



*Xidian University*

《操作系统课程设计》

## 实验2: Add Priority

黄伯虎



*School of Computer Science & Technology*



# 任务

- 原始Pintos系统中对于线程的调度，没有考虑优先级问题，采用的是最为简单的FCFS（先来先服务）策略。
- 本实验要求为Pintos建立优先级调度机制，确保任何时刻CPU上运行的都是最高优先级线程。



# Pintos线程优先级如何定义的?

in threads.h

```
/* Thread priorities. */  
#define PRI_MIN 0          /* Lowest priority. */  
#define PRI_DEFAULT 31    /* Default priority. */  
#define PRI_MAX 63        /* Highest priority. */
```

```
struct thread  
{  
    /* Owned by thread.c. */  
    tid_t tid;          /* Thread identifier. */  
    enum thread_status status; /* Thread state. */  
    char name[16];      /* Name (for debugging purposes). */  
    uint8_t *stack;     /* Saved stack pointer. */  
    int priority;        /* Priority. */  
    struct list_elem allelem; /* List element for all threads list. */  
  
    /* Shared between thread.c and synch.c. */  
    struct list_elem elem; /* List element. */  
}
```



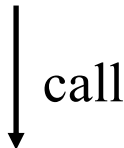
# 操作系统中何时会设置/改变优先级



## 1.线程生成时

in threads.c

```
tid_t  
thread_create (const char *name, int priority,  
               thread_func *function, void *aux)
```



```
init_thread (struct thread *t, const char *name, int priority)
```



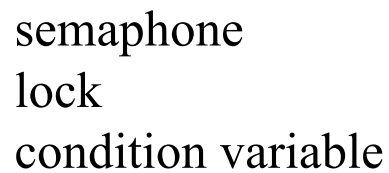
# 操作系统中何时会设置/改变优先级



## 2.通过thread\_set\_priority(函数)改变

in threads.c

```
/* Sets the current thread's priority to NEW_PRIORITY. */  
void thread_set_priority (int new_priority)  
{  
    thread_current ()->priority = new_priority;  
}
```





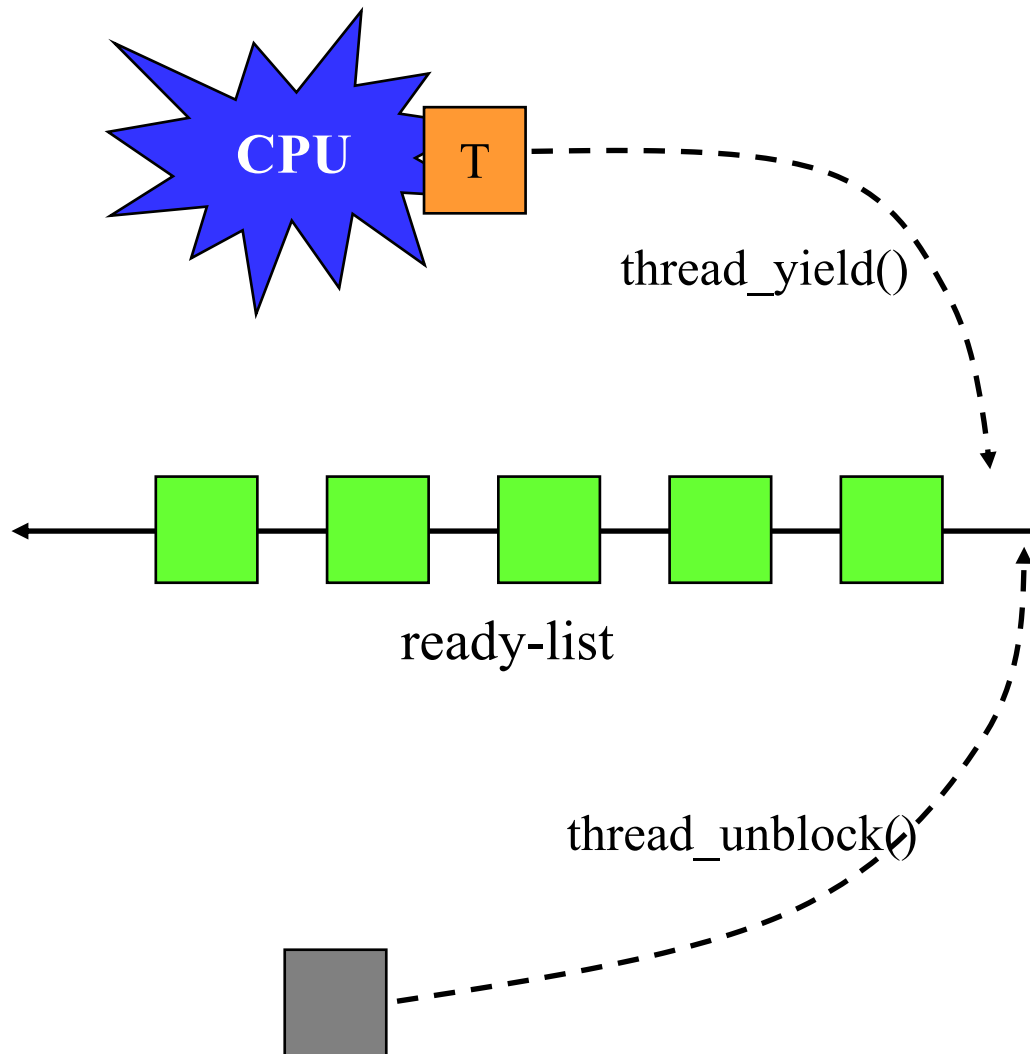
# 新线程生成时

```
tid_t  
thread_create (const char *name, int priority,  
               thread_func *function, void *aux)
```

