

```
import numpy as np
from sklearn.neural_network import MLPClassifier
# Define training data for digits 0-9
digits = [
  [[1, 1, 1],
   [1, 0, 1],
   [1, 0, 1],
   [1, 0, 1],
   [1, 1, 1]], #0
  [[0, 1, 0],
  [1, 1, 0],
   [0, 1, 0],
   [0, 1, 0],
   [1, 1, 1]], #1
  [[1, 1, 1],
   [0, 0, 1],
   [1, 1, 1],
   [1, 0, 0],
   [1, 1, 1]], # 2
  [[1, 1, 1],
   [0, 0, 1],
   [0, 1, 1],
   [0, 0, 1],
   [1, 1, 1]], #3
  [[1, 0, 1],
   [1, 0, 1],
   [1, 1, 1],
   [0, 0, 1],
   [0, 0, 1]], #4
  [[1, 1, 1],
   [1, 0, 0],
   [1, 1, 1],
   [0, 0, 1],
  [1, 1, 1]], #5
  [[1, 1, 1],
   [1, 0, 0],
  [1, 1, 1],
   [1, 0, 1],
   [1, 1, 1]], #6
```

```
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  [0, 0, 1],
  [0, 1, 0],
   [1, 0, 0],
   [1, 0, 0]], #7
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  [1, 1, 1],
   [1, 0, 1],
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   [1, 1, 1],
   [0, 0, 1],
   [1, 1, 1]] #9
1
# Convert to numpy array
X_train = np.array(digits)
# Flatten and reshape training data
X_train_flat = X_train.reshape(len(X_train), -1)
# Define labels
y_{train} = list(range(10)) # [0,1,2,3,4,5,6,7,8,9]
# Initialize and train MLPClassifier
clf = MLPClassifier(hidden_layer_sizes=(10,), activation='relu', max_iter=2000, random_state=42)
clf.fit(X_train_flat, y_train)
# Define test data (same as training for simplicity here)
X_test = np.array(digits)
# Flatten and reshape test data
X_{test_flat} = X_{test.reshape(len(X_{test}), -1)}
# Predict using trained model
predictions = clf.predict(X_test_flat)
# Output
for i, pred in enumerate(predictions):
  print(f"Test {i}: Predicted number is {pred}")
explain this code line by line
```

Of course! I'll explain your code **line by line**, clearly:

```
import numpy as np
from sklearn.neural_network import MLPClassifier
```

• Import libraries:

- `numpy` (as `np`) for array operations.
- `MLPClassifier` from `sklearn.neural_network`, which is a **Multi-Layer Perceptron** (a type of artificial neural network) for classification tasks.

```
python

# Define training data for digits 0-9
digits = [
    [[1, 1, 1],
       [1, 0, 1],
       [1, 0, 1],
       [1, 0, 1],
       [1, 1, 1]], # 0
    ...
]
```

• Create input data:

- `digits` is a list of 10 patterns, each representing the numbers 0–9.
- Each pattern is a **5×3 grid** (`1` for "on" pixels and `0` for "off" pixels).
- Example: The first pattern looks like a "0".

```
python

# Convert to numpy array
X_train = np.array(digits)
```

• Convert the `digits` list into a NumPy array.

• This makes it easier to process the data numerically.

```
python

# Flatten and reshape training data
X_train_flat = X_train.reshape(len(X_train), -1)
```

Flatten each 5×3 grid into a 1D array.

- o `reshape(len(X_train), -1)` means:
 - There are `len(X_train)` = 10 samples.
 - `-1` automatically calculates the number of features (5×3=15 features for each digit).
- Result: `X_train_flat` becomes a 10×15 matrix (10 digits, each described by 15 numbers).

```
python

# Define labels
y_train = list(range(10)) # [0,1,2,3,4,5,6,7,8,9]
```

• Create labels:

- Each pattern gets a label (0 to 9).
- So digit 0 is labeled as 0, digit 1 as 1, and so on.

```
python

# Initialize and train MLPClassifier
clf = MLPClassifier(hidden_layer_sizes=(10,), activation='relu', max_iter=2000, random_state=42)
```

• Initialize the neural network:

- **hidden_layer_sizes=(10,)** → 1 hidden layer with 10 neurons.
- o **activation='relu'** → Using **ReLU** (Rectified Linear Unit) activation function.
- o max_iter=2000 → Train up to 2000 iterations (epochs) for better convergence.
- random_state=42 → Fix randomness for reproducibility (you get the same results every time you run).

```
python

clf.fit(X_train_flat, y_train)
```

• Train the neural network:

- Inputs: `X_train_flat` (features)
- Outputs: `y train` (labels)
- The model learns patterns that map each 5×3 grid to the correct digit.

```
python

# Define test data (same as training for simplicity here)
X_test = np.array(digits)
```

• Prepare test data:

• Here, for simplicity, you use the same `digits` for testing.

```
python

# Flatten and reshape test data
X_test_flat = X_test.reshape(len(X_test), -1)
```

• Flatten the test data:

• Like before, reshape into a **10×15** array.

```
python

# Predict using trained model
predictions = clf.predict(X_test_flat)
```

• Make predictions:

• The model predicts the digit for each test sample.

```
# Output
for i, pred in enumerate(predictions):
    print(f"Test {i}: Predicted number is {pred}")
```

• Print the results:

o For each test sample, display the predicted number.

In short:

- You create simple digit images (grids).
- Flatten the grids into **feature vectors**.
- Train a **small neural network** to classify them.
- Then **test** it (on the same samples) and **print predictions**.

Would you also like me to show a **diagram of the flow** or **visualize the digits** for better understanding?

It will make it even easier!



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" hidden_neurons = 4\n",
   output_neurons = y.shape[1]\n",
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   output_bias = np.random.uniform(size=(1, output_neurons))\n",
11
   \n",
   for i in range(epochs):\n",
п
     # Forward propagation\n",
11
     hidden_layer_activation = np.dot(X, hidden_weights) + hidden_bias\n",
п
     hidden_layer_output = sigmoid(hidden_layer_activation)\n",
"\n",
п
      output_layer_activation = np.dot(hidden_layer_output, output_weights) + output_bias\n",
11
      predicted_output = sigmoid(output_layer_activation)\n",
"\n",
      # Backpropagation\n",
11
     error = y - predicted_output\n",
11
     d_predicted_output = error * sigmoid_derivative(predicted_output)\n",
"\n",
      error_hidden_layer = d_predicted_output.dot(output_weights.T)\n",
п
     d_hidden_layer = error_hidden_layer * sigmoid_derivative(hidden_layer_output)\n",
"\n",
     # Update weights and biases\n",
     output_weights += hidden_layer_output.T.dot(d_predicted_output) * learning_rate\n",
     output_bias += np.sum(d_predicted_output, axis=0, keepdims=True) * learning_rate\n",
     hidden_weights += X.T.dot(d_hidden_layer) * learning_rate\n",
```

```
hidden bias += np.sum(d hidden layer, axis=0, keepdims=True) * learning rate\n",
 " \n",
 " return predicted output\n",
  "# Example usage\n",
  X = np.array([[0, 0, 1], [0, 1, 1], [1, 0, 1], [1, 1, 1]])\n",
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 "print(predicted_output)\n"
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```

```
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```

Of course! Let's go line-by-line and explain your second code block carefully:

```
python
import numpy as np
```

- Import the numpy library as `np`.
- Numpy helps with handling arrays and performing matrix operations easily.

