

# SAUL H. SERRANO

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## Education

### California State University Sacramento

Expected Graduation: Fall 2025

*B.S. in Computer Engineering (Senior)*

*Sacramento, CA*

- Dean's Honor List Recipient
- Society of Hispanic Professional Engineers (SHPE)

## Certifications

**NVIDIA** - Building LLM Applications with Prompt Engineering

**Splunk** - Introduction to Enterprise Security

## Relevant Coursework

- |                         |                        |                     |                       |
|-------------------------|------------------------|---------------------|-----------------------|
| • Embedded Systems      | • Circuit Analysis     | • Operating System  | • Computer Networks   |
| • Robotics              | • Electronics          | Pragmatics          | • Discrete Structures |
| • Computer Organization | • Signals and Systems  | • Data Structures & | • Object Oriented     |
| • Advanced Logic Design | • Probability & Random | Algorithms          | Programming           |
| • CMOS & VLSI           | Signals                | • UNIX              | • Calculus II         |

## Project Experience

### AI Email Agent | *Python, LangChain, LLMs, Automation, Edge AI*

7/25 – Present

- Developed an **AI**-powered email assistant to automate my email inbox and increase productivity.
- Leverage **local** large language models **LLM's** and **LangChain** to create private and modular AI code
- Utilized Prompt Engineering and rule-based logic to identify reply requirements and generate draft responses aligned with personal communication standards and guidelines
- Planned deployment on **NVIDIA Jetson Nano**, enabling on-device inference and **edge computing** for autonomous execution in a local private environment.

### Autonomous Robot Dog | *Python, Raspberry Pi, Motors, Sensors, Computer Vision, Robotics*

8/25 – Present

- Lead a team to build and program a robotic dog using a **Raspberry Pi** to control motors based on sensor input
- Integrated **computer vision** and **AI** to allow for autonomous capabilities based on the world it sees
- Developed modular robotics control software for gait sequencing, servo coordination, and sensor data input
- Planned participation in **autonomous robot dog fight** at the end of 2025

### CrowdX - New Age Crowdfunding | *Python, JavaScript, Django, Next.js*

6/25 – Present

- A **full-stack** crowdfunding application where students and recent grads can showcase their projects, collect funding, and be discovered
- Lead a team of engineers developing a backend **Django** and frontend **Next.js** server in a modular and scalable approach
- Developed features such as custom **API's**, **JWT Authentication**, and Multi-Factor Authentication **MFA** to provide secure and role-based access to resources
- Directed project development using **Agile** workflows and **Git**-based version control, improving team coordination and delivery efficiency.
- Planned deployment in **Cloud hosted** servers which allow for scaling as the project grows

### Operating System Development | *C, CSUS SPEDE*

2/25 - 5/25

- Built a custom operating system in C from the ground up, applying core concepts such as **process** creation, **context switching**, **memory management**, and user **I/O handling**.
- Transformed theoretical knowledge into practice through phased development on a virtualized **Linux** environment
- Served as team lead, coordinating **version control** in **Git/GitHub** and spearheading kernel-level **debugging** efforts with **GDB**.

### Arithmetic Logic Unit (ALU) | *Cadence Virtuoso, CMOS Circuit Design*

2/24 – 5/24

- Designed an 8-bit Arithmetic Logic Unit using 45nm **CMOS** technology, building **custom schematics** and layouts for core components including logic gates, adders, subtractors, and multipliers.
- Verified **circuit validity** and **design integrity** by successfully passing Design Rule Check (**DRC**) and Layout Versus Schematic (**LVS**) reports in Cadence Virtuoso.
- Demonstrated understanding of digital logic and physical layout constraints while **optimizing for performance**.

- Directed collaborative design of a RC Vehicle utilizing a **STM Microprocessor** to control servo and motors controlled by **embedded** software
- Implemented **UART**-based serial communication to receive wireless commands and modulate **PWM** signals for real-time motor actuation.
- **Troubleshoot** hardware-software integration using a **UNIX** terminal and **Oscilloscope** to verify signal timing, connectivity, and motor response.

## Technical Skills

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**Programming Languages:** Python, C, Java, HTML/CSS, Javascript, VHDL, Verilog

**Tools & Platforms:** VSCode, Git, GitHub, Docker, Linux/UNIX, Wireshark, Cadence Virtuoso

**Frameworks & Technologies:** Django, Next.js, LangChain, PostgreSQL

**Languages:** Spanish (Native), English (Native)

## Work Experience

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### Costco Wholesale

July 2020 – Present

*Backup Supervisor, Sales Representative*

*Sacramento, CA*

- Led a team of 10+ associates in high-volume retail operations, using analytics to optimize product placement and streamline workflow.
- Built trust with customers simplifying advanced technology features into clear, actionable benefits, improving customer confidence and purchase decisions.
- Adapted rapidly to shifting priorities during high-traffic sales events, optimizing task delegation and schedule adjustments to improve team coordination and member experience
- Trained and mentored new team members, creating peer on-boarding guide that reduced training time by 20% and increased role readiness

### ACR Glass and Doors

June 2019 – August 2019

*Design & Project Manager Intern*

*Oakland, CA*

- Designed 2D schematics based on project specifications and city regulations to ensure compliance and accuracy.
- Collaborated with multiple teams to procure necessary materials by using effective written and verbal communication
- Enhanced professional skills in email correspondence and document management to improve organizational efficiency.