Lecture 18

Fitting CAR and SAR Models

Colin Rundel 3/29/2018 Fitting areal models

· Simultaneous Autogressve (SAR)

$$y(s_i) = \phi \sum_{j=1}^n W_{ij} \; y(s_j) + \epsilon$$

$$\mathbf{y} \sim \mathcal{N}(0, \sigma^2 ((\mathbf{I} - \phi \mathbf{W})^{-1})((\mathbf{I} - \phi \mathbf{W})^{-1})^t)$$

Conditional Autoregressive (CAR)

$$y(s_i)|\mathbf{y}_{-s_i} \sim \mathcal{N}\left(\phi \sum_{j=1}^n W_{ij} \; y(s_j), \; \sigma^2\right)$$

$$\mathbf{y} \sim \mathcal{N}(0, \ \sigma^2 \left(\mathbf{I} - \phi \mathbf{W}\right)^{-1})$$

3

Some generalizations

Generally speaking we will want to work with a scaled / normalized version of the weight matrix,

$$\frac{W_{ij}}{W_{i\cdot}}$$

When W is an adjacency matrix we can express this as

$$\mathbf{D}^{-1}\mathbf{W}$$

where
$$\mathbf{D}^{-1} = \mathrm{diag}(1/|N(\boldsymbol{s}_i)|).$$

We can also allow σ^2 to vary between locations, we can define this as $\mathbf{D}_{ au}=\mathrm{diag}(1/\sigma_i^2)$ and most often we use

$$\mathbf{D}_{\sigma}^{-1} = \operatorname{diag}\left(\frac{\sigma^2}{|N(s_i)|}\right) = \sigma^2 \mathbf{D}^{-1}.$$

4

Revised SAR Model

· Formula Model

$$\begin{split} y(s_i) &= X_{i\cdot}\beta + \phi \sum_{j=1}^n D_{jj}^{-1} \, W_{ij} \left(y(s_j) - X_{j\cdot}\beta \right) + \epsilon_i \\ & \qquad \qquad \epsilon \sim \mathcal{N}(\mathbf{0}, \, \sigma^2 \mathbf{D}^{-1}) \end{split}$$

· Joint Model

· Formula Model

$$\begin{split} y(s_i) &= X_{i\cdot}\beta + \phi \sum_{j=1}^n D_{jj}^{-1} \, W_{ij} \left(y(s_j) - X_{j\cdot}\beta \right) + \epsilon_i \\ & \qquad \qquad \epsilon \sim \mathcal{N}(\mathbf{0}, \, \sigma^2 \mathbf{D}^{-1}) \end{split}$$

· Joint Model

$$\begin{split} \mathbf{y} &= \mathbf{X}\boldsymbol{\beta} + \phi\mathbf{D}^{-1}\mathbf{W}\left(\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\right) + \boldsymbol{\epsilon} \\ \left(\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\right) &= \phi\mathbf{D}^{-1}\mathbf{W}\left(\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\right) + \boldsymbol{\epsilon} \\ \left(\mathbf{y} - \mathbf{X}\boldsymbol{\beta}\right)(\mathbf{I} - \phi\mathbf{D}^{-1}\mathbf{W})^{-1} &= \boldsymbol{\epsilon} \\ \mathbf{y} &= \mathbf{X}\boldsymbol{\beta} + (\mathbf{I} - \phi\mathbf{D}^{-1}\mathbf{W})^{-1}\boldsymbol{\epsilon} \end{split}$$

5

· Formula Model

$$\begin{split} y(s_i) &= X_{i\cdot}\beta + \phi \sum_{j=1}^n D_{jj}^{-1} \, W_{ij} \left(y(s_j) - X_{j\cdot}\beta \right) + \epsilon_i \\ & \qquad \qquad \epsilon \sim \mathcal{N}(\mathbf{0}, \, \sigma^2 \mathbf{D}^{-1}) \end{split}$$

· Joint Model

$$\begin{split} \mathbf{y} &= \mathbf{X}\boldsymbol{\beta} + \phi \mathbf{D}^{-1}\mathbf{W} \left(\mathbf{y} - \mathbf{X}\boldsymbol{\beta} \right) + \boldsymbol{\epsilon} \\ & \left(\mathbf{y} - \mathbf{X}\boldsymbol{\beta} \right) = \phi \mathbf{D}^{-1}\mathbf{W} \left(\mathbf{y} - \mathbf{X}\boldsymbol{\beta} \right) + \boldsymbol{\epsilon} \\ & \left(\mathbf{y} - \mathbf{X}\boldsymbol{\beta} \right) (\mathbf{I} - \phi \mathbf{D}^{-1}\mathbf{W})^{-1} = \boldsymbol{\epsilon} \\ & \mathbf{y} = \mathbf{X}\boldsymbol{\beta} + (\mathbf{I} - \phi \mathbf{D}^{-1}\mathbf{W})^{-1}\boldsymbol{\epsilon} \end{split}$$
$$\mathbf{y} \sim \mathcal{N} \left(\mathbf{X}\boldsymbol{\beta}, (\mathbf{I} - \phi \mathbf{D}^{-1}\mathbf{W})^{-1}\sigma^2 \mathbf{D}^{-1} \left((\mathbf{I} - \phi \mathbf{D}^{-1}\mathbf{W})^{-1} \right)^t \right) \end{split}$$

Г,

Revised CAR Model

· Conditional Model

$$y(s_i)|\mathbf{y}_{-s_i} \sim \mathcal{N}\left(X_{i\cdot}\beta + \phi\sum_{j=1}^n \frac{W_{ij}}{D_{ii}}\left(y(s_j) - X_{j\cdot}\beta\right),\; \sigma^2 D_{ii}^{-1}\right)$$

· Joint Model

6

Revised CAR Model

· Conditional Model

$$y(s_i)|\mathbf{y}_{-s_i} \sim \mathcal{N}\left(X_{i\cdot}\beta + \phi\sum_{j=1}^n \frac{W_{ij}}{D_{ii}}\left(y(s_j) - X_{j\cdot}\beta\right),\; \sigma^2 D_{ii}^{-1}\right)$$

· Joint Model

$$\mathbf{y} \sim \mathcal{N}(\mathbf{X}\boldsymbol{\beta}, \ \Sigma_{CAR})$$

Revised CAR Model

· Conditional Model

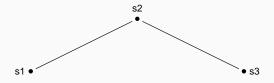
$$y(s_i)|\mathbf{y}_{-s_i} \sim \mathcal{N}\left(X_{i\cdot}\beta + \phi\sum_{j=1}^n \frac{W_{ij}}{D_{ii}}\left(y(s_j) - X_{j\cdot}\beta\right), \ \sigma^2 D_{ii}^{-1}\right)$$

· Joint Model

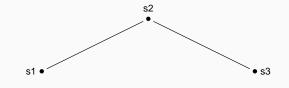
$$\begin{split} \boldsymbol{\Sigma}_{CAR} &= (\mathbf{D}_{\sigma} \left(\mathbf{I} - \phi \mathbf{D}^{-1} \mathbf{W}\right))^{-1} \\ &= (1/\sigma^2 \mathbf{D} \left(\mathbf{I} - \phi \mathbf{D}^{-1} \mathbf{W}\right))^{-1} \\ &= (1/\sigma^2 (\mathbf{D} - \phi \mathbf{W}))^{-1} \\ &= \sigma^2 (\mathbf{D} - \phi \mathbf{W})^{-1} \end{split}$$

 $\mathbf{v} \sim \mathcal{N}(\mathbf{X}\boldsymbol{\beta}, \Sigma_{CAB})$

Toy CAR Example



Toy CAR Example



$$\mathbf{W} = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix} \qquad \qquad \mathbf{D} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

. .

$$\Sigma = \sigma^2 \left(\mathbf{D} - \phi \, \mathbf{W} \right) = \sigma^2 \, \begin{pmatrix} 1 & -\phi & 0 \\ -\phi & 2 & -\phi \\ 0 & -\phi & 1 \end{pmatrix}^{-1}$$

7

When does Σ exist?

```
check sigma = function(phi) {
 Sigma_inv = matrix(c(1,-phi,0,-phi,2,-phi,0,-phi,1), ncol=3, byrow=TRUE)
 solve(Sigma inv)
check sigma(phi=0)
## [,1][,2][,3]
## [1.] 1 0.0 0
## [2,] 0 0.5 0
## [3,] 0 0.0 1
check sigma(phi=0.5)
   [,1] [,2] [,3]
##
## [1,] 1.1666667 0.3333333 0.1666667
## [2,] 0.3333333 0.6666667 0.3333333
## [3,] 0.1666667 0.3333333 1.1666667
check sigma(phi=-0.6)
   [,1] [,2] [,3]
##
## [1.] 1.28125 -0.46875 0.28125
## [2,] -0.46875 0.78125 -0.46875
## [3.] 0.28125 -0.46875 1.28125
```

```
check_sigma(phi=1)
## Error in solve.default(Sigma inv): Lapack routine dgesv: system is exactl
check sigma(phi=-1)
## Error in solve.default(Sigma_inv): Lapack routine dgesv: system is exactl
check_sigma(phi=1.2)
## [,1] [,2] [,3]
## [1,] -0.6363636 -1.363636 -1.6363636
## [2,] -1.3636364 -1.136364 -1.3636364
## [3,] -1.6363636 -1.363636 -0.6363636
check_sigma(phi=-1.2)
        [,1] [,2] [,3]
##
```

[1,] -0.6363636 1.363636 -1.6363636 ## [2,] 1.3636364 -1.136364 1.3636364 ## [3,] -1.6363636 1.363636 -0.6363636

When is Σ positive semidefinite?

```
check sigma pd = function(phi) {
 Sigma inv = matrix(c(1,-phi,0,-phi,2,-phi,0,-phi,1), ncol=3, byrow=TRUE)
 chol(solve(Sigma inv))
check sigma pd(phi=0)
## [,1] [,2] [,3]
## [1.] 1 0.0000000 0
## [2.] 0 0.7071068 0
## [3,] 0 0.0000000 1
check sigma pd(phi=0.5)
## [,1] [,2] [,3]
## [1,] 1.080123 0.3086067 0.1543033
## [2.] 0.000000 0.7559289 0.3779645
## [3.] 0.000000 0.0000000 1.0000000
check_sigma_pd(phi=-0.6)
  [,1] [,2] [,3]
##
## [1,] 1.131923 -0.4141182 0.2484709
## [2.] 0.000000 0.7808688 -0.4685213
## [3.] 0.000000 0.0000000 1.0000000
```

```
check_sigma_pd(phi=1)
## Error in solve.default(Sigma_inv): Lapack routine dgesv: system is exactl
check_sigma_pd(phi=-1)
## Error in solve.default(Sigma_inv): Lapack routine dgesv: system is exactl
check_sigma_pd(phi=1.2)
## Error in chol.default(solve(Sigma_inv)): the leading minor of order 1 is
check_sigma_pd(phi=-1.2)
```

Error in chol.default(solve(Sigma inv)): the leading minor of order 1 is

Conclusions

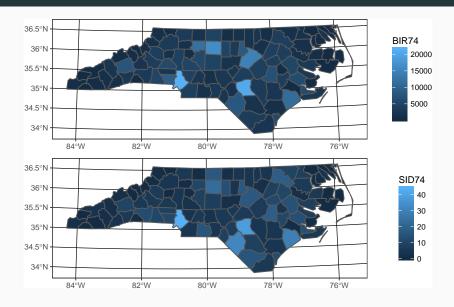
Generally speaking just like the AR(1) model for time series we require that $|\phi|<1$ for the CAR model to be proper.

These results for ϕ also apply in the context where σ_i^2 is constant across locations (i.e. $\Sigma = (\sigma^2 \, (\mathbf{I} - \phi \mathbf{D}^{-1} \mathbf{W}))^{-1})$

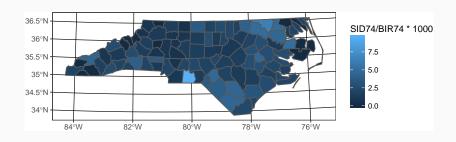
As a side note, the special case where $\phi=1$ is known as an intrinsic autoregressive (IAR) model and they are popular as an *improper* prior for spatial random effects. An additional sum constraint is necessary for identifiability $(\sum_{i=1}^n y(s_i)=0)$.

12

Example - NC SIDS



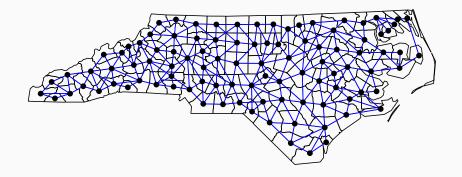
ggplot() + geom_sf(data=nc, aes(fill=SID74/BIR74*1000))



Using spautolm from spdep

```
library(spdep)
W = st_touches(nc, sparse=FALSE)
listW = mat2listw(W)
listW
## Characteristics of weights list object:
## Neighbour list object:
## Number of regions: 100
## Number of nonzero links: 490
## Percentage nonzero weights: 4.9
## Average number of links: 4.9
##
## Weights style: M
## Weights constants summary:
##
            nn S0 S1
                          52
      n
## M 100 10000 490 980 10696
```

```
nc_coords = nc %>% st_centroid() %>% st_coordinates()
plot(st_geometry(nc))
plot(listW, nc_coords, add=TRUE, col="blue", pch=16)
```



Moran's I

```
spdep::moran.test(nc$SID74, listW)
##
   Moran I test under randomisation
##
##
## data: nc$SID74
## weights: listW
##
## Moran I statistic standard deviate = 2.1707, p-value = 0.01498
## alternative hypothesis: greater
## sample estimates:
## Moran I statistic Expectation Variance
##
        0.119089049 -0.010101010 0.003542176
spdep::moran.test(1000*nc$SID74/nc$BIR74, listW)
##
   Moran I test under randomisation
##
##
## data: 1000 * nc$SID74/nc$BIR74
## weights: listW
##
## Moran I statistic standard deviate = 3.6355, p-value = 0.0001387
## alternative hypothesis: greater
## sample estimates:
## Moran I statistic Expectation Variance
        0.210046454 -0.010101010 0.003666802
##
```

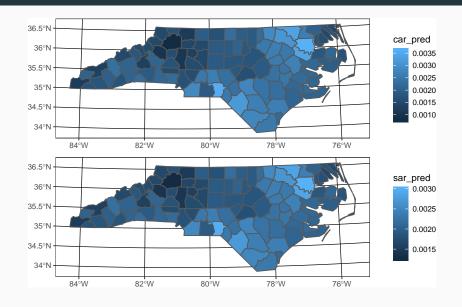
Geary's C

```
spdep::geary.test(nc$SID74, listW)
##
##
   Geary C test under randomisation
##
## data: nc$SID74
## weights: listW
##
## Geary C statistic standard deviate = 0.91949, p-value = 0.1789
## alternative hypothesis: Expectation greater than statistic
## sample estimates:
## Geary C statistic Expectation Variance
##
         0.88988684 1.00000000 0.01434105
spdep::geary.test(nc$SID74/nc$BIR74, listW)
##
   Geary C test under randomisation
##
##
## data: nc$SID74/nc$BIR74
## weights: listW
##
## Geary C statistic standard deviate = 3.0989, p-value = 0.0009711
  alternative hypothesis: Expectation greater than statistic
## sample estimates:
## Geary C statistic Expectation Variance
         0.67796679
                          1.00000000
                                           0.01079878
##
```

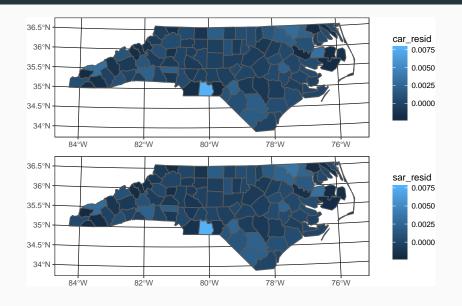
```
nc car = spautolm(formula = SID74/BIR74 ~ 1, data = nc,
                 listw = listW, family = "CAR")
summary(nc car)
##
## Call: spautolm(formula = SID74/BIR74 ~ 1. data = nc. listw = listW.
      family = "CAR")
##
##
## Residuals:
##
          Min
                       10
                               Median
                                              30
                                                          Max
## -0.00213872 -0.00083535 -0.00022355 0.00055014 0.00768640
##
## Coefficients:
                Estimate Std. Error z value Pr(>|z|)
##
## (Intercept) 0.00200203 0.00024272 8.2484 2.22e-16
##
## Lambda: 0.13062 LR test value: 8.6251 p-value: 0.0033157
## Numerical Hessian standard error of lambda: 0.030469
##
## Log likelihood: 508.3767
## ML residual variance (sigma squared): 2.1205e-06, (sigma: 0.0014562)
## Number of observations: 100
## Number of parameters estimated: 3
## AIC: -1010.8
```

```
nc sar = spautolm(formula = SID74/BIR74 ~ 1, data = nc,
                 listw = listW, family = "SAR")
summary(nc sar)
##
## Call: spautolm(formula = SID74/BIR74 ~ 1. data = nc. listw = listW.
      familv = "SAR")
##
##
## Residuals:
##
          Min
                      10
                               Median
                                              30
                                                          Max
## -0.00209307 -0.00087039 -0.00020274 0.00051156 0.00762830
##
## Coefficients:
                Estimate Std. Error z value Pr(>|z|)
##
## (Intercept) 0.00201084 0.00023622 8.5127 < 2.2e-16
##
## Lambda: 0.079934 LR test value: 8.8911 p-value: 0.0028657
## Numerical Hessian standard error of lambda: 0.0246
##
## Log likelihood: 508.5097
## ML residual variance (sigma squared): 2.1622e-06, (sigma: 0.0014704)
## Number of observations: 100
## Number of parameters estimated: 3
## AIC: -1011
```

