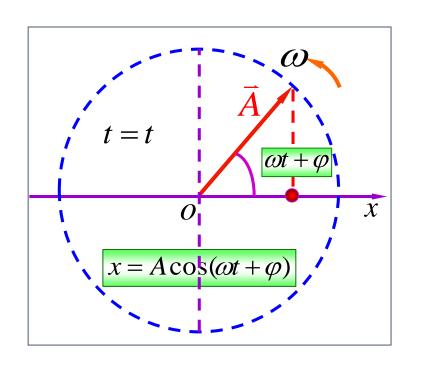
简谐运动的基本特征

- 1、运动学特征 $x = A\cos(\omega t + \varphi)$
- 2、动力学特征 $\ddot{x} + \omega^2 x = 0$ $\omega = \sqrt{\frac{k}{m}}$
- 3、能量特征

$$E = \frac{1}{2}mv^2 + \frac{1}{2}kx^2 = \frac{1}{2}kA^2$$

简谐振动的几何表示: 旋转矢量



以*o*为原 点旋转矢量 A 的端点在 x 轴 的投影点的 上的投影点的 运动为简谐运 动.



一 単摆

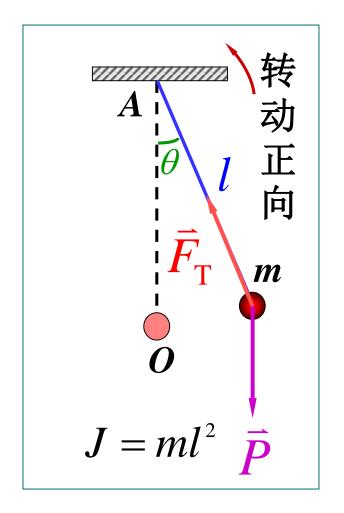
动力学分析:

$$\theta < 5^{\circ}$$
 时, $\sin \theta \approx \theta$

$$M = -mgl\sin\theta \approx -mgl\theta$$

$$-mgl\theta = J\frac{\mathrm{d}^2\theta}{\mathrm{d}t^2}$$

$$\frac{\mathrm{d}^2 \theta}{\mathrm{d}t^2} = -\frac{g}{l} \theta$$



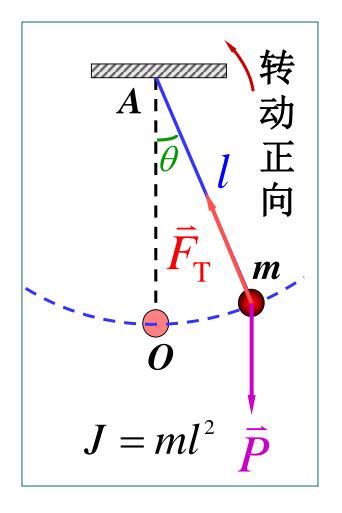


$$\frac{\mathrm{d}^2 \theta}{\mathrm{d}t^2} = -\frac{g}{l}\theta$$

$$\frac{\mathrm{d}^2\theta}{\mathrm{d}t^2} = -\omega^2\theta$$

$$\theta = \theta_{\rm m} \cos(\omega t + \varphi)$$

$$T = 2\pi \sqrt{\frac{l}{g}}$$





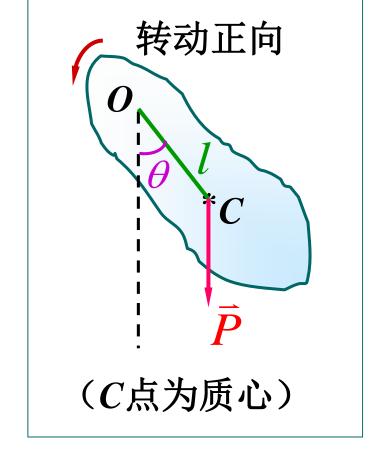
复摆 $(\theta < 5^{\circ})$

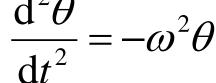
$$\vec{M} = \vec{l} \times \vec{F}$$

$$M = -mgl\sin\theta$$

$$= J\beta = J \frac{\mathrm{d}^2 \theta}{\mathrm{d}t^2}$$

$$= J\beta = J \frac{d^{2}\theta}{dt^{2}}$$
$$-mgl\theta = J \frac{d^{2}\theta}{dt^{2}}$$







