optimizers In [144... import matplotlib.pylab as plt p1 = sorted(plot1.items()) p2 = sorted(plot2.items()) p3 = sorted(plot3.items()) a, b = zip(*p1)c, d = zip(*p2)e, f = zip(*p3)plt.plot(a, b, label='Vanilla update ') plt.plot(c, d, label='Momentum update') plt.plot(e, f, label='Adam update') plt.xlabel('Epochs') plt.ylabel('Loss') plt.legend(loc="upper right") plt.show() Vanilla update Momentum update 0.20 Adam update 0.15 0.10 0.05 0.00 40 60 100 In []: