# ESP32-SOLO-1

# **Datasheet**



## **About This Document**

This document provides the specifications for the ESP32-SOLO-1 module.

## **Document Updates**

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## **Revision History**

For revision history of this document, please refer to the last page.

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# Contents

1	Overview	6
<b>2</b> 2.1 2.2 2.3	Pin Definitions Pin Layout Pin Description Strapping Pins	8 8 10
<b>3</b> 3.1 3.2 3.3 3.4	Functional Description CPU and Internal Memory External Flash and SRAM Crystal Oscillators RTC and Low-Power Management	12 12 12 12 13
4	Peripherals and Sensors	14
<b>5</b> 5.1 5.2 5.3 5.4 5.5	Electrical Characteristics  Absolute Maximum Ratings  Recommended Operating Conditions  DC Characteristics (3.3 V, 25 °C)  Wi-Fi Radio  Bluetooth LE Radio  5.5.1 Receiver  5.5.2 Transmitter  Reflow Profile	15 15 15 16 17 17 17
6	Schematics	19
7	Peripheral Schematics	20
8	Physical Dimensions	21
9	Recommended PCB Land Pattern	22
10.1	Learning Resources  Must-Read Documents  Must-Have Resources	23 23 23
Rev	vision History	25

# **List of Tables**

1	ESP32-SOLO-1 Ordering Information	6
2	ESP32-SOLO-1 Specifications	6
3	Pin Definitions	8
4	Strapping Pins	10
5	Absolute Maximum Ratings	15
6	Recommended Operating Conditions	15
7	DC Characteristics (3.3 V, 25 °C)	15
8	Wi-Fi Radio Characteristics	16
9	Receiver Characteristics – BLE	17
10	Transmitter Characteristics – BLE	17

# **List of Figures**

1	ESP32-SOLO-1 Pin Layout (Top View)	8
2	Reflow Profile	18
3	ESP32-SOLO-1 Schematics	19
4	ESP32-SOLO-1 Peripheral Schematics	20
5	Physical Dimensions of ESP32-SOLO-1	21
6	Recommended PCB Land Pattern of ESP32-SOLO-1	22

## 1 Overview

ESP32-SOLO-1 is a powerful, generic Wi-Fi+BT+BLE MCU module that targets a wide variety of applications, ranging from low-power sensor networks to the most demanding tasks, such as voice encoding, music streaming and MP3 decoding.

Two different temperature variants of ESP32-SOLO-1 are available. Details are listed as follows:

Module	Chip embed- ded	Recommended operating temperature range	Flash	Dimensions (mm)
ESP32-SOLO-1 (Default Version)	ESP32-S0WD	-40 °C ∼ +85 °C	4 MB	(18.00±0.10)×(25.50±0.10)×(3.10±0.10)
ESP32-SOLO-1 (High Temp Version)	ESP32-S0WD	-40 °C ∼ +105 °C	4 MB	(18.00±0.10)×(25.50±0.10)×(3.10±0.10)

Table 1: ESP32-SOLO-1 Ordering Information

For detailed ordering information, please see <u>Espressif Product Ordering Information</u>. The information in this datasheet is applicable to both modules.

At the core of this module is the ESP32-S0WD chip. ESP32-S0WD is a member of the ESP32 family of chips, which features a single core and contains all the peripherals of its dual-core counterparts. Available in a 5×5 mm QFN, ESP32-S0WD offers great value for money, with its sustained performance when powering complex IoT applications.

#### Note:

\* For details on the part numbers of the ESP32 family of chips, please refer to the document ESP32 Datasheet.

The integration of Bluetooth, Bluetooth LE and Wi-Fi ensures that a wide range of applications can be targeted, and that the module is all-around: using Wi-Fi allows a large physical range and direct connection to the internet through a Wi-Fi router, while using Bluetooth allows the user to conveniently connect to the phone or broadcast low energy beacons for its detection. The sleep current of the ESP32 chip is less than 5  $\mu$ A, making it suitable for battery powered and wearable electronics applications. The module supports a data rate of up to 150 Mbps, and 20 dBm output power at the antenna to ensure the widest physical range. Several peripherals facilitate integration with other electronic devices. As such the chip does offer industry-leading specifications and ultra-high performance for electronic integration, range, power consumption, and connectivity.

The operating system chosen for ESP32 is freeRTOS with LwIP; TLS 1.2 with hardware acceleration is built in as well. Secure (encrypted) over the air (OTA) upgrade is also supported, so that developers can upgrade their products even after their release at minimum cost and effort.

Table 2 provides the specifications of ESP32-SOLO-1.

Table 2: ESP32-SOLO-1 Specifications

Categories	Items	Specifications
	RF certification	FCC/CE/IC/KCC/SRRC/NCC/TELEC
Certification	Wi-Fi certification	Wi-Fi Alliance
	Green certification	RoHS/REACH

Categories	Items	Specifications		
Test	Reliablity	HTOL/HTSL/uHAST/TCT/ESD		
		802.11 b/g/n (802.11n up to 150 Mbps)		
Wi-Fi	Protocols	A-MPDU and A-MSDU aggregation and 0.4 $\mu$ s guard in-		
VVI-FI		terval support		
	Frequency range	2.4 ~ 2.5 GHz		
	Protocols	Bluetooth v4.2 BR/EDR and BLE specification		
		NZIF receiver with -97 dBm sensitivity		
Bluetooth	Radio	Class-1, class-2 and class-3 transmitter		
		AFH		
	Audio	CVSD and SBC		
		SD card, UART, SPI, SDIO, I2C, LED PWM, Motor PWM,		
	Module interfaces	I <sup>2</sup> S, IR, pulse counter, GPIO, capacitive touch sensor,		
	Module lifterfaces	ADC, DAC, Two-Wire Automotive Interface (TWAI®, com-		
		patible with ISO11898-1)		
	On-chip sensor	Hall sensor		
Hardware	Integrated crystal	40 MHz crystal		
пагижаге	Integrated SPI flash	4 MB		
	Operating voltage/Power supply	3.0 V ~ 3.6 V		
	Minimum current delivered by	500 mA		
	power supply	300 MA		
	Operating temperature range	-40 °C ~ +85 °C or −40 °C ~ +105 °C		
	Package size	(18.00±0.10) mm × (25.50±0.10) mm × (3.10±0.10) mm		
	Moisture sensitivity level (MSL)	Level 3		

## **Pin Definitions**

#### 2.1 Pin Layout

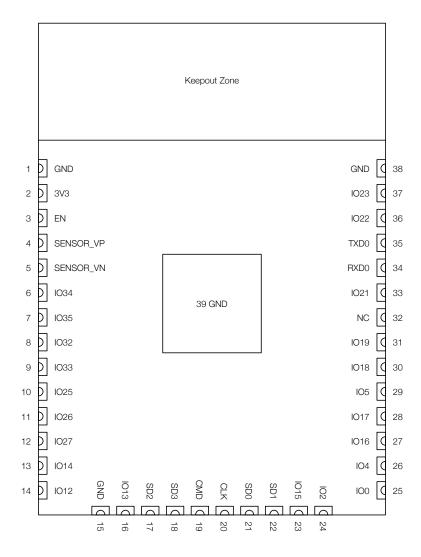


Figure 1: ESP32-SOLO-1 Pin Layout (Top View)

#### **Pin Description** 2.2

ESP32-SOLO-1 has 38 pins. See pin definitions in Table 3.

Table 3: Pin Definitions

Name	No.	Туре	Function
GND	1	Р	Ground
3V3	2	Р	Power supply
EN	3	I	Module-enable signal. Active high.
SENSOR_VP	4	I	GPIO36, ADC1_CH0, RTC_GPIO0
SENSOR_VN	5	I	GPIO39, ADC1_CH3, RTC_GPIO3
IO34	6	I	GPIO34, ADC1_CH6, RTC_GPIO4

Name	No.	Type	Function
IO35	7	I	GPIO35, ADC1_CH7, RTC_GPIO5
1032	8	I/O	GPIO32, XTAL_32K_P (32.768 kHz crystal oscillator input), ADC1_CH4,
1032	0	1/0	TOUCH9, RTC_GPIO9
IO33	0	I/O	GPIO33, XTAL_32K_N (32.768 kHz crystal oscillator output), ADC1_CH5,
1033	9	1/0	TOUCH8, RTC_GPIO8
IO25	10	I/O	GPIO25, DAC_1, ADC2_CH8, RTC_GPIO6, EMAC_RXD0
IO26	11	I/O	GPIO26, DAC_2, ADC2_CH9, RTC_GPIO7, EMAC_RXD1
IO27	12	I/O	GPIO27, ADC2_CH7, TOUCH7, RTC_GPIO17, EMAC_RX_DV
IO14	13	I/O	GPIO14, ADC2_CH6, TOUCH6, RTC_GPIO16, MTMS, HSPICLK, HS2_CLK,
1014	13	1/0	SD_CLK, EMAC_TXD2
IO12	14	I/O	GPIO12, ADC2_CH5, TOUCH5, RTC_GPIO15, MTDI, HSPIQ, HS2_DATA2,
1012	14	1/0	SD_DATA2, EMAC_TXD3
GND	15	Р	Ground
IO13	16	I/O	GPIO13, ADC2_CH4, TOUCH4, RTC_GPIO14, MTCK, HSPID, HS2_DATA3,
1010	10	1/0	SD_DATA3, EMAC_RX_ER
SHD/SD2*	17	I/O	GPIO9, SD_DATA2, SPIHD, HS1_DATA2, U1RXD
SWP/SD3*	18	I/O	GPIO10, SD_DATA3, SPIWP, HS1_DATA3, U1TXD
SCS/CMD*	19	I/O	GPIO11, SD_CMD, SPICS0, HS1_CMD, U1RTS
SCK/CLK*	20	I/O	GPIO6, SD_CLK, SPICLK, HS1_CLK, U1CTS
SDO/SD0*	21	I/O	GPIO7, SD_DATA0, SPIQ, HS1_DATA0, U2RTS
SDI/SD1*	22	I/O	GPIO8, SD_DATA1, SPID, HS1_DATA1, U2CTS
IO15	23	I/O	GPIO15, ADC2_CH3, TOUCH3, MTDO, HSPICS0, RTC_GPIO13, HS2_CMD,
1013	20	1/0	SD_CMD, EMAC_RXD3
102	24	I/O	GPIO2, ADC2_CH2, TOUCH2, RTC_GPIO12, HSPIWP, HS2_DATA0,
102	24	1/0	SD_DATA0
100	25	I/O	GPIO0, ADC2_CH1, TOUCH1, RTC_GPIO11, CLK_OUT1, EMAC_TX_CLK
104	26	I/O	GPIO4, ADC2_CH0, TOUCH0, RTC_GPIO10, HSPIHD, HS2_DATA1,
104	20	1/0	SD_DATA1, EMAC_TX_ER
IO16	27	I/O	GPIO16, HS1_DATA4, U2RXD, EMAC_CLK_OUT
IO17	28	I/O	GPIO17, HS1_DATA5, U2TXD, EMAC_CLK_OUT_180
IO5	29	I/O	GPIO5, VSPICSO, HS1_DATA6, EMAC_RX_CLK
IO18	30	I/O	GPIO18, VSPICLK, HS1_DATA7
IO19	31	I/O	GPIO19, VSPIQ, U0CTS, EMAC_TXD0
NC	32	-	-
IO21	33	I/O	GPIO21, VSPIHD, EMAC_TX_EN
RXD0	34	I/O	GPIO3, U0RXD, CLK_OUT2
TXD0	35	I/O	GPIO1, U0TXD, CLK_OUT3, EMAC_RXD2
IO22	36	I/O	GPIO22, VSPIWP, U0RTS, EMAC_TXD1
IO23	37	I/O	GPIO23, VSPID, HS1_STROBE
GND	38	Р	Ground

### Notice:

<sup>\*</sup> Pins SCK/CLK, SDO/SD0, SDI/SD1, SHD/SD2, SWP/SD3 and SCS/CMD, namely, GPIO6 to GPIO11 are connected

to the integrated SPI flash integrated on the module and are not recommended for other uses.

#### **Strapping Pins** 2.3

ESP32 has five strapping pins, which can be seen in Chapter 6 Schematics:

- MTDI
- GPIO0
- GPIO2
- MTDO
- GPI05

Software can read the values of these five bits from register "GPIO\_STRAPPING".

During the chip's system reset release (power-on-reset, RTC watchdog reset and brownout reset), the latches of the strapping pins sample the voltage level as strapping bits of "0" or "1", and hold these bits until the chip is powered down or shut down. The strapping bits configure the device's boot mode, the operating voltage of VDD\_SDIO and other initial system settings.

Each strapping pin is connected to its internal pull-up/pull-down during the chip reset. Consequently, if a strapping pin is unconnected or the connected external circuit is high-impedance, the internal weak pull-up/pull-down will determine the default input level of the strapping pins.

To change the strapping bit values, users can apply the external pull-down/pull-up resistances, or use the host MCU's GPIOs to control the voltage level of these pins when powering on ESP32.

After reset release, the strapping pins work as normal-function pins.

Refer to Table 4 for a detailed boot-mode configuration by strapping pins.

Table 4: Strapping Pins

	Voltage of Internal LDO (VDD_SDIO)								
Pin	Default	3.3 V		ault 3.3 V 1.8 V		3 V			
MTDI	Pull-down	(	)	-	1				
		Вс	ooting Mode						
Pin	Default	SPL	Boot	Downlo	ad Boot				
GPI00	Pull-up	-	1	(	)				
GPIO2	Pull-down	Don't	-care	0					
E	Enabling/Disa	bling Debugging	g Log Print over	U0TXD During I	Booting				
Pin	Default	UOTXD	Active	UOTXE	) Silent				
MTDO	Pull-up	-	1	(	)				
		Timinç	g of SDIO Slave						
		FE Sampling	FE Sampling	RE Sampling	RE Sampling				
Pin	Default	FE Output	RE Output	FE Output	RE Output				
MTDO	Pull-up	0	0	1	1				
GPIO5	Pull-up	0	1	0	1				

#### Note:

- FE: falling-edge, RE: rising-edge.
- Firmware can configure register bits to change the settings of "Voltage of Internal LDO (VDD\_SDIO)" and "Timing of SDIO Slave" after booting.

## 3 Functional Description

This chapter describes the modules and functions integrated in ESP32-SOLO-1.

## 3.1 CPU and Internal Memory

ESP32-S0WD contains one low-power Xtensa® 32-bit LX6 microprocessor. The internal memory includes:

- 448 KB of ROM for booting and core functions.
- 520 KB of on-chip SRAM for data and instructions.
- 8 KB of SRAM in RTC, which is called RTC FAST Memory and can be used for data storage; it is accessed by the main CPU during RTC Boot from the Deep-sleep mode.
- 8 KB of SRAM in RTC, which is called RTC SLOW Memory and can be accessed by the co-processor during the Deep-sleep mode.
- 1 Kbit of eFuse: 256 bits are used for the system (MAC address and chip configuration) and the remaining 768 bits are reserved for customer applications, including flash-encryption and chip-ID.

#### 3.2 External Flash and SRAM

ESP32 supports multiple external QSPI flash and SRAM chips. More details can be found in Chapter SPI in the ESP32 Technical Reference Manual. ESP32 also supports hardware encryption/decryption based on AES to protect developers' programs and data in flash.

ESP32 can access the external QSPI flash and SRAM through high-speed caches.

- The external flash can be mapped into CPU instruction memory space and read-only memory space simultaneously.
  - When external flash is mapped into CPU instruction memory space, up to 11 MB + 248 KB can be mapped at a time. Note that if more than 3 MB + 248 KB are mapped, cache performance will be reduced due to speculative reads by the CPU.
  - When external flash is mapped into read-only data memory space, up to 4 MB can be mapped at a time. 8-bit, 16-bit and 32-bit reads are supported.
- External SRAM can be mapped into CPU data memory space. Up to 4 MB can be mapped at a time. 8-bit, 16-bit and 32-bit reads and writes are supported.

ESP32-SOLO-1 integrates a 4 MB SPI flash, which is connected to GPIO6, GPIO7, GPIO8, GPIO9, GPIO10 and GPIO11. These six pins cannot be used as regular GPIOs.

## 3.3 Crystal Oscillators

The module uses a 40-MHz crystal oscillator.

## RTC and Low-Power Management

With the use of advanced power-management technologies, ESP32 can switch between different power modes.

For details on ESP32's power consumption in different power modes, please refer to section "RTC and Low-Power Management" in ESP32 Datasheet.

Please refer to Section Peripherals and Sensors in *ESP32 Datasheet*.

## Note:

External connections can be made to any GPIO except for GPIOs in the range 6-11. These six GPIOs are connected to the module's integrated SPI flash. For details, please see Section 6 Schematics.

## 5 Electrical Characteristics

## 5.1 Absolute Maximum Ratings

Stresses beyond the absolute maximum ratings listed in Table 5 below may cause permanent damage to the device. These are stress ratings only, and do not refer to the functional operation of the device that should follow the recommended operating conditions.

Unit Symbol Parameter Min Max VDD33 3.6 V Power supply voltage -0.3Cumulative IO output current 1,100  $|_{output}^{-1}|$ mΑ -40 °С  $T_{store}$ Storage temperature 150

**Table 5: Absolute Maximum Ratings** 

- The module worked properly after a 24-hour test in ambient temperature at 25 °C, and the IOs in three domains (VDD3P3\_RTC, VDD3P3\_CPU, VDD\_SDIO) output high logic level to ground. Please note that pins occupied by flash and/or PSRAM in the VDD\_SDIO power domain were excluded from the test.
- 2. Please see Appendix IO\_MUX of ESP32 Datasheet for IO's power domain.

## 5.2 Recommended Operating Conditions

**Table 6: Recommended Operating Conditions** 

Symbol	Parameter	Min	Тур	Max	Unit
VDD33	Power supply voltage	3.0	3.3	3.6	V
$ V_{VDD} $	Current delivered by external power supply	0.5	-	-	Α
Т	Operating temperature	-40	-	85 or 105, depending on model	°C

## 5.3 DC Characteristics (3.3 V, 25 °C)

Table 7: DC Characteristics (3.3 V, 25 °C)

Symbol	Paramet	Min	Тур	Max	Unit	
$C_{IN}$	Pin capacitance	-	2	-	рF	
$V_{IH}$	High-level input voltage		0.75×VDD <sup>1</sup>	-	VDD1+0.3	V
$V_{IL}$	Low-level input voltage	Low-level input voltage			0.25×VDD <sup>1</sup>	V
$ I_{IH} $	High-level input current	-	-	50	nA	
$ I_{IL} $	Low-level input current	-	-	50	nA	
$V_{OH}$	High-level output voltage	0.8×VDD <sup>1</sup>	-	-	V	
$V_{OL}$	Low-level output voltage	-	-	0.1×VDD <sup>1</sup>	V	
	High-level source current	VDD3P3_CPU		40	_	mA
	$(VDD^1 = 3.3 \text{ V})$	power domain 1, 2	_	40	_	ША
Larr	$V_{OH} >= 2.64 \text{ V},$	VDD3P3_RTC	_	40	_	mA
$  _{OH}$	output drive strength set	power domain 1, 2	_	40	_	

to the maximum)

Symbol	Parameter	Min	Тур	Max	Unit	
		VDD_SDIO power		20	_	mΛ
		domain <sup>1, 3</sup>	-	20	-	mA
	Low-level sink current					
$I_{OL}$	$ $ (VDD $^1$ = 3.3 V, V $_{OL}$ = 0.495 V	-	28	-	mA	
	output drive strength set to the maximum)					
$R_{PU}$	Resistance of internal pull-up	-	45	-	kΩ	
$R_{PD}$	Resistance of internal pull-dov	-	45	-	kΩ	
$V_{IL\_nRST}$	Low-level input voltage of CHIP_PU		_	_	0.6	V
	to power off the chip		_	_	0.0	V

#### Notes:

- 1. Please see Appendix IO\_MUX of ESP32 Datasheet for IO's power domain. VDD is the I/O voltage for a particular power domain of pins.
- 2. For VDD3P3\_CPU and VDD3P3\_RTC power domain, per-pin current sourced in the same domain is gradually reduced from around 40 mA to around 29 mA,  $V_{OH}$ >=2.64 V, as the number of current-source pins increases.
- 3. Pins occupied by flash and/or PSRAM in the VDD\_SDIO power domain were excluded from the test.

### 5.4 Wi-Fi Radio

Table 8: Wi-Fi Radio Characteristics

Parameter	Condition	Min	Typical	Max	Unit
Operating frequency range $^{note1}$	-	2412	-	2484	MHz
Output impedance note2	-	-	note 2	-	Ω
TX power note3	11n, MCS7	12	13	14	dBm
1 × power	11b mode	17.5	18.5	20	dBm
	11b, 1 Mbps	-	-98	-	dBm
	11b, 11 Mbps	-	-89	-	dBm
	11g, 6 Mbps	-	-92	-	dBm
Sensitivity	11g, 54 Mbps	-	-74	-	dBm
Sensitivity	11n, HT20, MCS0	-	-91	-	dBm
	11n, HT20, MCS7	-	-71	-	dBm
	11n, HT40, MCS0	-	-89	-	dBm
	11n, HT40, MCS7	-	-69	-	dBm
	11g, 6 Mbps	-	31	-	dB
Adjacent channel rejection	11g, 54 Mbps	-	14	-	dB
Adjacent charmen rejection	11n, HT20, MCS0	-	31	-	dB
	11n, HT20, MCS7	-	13	-	dB

- 1. Device should operate in the frequency range allocated by regional regulatory authorities. Target operating frequency range is configurable by software.
- 2. For the modules that use IPEX antennas, the output impedance is 50  $\Omega$ . For other modules without IPEX antennas, users do not need to concern about the output impedance.
- 3. Target TX power is configurable based on device or certification requirements.

#### **Bluetooth LE Radio** 5.5

## 5.5.1 Receiver

Table 9: Receiver Characteristics - BLE

Parameter	Conditions	Min	Тур	Max	Unit
Sensitivity @30.8% PER	-	-	-97	-	dBm
Maximum received signal @30.8% PER	-	0	-	-	dBm
Co-channel C/I	-	-	+10	-	dB
	F = F0 + 1 MHz	-	-5	-	dB
	F = F0 – 1 MHz	-	-5	-	dB
Adjacent channel coloctivity C/I	F = F0 + 2 MHz	-	-25	-	dB
Adjacent channel selectivity C/I	F = F0 - 2 MHz	-	-35	-	dB
	F = F0 + 3 MHz	-	-25	-	dB
	F = F0 - 3 MHz	-	-45	-	dB
Out-of-band blocking performance	30 MHz ~ 2000 MHz	-10	-	-	dBm
	2000 MHz ~ 2400 MHz	-27	-	-	dBm
	2500 MHz ~ 3000 MHz	-27	-	-	dBm
	3000 MHz ~ 12.5 GHz	-10	-	-	dBm
Intermodulation	-	-36	-	-	dBm

## 5.5.2 Transmitter

Table 10: Transmitter Characteristics - BLE

Parameter	Conditions	Min	Тур	Max	Unit
RF transmit power	-	-	0	-	dBm
Gain control step	-	-	3	-	dB
RF power control range	-	-12	-	+9	dBm
	$F = F0 \pm 2 MHz$	-	-52	-	dBm
Adjacent channel transmit power	$F = F0 \pm 3 \text{ MHz}$	-	-58	-	dBm
	$F = F0 \pm > 3 MHz$	-	-60	-	dBm
$\Delta \ f1_{ ext{avg}}$	-	-	-	265	kHz
$\Delta~f2_{ ext{max}}$	-	247	-	-	kHz
$\Delta~f2_{ m avg}/\Delta~f1_{ m avg}$	-	-	0.92	-	-
ICFT	-	-	-10	-	kHz
Drift rate	-	-	0.7	-	kHz/50 μs
Drift	-	-	2	-	kHz

#### **Reflow Profile** 5.6

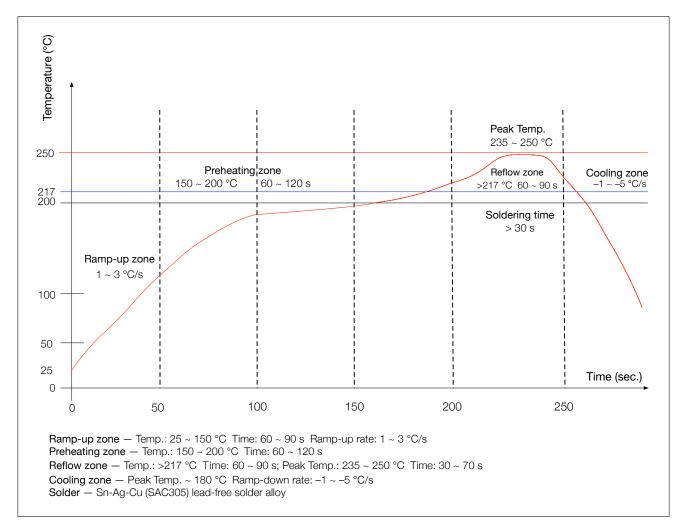


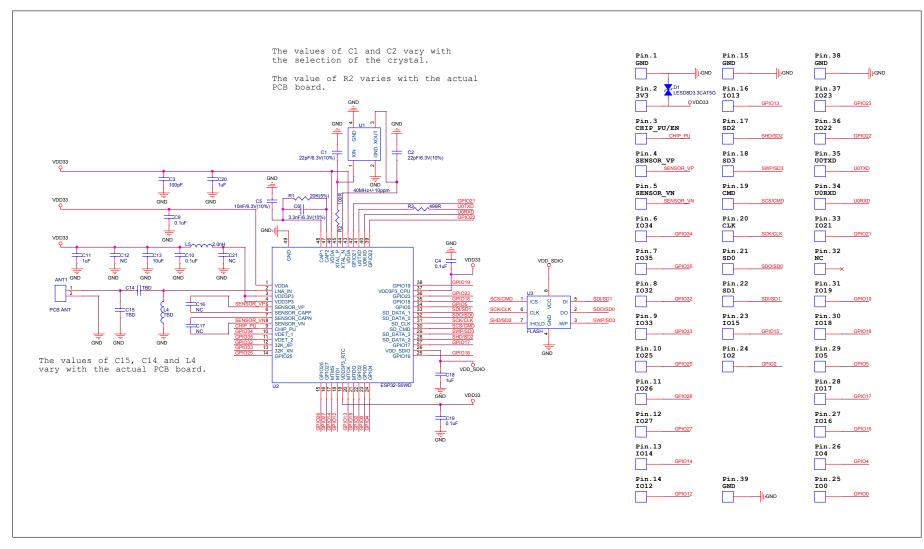
Figure 2: Reflow Profile

### Note:

Solder the module in a single reflow.

## 6 Schematics

This is the reference design of the module.



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Schematics

Figure 3: ESP32-SOLO-1 Schematics

## 7 Peripheral Schematics

This is the typical application circuit of the module connected with peripheral components (for example, power supply, antenna, reset button, JTAG interface, and UART interface).

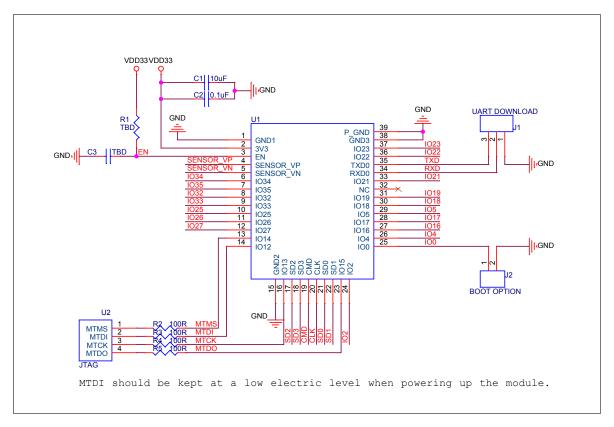


Figure 4: ESP32-SOLO-1 Peripheral Schematics

#### Note:

- Soldering Pad 39 to the Ground of the base board is not necessary for a satisfactory thermal performance. If users do want to solder it, they need to ensure that the correct quantity of soldering paste is applied.
- To ensure the power supply to the ESP32 chip during power-up, it is advised to add an RC delay circuit at the EN pin. The recommended setting for the RC delay circuit is usually R = 10 k $\Omega$  and C = 1  $\mu$ F. However, specific parameters should be adjusted based on the power-up timing of the module and the power-up and reset sequence timing of the chip. For ESP32's power-up and reset sequence timing diagram, please refer to Section *Power Scheme* in *ESP32 Datasheet*.