线程生成后，当前线程和ready-list中线程  
优先级比较，确定当前线程是否让出CPU



# ready-list的有序化



```
void
thread_yield (void)
{
    struct thread *cur = thread_current ();
    enum intr_level old_level;

    ASSERT (!intr_context ());

    old_level = intr_disable ();
    if (cur != idle_thread)
        list_push_back (&ready_list, &cur->elem);
    cur->status = THREAD_READY;
    schedule ();
    intr_set_level (old_level);
}
```

```
void
thread_unblock (struct thread *t)
{
    enum intr_level old_level;

    ASSERT (is_thread (t));

    old_level = intr_disable ();
    ASSERT (t->status == THREAD_BLOCKED);
    list_push_back (&ready_list, &t->elem);
    t->status = THREAD_READY;
    intr_set_level (old_level);
}
```





# ready-list的有序化

```
void
list_insert_ordered (struct list *list, struct list_elem *elem,
                    list_less_func *less, void *aux)
{
    struct list_elem *e;

    ASSERT (list != NULL);
    ASSERT (elem != NULL);
    ASSERT (less != NULL);

    for (e = list_begin (list); e != list_end (list); e = list_next (e))
        if (less (elem, e, aux))
            break;
    return list_insert (e, elem);
}
```



## 调用thread\_set\_priority()改变线程优先级时

```
void  
thread_set_priority (int new_priority)  
{  
    thread_current ()->priority = new_priority;  
}
```

优先级更改后，应当立即比较当前线程和ready-list中线程优先级，确定当前线程是否让出CPU



# 线程同步机制



## Semaphore

```

/* A counting semaphore. */
struct semaphore
{
    unsigned value;          /* Current value. */
    struct list waiters;     /* List of waiting threads. */
};

```

```

void
sema_down (struct semaphore *sema)
{
    enum intr_level old_level;

    ASSERT (sema != NULL);
    ASSERT (!intr_context ());

    old_level = intr_disable ();
    while (sema->value == 0)
    {
        list_push_back (&sema->waiters, &thread_current ()->elem);
        thread_block ();
    }
    sema->value--;
    intr_set_level (old_level);
}

```

```

void
sema_up (struct semaphore *sema)
{
    enum intr_level old_level;

    ASSERT (sema != NULL);

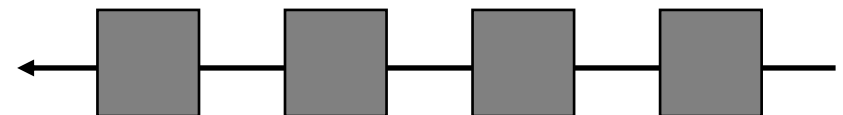
    old_level = intr_disable ();
    if (!list_empty (&sema->waiters))
        thread_unblock (list_entry (list_pop_front (&sema->waiters),
                                         struct thread, elem));

    sema->value++;
    intr_set_level (old_level);
}

```

我们的工作:

- 使list有序化
- unblock后进行优先级比较



block list/sema->waiters



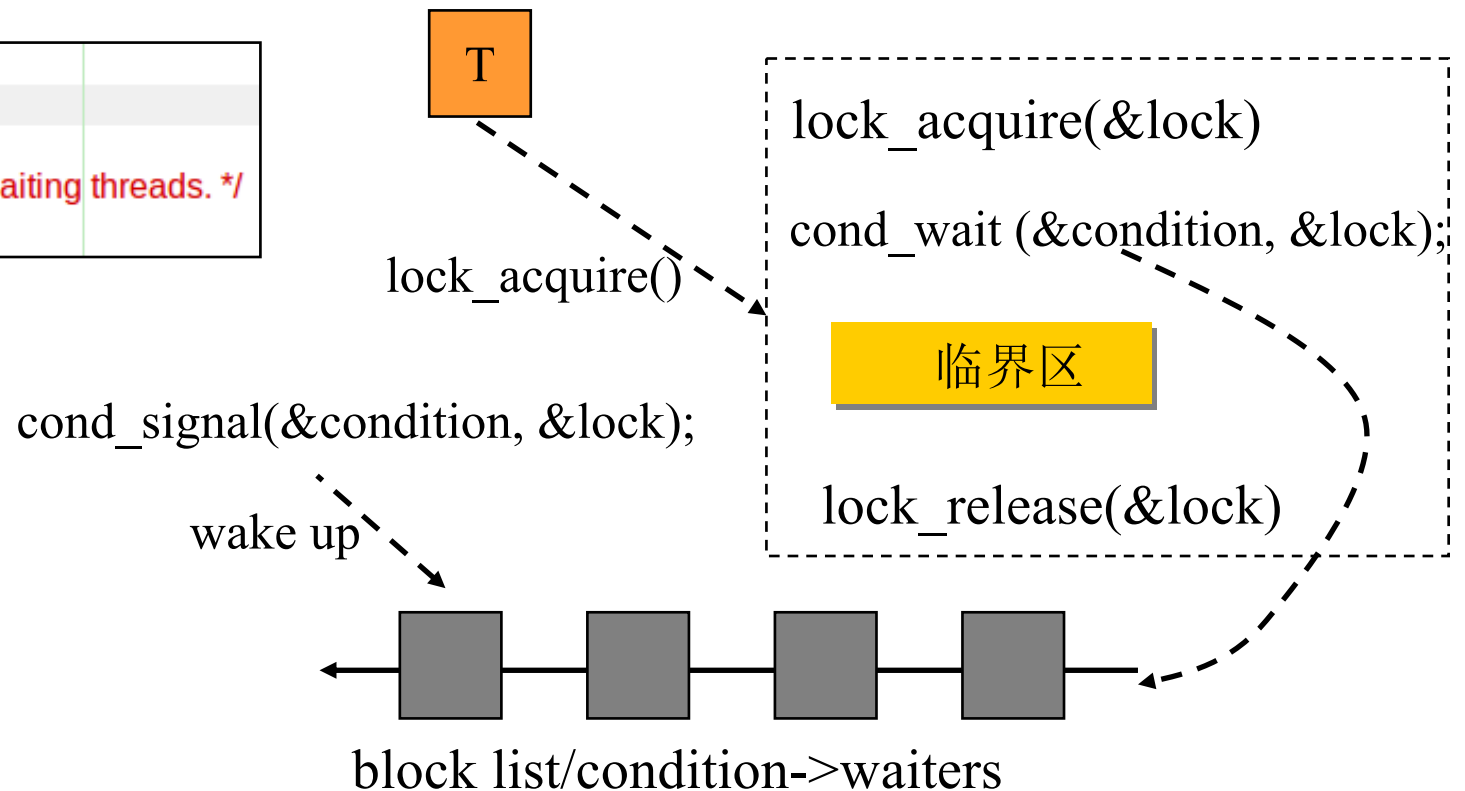
# 线程同步机制



## Lock, Condition variable

```
/* Lock. */  
struct lock  
{  
    struct thread *holder; /* Thread holding lock (for debugging). */  
    struct semaphore semaphore; /* Binary semaphore controlling access. */  
};
```

```
/* Condition variable. */  
struct condition  
{  
    struct list waiters; /* List of waiting threads. */  
};
```