```
python
# Set seed for reproducibility
```

- Comment: A suggestion to fix random numbers for reproducibility (but actual seed setting is missing).
- Usually you would have something like `np.random.seed(42)` here.

```
python
# Define sigmoid and its derivative
```

• **Comment**: Now you are defining the activation function (**sigmoid**) and its derivative.

```
python

def sigmoid(x):
    return 1 / (1 + np.exp(-x))
```

- Define the sigmoid activation function.
- It "squashes" any real number to the range (0, 1).
- It is used for introducing non-linearity and for outputting probabilities.

```
python

def sigmoid_derivative(x):
    return x * (1 - x)
```

- Derivative of sigmoid function.
- Useful for **backpropagation** (to update weights).

```
# Training function
def train_neural_network(X, y, learning_rate, epochs):
```

- Define a function `train_neural_network` which will train a simple neural network.
- Inputs:
 - ∘ `x`: Training input data.
 - ∘ `y`: Target labels.
 - `learning rate`: Step size for weight updates.
 - `epochs`: Number of times to repeat training.

```
input_neurons = X.shape[1]
hidden_neurons = 4
output_neurons = y.shape[1]
```

- Set number of neurons:
 - `input neurons`: Based on features in `X` (here 3 inputs).
 - `hidden_neurons`: 4 hidden neurons (hardcoded).
 - o `output_neurons`: Output neurons, based on label size (1 output here).

```
hidden_weights = np.random.uniform(size=(input_neurons, hidden_neurons))
hidden_bias = np.random.uniform(size=(1, hidden_neurons))
output_weights = np.random.uniform(size=(hidden_neurons, output_neurons))
output_bias = np.random.uniform(size=(1, output_neurons))
```

- Randomly initialize weights and biases for:
 - Hidden layer and output layer.
- They are initialized with random values between 0 and 1.

```
python
    for i in range(epochs):
```

• Loop over number of epochs to train the model many times.

```
python
hidden_layer_activation = np.dot(X, hidden_weights) + hidden_bias
```

• Input to hidden layer = (Input * Weights) + Bias.



```
python
hidden_layer_output = sigmoid(hidden_layer_activation)
```

• Apply sigmoid activation on hidden layer.

```
python

output_layer_activation = np.dot(hidden_layer_output, output_weights) + output_bias
```

• Input to output layer = (Hidden output * Weights) + Bias.

```
python
predicted_output = sigmoid(output_layer_activation)
```

• Apply sigmoid activation to get final predicted output.

```
# Backpropagation
error = y - predicted_output
```

• Calculate error between true label and predicted output.

```
python

d_predicted_output = error * sigmoid_derivative(predicted_output)
```

• Gradient at output layer (how much to change the output layer weights).

```
python
error_hidden_layer = d_predicted_output.dot(output_weights.T)
```

• Error propagated back to hidden layer.

```
python

d_hidden_layer = error_hidden_layer * sigmoid_derivative(hidden_layer_output)
```

• Gradient at hidden layer.

```
python

output_weights += hidden_layer_output.T.dot(d_predicted_output) * learning_rate
 output_bias += np.sum(d_predicted_output, axis=0, keepdims=True) * learning_rate
```

• Update output layer weights and biases using gradients.

```
python

hidden_weights += X.T.dot(d_hidden_layer) * learning_rate
hidden_bias += np.sum(d_hidden_layer, axis=0, keepdims=True) * learning_rate
```

• Update hidden layer weights and biases using gradients.

```
python

return predicted_output
```

After training, return the final predicted output.

```
python

# Example usage
X = np.array([[0, 0, 1], [0, 1, 1], [1, 0, 1], [1, 1, 1]])
y = np.array([[0], [1], [0]])
```

- Define **input samples** `X` and corresponding **labels** `y`.
- This looks like a basic XOR problem dataset.

```
python

# Train the Neural Network
predicted_output = train_neural_network(X, y, learning_rate=0.1, epochs=10000)
```

- Call the training function.
- Train the neural network with:
 - learning rate = 0.1
 - epochs = 10,000

```
python

# Print the output
print(predicted_output)
```

- Print the final predicted output after training.
- The output will be an array of values close to 0 or 1 (but not exactly due to sigmoid activation).

Example Final Output:

```
[[0.02]
[0.94]
[0.94]
[0.07]]
```

• Close to expected outputs:

```
o (0,1,1,0)
```

Summary:

You manually implemented a **simple 1-hidden-layer neural network** from scratch:

- Used **Sigmoid Activation**.
- Did Forward Propagation.
- Did **Backpropagation** to update weights and biases.
- No external library like `sklearn` used for training.
- Simple and excellent for understanding how neural networks learn internally.

Would you also like me to draw a small **diagram** of how the data flows between input, hidden, and output layers for better clarity? **(It'll be simple and super helpful!)**Just let me know!



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"Y = np.array([[0], [1], [1], [0]])\n",
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"# Weights from hidden to output layer\n",
"W2 = np.random.uniform(size=(hidden_neuron, output_neuron))\n",
"# Bias for hidden layer\n",
"b1 = np.random.uniform(size=(1, hidden_neuron))\n",
"# Bias for output layer\n",
"b2 = np.random.uniform(size=(1, output_neuron))\n",
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"# Define the sigmoid activation function and its derivative\n",
"def sigmoid(x):\n",
" return 1 / (1 + np.exp(-x))\n",
"def sigmoid_derivative(x):\n",
" return x * (1 - x)\n",
"# Train the network using backpropagation\n",
"for i in range(epochs):\n",
" # Forward pass\n",
" hidden_layer_input = np.dot(X, W1) + b1\n",
" hidden_layer_output = sigmoid(hidden_layer_input)\n",
" output_layer_input = np.dot(hidden_layer_output, W2) + b2\n",
" output_layer_output = sigmoid(output_layer_input)\n",
"\n",
   # Backward pass\n",
```

```
output error = Y - output layer output\n",
 " output_delta = output_error * sigmoid_derivative(output_layer_output)\n",
 "\n",
 " hidden error = output delta.dot(W2.T)\n",
 " hidden_delta = hidden_error * sigmoid_derivative(hidden_layer_output)\n",
 "\n",
 " # Update weights and biases\n",
 " W2 += np.dot(hidden_layer_output.T, output_delta) * learning_rate\n",
 " b2 += np.sum(output delta, axis=0, keepdims=True) * learning rate\n",
 " W1 += np.dot(X.T, hidden_delta) * learning_rate\n",
 " b1 += np.sum(hidden_delta, axis=0, keepdims=True) * learning_rate\n",
 "\n",
 "# Test the network with some example inputs\n",
 x_{test} = np.array([[0, 0], [0, 1], [1, 0], [1, 1]])\n",
 y_{test} = np.array([[0], [1], [1], [0]])\n'',
 "\n",
 "hidden_layer_input = np.dot(x_test, W1) + b1\n",
 "hidden layer output = sigmoid(hidden layer input)\n",
 "output_layer_input = np.dot(hidden_layer_output, W2) + b2\n",
 "output_layer_output = sigmoid(output_layer_input)\n",
 "\n",
 "print(\"Input:\")\n",
 "print(x_test)\n",
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 "print(\"Expected Output:\")\n",
 "print(y_test)\n"
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```

Of course! Let's **explain your second code cell line-by-line** clearly:

Import Libraries

```
import numpy as np
```

• Import the **NumPy** library, which helps in working with arrays, matrices, and numerical operations.

Define Network Parameters

```
input_neuron = 2
hidden_neuron = 4
output_neuron = 1
learning_rate = 0.1
epochs = 10000
```

- `input_neuron = 2`: Two inputs (because XOR input has 2 values, e.g., [0,1]).
- `hidden_neuron = 4`: You are using 4 neurons in the hidden layer (a choice; could be more or fewer).
- `output neuron = 1`: Only one output (either 0 or 1 for XOR).
- `learning rate = 0.1`: How fast the network learns (small changes in weight updates).
- `epochs = 10000`: How many iterations (training cycles) to train.

Define Training Data (XOR Problem)

```
python

X = np.array([[0, 0], [0, 1], [1, 0], [1, 1]])
Y = np.array([[0], [1], [0]])
```

- `x`: Inputs standard XOR truth table inputs.
- `Y`: Expected Outputs for XOR:

```
\circ 0 XOR 0 = 0
```

- O XOR 1 = 1
- 1 XOR 0 = 1
- 1 XOR 1 = 0

Initialize Weights and Biases

```
python

W1 = np.random.uniform(size=(input_neuron, hidden_neuron))
W2 = np.random.uniform(size=(hidden_neuron, output_neuron))
b1 = np.random.uniform(size=(1, hidden_neuron))
b2 = np.random.uniform(size=(1, output_neuron))
```

- `W1`: Random weights from **input layer** → **hidden layer**.
- `W2`: Random weights from hidden layer → output layer.
- `b1`: Bias for hidden layer.
- `b2`: Bias for output layer.

(Weights and biases are initialized randomly)

Define Activation Functions

```
python

def sigmoid(x):
    return 1 / (1 + np.exp(-x))
```

• The **sigmoid function** "squashes" values between **0 and 1**.

```
python

def sigmoid_derivative(x):
    return x * (1 - x)
```

• The **derivative** of the sigmoid function, used in **backpropagation** to adjust weights.

Training the Network (Forward + Backward Pass)

```
python
for i in range(epochs):
```

• Loop through **10000 times** to train the network.

Forward Propagation



```
hidden_layer_input = np.dot(X, W1) + b1
hidden_layer_output = sigmoid(hidden_layer_input)
output_layer_input = np.dot(hidden_layer_output, W2) + b2
output_layer_output = sigmoid(output_layer_input)
```

- hidden_layer_input: Multiply inputs and weights, then add bias.
- hidden_layer_output: Apply sigmoid activation to the hidden layer.
- output_layer_input: Multiply hidden outputs and second set of weights, add output bias.
- **output_layer_output**: Apply **sigmoid** again for final prediction.

Backward Propagation

```
python

output_error = Y - output_layer_output
output_delta = output_error * sigmoid_derivative(output_layer_output)
```

- Calculate the **error**: (Expected output Predicted output).
- Calculate **output delta**: How much change is needed at output.

```
python
hidden_error = output_delta.dot(W2.T)
hidden_delta = hidden_error * sigmoid_derivative(hidden_layer_output)
```

- Find how much error is at the hidden layer (by back-propagating).
- Calculate **hidden delta**: How much change is needed at hidden.

Update Weights and Biases

```
python

W2 += np.dot(hidden_layer_output.T, output_delta) * learning_rate
b2 += np.sum(output_delta, axis=0, keepdims=True) * learning_rate
W1 += np.dot(X.T, hidden_delta) * learning_rate
b1 += np.sum(hidden_delta, axis=0, keepdims=True) * learning_rate
```

- Adjust `W2`, `b2`, `W1`, `b1` according to calculated deltas multiplied by learning rate.
- This is how the model "learns" by minimizing the error!

Testing the Network After Training

```
python

x_test = np.array([[0, 0], [0, 1], [1, 0], [1, 1]])
```



```
y_{test} = np.array([[0], [1], [1], [0]])
```

• Inputs and expected outputs for testing (same as training data).

Forward Pass for Testing

```
hidden_layer_input = np.dot(x_test, W1) + b1
hidden_layer_output = sigmoid(hidden_layer_input)
output_layer_input = np.dot(hidden_layer_output, W2) + b2
output_layer_output = sigmoid(output_layer_input)
```

• Same forward propagation but now for testing data.

Print Results

```
print("Input:")
print(x_test)
print("Output:")
print(output_layer_output)
print("Expected Output:")
print(y_test)
```

- Prints:
 - Test Inputs.
 - Predicted Outputs.
 - Actual Expected Outputs.

In Short:

This code trains a **simple 2-4-1 Neural Network** to learn the **XOR** function using **sigmoid activation** and **backpropagation**.

ightharpoonup Initially, outputs will not match perfectly, but after 10,000 epochs, they should be close to m 0 or m 1.

Would you also like me to draw a **diagram** showing the architecture (input \rightarrow hidden \rightarrow output) to visualize it better? \cancel{A} $\not \Leftrightarrow$

(Just say "yes" if you want!)



import numpy as np

class ART1:

```
def __init__(self, input_size, num_categories, vigilance):
    self.input_size = input_size
    self.num_categories = num_categories
    self.vigilance = vigilance
    # Weight initialization (set to 1s, classical ART1)
    self.weights = np.ones((num_categories, input_size * 2)) # for complement coding
  def complement code(self, input vector):
    # Add complement to input vector (1s and 0s assumed)
    return np.concatenate([input_vector, 1 - input_vector])
  def match_category(self, input_vector):
    # Calculate match (activation) as sum of minimums
    return np.array([np.sum(np.minimum(input_vector, w)) for w in self.weights])
  def vigilance_test(self, input_vector, category_index):
    # Match quality (fuzzy match) test
    numerator = np.sum(np.minimum(input_vector, self.weights[category_index]))
    denominator = np.sum(input_vector)
    return numerator / denominator >= self.vigilance
  def train(self, input_patterns):
    for pattern in input_patterns:
      input_vector = self.complement_code(pattern)
      while True:
         match_scores = self.match_category(input_vector)
         # Choose best matching category
         chosen = np.argmax(match_scores)
         # If it passes vigilance, learn
        if self.vigilance_test(input_vector, chosen):
           self.weights[chosen] = np.minimum(self.weights[chosen], input_vector)
           break
         else:
           # Disable this category for current input
           self.weights[chosen] = np.zeros_like(self.weights[chosen])
  def predict(self, input_vector):
    input_vector = self.complement_code(input_vector)
    match_scores = self.match_category(input_vector)
    return np.argmax(match_scores)
# --- Example usage ---
inputs = np.array([
  [1, 0, 0, 0],
  [0, 1, 0, 1],
  [1, 1, 0, 0],
  [0, 0, 1, 1]
```

Of course! Let's go line-by-line through your ART1 neural network code:

```
python
import numpy as np
```

• Imports the **NumPy** library for array operations (needed for fast mathematical calculations).

```
python

class ART1:
```

• Defines a **class** called **`ART1`**, which implements the **Adaptive Resonance Theory 1** algorithm (unsupervised clustering for binary input).

```
python

def __init__(self, input_size, num_categories, vigilance):
```

- **Constructor** (`__init__` function) that runs when you create an ART1 object.
- It receives:
 - `input size`: Number of input features.
 - `num_categories`: Maximum number of clusters/categories.
 - `vigilance`: A threshold to determine how strict matching should be (between 0 and 1).

```
python

self.input_size = input_size
self.num_categories = num_categories
self.vigilance = vigilance
```

Saves the input parameters inside the object for later use.

```
python

self.weights = np.ones((num_categories, input_size * 2))  # for complement coding
```

- Initializes the **weights** as a 2D array full of ones.
- Size = (number of categories) × (input size × 2), because **complement coding** is used (more on this soon).

```
python

def complement_code(self, input_vector):
```

- Defines a function to create **complement coded** input vectors.
- Complement coding is a technique that helps ART1 preserve information better by adding `(1 input)` for each input feature.

```
python

return np.concatenate([input_vector, 1 - input_vector])
```

• Takes the input vector (like `[1, 0]`) and adds its complement (`[0, 1]`), making it `[1, 0, 0, 1]`.

```
python

def match_category(self, input_vector):
```

• Defines a function to find **how well** the input matches **each category**.

```
python

return np.array([np.sum(np.minimum(input_vector, w)) for w in self.weights])
```

- For each weight vector (category):
 - Calculates the **element-wise minimum** between the input and the weight.
 - Sums these minimum values.
 - The higher the sum, the better the match.

```
python

def vigilance_test(self, input_vector, category_index):
```

Defines a function to check if a chosen category passes the vigilance test.

```
numerator = np.sum(np.minimum(input_vector, self.weights[category_index]))
denominator = np.sum(input_vector)
```

- Calculates:
 - **Numerator**: How much of the input is actually matched by the category.
 - **Denominator**: Total active features in input.

```
python
return numerator / denominator >= self.vigilance
```

- If the match is **good enough** (ratio ≥ vigilance), returns **True**.
- Otherwise, returns False (category fails vigilance check).

```
python

def train(self, input_patterns):
```

• Defines a **training function** that takes multiple input patterns and tries to cluster them.

```
python

for pattern in input_patterns:
```

• Loop through each input pattern.

```
python
input_vector = self.complement_code(pattern)
```

• Apply **complement coding** to the pattern.

```
python

while True:
```

• Keeps trying until the input is assigned to a category.

```
python

match_scores = self.match_category(input_vector)
```

Calculate how well the input matches every category.



```
python
    chosen = np.argmax(match_scores)
```

• Choose the category with the highest match score.

```
python

if self.vigilance_test(input_vector, chosen):
```

• **Check** if the chosen category **passes** the vigilance test.

```
python

self.weights[chosen] = np.minimum(self.weights[chosen], input_vector)
```

- **Learn**: Update the category's weights by taking the **element-wise minimum** between the current weight and the input.
- Makes the category more specialized to the pattern.

```
python break
```

• Successfully assigned; exit the loop.

```
python else:
```

• If vigilance test **fails**:

```
python

self.weights[chosen] = np.zeros_like(self.weights[chosen])
```

• **Disable** the category by setting all its weights to 0 (so it can't be selected again for this pattern).

```
python

def predict(self, input_vector):
```

• Defines a **prediction function**.

```
python
input_vector = self.complement_code(input_vector)
```

• Apply complement coding to the input.

```
python

match_scores = self.match_category(input_vector)
```

• Calculate match scores with all categories.

```
python
    return np.argmax(match_scores)
```

• Return the index (category number) with the highest match.

Example usage

```
inputs = np.array([
     [1, 0, 0, 0],
     [0, 1, 0, 1],
     [1, 1, 0, 0],
     [0, 0, 1, 1]
])
```

• Defines 4 binary input patterns.

```
python
art = ART1(input_size=4, num_categories=4, vigilance=0.7)
```

- Create an ART1 network:
 - o 4 input features
 - 4 maximum categories
 - Vigilance threshold of 0.7

```
python
art.train(inputs)
```

• Train the ART1 model on the given inputs.

```
print("\nPredictions:")
for input_vector in inputs:
    category = art.predict(input_vector)
    print(f"Input: {input_vector}, Predicted Category: {category}")
```

- Loop over all input patterns again.
- Predict which category each pattern belongs to.
- Print the input and its predicted category.

In short:

- ART1 clusters binary input patterns into categories.
- It **learns adaptively** and ensures new inputs match well enough (**vigilance**), otherwise creates new categories.
- **Complement coding** helps in stability and discrimination.
- Weights are reduced (element-wise minimum) to maintain the best matching features only.

Would you like me to also create a **simple visual flowchart** or **example run** for easier understanding?



(If yes, just say!)



```
import numpy as np
class HopfieldNetwork:
  def __init__(self):
    self.weights = None
  def train(self, patterns):
    num_neurons = patterns.shape[1]
    self.weights = np.zeros((num_neurons, num_neurons))
    for p in patterns:
      self.weights += np.outer(p, p)
    np.fill_diagonal(self.weights, 0) # Remove self-connections
    self.weights /= patterns.shape[0] # Normalize
  def activation(self, x):
    return np.where(x \ge 0, 1, -1)
  def recall(self, pattern, steps=5):
    output = pattern.copy()
    for _ in range(steps):
```

```
output = self.activation(np.dot(self.weights, output))
    return output
# --- Example usage ---
if __name__ == "__main__":
  # Define binary patterns to store (-1 and 1)
  patterns = np.array([
    [1, 1, -1, -1],
    [-1, -1, 1, 1],
    [1, -1, 1, -1],
    [-1, 1, -1, 1]
  ])
  hopfield_net = HopfieldNetwork()
  hopfield net.train(patterns)
                                                                                      print("Testing recall
on original patterns:")
  for i, p in enumerate(patterns):
    output = hopfield_net.recall(p)
    print(f"Pattern {i+1}:")
    print("Input: ", p)
    print("Output: ", output)
    print()
  # Test with noisy input
  noisy_input = np.array([1, 1, -1, 1]) # Flip one bit of first pattern
  output = hopfield_net.recall(noisy_input)
  print("Testing with noisy input:")
  print("Noisy input: ", noisy_input)
  print("Recovered: ", output)
.....explain this code line by line
```

Of course! Let's go line-by-line and explain your Hopfield network code clearly:

```
python
import numpy as np
```

• Import the **NumPy** library to handle matrices and arrays efficiently.

```
python
class HopfieldNetwork:
```

• Define a **class** named `HopfieldNetwork` that models a **Hopfield neural network** (an associative memory system).

```
python

def __init__(self):
    self.weights = None
```

- **Constructor** (`__init__` method) initializes the `weights` attribute to `None`.
- `weights` will later store the connection strengths between neurons.

```
python

def train(self, patterns):
```

• Define a **train** method to **store** (memorize) patterns into the network.

```
python
num_neurons = patterns.shape[1]
```

- Find out how many **neurons** (features) each pattern has.
- `patterns` is a 2D array: rows = patterns, columns = neurons.

```
python

self.weights = np.zeros((num_neurons, num_neurons))
```

- Create a weight matrix initialized to all zeros.
- Size = (number of neurons × number of neurons).

```
for p in patterns:
    self.weights += np.outer(p, p)
```

- Loop over each pattern `p`.
- Update the weights by **adding** the outer product of `p` with itself.
 - The outer product builds a full matrix based on how each neuron should influence others.

```
np.fill_diagonal(self.weights, 0) # Remove self-connections
```

- Set the **diagonal** of the weight matrix to 0.
- No neuron should influence itself.

```
python
self.weights /= patterns.shape[0] # Normalize
```

- **Normalize** the weights by dividing by the number of patterns.
- This prevents the weights from becoming too large as you store more patterns.

```
python

def activation(self, x):
```

• Define an activation function.

- For each neuron:
 - o If the input is ≥ 0, output 1.
 - ∘ If the input is **< 0**, output **-1**.
- This ensures binary-like output values (-1 or 1).

```
python

def recall(self, pattern, steps=5):
```

- Define a recall method:
 - It tries to recover (retrieve) a stored pattern starting from an input.
 - It will update the pattern for a fixed number of steps.

```
python

output = pattern.copy()
```

• Copy the input pattern to `output` (so as not to modify the original input).

```
python

for _ in range(steps):
    output = self.activation(np.dot(self.weights, output))
```

- For each step:
 - Multiply the weights with the current output (`dot` product).

• Apply the activation function to decide new neuron states.

```
python
return output
```

• After updating the neurons for `steps` times, return the final recalled pattern.

Now the example usage:

```
python
if __name__ == "__main__":
```

• Run this part **only if** the file is executed directly (not imported as a module).

```
patterns = np.array([
        [1, 1, -1, -1],
        [-1, -1, 1],
        [1, -1, 1, -1],
        [-1, 1, -1, 1]
])
```

- Define 4 training patterns.
- Each pattern is a vector of -1s and 1s.

```
python

hopfield_net = HopfieldNetwork()
hopfield_net.train(patterns)
```

- Create an instance of the Hopfield network.
- Train it on the given patterns (store them into memory).

```
print("Testing recall on original patterns:")
for i, p in enumerate(patterns):
    output = hopfield_net.recall(p)
    print(f"Pattern {i+1}:")
    print("Input: ", p)
    print("Output: ", output)
    print()
```

- Loop over each stored pattern:
 - Test if the network can recall (retrieve) the pattern correctly.

Print input and recalled output.

```
python
noisy_input = np.array([1, 1, -1, 1]) # Flip one bit of first pattern
```

• Create a **noisy version** of the first pattern by flipping one bit.

```
python

output = hopfield_net.recall(noisy_input)
```

• Try to **recall** the original pattern from the noisy input.

```
print("Testing with noisy input:")
print("Noisy input: ", noisy_input)
print("Recovered: ", output)
```

- Print the noisy input and the **recovered** pattern.
- **Goal:** See if the Hopfield network can correct the noise and retrieve the correct pattern.

In short:

- Hopfield networks can store patterns and retrieve them even if the input is noisy.
- It uses a **weight matrix** learned by **outer products** of the patterns.
- Updates the neurons in parallel for a few steps.
- Uses simple binary threshold activation (1 or -1).

Would you like me to also show you a **simple small visual animation** of how noisy recall works step-by-step?

(It will make it even easier!)

Just let me know! 📈



```
import tensorflow as tf
import numpy as np
import cv2

# Load the pre-trained model
model = tf.saved_model.load('D:\\faster_rcnn_resnet50_v1_640x640_coco17_tpu-8\\saved_model')

# Load the label map
label_map = {1: 'person', 3: 'car', 18: 'dog'} # Replace with your label map
```

```
# Load and preprocess the input image
image = cv2.imread("C:/Users/athar/OneDrive/Desktop/Practical/ANNPrac/image.jpg")
image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
# Convert to uint8 (Fix for TypeError)
image = tf.convert_to_tensor(image, dtype=tf.uint8)
# Expand dimensions for batch processing
image = tf.expand_dims(image, axis=0)
# Run object detection
detections = model(image)
# Extract results
boxes = detections['detection_boxes'][0].numpy()
scores = detections['detection_scores'][0].numpy()
classes = detections['detection_classes'][0].numpy().astype(int)
# Set confidence threshold
threshold = 0.5
filtered boxes = boxes[scores >= threshold]
filtered_classes = classes[scores >= threshold]
# Convert tensor back to numpy for OpenCV drawing
image_np = image.numpy()[0]
# Draw bounding boxes and labels
for box, cls in zip(filtered_boxes, filtered_classes):
  ymin, xmin, ymax, xmax = box
  h, w, _ = image_np.shape
  ymin, xmin, ymax, xmax = int(ymin * h), int(xmin * w), int(ymax * h), int(xmax * w)
  label = label_map.get(cls, 'Unknown')
  cv2.rectangle(image_np, (xmin, ymin), (xmax, ymax), (0, 255, 0), 2)
  cv2.putText(image_np, label, (xmin, ymin - 10), cv2.FONT_HERSHEY_SIMPLEX, 0.9, (0, 255, 0), 2)
# Display the image with detections
cv2.imshow('Object Detection', image_np)
cv2.waitKey(0)
cv2.destroyAllWindows()
                                    .....expalin this code line by line
```

Of course! Let's go line by line and explain your TensorFlow object detection code clearly:

```
import tensorflow as tf
import numpy as np
import cv2
```



- Import necessary libraries:
 - o `tensorflow` for running the detection model,
 - o `numpy` for numerical operations,
 - o `cv2` (OpenCV) for image processing and visualization.

```
python

# Load the pre-trained model
model = tf.saved_model.load('D:\\faster_rcnn_resnet50_v1_640x640_coco17_tpu-8\\saved_model')
```

- Load a pre-trained Faster R-CNN ResNet50 model from a saved path.
- `tf.saved_model.load` loads the entire trained model into memory.

```
python

# Load the label map
label_map = {1: 'person', 3: 'car', 18: 'dog'} # Replace with your label map
```

- Create a **label map** that maps **class IDs** (like 1, 3, 18) to **human-readable labels** (like 'person', 'car', 'dog').
- Normally you would load the full COCO label map, but here you manually defined a small one.

```
python

# Load and preprocess the input image
image = cv2.imread("C:/Users/athar/OneDrive/Desktop/Practical/ANNPrac/image.jpg")
```

- Load an image from your computer using OpenCV.
- Image is loaded in **BGR** color format by default.

```
python
image = cv2.cvtColor(image, cv2.COLOR_BGR2RGB)
```

• Convert the image from **BGR** to **RGB** because TensorFlow models expect RGB input.

```
python

# Convert to uint8 (Fix for TypeError)
image = tf.convert_to_tensor(image, dtype=tf.uint8)
```

- Convert the image from NumPy array to TensorFlow tensor of type unsigned 8-bit integer (`uint8`).
- Required format for TensorFlow models.



```
# Expand dimensions for batch processing
image = tf.expand_dims(image, axis=0)
```

- Add an extra dimension to the image to represent a **batch** of size 1.
- Deep learning models expect inputs like `[batch_size, height, width, channels]`.

```
python

# Run object detection
detections = model(image)
```

- Pass the image through the model to get **detections**.
- `detections` is a dictionary containing outputs like:
 - o `detection_boxes`
 - o `detection_scores`
 - `detection classes`
 - o etc.

```
# Extract results
boxes = detections['detection_boxes'][0].numpy()
scores = detections['detection_scores'][0].numpy()
classes = detections['detection_classes'][0].numpy().astype(int)
```

- Extract specific parts from the detections:
 - `boxes`: bounding box coordinates for each detected object.
 - o `scores`: confidence scores (how sure the model is about the detection).
 - o `classes`: class IDs for each detected object.
- Use `[0]` because there's only **one image** in the batch.
- Convert tensors to NumPy arrays for further processing.

```
python

# Set confidence threshold
threshold = 0.5
```

• Set a threshold: only keep detections with confidence score >= 50%.

```
python

filtered_boxes = boxes[scores >= threshold]
filtered_classes = classes[scores >= threshold]
```

- Filter the bounding boxes and classes based on the threshold.
- Only keep the high-confidence detections.

```
python

# Convert tensor back to numpy for OpenCV drawing
image_np = image.numpy()[0]
```

- Convert the tensor image back to a NumPy array for **OpenCV drawing**.
- Again `[0]` because batch size = 1.

```
python

# Draw bounding boxes and labels
for box, cls in zip(filtered_boxes, filtered_classes):
```

• Loop through each filtered detection (bounding box and class).

```
python

ymin, xmin, ymax, xmax = box
h, w, _ = image_np.shape
ymin, xmin, ymax, xmax = int(ymin * h), int(xmin * w), int(ymax * h), int(xmax * w)
```

- Each bounding box is normalized (values between 0 and 1).
- Multiply by image height `h` and width `w` to get pixel coordinates.

```
python
label = label_map.get(cls, 'Unknown')
```

- Find the label name for the detected class.
- If class ID not found in `label_map`, default to `'Unknown'`.

```
python

cv2.rectangle(image_np, (xmin, ymin), (xmax, ymax), (0, 255, 0), 2)
```

• Draw a green bounding box around the detected object.

```
python

cv2.putText(image_np, label, (xmin, ymin - 10), cv2.FONT_HERSHEY_SIMPLEX, 0.9, (0, 255, 0), 2)
```

• Draw the **label text** (e.g., "dog", "person") above the bounding box.

```
# Display the image with detections
cv2.imshow('Object Detection', image_np)
cv2.waitKey(0)
cv2.destroyAllWindows()
```

- **Display** the resulting image with drawn boxes and labels in a window.
- `cv2.waitKey(0)` waits indefinitely for any key press.
- `cv2.destroyAllWindows()` closes the window.

🔥 Summary:

- Load model
- Load and prepare the image
- Detect objects
- Filter based on confidence
- Draw bounding boxes and labels
- Display the final annotated image 🗸

Would you also like me to explain **how you could improve it** (like dynamic label loading or using TensorFlow's `object_detection` API visualization tools)?

It would make your project even more professional!



```
import tensorflow as tf
from tensorflow import keras
from tensorflow.keras import layers, models
import matplotlib.pyplot as plt
import numpy as np
import os
# Load and preprocess dataset (CIFAR-10 for demonstration)
(x_train, y_train), (x_test, y_test) = keras.datasets.cifar10.load_data()
# Normalize pixel values to be between 0 and 1
x_{train}, x_{test} = x_{train} / 255.0, x_{test} / 255.0
# Convert labels to categorical format
y_train, y_test = keras.utils.to_categorical(y_train, 10), keras.utils.to_categorical(y_test, 10)
# Data Augmentation
data_augmentation = keras.Sequential([
  layers.RandomFlip("horizontal"),
  layers.RandomRotation(0.1),
```

```
layers.RandomZoom(0.1),
])
# Build CNN Model
def build_model():
  model = models.Sequential([
    data_augmentation,
    layers.Conv2D(32, (3, 3), activation='relu', input_shape=(32, 32, 3)),
    layers.BatchNormalization(),
    layers.MaxPooling2D((2, 2)),
    layers.Dropout(0.25),
    layers.Conv2D(64, (3, 3), activation='relu'),
    layers.BatchNormalization(),
    layers.MaxPooling2D((2, 2)),
    layers.Dropout(0.25),
    layers.Conv2D(128, (3, 3), activation='relu'),
    layers.BatchNormalization(),
    layers.MaxPooling2D((2, 2)),
    layers.Dropout(0.25),
    layers.Flatten(),
    layers.Dense(256, activation='relu'),
    layers.BatchNormalization(),
    layers.Dropout(0.5),
    layers.Dense(10, activation='softmax')
  ])
  return model
# Compile Model
model = build_model()
model.compile(optimizer=keras.optimizers.Adam(learning_rate=0.001),
        loss='categorical_crossentropy',
        metrics=['accuracy'])
# Train the Model
history = model.fit(x_train, y_train, epochs=20, batch_size=64, validation_data=(x_test, y_test))
# Plot Accuracy & Loss
fig, axs = plt.subplots(2, 1, figsize=(10, 8))
# Accuracy Graph
axs[0].plot(history.history['accuracy'], label='Train Accuracy')
axs[0].plot(history.history['val_accuracy'], label='Validation Accuracy')
axs[0].set_title('Model Accuracy')
axs[0].set_ylabel('Accuracy')
axs[0].set_xlabel('Epoch')
axs[0].legend()
# Loss Graph
```

```
axs[1].plot(history.history['loss'], label='Train Loss')
axs[1].plot(history.history['val_loss'], label='Validation Loss')
axs[1].set_title('Model Loss')
axs[1].set_ylabel('Loss')
axs[1].set_xlabel('Epoch')
axs[1].legend()

plt.tight_layout()
plt.show()

# Evaluate Model
final_loss, final_acc = model.evaluate(x_test, y_test)
print(f"Final Test Accuracy: {final_acc:.4f}")
.....explain this code line by line
```

Of course! Let's **explain your code line by line** so you fully understand it:

```
import tensorflow as tf
from tensorflow import keras
from tensorflow.keras import layers, models
import matplotlib.pyplot as plt
import numpy as np
import os
```

- Import essential libraries:
 - `tensorflow`, `keras`, and `layers/models` for building and training the CNN.
 - `matplotlib.pyplot` for plotting graphs.
 - `numpy` for numerical operations.
 - o `os` (not used in this code, but often for file paths).

```
python

# Load and preprocess dataset (CIFAR-10 for demonstration)
(x_train, y_train), (x_test, y_test) = keras.datasets.cifar10.load_data()
```

- Load the **CIFAR-10 dataset** (60,000 small color images, 10 classes like airplane, car, cat, etc.).
- It automatically splits into:
 - o `x_train`, `y_train`: training data and labels
 - `x_test`, `y_test`: testing data and labels

```
# Normalize pixel values to be between 0 and 1
x_train, x_test = x_train / 255.0, x_test / 255.0
```

- Images have pixel values between 0-255.
- Normalize them to range **[0,1]** by dividing by 255 to speed up training and improve convergence.

```
python

# Convert labels to categorical format
y_train, y_test = keras.utils.to_categorical(y_train, 10), keras.utils.to_categorical(y_test, 10)
```

- Labels (originally integers like 0,1,2...) are **one-hot encoded**.
 - Example: Label `3` → `[0,0,0,1,0,0,0,0,0,0]`
- Required for classification using `softmax` at the output layer.

- Data augmentation to artificially increase training data by modifying images:
 - Random flip horizontally,
 - Small rotation (10% of 360°),
 - o Small zoom.
- Helps improve model's ability to generalize.

```
python

# Build CNN Model
def build_model():
```

• Define a **function** `build_model()` to create and return the CNN.

```
python

model = models.Sequential([
```

• Start a **Sequential model** (stacking layers one after another).

```
python

data_augmentation,
```

• Apply data augmentation layer first (only during training).

```
python
layers.Conv2D(32, (3, 3), activation='relu', input_shape=(32, 32, 3)),
```

- 2D Convolution Layer:
 - 32 filters of size 3×3,
 - `ReLU` activation,
 - Input shape is (32x32 pixels, 3 color channels).

```
python
layers.BatchNormalization(),
```

• Normalize activations from the previous layer to make training faster and more stable.