 $| \infty |$ 

# 8 Physical Dimensions

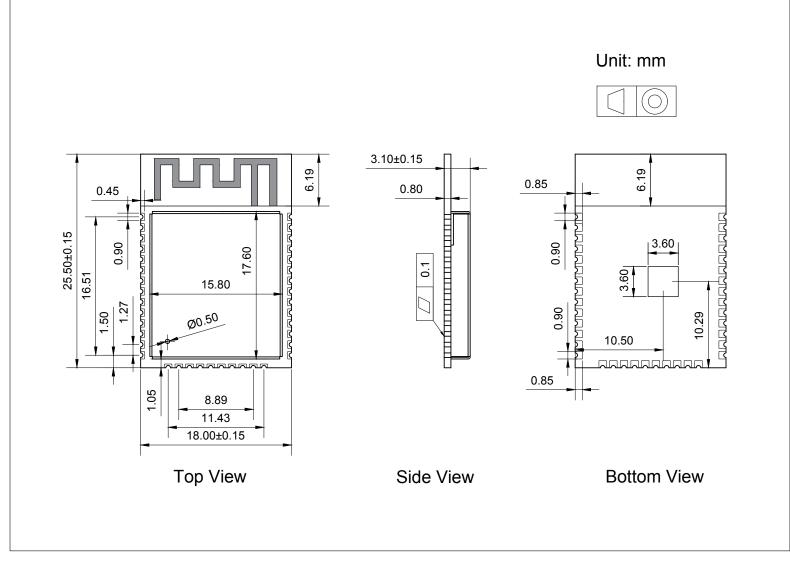


Figure 5: Physical Dimensions of ESP32-SOLO-1

## **Recommended PCB Land Pattern**

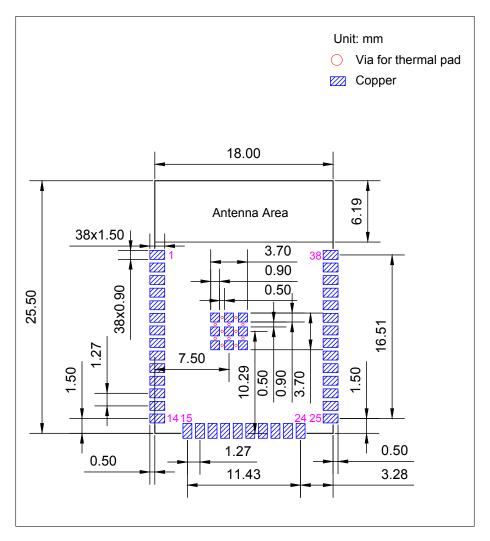


Figure 6: Recommended PCB Land Pattern of ESP32-SOLO-1

## **Learning Resources**

#### 10.1 **Must-Read Documents**

The following link provides documents related to ESP32.

#### • ESP32 Datasheet

This document provides an introduction to the specifications of the ESP32 hardware, including overview, pin definitions, functional description, peripheral interface, electrical characteristics, etc.

#### • ESP32 ECO V3 User Guide

This document describes differences between V3 and previous ESP32 silicon wafer revisions.

#### • ECO and Workarounds for Bugs in ESP32

This document details hardware errata and workarounds in the ESP32.

#### • ESP-IDF Programming Guide

It hosts extensive documentation for ESP-IDF ranging from hardware guides to API reference.

#### • ESP32 Technical Reference Manual

The manual provides detailed information on how to use the ESP32 memory and peripherals.

### • ESP32 Hardware Resources

The zip files include the schematics, PCB layout, Gerber and BOM list of ESP32 modules and development boards.

#### • ESP32 Hardware Design Guidelines

The guidelines outline recommended design practices when developing standalone or add-on systems based on the ESP32 series of products, including the ESP32 chip, the ESP32 modules and development boards.

#### ESP32 AT Instruction Set and Examples

This document introduces the ESP32 AT commands, explains how to use them, and provides examples of several common AT commands.

• Espressif Products Ordering Information

#### 10.2 **Must-Have Resources**

Here are the ESP32-related must-have resources.

### • ESP32 BBS

This is an Engineer-to-Engineer (E2E) Community for ESP32 where you can post questions, share knowledge, explore ideas, and help solve problems with fellow engineers.

### • ESP32 GitHub

ESP32 development projects are freely distributed under Espressif's MIT license on GitHub. It is established to help developers get started with ESP32 and foster innovation and the growth of general knowledge about the hardware and software surrounding ESP32 devices.

#### • ESP32 Tools

This is a webpage where users can download ESP32 Flash Download Tools and the zip file "ESP32 Certification and Test".

## • ESP-IDF

This webpage links users to the official IoT development framework for ESP32.

## • ESP32 Resources

This webpage provides the links to all available ESP32 documents, SDK and tools.