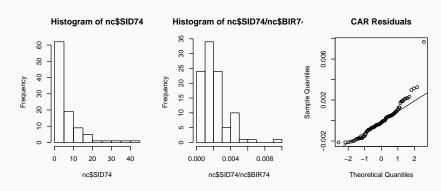
Predictions



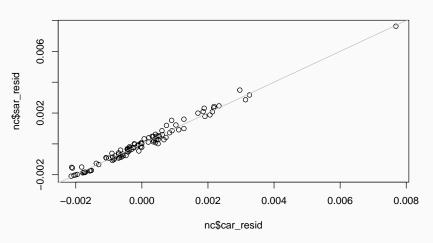
Residuals



What's wrong?



CAR vs SAR Residuals



Stan CAR Model

```
car model = "
data {
  int<lower=0> N;
 vector[N] v;
 matrix[N,N] W;
  matrix[N,N] D;
parameters {
  vector[N] w_s;
 real beta;
  real<lower=0> sigma2;
  real<lower=0> sigma2_w;
  real<lower=0,upper=1> phi;
transformed parameters {
  vector[N] y_pred = beta + w_s;
model {
  matrix[N.N] Sigma inv = (D - phi * W) / sigma2:
 w_s ~ multi_normal_prec(rep_vector(0,N), Sigma_inv);
  beta \sim normal(0,10);
  sigma2 \sim cauchy(0,5);
  sigma2_w \sim cauchy(0,5);
  y ~ normal(beta+w s, sigma2 w);
```

```
data = list(
    N = nrow(nc),
    y = nc$SID74 / nc$BIR74,
    W = W * 1,
    D = diag(rowSums(W))
)

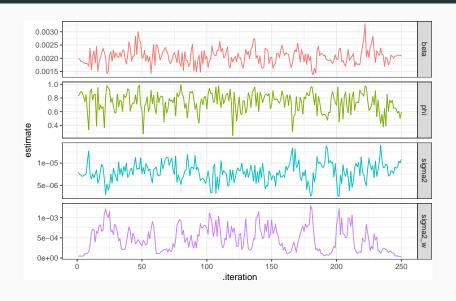
car_fit = rstan::stan(
    model_code = car_model, data = data,
    iter = 10000, chains = 1, thin=20
)
```

```
data = list(
    N = nrow(nc),
    y = nc$SID74 / nc$BIR74,
    W = W * 1,
    D = diag(rowSums(W))
)

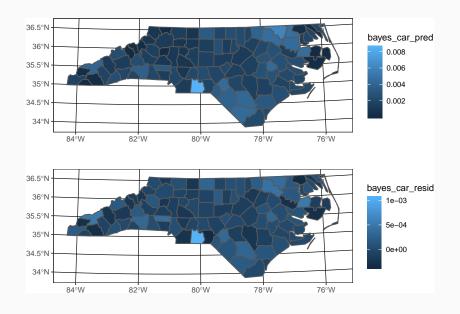
car_fit = rstan::stan(
    model_code = car_model, data = data,
    iter = 10000, chains = 1, thin=20
)
```

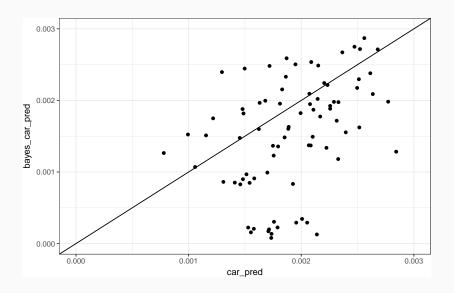
Why don't we use the conditional definition for the y's?

