

LINGI2261: Artificial Intelligence

Assignment 4: Local Search and Propositional Logic

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Guidelines

- This assignment is due on **Thursday 06 May, 6:00 pm**.
- **No delay** will be tolerated.
- **Document** your source code (at least the difficult or more technical parts of your programs). Python docstrings for important classes, methods and functions are also welcome.
- Copying code or answers from other groups (or from the internet) is strictly forbidden. Each source of inspiration must be clearly indicated.
- Source code shall be submitted on the online **INGInious** system. Only programs submitted via this procedure will be graded. No program sent by email will be accepted.
- Respect carefully the **specifications** given for your program (arguments, input/output format, etc.) as the program testing system is **fully automated**.
- The answer to questions must be given by filling in the latex template provided. The final file must be submitted on **gradescope**. No report sent by email will be accepted.
- Nothing must be modified in the template except your answer that you insert in the *answer* environments as well as your names and your group number. The names are provided through the command *students* while the command *group* is used for the group number. The dimensions of *answer* fields **must not** be modified either. For the tables, put your answer between the "&" symbols. Any other changes to the file will **invalidate** your submission.
- To submit on gradescope, go to <https://gradescope.com> and click on the "log in" button. Then choose the "school credentials" option and search for *UCLouvain Username*. Log in with your global username and password. Find the course LINGI2261 and the Assignment 4, then submit your report. Only one member should submit the report and add the second as group member.
- For those who have not been automatically added to the course, at the right bottom of gradescope homepage, click on "Enroll on course" button and type the code **86KJVB**.
- Check this link if you have any trouble with group submission <https://help.gradescope.com/article/m5qz2xsnjy-student-add-group-members>



Deliverables

- The answers to all the questions in a report on **INGInious**. **Do not forget to put your group number on the front page as well as the INGInious id of both**

group members.

- The following files are to be submitted:
 - `binpacking_max.py`: your *maxvalue* local search for Knapsack problem, to submit on INGIous in the *Assignment4: Bin packing max value* task.
 - `binpacking_random_max.py`: your *randomized max value* local search for Knapsack problem, to submit on INGIous in the *Assignment4: Bin packing randomized maxvalue* task.
 - `cgp_solver.py`: which contains `get_expression` method to solve the Color Grid problem, to submit on INGIous in the *Assignment4: Color Grid Problem* task.

1 The bin packing problem (13 pts)

In this assignment you will design an algorithm to solve the infamous bin packing problem. You are provided with a set of items, each having a specific size to pack into a certain number of bins having a maximal capacity. Your task is to find a good configuration of packing such that the number of bins needed is minimal. Figure 1 shows an example of a solution for bin packing problem.

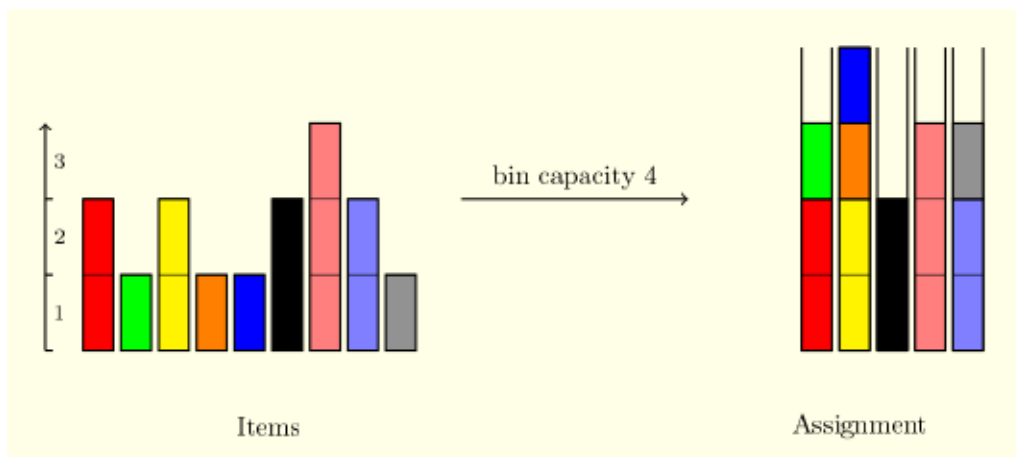


Figure 1: Example of a bin packing problem: Here it took 4 bins of capacity 4 to pack the 9 items.