# **Revision History**

Updated Figure 5: Physical Dimensions of ESP32-SOLO-1 and Figure 6:  Recommended PCB Land Pattern of ESP32-SOLO-1.  Modified the note below Figure 2: Reflow Profile.  Updated TwAl™ in Table 2:  Updated Trigure 2 and added a note under it;  Added notes about schematics and peripheral schematics;  Fixed some typos;  Updated the C value in RC delay circuit from 0.1 μF to 1 μF;  Provided feedback link.  Changed the supply voltage range from 2.7 V ~ 3.6 V to 3.0 V ~ 3.6 V;  Updated Figure 9 Recommended PCB Land Pattern.  Added a new variant with high temperature range (~40 °C ~ +105 °C) in Chapter 1 Overview;  Added Moisture sensitivity level (MSL) 3 in Table 2 ESP32-SOLO-1 Specifications;  Added notes about "Operating frequency range" and "TX power" under Table 8 Wi-Fi Radio Characteristics.  2019.01  V1.4  Changed the RF power control range in Table 10 from −12 ~ +12 to −12 ~ +9 dBm.  • Updated the descriptions of pins IO16 and IO17 in Table 3: Pin Definitions;  • Added "Cumulative IO output current" entry to Table 5: Absolute Maximum Ratings;  • Added more parameters to Table 7: DC Characteristics.  • Added certifications and reliability test items the module has passed	Date	Version	Release notes
Updated Figure 2 and added a note under it; Added notes about schematics and peripheral schematics; Fixed some typos; Updated the C value in RC delay circuit from 0.1 μF to 1 μF; Provided feedback link.  Changed the supply voltage range from 2.7 V ~ 3.6 V to 3.0 V ~ 3.6 V; Updated Section 7 Peripheral Schematics and added a note about RC delay circuit under it; Updated Figure 9 Recommended PCB Land Pattern.  Added a new variant with high temperature range (-40 °C ~ +105 °C) in Chapter 1 Overview; Added Moisture sensitivity level (MSL) 3 in Table 2 ESP32-SOLO-1 Specifications; Added notes about "Operating frequency range" and "TX power" under Table 8 Wi-Fi Radio Characteristics.  2019.01  V1.4  Changed the RF power control range in Table 10 from −12 ~ +12 to −12 ~ +9 dBm.  • Updated the descriptions of pins IO16 and IO17 in Table 3: Pin Definitions; • Added "Cumulative IO output current" entry to Table 5: Absolute Maximum Ratings; • Added more parameters to Table 7: DC Characteristics.  Updated the hole diameter in the shield from 1.00 mm to 0.50 mm, in Figure 5. Added RoHS certification.	2021-02-04	V1.8	Recommended PCB Land Pattern of ESP32-SOLO-1.  Modified the note below Figure 2: Reflow Profile.
Updated Section 7 Peripheral Schematics and added a note about RC delay circuit under it; Updated Figure 9 Recommended PCB Land Pattern.  Added a new variant with high temperature range (-40 °C ~ +105 °C) in Chapter 1 Overview; Added Moisture sensitivity level (MSL) 3 in Table 2 ESP32-SOLO-1 Specifications; Added notes about "Operating frequency range" and "TX power" under Table 8 Wi-Fi Radio Characteristics.  Changed the RF power control range in Table 10 from -12 ~ +12 to -12 ~ +9 dBm.  • Updated the descriptions of pins IO16 and IO17 in Table 3: Pin Definitions; • Added "Cumulative IO output current" entry to Table 5: Absolute Maximum Ratings; • Added more parameters to Table 7: DC Characteristics.  2018.09  V1.2  Updated the hole diameter in the shield from 1.00 mm to 0.50 mm, in Figure 5. Added RoHS certification.	2020-11-27	V1.7	Updated Figure 2 and added a note under it; Added notes about schematics and peripheral schematics; Fixed some typos; Updated the C value in RC delay circuit from 0.1 $\mu$ F to 1 $\mu$ F;
Chapter 1 Overview; Added Moisture sensitivity level (MSL) 3 in Table 2 ESP32-SOLO-1 Specifications; Added notes about "Operating frequency range" and "TX power" under Table 8 Wi-Fi Radio Characteristics.  2019.01  V1.4  Changed the RF power control range in Table 10 from -12 ~ +12 to -12 ~ +9 dBm.  • Updated the descriptions of pins IO16 and IO17 in Table 3: Pin Definitions;  • Added "Cumulative IO output current" entry to Table 5: Absolute Maximum Ratings;  • Added more parameters to Table 7: DC Characteristics.  Updated the hole diameter in the shield from 1.00 mm to 0.50 mm, in Figure 5. Added RoHS certification.	2019.09	V1.6	Updated Section 7 Peripheral Schematics and added a note about RC delay circuit under it;
<ul> <li>V1.4 ~ +9 dBm.</li> <li>Updated the descriptions of pins IO16 and IO17 in Table 3: Pin Definitions;</li> <li>Added "Cumulative IO output current" entry to Table 5: Absolute Maximum Ratings;</li> <li>Added more parameters to Table 7: DC Characteristics.</li> <li>Updated the hole diameter in the shield from 1.00 mm to 0.50 mm, in Figure 5. Added RoHS certification.</li> </ul>	2019.07	V1.5	Chapter 1 Overview; Added Moisture sensitivity level (MSL) 3 in Table 2 ESP32-SOLO-1 Specifications; Added notes about "Operating frequency range" and "TX power" under
initions;  • Added "Cumulative IO output current" entry to Table 5: Absolute Maximum Ratings; • Added more parameters to Table 7: DC Characteristics.  Updated the hole diameter in the shield from 1.00 mm to 0.50 mm, in Figure 5. Added RoHS certification.	2019.01	V1.4	
2018.09 V1.2 Figure 5. Added RoHS certification.	2018.09	V1.3	<ul><li>initions;</li><li>Added "Cumulative IO output current" entry to Table 5: Absolute Maximum Ratings;</li></ul>
Added certifications and reliability test items the module has passed	2018.09	V1.2	
in Table 2: ESP32-SOLO-1 Specifications, and removed software-specific information;  • Updated section 3.4: RTC and Low-Power Management;  • Changed the modules' dimensions from (18±0.2) mm x (25.5 ±0.2) mm x (3.1±0.15) mm to (18.00±0.10) mm x (25.50±0.10) mm x (3.10±0.10) mm;  • Updated Table 8: Wi-Fi Radio;  • Updated Figure 8: Physical Dimensions.	2018.08	V1.1	<ul> <li>in Table 2: ESP32-SOLO-1 Specifications, and removed software-specific information;</li> <li>Updated section 3.4: RTC and Low-Power Management;</li> <li>Changed the modules' dimensions from (18±0.2) mm x (25.5 ±0.2) mm x (3.1±0.15) mm to (18.00±0.10) mm x (25.50±0.10) mm x (3.10±0.10) mm;</li> <li>Updated Table 8: Wi-Fi Radio;</li> </ul>
2018.06 V1.0 First release.	2018.06	V1.0	



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