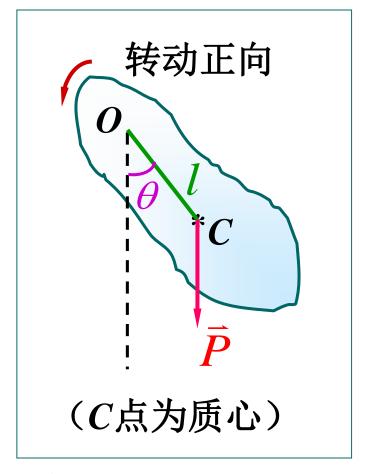
$$\frac{\mathrm{d}^2\theta}{\mathrm{d}t^2} = -\omega^2\theta$$

$$\omega = \sqrt{\frac{mgl}{J}}$$

$$\Rightarrow T = \frac{2\pi}{\omega} = 2\pi \sqrt{\frac{J}{mgl}}$$

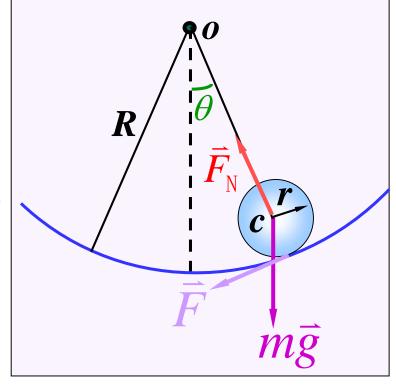
$$T = 2\pi \sqrt{\frac{J}{mgl}}$$

$$\theta = \theta_{m} \cos(\omega t + \varphi)$$
 角谐振动





例 一半径为 r 的均 质球,可沿半径为 R 的固 定大球壳的内表面作纯 滚动(如图示).试求圆球绕平衡位置作微小运动的动力学方程及其周期.





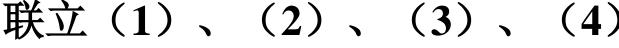
解:

$$-(mg\sin\theta+F)=ma_t(1)$$

$$Fr = \frac{2}{5}mr^2\alpha \tag{2}$$

$$a_t = (R - r) \frac{\mathrm{d}^2 \theta}{\mathrm{d}t^2} \tag{3}$$

$$a_t = r\alpha \tag{4}$$



式,得运动方程

$$\frac{R}{|\vec{F}|}$$

$$\frac{\vec{F}}{mg}$$

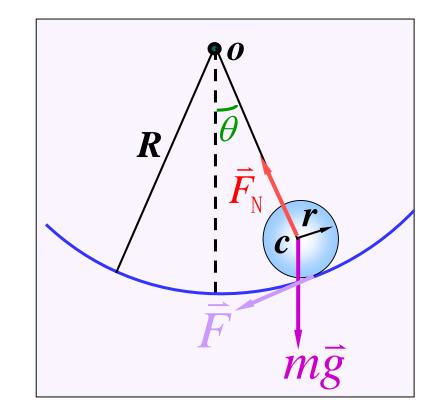
$$(4)$$



$$\frac{7}{5}(R-r)\frac{\mathrm{d}^2\theta}{\mathrm{d}t^2} = -g\sin\theta$$

 $\sin \theta \approx \theta$

$$\frac{\mathrm{d}^2 \theta}{\mathrm{d}t^2} = -\omega^2 \theta$$



$$T = 2\pi \sqrt{\frac{7(R-r)}{5g}}$$



简谐运动SHM

1、能量特征:

简谐振子的势能

$$E_p(x) \equiv V(x)$$

$$= V(0) + V'(0)x + (1/2)V''(0)x^2 + \dots$$

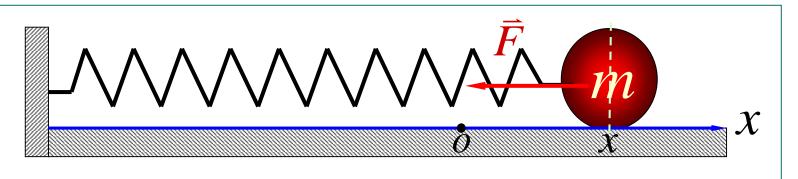
平衡位置: x = 0, V(0) = 0

平衡条件: V'(0)=0

稳定平衡: V"(0)>0



卧式弹簧振子的势能和机械能



$$F = -kx$$

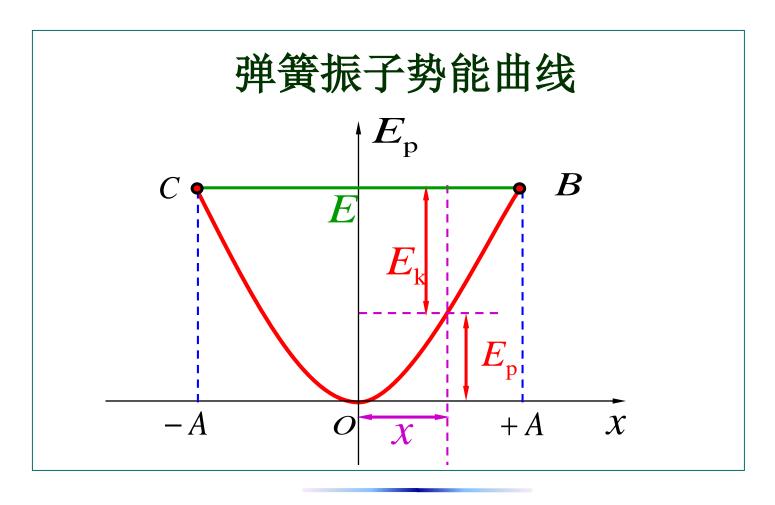
$$E_p(x) = \frac{1}{2}kx^2$$

$$E = \frac{1}{2}mv^2 + \frac{1}{2}kx^2 = 常量$$

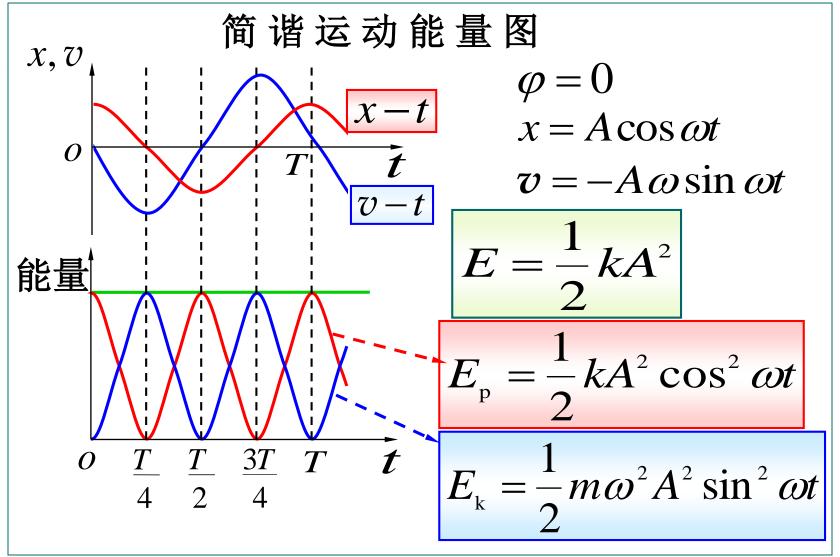
线性回 复力是保守 力,作简谐 力,的系统 机械能守恒.



弹簧振子势能 $E_p(x) = (1/2)kx^2$









9-5 当质点以频率 ν 作简谐振动时,它的 动能的变化频率为

$$(\mathbf{A})\nu$$



(A) ν **(B)** 2ν **(C)** 4ν **(D)** $\nu/2$

$$E_{\rm k} = \frac{1}{2}mv^2 = \frac{1}{2}kA^2\sin^2(\omega t + \varphi)$$

$$= \frac{1}{2}kA^2 \left[\frac{1 - \cos(2\omega t + 2\varphi)}{2} \right]$$

$$v = \frac{\omega}{2\pi}$$

$$v = \frac{\omega}{2\pi} \qquad \qquad v' = \frac{\omega'}{2\pi} = 2v$$



简谐振子的动能和势能的相位差是

- (A) 0
- (B) π
- (C) $\pi/2$
- (D) 不确定(取决于振动初相位)

Answer: B (反相, in phase)



例 质量为0.10 kg的物体,以振幅 $1.0 \times 10^{-2} \text{ m}$ 作简谐运动,其最大加速度为 $4.0 \text{ m} \cdot \text{s}^{-2}$,求:

- (1) 振动的周期;
- (2) 通过平衡位置的动能;
- (3) 总能量;
- (4) 物体在何处其动能和势能相等?

已知
$$m = 0.10 \,\mathrm{kg}$$
, $A = 1.0 \times 10^{-2} \,\mathrm{m}$, $a_{\mathrm{max}} = 4.0 \,\mathrm{m} \cdot \mathrm{s}^{-2}$

$$a_{\text{max}} = 4.0 \,\text{m} \cdot \text{s}^{-2}$$

求:(1) T; (2) $E_{k,max}$ (3) E; (4) 何处动势能相等?