```
python
layers.MaxPooling2D((2, 2)),
```

• Reduce image size by taking the maximum over a 2×2 area (downsampling).

```
python
layers.Dropout(0.25),
```

• Randomly set 25% of activations to zero during training (helps prevent **overfitting**).

```
layers.Conv2D(64, (3, 3), activation='relu'),
layers.BatchNormalization(),
layers.MaxPooling2D((2, 2)),
layers.Dropout(0.25),
```

- 2nd Convolution block:
 - More filters (64),
 - Same pattern: $conv \rightarrow batchnorm \rightarrow pool \rightarrow dropout$.

```
layers.Conv2D(128, (3, 3), activation='relu'),
layers.BatchNormalization(),
layers.MaxPooling2D((2, 2)),
layers.Dropout(0.25),
```

• 3rd Convolution block:

• Even more filters (128) for capturing complex patterns.

```
python
layers.Flatten(),
```

• Flatten output into a 1D vector to feed into Dense layers.

```
python
layers.Dense(256, activation='relu'),
```

• Fully connected (dense) layer with 256 neurons, `ReLU` activation.

```
layers.BatchNormalization(),
layers.Dropout(0.5),
```

• Normalize and apply a **stronger dropout (50%)** for further regularization before output.

```
python
layers.Dense(10, activation='softmax')
```

- Final output layer:
 - 10 neurons (for 10 classes),
 - `softmax` activation to output **probability distribution** over classes.

```
python

])
return model
```

• Close the model and return it.

- Build and **compile** the model:
 - Adam optimizer with learning rate 0.001,

- o Categorical crossentropy loss (for multi-class classification),
- Monitor accuracy during training.

```
python

# Train the Model
history = model.fit(x_train, y_train, epochs=20, batch_size=64, validation_data=(x_test, y_test))
```

- Train the model for 20 epochs with a batch size of 64.
- Use `x_test`, `y_test` for **validation** after every epoch.
- Save training progress into `history`.

```
python

# Plot Accuracy & Loss
fig, axs = plt.subplots(2, 1, figsize=(10, 8))
```

• Create two subplots (one for accuracy, one for loss) with size 10×8 inches.

```
# Accuracy Graph
axs[0].plot(history.history['accuracy'], label='Train Accuracy')
axs[0].plot(history.history['val_accuracy'], label='Validation Accuracy')
axs[0].set_title('Model Accuracy')
axs[0].set_ylabel('Accuracy')
axs[0].set_xlabel('Epoch')
axs[0].legend()
```

- Plot the training and validation accuracy over epochs.
- Add labels, title, and legends.

```
python

# Loss Graph
axs[1].plot(history.history['loss'], label='Train Loss')
axs[1].plot(history.history['val_loss'], label='Validation Loss')
axs[1].set_title('Model Loss')
axs[1].set_ylabel('Loss')
axs[1].set_xlabel('Epoch')
axs[1].legend()
```

• Plot the training and validation **loss** over epochs similarly.

```
python

plt.tight_layout()
plt.show()
```

Adjust layout and display the graphs.

```
# Evaluate Model
final_loss, final_acc = model.evaluate(x_test, y_test)
print(f"Final Test Accuracy: {final_acc:.4f}")
```

- Evaluate the final model performance on the test set.
- Print the final **accuracy** (formatted to 4 decimal places).

† Summary:

- Load CIFAR-10 dataset
- Normalize and augment images
- Build a CNN model
- Train and validate the model
- Plot training progress
- Evaluate final performance

Would you like me to also give you a **diagram** showing the CNN structure you built? **(i)** (It would be helpful for your notes or presentation!)

Let me know! 🚀



```
import tensorflow as tf
from tensorflow import keras
from tensorflow.keras import layers
# Load MNIST dataset
(x_train, y_train), (x_test, y_test) = keras.datasets.mnist.load_data()
x train, x test = x train / 255.0, x test / 255.0 # Normalize
# Reshape for CNN (adding channel dimension)
x_{train} = x_{train.reshape}(-1, 28, 28, 1)
x_{test} = x_{test.reshape}(-1, 28, 28, 1)
# Define CNN model
model = keras.Sequential([
  layers.Conv2D(32, (3, 3), activation='relu', input_shape=(28, 28, 1)),
  layers.MaxPooling2D((2, 2)),
  layers.Conv2D(64, (3, 3), activation='relu'),
  layers.MaxPooling2D((2, 2)),
  layers.Conv2D(64, (3, 3), activation='relu'),
  layers.Flatten(),
  layers.Dense(64, activation='relu'),
  layers.Dense(10, activation='softmax') # Output layer for 10 classes
```

```
# Compile model
model.compile(optimizer='adam', loss='sparse_categorical_crossentropy', metrics=['accuracy'])

# Train model
model.fit(x_train, y_train, epochs=5, validation_data=(x_test, y_test))

# Evaluate model
test_loss, test_acc = model.evaluate(x_test, y_test)
print(f"Test Accuracy: {test_acc:.4f}")
......explain this code line by line
```

Of course! Let's **explain your second code line by line**:

```
import tensorflow as tf
from tensorflow import keras
from tensorflow.keras import layers
```

- Import libraries:
 - `tensorflow` and `keras` for building deep learning models.
 - `layers` for adding CNN layers easily.

```
python
# Load MNIST dataset
(x_train, y_train), (x_test, y_test) = keras.datasets.mnist.load_data()
```

- Load the MNIST dataset:
 - Handwritten digits (0–9).
 - 60,000 training images and 10,000 testing images.
 - Each image is 28×28 pixels in grayscale.

```
python
x_train, x_test = x_train / 255.0, x_test / 255.0 # Normalize
```

- Normalize pixel values from `[0, 255]` to `[0, 1]`.
- Helps the neural network train faster and more accurately.

```
# Reshape for CNN (adding channel dimension)
x_train = x_train.reshape(-1, 28, 28, 1)
```

```
x_{test} = x_{test.reshape(-1, 28, 28, 1)}
```

- CNNs expect 4D input: (batch_size, height, width, channels).
- MNIST is grayscale, so **channels=1**.
- `-1` means "infer batch size automatically" (it keeps the number of samples the same).

```
python

# Define CNN model
model = keras.Sequential([
```

• Start defining a **Sequential model** — simple layer-by-layer model.

```
python
layers.Conv2D(32, (3, 3), activation='relu', input_shape=(28, 28, 1)),
```

• 1st Convolution Layer:

- o 32 filters (kernels) of size 3×3,
- o Activation: ReLU,
- o Input size: 28×28×1.

```
python
layers.MaxPooling2D((2, 2)),
```

• Max Pooling Layer:

- Downsample (reduce) the feature maps by selecting maximum value from 2×2 regions.
- Helps in reducing computation and controlling overfitting.

```
python
layers.Conv2D(64, (3, 3), activation='relu'),
```

• 2nd Convolution Layer:

- 64 filters of size 3×3,
- `ReLU` activation.

```
python
layers.MaxPooling2D((2, 2)),
```

Again Max Pooling to further reduce spatial size.

```
python
layers.Conv2D(64, (3, 3), activation='relu'),
```

• 3rd Convolution Layer:

- o 64 filters again,
- No pooling after this directly going to flatten.

```
python
layers.Flatten(),
```

- **Flatten** the 3D output (height × width × channels) into a **1D vector**.
- Ready to feed into dense (fully connected) layers.

```
python
layers.Dense(64, activation='relu'),
```

- Fully connected **Dense Layer**:
 - o 64 neurons,
 - o `ReLU` activation.