Model Results



Predictions





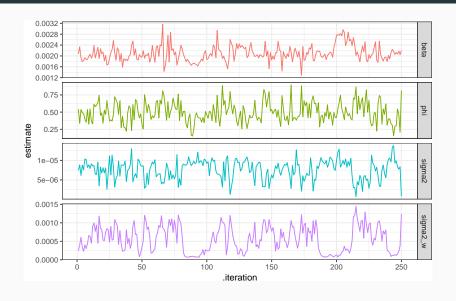
$$\Sigma_{SAR} = (\mathbf{I} - \phi \mathbf{D}^{-1} \, \mathbf{W})^{-1} \sigma^2 \, \mathbf{D}^{-1} \, \big((\mathbf{I} - \phi \mathbf{D}^{-1} \, \mathbf{W})^{-1} \big)^t$$

$$\begin{split} \boldsymbol{\Sigma}_{SAR}^{-1} &= \left((\mathbf{I} - \phi \mathbf{D}^{-1} \, \mathbf{W})^{-1} \sigma^2 \, \mathbf{D}^{-1} \left((\mathbf{I} - \phi \mathbf{D}^{-1} \, \mathbf{W})^{-1} \right)^t \right)^{-1} \\ &= \left(\left((\mathbf{I} - \phi \mathbf{D}^{-1} \, \mathbf{W})^{-1} \right)^t \right)^{-1} \frac{1}{\sigma^2} \, \mathbf{D} \left(\mathbf{I} - \phi \mathbf{D}^{-1} \, \mathbf{W} \right) \\ &= \frac{1}{\sigma^2} \left(\mathbf{I} - \phi \mathbf{D}^{-1} \, \mathbf{W} \right)^t \, \mathbf{D} \left(\mathbf{I} - \phi \mathbf{D}^{-1} \, \mathbf{W} \right) \end{split}$$

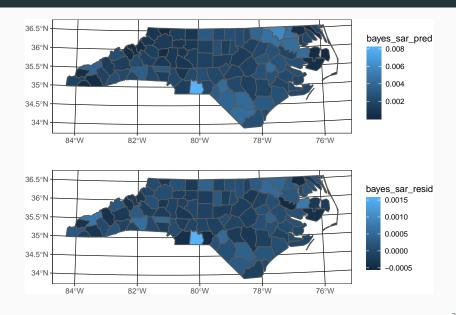
Jags SAR Model

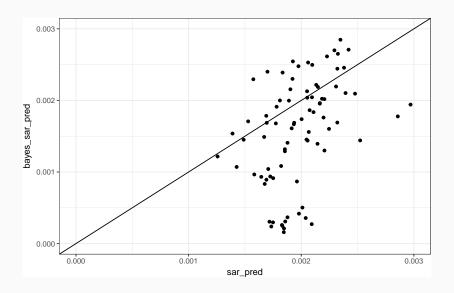
```
sar model = "
data {
  int<lower=0> N:
  vector[N] v;
  matrix[N,N] W_tilde;
  matrix[N.N] D:
transformed data {
  matrix[N,N] I = diag_matrix(rep_vector(1, N));
                                                            D = diag(rowSums(W))
parameters {
                                                            D inv = diag(1/diag(D))
  vector[N] w s;
                                                            data = list(
  real beta:
                                                              N = nrow(nc),
  real<lower=0> sigma2:
                                                              v = nc\$SID74 / nc\$BIR74.
  real<lower=0> sigma2 w;
                                                              x = rep(1, nrow(nc)),
  real<lower=0.upper=1> phi:
                                                              D inv = D inv,
                                                              W_tilde = D_inv %*% W
transformed parameters {
  vector[N] y_pred = beta + w_s;
                                                            sar fit = rstan::stan(
model {
                                                              model code = sar model, data = data,
  matrix[N.N] C = I - phi * W tilde:
                                                              iter = 10000. chains = 1. thin=20
  matrix[N,N] Sigma inv = C' * D * C / sigma2;
  w s ~ multi normal_prec(rep_vector(0,N), Sigma_inv);
  beta ~ normal(0.10):
  sigma2 \sim cauchy(0,5);
  sigma2_w ~ cauchy(0,5);
  v ~ normal(beta + w s, sigma2 w);
```

Model Results



Predictions





Comparing Predictions

```
# RMSE
sqrt(mean(nc$bayes_car_resid^2))
## [1] 0.0002092447

sqrt(mean(nc$bayes_sar_resid^2))
## [1] 0.0002983034

sqrt(mean(nc$car_resid^2))
## [1] 0.001448564

sqrt(mean(nc$sar_resid^2))
## [1] 0.001470432
```

Comparing Parameters