Source: <https://scip.zib.de/doc/html/binpacking.png>

Formally, the bin packing problem is defined as follows¹ : given a finite set $U = \{u_1, u_2, \dots, u_n\}$ of items and a rational size $s(u) \in]0, 1]$, for each item $u \in U$, find a partition of U into disjoint subsets U_1, U_2, \dots, U_k such that the sum of the item sizes in each U_i is no more than 1 and k is as small as possible. Without loss of generality, the bin packing problem is considered to be the problem of packing a finite set of items of integer sizes $s(u_i) \in [0, C]$ into bins of capacity C to minimize the number of bins.

¹Michael R Garey and David S Johnson. *Computers and intractability*. Vol. 29. wh freeman New York, 2002.

1.1 Objective function

A solution to bin packing problem can be evaluated by using different functions provided in the literature, each with its particularity. The one provided here is called *Fitness*.²

$$Fitness = 1 - \left(\frac{\sum_{i=1}^n (fullness_i / C)^2}{k} \right)$$

where k = number of bins, $fullness_i$ = sum of all the pieces in bin i , and C = bin capacity. The function puts a premium on bins that are filled completely, or nearly so. It returns a value between zero and one, where lower is better, and a set of completely full bins would return a value of zero. In this case, the objective would be to minimize this function.

1.2 Neighborhood

In local search, we have to build at each decision time a neighborhood in which a solution is picked depending on a specific criterion. We suggest here two types of actions to build your neighborhood all based on swap moves. **The capacity constraint of the bins cannot be violated during building of the neighborhood.**

Swap two items This kind of action allows you to change positions of items into bins, so you modify the fullness of involving bins but without reducing the number of bins used for the solution. Figure 2 shows an example of this action.

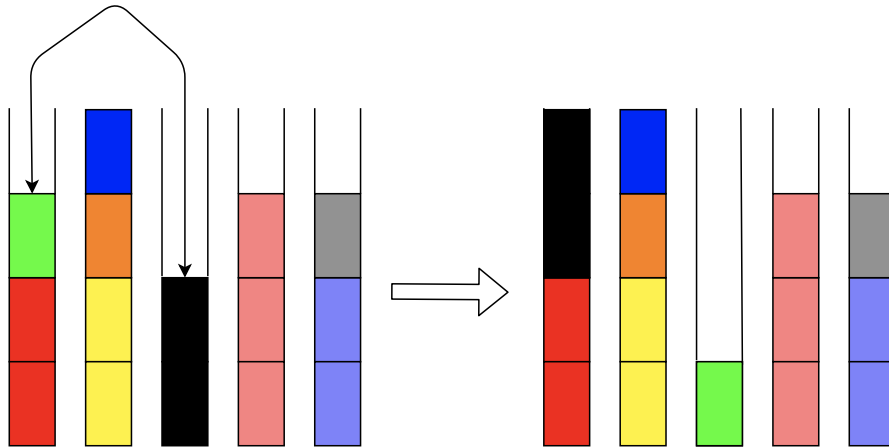


Figure 2: Swap of two items

Swap an item and a blank space Contrary to the previous action. This one can allow you to reduce the number of bins used from a configuration to another one since it allows to swap an item and a blank space : it is a kind of *move*. Figure 3 shows an example of this situation.

You are not obliged to use the proposed objective function as well as techniques for building the neighborhood. You can use your owns but you have to specify in you report the ones you used. However, note that your result will be evaluated with the fitness score.

²Matthew Hyde et al. "A hyflex module for the one dimensional bin-packing problem". In: *School of Computer Science, University of Nottingham, Tech. Rep* (2009).

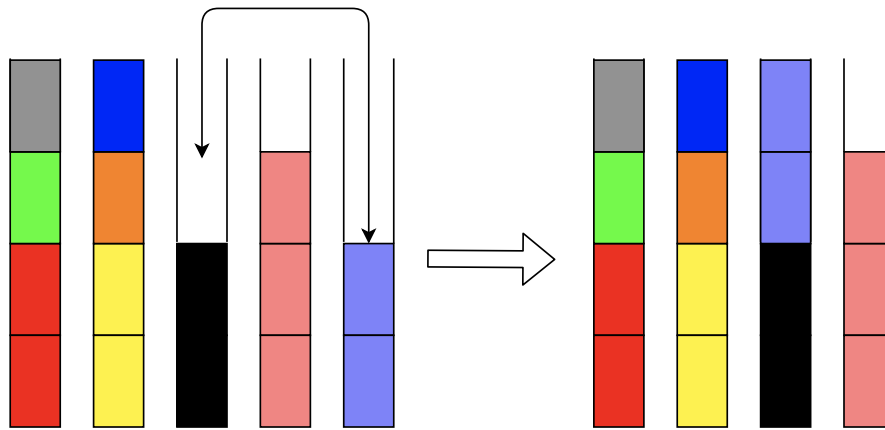


Figure 3: Swap of an item and a blank space (Move of an item)

A bin packing input contains $n+1$ lines. The first line contains an integer which represent the number n of items in the problem and the maximal capacity C of bins. The n following lines present the data for each of the items. Each line contains two integers. The first one is item's index i and the second is its size $s(u_i)$.

The format for describing the different instances on which you will have to test your program is the following:

Input format

| | |
|-----|----------|
| n | C |
| 1 | $s(u_1)$ |
| 2 | $s(u_2)$ |
| ... | |
| n | $s(u_n)$ |

For this assignment, you will use *Local Search* to find good solutions to the bin packing problem. The test instances can be found on Moodle. A template for your code is also provided. The output format **must** be the following:

Output format

| |
|--|
| $U_1 = \{u_i \in U \mid u_i \in U_1\}$ |
| ... |
| $U_k = \{u_i \in U \mid u_i \in U_k\}$ |

Where k is the total number of bins used to pack all the items.

For example, the input and an output for the bin packing problem of Figure 1 could be:

Input format

```
9 4
1 2
2 1
3 2
4 1
5 1
6 2
7 3
8 2
9 1
```

Output format

```
1 2 9
8 6
7
4 5 3
```

Diversification versus Intensification

The two key principles of Local Search are intensification and diversification. Intensification is targeted at enhancing the current solution and diversification tries to avoid the search from falling into local optima. Good local search algorithms have a tradeoff between these two principles. For this part of the assignment, you will have to experiment this tradeoff.



Questions

1. (1 pt) Formulate the bin packing problem as a Local Search problem (problem, cost function, feasible solutions, optimal solutions).
2. (5 pts) You are given a template on Moodle: *binpacking.py*. Implement your own extension of the *Problem* class from *aima-python3*. Implement the *maxvalue* and *randomized maxvalue* strategies. To do so, you can get inspiration from the *randomwalk* function in *search.py*. Your program will be evaluated on 15 instances (during 1 minute) of which 5 are hidden. We expect you to solve at least 12 out the 15.
 - (a) *maxvalue* chooses the best node (i.e., the node with minimum value) in the neighborhood, even if it degrades the quality of the current solution. The *maxvalue* strategy should be defined in a function called *maxvalue* with the following signature: `maxvalue(problem, limit=100, callback=None)`.
 - (b) *randomized maxvalue* chooses the next node randomly among the 5 best neighbors (again, even if it degrades the quality of the current solution). The *randomized maxvalue* strategy should be defined in a function called *randomized_maxvalue* with the following signature: `randomized_maxvalue(problem, limit=100, callback=None)`.
3. (3 pts) Compare the 2 strategies implemented in the previous question and

randomwalk defined in *search.py* on the given bin packing instances. Report, in a table, the computation time, the value of the best solution (in term of fitness) and the number of steps needed to reach the best result. For the randomized max value and the random walk, each instance should be tested 10 times to reduce the effects of the randomness on the result. When multiple runs of the same instance are executed, report the mean of the quantities.

4. (4 pts) Answer the following questions:

- (a) What is the best strategy?
- (b) Why do you think the best strategy beats the other ones?
- (c) What are the limitations of each strategy in terms of diversification and intensification?
- (d) What is the behavior of the different techniques when they fall in a local optimum?

2 Propositional Logic (7 pts)

2.1 Models and Logical Connectives (1 pt)

Consider the vocabulary with four propositions A , B , C and D and the following sentences:

- $(\neg A \vee C) \wedge (\neg B \vee C)$
- $(C \Rightarrow \neg A) \wedge \neg(B \vee C)$
- $(\neg A \vee B) \wedge \neg(B \Rightarrow \neg C) \wedge \neg(\neg D \Rightarrow A)$



Questions

1. (1 pt) For each sentence, give its number of valid interpretations, i.e. the number of times the sentence is true (considering for each sentence **all the proposition variables** A , B , C and D).

2.2 Color Grid Problem (6 pts)

The Color Grid Problem can be defined as follow. Given an square grid of shape $n_rows \times n_columns$, a grid coloring assigns a color to each cell, such that all cell on the same line (vertical, horizontal, diagonal) have different colors. A color grid uses n_colors colors such that $n_rows = n_columns = n_colors$. The Color Grid Problem asks whether such a grid exists. Figures 4 below shows an example of a valid coloring (left) and an invalid coloring (right).

Your task is to model this problem with propositional logic. We define $n_rows \times n_columns \times n_colors$ variables: C_{ijk} is *true* iff cell at position (i, j) is assigned to color k ; *false* otherwise. The grid origin $(0, 0)$ is at left top corner.

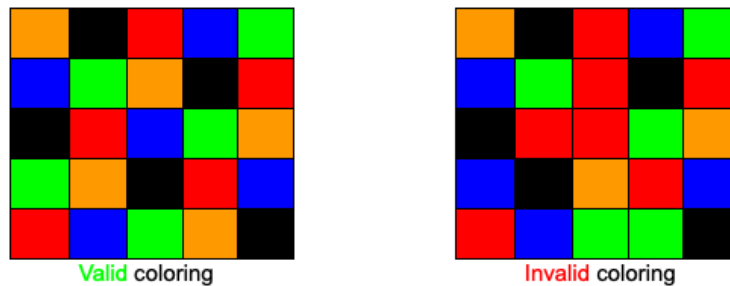


Figure 4: Example of graph coloring



Questions

1. (2 pts) Explain how you can express this problem with propositional logic. For each sentence, give its interpretation.
2. (2 pts) Translate your model into Conjunctive Normal Form (CNF).

On the Moodle site, you will find an archive `cgp.zip` containing the following files:

- `instances` is a directory containing a few instances for you to test this problem.
- `solve_linux.py` / `solve_mac.py` is a python file used to solve the color grid Problem, whether you machine is running on Linux or Mac.
- `cgp_solver.py` is the skeleton of a Python module to formulate the problem into an CNF.
- `minisat.py` is a simple Python module to interact with MiniSat.
- `clause.py` is a simple Python module to represent your clauses.
- `minisatLinux` / `minisatMac` is a pre-compiled MiniSat binary that should run on the machines in the computer labs or your machine depending on the os.

To solve the Color Grid Problem for instance on Linux machine, enter the following command in a terminal:

```
python3 solve_linux.py INSTANCE_FILE
```

where `INSTANCE_FILE` is the color grid instance file. To have different versions of a problem of specific size, the instance file is not only composed of the size of the problem but some colors of the grid are fixed and provided. It is described as follows:



Instance input format

```
size n
p1.i p1.j p1.k
p2.i p2.j p2.k
...
pn.i pn.j pn.k
```

where *size* represents the value of the three (03) parameters of the problem shape since the grid is square. *n* is the number of cells' information provided. The *n* following lines represent

information about the fixed cells and are composed of three integers representing respectively values of x axis, y axis and color index, all starting from 0.



Example of input

```
5 3
0 0 2
3 2 3
4 1 0
```



Questions

3. (2 pts) Modify the function `get_expression(size)` in `cgp_solver.py` such that it outputs a list of clauses modeling the color grid problem for the given input. Submit your code on INGIous inside the *Assignment4: Color Grid Problem* task. The file `cgp_solver.py` is the *only* file that you need to modify to solve this problem. Your program will be evaluated on 10 instances of which 5 are hidden. We expect you to solve at least 8 out the 10.