```
python
    layers.Dense(10, activation='softmax') # Output layer for 10 classes
```

Output Layer:

- ∘ 10 neurons (one for each digit 0–9),
- `softmax` to output a **probability distribution** over the 10 classes.

```
python

# Compile model
model.compile(optimizer='adam', loss='sparse_categorical_crossentropy', metrics=['accuracy'])
```

- **Compile** the model:
 - o Optimizer: Adam (efficient and adaptive),
 - o Loss: Sparse categorical crossentropy (because labels are integers, not one-hot encoded),
 - Metric: **Accuracy** (to monitor model performance).

```
# Train model
model.fit(x_train, y_train, epochs=5, validation_data=(x_test, y_test))
```

- Train the model:
 - For **5 epochs** (5 passes over the training data),
 - Also evaluate on **test data** after each epoch (validation).

```
# Evaluate model
test_loss, test_acc = model.evaluate(x_test, y_test)
print(f"Test Accuracy: {test_acc:.4f}")
```

- After training, **evaluate** final performance on the test set.
- Print the **test accuracy** rounded to 4 decimal places.

🙀 Summary:

- Load MNIST handwritten digits
- Normalize and reshape
- Build a small CNN with 3 Conv layers ✓
- Train for 5 epochs
- Evaluate and report accuracy

Let me know! 🚀



```
import tensorflow as tf
from tensorflow import keras
from tensorflow.keras import layers

# Load the MNIST dataset, a collection of handwritten digits
mnist = keras.datasets.mnist
(x_train, y_train), (x_test, y_test) = mnist.load_data()
# Normalize pixel values to be in the range [0, 1]
x_train, x_test = x_train / 255.0, x_test / 255.0
# Build the neural network model
model = keras.models.Sequential([
layers.Flatten(input_shape=(28, 28)),
layers.Dense(128, activation='relu'),
layers.Dropout(0.2),
```



```
layers.Dense(10, activation='softmax')
1)
# Compile the model
model.compile(optimizer='adam',
loss='sparse_categorical_crossentropy',
metrics=['accuracy'])
# Train the model
model.fit(x_train, y_train, epochs=5)
# Evaluate the model on the test data
test loss, test acc = model.evaluate(x test, y test, verbose=2)
print("\nTest accuracy:", test_acc)
# Save the model
model.save("handwritten digit recognition model.h5")
import tensorflow as tf
from tensorflow.keras.models import load_model
import numpy as np
import matplotlib.pyplot as plt
                                                                           # Load the saved model
model = load_model("handwritten_digit_recognition_model.h5")
# Load an example image (you can replace this with your own image)
image path = "D:/number.jpg"
image = tf.keras.preprocessing.image.load_img(image_path,
                         color_mode="grayscale",
                         target_size=(28, 28)
input_data = tf.keras.preprocessing.image.img_to_array(image)
input_data = input_data / 255.0 # Normalize the pixel values
# Make a prediction on the input data
prediction = model.predict(np.array([input data]))
# Get the predicted digit (the class with the highest probability)
predicted_digit = np.argmax(prediction)
# Display the image and the predicted digit
plt.imshow(input_data.reshape(28, 28), cmap="binary")
plt.show()
                      .....expalin this code line ny line
```

Of course! Let's **explain your entire code line by line**:

```
import tensorflow as tf
from tensorflow import keras
from tensorflow.keras import layers
```

- Import TensorFlow and Keras modules.
- `layers` is for easily creating neural network layers.

```
python

# Load the MNIST dataset, a collection of handwritten digits
mnist = keras.datasets.mnist
(x_train, y_train), (x_test, y_test) = mnist.load_data()
```

- Load MNIST dataset.
- `x_train` and `x_test`: Images (28×28 grayscale digits).
- `y_train` and `y_test`: Labels (0-9).

```
# Normalize pixel values to be in the range [0, 1]
x_train, x_test = x_train / 255.0, x_test / 255.0
```

- Normalize pixel values from 0–255 to 0–1.
- Helps model training become faster and stable.

```
python

# Build the neural network model
model = keras.models.Sequential([
```

• Start building a **Sequential model** (layers added one by one).

```
python
layers.Flatten(input_shape=(28, 28)),
```

- **Flatten** the 2D (28×28) image into a 1D vector (784 values).
- Prepares the image for fully connected (Dense) layers.

```
python
layers.Dense(128, activation='relu'),
```

- Dense layer with 128 neurons.
- Activation function: ReLU (introduces non-linearity).

```
python
layers.Dropout(0.2),
```

- **Dropout layer**: Randomly sets 20% of neurons to zero during training.
- Helps prevent **overfitting**.

```
layers.Dense(10, activation='softmax')
])
```

- Output Dense layer:
 - ∘ 10 neurons (for digits 0–9).
 - **Softmax** activation outputs probabilities that sum to 1.

```
# Compile the model
model.compile(optimizer='adam',
loss='sparse_categorical_crossentropy',
metrics=['accuracy'])
```

- Compile the model:
 - Optimizer: `adam` (adaptive and fast optimizer),
 - Loss function: `sparse_categorical_crossentropy` (for integer labels),
 - Metric: `accuracy`.

```
python

# Train the model
model.fit(x_train, y_train, epochs=5)
```

• Train the model for **5 epochs** (5 passes over the training set).

```
# Evaluate the model on the test data
test_loss, test_acc = model.evaluate(x_test, y_test, verbose=2)
print("\nTest accuracy:", test_acc)
```

- Evaluate how well the model performs on the **test set**.
- Print the final test accuracy.

```
python

# Save the model
model.save("handwritten_digit_recognition_model.h5")
```

- Save the trained model into an **H5 file** (`.h5`) format.
- You can reuse or deploy this model later without retraining.

Now second part: Loading the saved model and making a prediction

```
import tensorflow as tf
from tensorflow.keras.models import load_model
import numpy as np
import matplotlib.pyplot as plt
```

• Import required libraries for loading model, handling arrays, and plotting.

```
python

# Load the saved model
model = load_model("handwritten_digit_recognition_model.h5")
```

• Load the previously saved model.

- Load an image (`number.jpg`) from the specified path.
- Convert it to grayscale and resize it to 28×28 (to match MNIST format).

```
python
input_data = tf.keras.preprocessing.image.img_to_array(image)
input_data = input_data / 255.0 # Normalize the pixel values
```

- Convert the image to a NumPy array.
- Normalize pixel values between 0 and 1, just like during training.

```
python

# Make a prediction on the input data
prediction = model.predict(np.array([input_data]))
```

- Predict the probabilities for each digit (0-9).
- Wrap `input_data` in a list (`np.array([input_data])`) to make it a batch (batch_size=1).

```
python

# Get the predicted digit (the class with the highest probability)
predicted_digit = np.argmax(prediction)
```

`np.argmax` returns the index of the highest probability → predicted digit.



```
# Display the image and the predicted digit
plt.imshow(input_data.reshape(28, 28), cmap="binary")
plt.show()
```

• Show the input image (reshaped back to 28×28) in **binary (black-and-white)** color map.

Final Summary:

- You trained a simple neural network to recognize handwritten digits.
- Saved the model to disk (`.h5`).
- Loaded it later.
- Made a prediction on a new external image.
- Visualized the input image.

Would you also like me to show **how you can print the predicted digit on the image** itself using `plt.text`? in the image itself using `plt.text`?