Proof:
$$a_{\text{max}} = A\omega^2$$
 $\omega = \sqrt{\frac{a_{\text{max}}}{A}} = 20 \text{ s}^{-1}$

$$T = \frac{2\pi}{\omega} = 0.314 \text{ s}$$

(2)
$$E_{k,max} = \frac{1}{2}mv_{max}^2 = \frac{1}{2}m\omega^2 A^2 = 2.0 \times 10^{-3} \text{ J}$$

(3)
$$E = E_{\text{k max}} = 2.0 \times 10^{-3} \text{ J}$$

(3)
$$E = E_{k,max} = 2.0 \times 10^{-3} \text{ J}$$

(4) $E_k = E_p$ $E_p = \frac{1}{2}kx^2 = \frac{1}{2}m\omega^2x^2$
 $x = \pm 0.707 \text{ cm}$

保守系统/简谐振子的能量特征

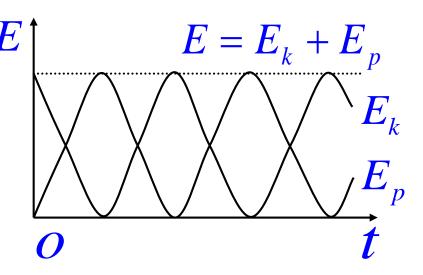
保守系统:

无内部耗散(阻尼)无外界驱动

能量守衡

$$E = E_k + E_p$$

$$H = T + V$$



势能形式 $E_p = (1/2)kx^2$



竖式弹簧振子的势能(以平衡位置为零点)

$$mg = k\Delta I_0$$

$$E_p = -mgx + \frac{1}{2}k(x + \Delta I_0)^2 - \frac{1}{2}k\Delta I_0^2$$

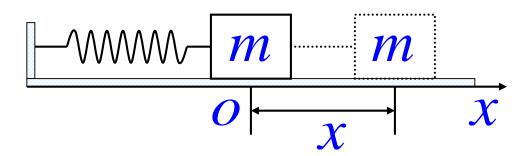
$$= \frac{1}{2}kx^2$$

Ref: Ex9-11斜面上的弹簧振子(串联)



2、动力学特征

(1)弹簧振子:



$$E = \frac{1}{2}mv^2 + \frac{1}{2}kx^2 = 常量$$

$$\ddot{x} + \omega^2 x = 0$$

$$\omega = \sqrt{k/m}$$

$$x = A\cos(\omega t + \varphi)$$



$$E = \frac{1}{2}mv^2 + \frac{1}{2}kx^2 = 常量$$

$$\frac{d}{dt}(\frac{1}{2}mv^2 + \frac{1}{2}kx^2) = 0$$

$$mv\frac{\mathrm{d}v}{\mathrm{d}t} + kx\frac{\mathrm{d}x}{\mathrm{d}t} = 0$$

$$\frac{\mathrm{d}^2 x}{\mathrm{d}t^2} + \frac{k}{m}x = 0$$



2) 单摆

$$E = \frac{1}{2}m(l\dot{\theta})^2 + mgl(1 - \cos\theta)$$

$$=\frac{1}{2}J\dot{\theta}^2 + mgl(1-\cos\theta)$$

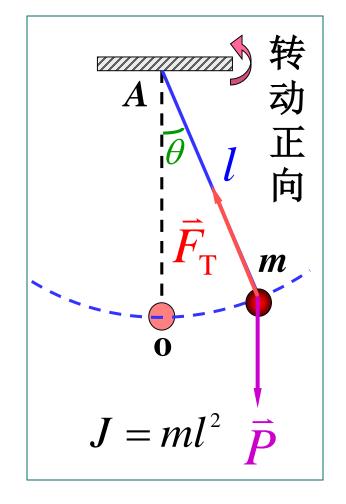
$$\ddot{\theta} + \frac{g}{l}\sin\theta = 0$$

$$\theta < 5^{\circ}$$
 时, $\sin\theta \approx \theta$



$$\ddot{\theta} + \omega^2 \theta = 0$$

$$\omega = \sqrt{g/l}$$



$$\theta = \theta_{\rm m} \cos(\omega t + \varphi)$$



(3) 复摆 $(\theta < 5^{\circ})$

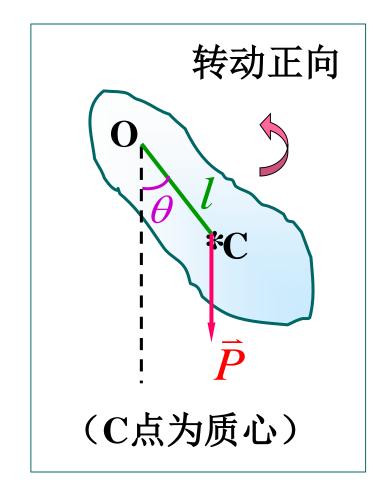
$$E = \frac{1}{2}J\dot{\theta}^{2} + mgl(1 - \cos\theta)$$

$$\ddot{\theta} + \frac{mgl}{J}\sin\theta = 0$$

$$\ddot{\theta} + \omega^{2}\theta = 0$$

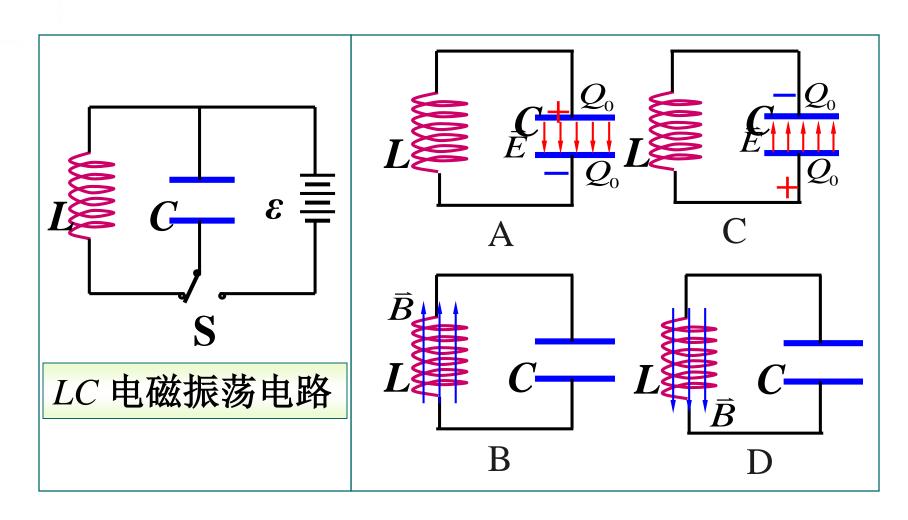
$$\omega = \sqrt{\frac{mgl_{co}}{J_{o}}}$$

$$\theta = \theta_{m}\cos(\omega t + \varphi)$$





(4) 9-7无阻尼自由电磁振荡p29



9-4 简谐运动的能量

在无阻尼自由电磁振荡过程中,电场能量和磁场能量不断的相互转化,其总和保持不变.

$$E = \frac{1}{2}LI^{2} + \frac{1}{2}\frac{Q^{2}}{C}$$

$$0 = LI\dot{I} + \frac{Q}{C}\dot{Q}$$

$$\ddot{Q} + \frac{1}{LC}Q = 0$$

$$\omega = \frac{1}{\sqrt{LC}}$$

$$Q = Q_0 \cos(\omega t + \varphi)$$

$$i = \frac{\mathrm{d}q}{\mathrm{d}t} = -\omega Q_0 \sin(\omega t + \varphi) = I_0 \cos(\omega t + \varphi + \frac{\pi}{2})$$



简谐运动的动力学特征

$$\ddot{x} + \omega^2 x = 0$$

弹簧振子

$$\omega = \sqrt{k/m}$$

单摆

$$\omega = \sqrt{g/l}$$

复摆

$$\omega = \sqrt{\frac{mgl_{CO}}{J_{O}}}$$

$$\omega = \frac{1}{\sqrt{I_{O}}}$$

LC自由电磁振荡



半径为r的匀质圆球,可沿半径为R的固定大球壳的内表面做纯滚动,如图所示。试求圆球绕平衡位置做微小运动的动力学方程及其周期。

$$v_C = (R - r)\dot{\theta} = r\omega$$

$$E_k = \frac{1}{2}mv_C^2 + \frac{1}{2}J_C\omega^2$$

$$E_p = mg(R - r)(1 - \cos\theta)$$



能量解法:

$$E = \frac{1}{2}mv_C^2 + \frac{1}{2}J_C\omega^2 + mg(R-r)(1-\cos\theta)$$

$$v_C = (R-r)\dot{\theta} = r\omega \qquad J_C = \frac{2}{5}mr^2$$

$$E = \frac{7}{10}m(R-r)^2\dot{\theta}^2 + mg(R-r)(1-\cos\theta)$$

$$\frac{7}{5}(R-r)\ddot{\theta} + g\sin\theta = 0 \quad \theta < 5^{\circ} \ \text{F}, \sin\theta \approx \theta$$

$$\ddot{\theta} + \frac{5g}{7(R-r)}\theta = 0 \qquad \omega = \sqrt{\frac{5g}{7(R-r)}}$$



3、运动学特征

物理量(x)是时间的余弦(或正弦)的函数

$$x = A\cos(\omega t + \varphi)$$

$$\theta = \theta_{\rm m} \cos(\omega t + \varphi)$$

$$Q = Q_0 \cos(\omega t + \varphi)$$