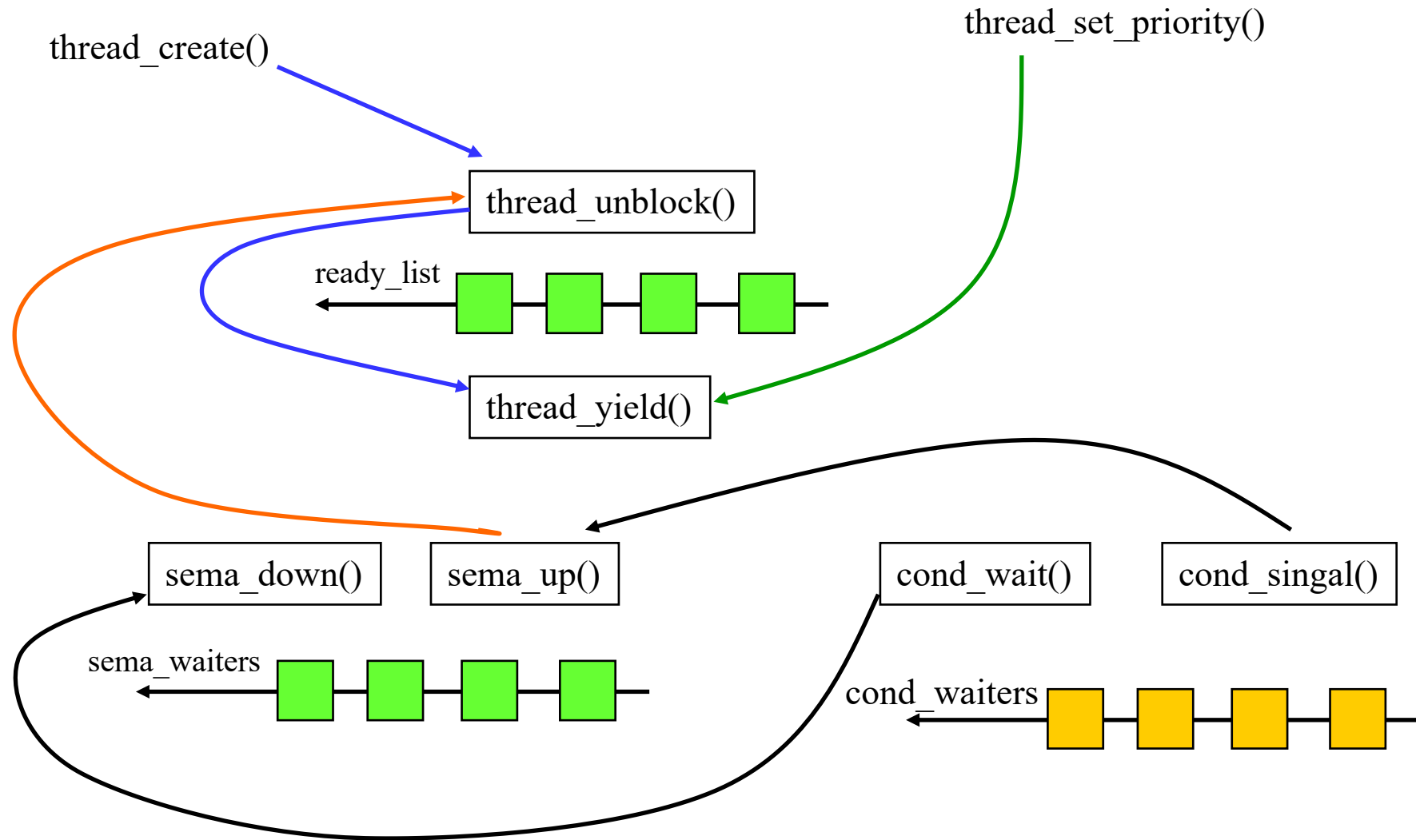
# 线程同步机制

修改此函数，使cond->waiters队列按优先级有序

```
void  
cond_wait (struct condition *cond, struct lock *lock)  
{  
    struct semaphore_elem waiter;  
  
    ASSERT (cond != NULL);  
    ASSERT (lock != NULL);  
    ASSERT (!intr_context ());  
    ASSERT (lock_held_by_current_thread (lock));  
  
    sema_init (&waiter.semaphore, 0);  
    list_push_back (&cond->waiters, &waiter.elem);  
    lock_release (lock);  
    sema_down (&waiter.semaphore);  
    lock_acquire (lock);  
}
```



# 调用关系总结





# 测试



如果你成功完成了这些任务，make check时：

- ❖ **alarm\_priority,**
- ❖ **priority-change**
- ❖ **priority-fifo**
- ❖ **priority-preempt**
- ❖ **priority-sema**
- ❖ **priority-condvar**

等6个检测就可以通过。